WWW.DZSC.CON 捷多邦,专业PCB打样工厂,24小时加 NJU6^{急4}52A

PACKAGE OUTLINE

BIT MAP LCD DRIVER

GENERAL DESCRIPTION

JRC 道彻NJU6452A供应商

The NJU6452A is a bit map LCD driver to display graphics or characters.

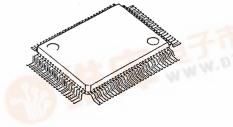
It contains 2,560 bit display data RAM, microprocessor interface circuits, instruction decoder, and 16-common and 61-segment drivers.

The bit image display data sent from 8- or 16-bit MPU are stored in the display data RAM and drives Dot Matrix LCD Panel by the common and segment drivers.

The 16-common and 61-segment drivers can drive graphics or 12-character 2-line with icon data.

The NJU6452A can combine with the NJU6452A or 6453A to expand the display capacity to 32 x 122 dots or 16 x 141 dots of graphics or character display by using the extension function of NJU6452A.

Furthermore, low current consumption due to the external clock input and wide operating voltage are useful apply to the small sized battery operated items.



NJU6452AF

FEATURES

Direct Correspondence between Display Data RAM and

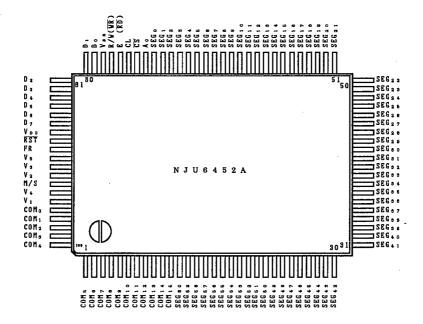
LCD Pixel

- Display Data RAM 2,560 bits 80 x 8 x 4
- Direct Interface with 8- or 16-bit MPU (Both of 68 and 80 type MPU can connect directly)
- Extension Function (can combine with NJU6452A or 6453A)
- Read Out From the Display Data RAM
- 16-common and 61-segment Drivers
- Programmable Duty Ratio ; 1/16 or 1/32 Duty
- Useful Instruction Set Display Data Read/Write, Display ON/OFF Cont, Display Data RAM Address Set, Status Read, Display Starting Line Set, Static Drive ON/OFF, Duty Ratio Setting, and Read Modify Write,
- Low Power Consumption
- External Clock Input (2kHz)
- Operating Voltage ---- 2.4V~6.0V
- LCD Driving Voltage --- 3.0V~13.5V WW.DZSC.COM
- Package Outline --- QFP 100 / Chip
- C-MOS Technology

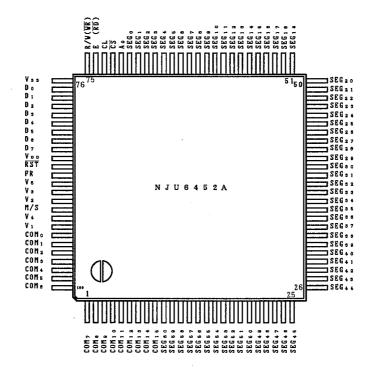




■ PIN CONFIGURATION (NJU6452AFC1)



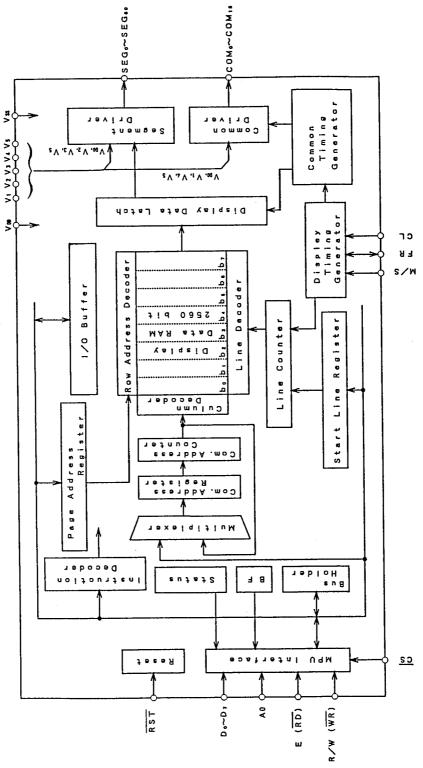
■ PIN CONFIGURATION (NJU6452AFG1)



Note) Pin configuration of "FG1" package is different from "FC1" package.

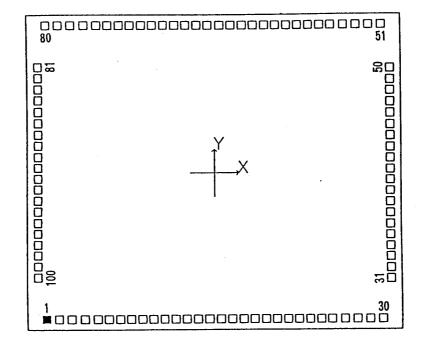


BLOCK DIAGRAM





PAD LOCATION



Chip CenterX=Oum, Y=OumChip Size4860um x 4160umChip Thickness400um ± 30umPad Size92um x 92um



PAD COORDINATES

Chip Size 4860um x 4160um(Chip Center X=0um, Y=0um)

| No. | Terminal Name | X=(um) | Y=(um) |
|----------|-------------------|--------|--------|
| 1 | COM₅ | -2130 | -1865 |
| 2 | COM | -1970 | -1865 |
| 3 | COM7 | -1810 | -1865 |
| 4 | COMB | -1650 | -1865 |
| 5 | COM® | -1490 | -1865 |
| 6 | COM10 | -1330 | -1865 |
| 7 | COM11 | -1190 | -1865 |
| 8 | COM12 | -1050 | -1865 |
| 9 | COM ₁₃ | - 910 | -1865 |
| 10 | COM14 | - 770 | -1865 |
| 11 | COM15 | - 630 | -1865 |
| 12 | S E G 60 | - 490 | -1865 |
| 13 | SEG 59 | - 350 | -1865 |
| 14 | SEG 58 | - 210 | -1865 |
| 15 | SEG 57 | - 70 | -1865 |
| 16 | SEG 56 | 70 | -1865 |
| 17 | SEG55 | 210 | -1865 |
| 18 | S E G 54 | 350 | -1865 |
| 19 | SEG 53 | 490 | -1865 |
| 20 | SEG 52 | 630 | -1865 |
| 21 | SEG 51 | 770 | -1865 |
| 22 | SEG 50 | 910 | -1865 |
| 23 | SEG ₄₉ | 1050 | -1865 |
| 24 | SEG 48 | 1190 | -1865 |
| 25 | SEG 47 | 1330 | -1865 |
| 26 | SEG ₄₆ | 1490 | -1865 |
| 27 | SEG 45 | 1650 | -1865 |
| 28 | SEG 44 | 1810 | -1865 |
| 29 | SEG ₄₃ | 1970 | -1865 |
| 30 | SEG 4 2 | - 2130 | -1865 |
| 31 | SEG ₄₁ | 2213 | -1354 |
| 32 | SEG40 | 2213 | -1214 |
| 33 | S E G 3 9 | 2213 | -1074 |
| 34 | SEG 38 | 2213 | - 934 |
| 35 | SEG 37 | 2213 | - 794 |
| 36 | S E G 36 | 2213 | - 654 |
| 37 | S E G 3 5 | 2213 | - 514 |
| 38 | SEG 34 | 2213 | - 374 |
| 39 | SEG ₃₃ | 2213 | - 234 |
| 40 | SEG 3 2 | 2213 | - 94 |
| 41 | SEG 3 1 | 2213 | 46 |
| 42 | SEG 30 | 2213 | 186 |
| 43 | S E G 29 | 2213 | 326 |
| 44 | S E G 28 | 2213 | 466 |
| 45 | S E G 27 | 2213 | 606 |
| 46 | SEG 26 | 2213 | 746 |
| 47 | SEG 25 | 2213 | 886 |
| 48 | S E G 24 | 2213 | 1026 |
| 49 | S E G 23 | 2213 | 1166 |
| 50 | S E G 2 2 | 2213 | 1306 |
| * Pad Si | | | |
| | | | |

| No. | Terminal Name | X=(um) | Y=(um) |
|------|-------------------|--------|--------|
| 51 | S E G 2 1 | 2130 | 1865 |
| 52 | SEG 20 | 1970 | 1865 |
| 53 | S E G 19 | 1810 | 1865 |
| 54 | S E G 18 | 1650 | 1865 |
| 55 | S E G 17 | 1490 | 1865 |
| 56 | SEG16 | 1330 | 1865 |
| 57 | S E G 1 5 | 1190 | 1865 |
| 58 | S E G 1 4 | 1050 | 1865 |
| 59 | SEG 13 | 910 | 1865 |
| 60 | S E G 1 2 | 770 | 1865 |
| 61 | SEGII | 630 | 1865 |
| 62 | SEG ₁₀ | 490 | 1865 |
| 63 | SEG, | 350 | 1865 |
| | | 210 | 1865 |
| 64 | SEG: | 70 | 1865 |
| 65 | SEG7 | | |
| 66 | SEG. | - 70 | 1865 |
| 67 | SEG₅ | - 210 | 1865 |
| 68 | SEG₄ | - 350 | 1865 |
| 69 | SEG 3 | - 490 | 1865 |
| 70 · | SEG₂ | - 630 | 1865 |
| 71 | SEG1 | - 770 | 1865 |
| 72 | SEGo | - 910 | 1865 |
| 73 | Ao | -1050 | 1865 |
| 74 | OSC1 | -1190 | 1865 |
| 75 | OSC2 | -1330 | 1865 |
| 76 | - E | -1490 | 1865 |
| 77 | R/W | -1650 | 1865 |
| 78 | Vss | -1810 | 1865 |
| 79 | DB ₀ | -1970 | 1865 |
| 80 | D B 1 | -2130 | 1865 |
| 81 | D B 2 | -2213 | 1330 |
| 82 | D B 3 | -2213 | 1190 |
| 83 | D B 4 | -2213 | 1050 |
| 84 | DB4 | -2213 | 910 |
| | | -2213 | 770 |
| 85 | | -2213 | 630 |
| 86 | <u> </u> | -2213 | 490 |
| 87 | | | 350 |
| 88 | RST | -2213 | |
| 89 | FR | -2213 | 210 |
| 90 | <u>V 5</u> | -2213 | 70 |
| 91 | V 3 | -2213 | - 70 |
| 92 | V 2 | -2213 | - 210 |
| 93 | M/S | -2213 | - 350 |
| 94 | V 4 | -2213 | - 490 |
| 95 | V 1 | -2213 | - 630 |
| 96 | COMo | -2213 | - 770 |
| 97 | COM | -2213 | - 910 |
| 98 | COM ₂ | -2213 | -1050 |
| 99 | COM3 | -2213 | -1190 |
| 100 | COM4 | -2213 | -1330 |



N J U 6 4 5 2 A

Terminal Description

| | | on | |
|----------------------|----------------------|-------------------------------|--|
| No | | Symbol | Function |
| FG1 | FC1 | | |
| 85 | 87 | | Power Supply : V _{DD} =+5V |
| 76 | 78 | Vss | GND : V _{ss} = OV |
| 88, 89 90, 92, 93 | 90, 91 92, 94, 95 | V_5, V_4 V_3, V_2, V_1 | LCD Driving Voltage Supplying Terminal. Following relation must be maintained. $V_{DD} \ge V_1 \ge V_2 \ge V_3 \ge V_4 \ge V_5$ |
| 72 | 74 | CS | Chip Select Signal Input Terminal. Normally input the decoded signal of Address Bus Signal. Active "L". |
| 73 | 75 | CL | Display Data Latch Signal Input Terminal. The Line Counter also count up by this signal rising timing. The synchronized signal of the NJU6450A is required. |
| 74 | 76 | E | <pre></pre> |
| | | (RD) | Connect to Enable Clock Input Terminal of 68 type MPU. Active "H". <when 80="" connect_to="" mpu="" the="" type=""> Connect to RD Signal Input Terminal of 80 type MPU. Active "L" During this terminal is "L", the Data Bus is output state.</when> |
| 75 | 77 | R/W | <pre>{When connect to the 68 type MPU> Connect to READ/WRITE Control Signal Input Terminal of 68 type MPU. R/W H L Status Read Write</pre> |
| | | (WR) | <when 80="" connect="" mpu="" the="" to="" type=""> Connect to WR Signal connecting terminal of 80 type MPU. Active "L". The data on the Data Bus is fetch at the rising edge of this signal.</when> |
| 71 | 73 | AO | Connect to the Address Bus of MPU. The data on the D ₀ ~D ₇ is distin- guished between Display Data and Instruction by this signal. AO H L Data Display Data Instruction |
| 77~84 | 79~86 | D o~ D 7 | Tri-state bilateral Data Bus. The data transmission between 8- or 16-bit MPU and NJU6452A is executed by this Bus. |
| 87 | 89 | FR | Alternating signal for LCD Driving output or input terminal. |
| | | | Output or input is determined by master or slave mode which selected by M/S terminal. M/S Master Slave FR Output Input |
| 94~100 | 96~100 | COM₀ ~COM₁₅ | Common output terminal. One output level out of V_{DD} , V_1 , V_4 , V_5 is selected by combination of FR and data of common counter. |
| 1~9 | 1~11 | (COM₃ 1 | FR H L |
| | | ~COM16) | Data H L H L |
| | | (Note) | Output V_5 V_1 V_{DD} V_4 |
| 70~10 | 72~12 | SEG₀ ∼SEG₅₀ | Segment output terminal. One output level out of V _{DD} , V ₂ , V ₃ , V ₅ is selected by combination of FR and data of Display RAM. FR H Data H L |
| | | | Output V_{DD} V_2 V_5 V_3 |
| 86 | 88 | RST | Reset and Interface type select terminal. The reset operation is performed by rise or fall edge of this signal. The input level after initialization selects the interface type of 68 or 80 type of MPU. MPU Edge Input Level after initialization selects the interface type of 68 or 80 type of MPU. MPU Edge Input Level after initialization 68 Type Rise 80 Type Fall |
| 91 | 93 | M/S (Note) | $\begin{array}{c ccccccccccccccccccccccccccccccccccc$ |

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Functional Description

- (1) Description for each blocks
 - (1-1) Busy Flag (BF)

When the internal circuits are in the operation mode, the busy flag(BF) is "1", and any instruction except the status read are inhibited.

The busy flag is output at D_7 terminal when status read instruction is executed.

If enough cycle time over than t_{cvc} is kept, no need to check the busy flag.

(1-2) Display Start Line Register

The Display Start Line Register is a pointer register which indicate the address in the Display Data RAM corresponded with COM_0 (normally it display the top line in the LCD Panel). This register can use for scroll the screen, change the display page and so on.

The Display Start Line instruction set the display start address of the Display Data RAM represented in 5-bit to this register.

(1-3) Line Counter

The Display Start Address stored in the Display Start Line Register is set to the Line Counter when the FR signal out from the NJU6452A is chenging.

The Line Counter count up by synchronizing common signal out from NJU6452A and generate the line address which addressing the read out line of Display Data RAM.

(1-4) Column Address Counter

The column address counter is 7-bit presettable counter which addressing the column address as shown as Fig. 1.

This counter increments "1" up to 50H when the Display Data Read/Write instruction is executed. The count up is stop at 50H (over 50H is non existing address) automatically by the count lock function.

Furthermore, this counter is independent with the Page Register.

(1-5) Page Register

This register gives page address of Display Data RAM as shown Fig. 1. When the MPU access the data by changing the page, the page address set instruction is required.

(1-6) Display Data RAM

Display Data Ram consist of 2,560 bits stores the bit image display data (each bit correspond to the each pixel so called bit map method). This RAM and MPU are operating independently, therefore, there is

no influence by the unsynchronize rewriting.

The each bit in the Display Data RAM correspond to the each dot of the LCD panel.

0 n = "1"

Off = "0"

The relation between column address and segment output can inverse by the Address Inverse Instruction ADC as shown Fig. 1.

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(1-7) Timing Generator

This Generator generates the common timing and frame signal for 1/16 and 1/32 duty selecting by Duty Select Instruction from the master clock.

In the case of the 1/32 duty, 2 chip of master and slave chip should be combined, and both of common are synchronized by the common multi-chip method. (Refer the figure shown below)

| FR (Master C | utput) | • |
|------------------|--|---|
| Master Common | $0\times1\times2$ -14×15 $0\times1\times2$ -14×15 $$ | • |
| Slave Common | | • |

(1-8) Display Data Latch

Display Data Latch stores 80-bit of one line display data for each common cycle which read out from the Display Data RAM temporary and transfer this data to the LCD Driver. The Display On/Off and Static Drive On/Off controls the latched data only, therefore, the data in the Display Data RAM is no change and keep on remaining.

(1-9) LCD Driving Circuits

This Driver is consists of 80-multiplexer which output the 4-level of LCD driving voltage. The output waveform is determined by the combination of the data in the Display Data Latch, Common Timing Generator and FR signal

(1-10) Display Timing Generator

This Generator generates the timing signal for the display system by combination of the master clock and Frame Driving Signal FR. The Frame Driving Signal FR has a function to generate the 2 frame alternative driving method waveform for the LCD panel, and synchronizing the line counter and common timing generator to the master LSI. Therefore, the FR signal must be 50% duty ratio clock signal which synchronized with the frame signal.



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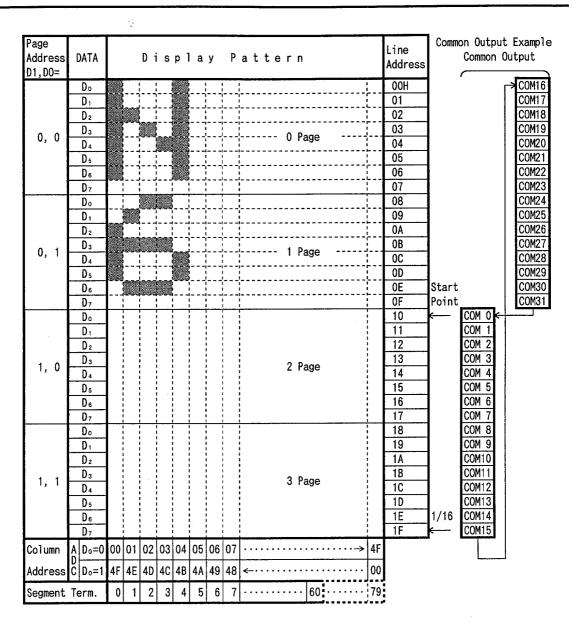


Fig. 1. Correspondence with Display Data RAM and address (For example the display start line is 10th and 1/32 duty)

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(1-11) Reset Circuits

The NJU6452A performs following initialization by detecting the rising or falling edge of the $\overline{\text{RST}}$ input after the power turns on.

Initialization

- Display Off
- ② Set the 1st line to the Display Start Register
- ③ Static Drive Off
- ④ Set the address "0" to the Column Address Counter
- (5) Set the page "3" to the Page Address Register
- ⑥ Select the 1/32 duty
- (7) Select the ADC : Counterclockwise output
 - (ADC instruction $D_0 = "0"$, ADC status flag "1")
- (8) Read Modify Write Mode Off

The $\overline{\text{RST}}$ terminal input level is used to select the interface of 80 or 68 type MPU as shown in Table. 2. Therefore, the "H" level input through the inverter is required when connecting the 80 type MPU, and "L" level input is required when connecting the 68 type MPU as shown in application circuits 1.

The $\overline{\text{RST}}$ terminal must be connect to the Reset Terminal of MPU and reset at same time with it. The dead-lock may occur if the no initialization by the $\overline{\text{RST}}$ terminal when the power terns on. By the RESET instruction, the initialization of ② and ⑤ mentioned above are executed.

5

(2) Instruction

The NJU6452A distinguish the signal on the data bus by combination of AO and $R/W(\overline{RD},\overline{WR})$. Normally, the busy check is not required as the NJU6452A is operating so first because of the decode of the instruction and execution are performs only depend on the internal timing which not depend on the external clock.

The Table. 1 shows the instruction codes of the NJU6452A.

N J U 6 4 5 2 A

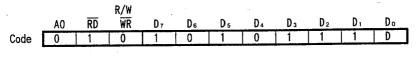
Table 1. Instruction Code

| | | | | C | o d | е | | | | | | Descript | ion | | |
|--------------------------|-----|----|-----|------------------|-------------|-----------|-----------------------|--------------|---------------|-----------|------------|---|---|--|--|
| Instruction | AO | RD | WR | D7 | De | Ds | D₄ | D₃ | D2 | Dı | Do | Descript | | | |
| Display On / Off | 0 | 1 | 0 | 1 | 0 | 1 | 0 | 1 | 1 | 1 | 0/1 | Whole Display On/Off. 1:On,O:Off(Power Save mode if the static Drive On) | | | |
| Display Start Line | 0 | 1 | 0 | 1 | 1 | 0 | Dis | play (| Start 1~31 | Addr) | ess | Determine the correspond to | Display Line the COMo. | | |
| Page Address Set | 0 | 1 | 0 | 1 | 0 | 1 | 1 | 1 | 0 | | ,ge ~3) | Set the Page o RAM to the Pag | | | |
| Column Address Set | 0 | 1 | 0 | 0 | | C | | Addr 0∼79 | | | | Set the Column Display Data R Column Registe | AM to the | | |
| Status Read | 0 | 0 | 1 | B U S Y | A D C | ON OFF | R E S E T | 0 | 0 | 0 | 0 | 0:Count | ng wise Output erclockwise Off O:Disp On | | |
| Write Display Data | 1 | 1 | 0 | | L | | Write | e Data | 1 | | | Write the data to the Display Data RAM. Write the predeter- mined add- ress of the Display Data | | | |
| Read Display Data | 1 | 0 | 1 | | | | Read | Data | | | | Read the data from the Display Data RAM. | RAM. The Column address inc- rement "1" after read or write. | | |
| ADC Select | 0 | 1 | 0 | 1 | 0 | 1 | 0 | 0 | 0 | 0 | 0/1 | Determine the counterclockwi of the Display O:Clockwise 1:Counterclo | se reading / Data RAM. | | |
| Static Drive On / Off | 0 | 1 | 0 | 1 | 0 | 1 | 0 | 0 | 1 | 0 | 0/1 | Static Driving 1:Static Dr | g. riving er Saving) | | |
| Duty Ratio Select | 0 | 1 | 0 | 1 | 0 | 1 | 0 | 1 | 0 | 0 | 0/1 | Select the du 1:1/32 Duty | ty ratio. y 0:1/16 Duty | | |
| Read Modify Write | 0 | 1 | 0 | 1 | 1 | 1 | 0 | 0 | 0 | 0 | 0 | Increment the Column Add- ress register when writing but no-change when reading. | | | |
| End | 0 | 1 | 0 | 1 | 1 | 1 | 0 | 1 | 1 | 1 | 0 | Release from the Read Modify Write Mode. | | | |
| Reset | 0 | 1 | 0 | 1 | 1 | 1 | 0 | 0 | 0 | 1 | 0 | Set the Display Start Line Register to 1st line, Page Add. Register to "3". | | | |
| Power Save (Dual | 0 | 1 | 0 | 1 | 0 | 1 | 0 | 1 | 1 | 1 | 0 | Set the power selecting Dis Static Drivin | play Off and | | |
| Command) | U U | | 1.0 | | U | | | U. | <u> </u> | ` | 1 | | | | |



- (3) Explanation of Instruction Code.
 - (a) Display On/Off

This instruction executes whole display On/Off no relation with the data in the Display Data RAM and internal conditions.



D 0 : Display On 1 : Display Off

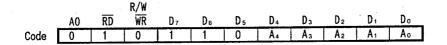
When the static driving mode is selected (static drive On) in display Off status, the internal circuits put on the power save mode.

(b) Display Start Line

This instruction set the line address as shown Fig. 1. The selected line in the Display Data RAM correspond to the COM_0 which display at the top of LCD panel.

The display area is set automatically from the selected line to the line which increased the number of duty ratio.

Therefore, the smooth scroll for vertical direction by changing the start line address one by one or page switching are available by this instruction.



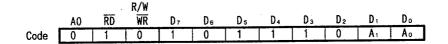
| A4 | Aз | A2 | Aı | Ao | Line Address |
|----|----------|----|----|----|--------------|
| 0 | 0 | 0 | 0 | 0 | 0 |
| | | | | 1 | 1 |
| 1 | 1 | 1 | 1 | 0 | 1E |
| 1 | <u> </u> | 1 | 1 | 1 | 1F |

(c) Page Address Set

When MPU access the Display Data RAM, the page address corresponded to the row address must be selected.

The access in the Display Data RAM is available by setting the page and column address. (Refer the Fig. 1.)

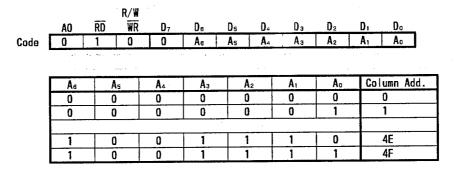
The display is no change when the page address is changed.



| A1 | Ao | Page |
|----|----|------|
| 0 | 0 | 0 |
| 0 | 1 | 1 |
| 1 | 0 | 2 |
| 1 | 1 | 3 |

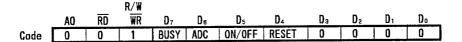
(d) Column Address Set

This instruction set the column address in the Display Data RAM.(See Fig.1.) When the MPU access the Display Data RAM continuously, the column address increase "1" automatically, therefore, the MPU can access the data only without address setting. The increment of the column address is stopped by the address of $50_{\rm H}$ automatically, but the page address is no change even if the column address increase to $50_{\rm H}$ and stop.



(e) Status Read

This instruction read out the internal status.



BUSY : BUSY=1 indicate the operating or the Reset cycle. The instruction can be input after the BUSY status change to "0".

ADC : Indicate the output correspondence of column(segment) address and segment driver.
0 :Counterclockwise Output(Inverse) Column Address 79-n ←→ Segment Driver n
1 :Clockwise Output (Normal) Column Address n ←→ Segment Driver n

ON/OFF : Indicate the whole display On/Off status.

0 : Whole Display "On"

- 1 : Whole Display "Off"
- (Note) The data "O=On" and "1=Off" of Display On/Off status read out is inverted with the Display On/Off instruction data of "1=On" and "O=OFf".

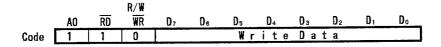
RESET : Indicate the initialization period by RST signal or reset instruction.

0: - -

1 : Initialization Period

(f) Write Display Data

This instruction write the 8-bit data on the data bus into the Display Data RAM. The column(segment) address increase "1" automatically when writing, therefore, the MPU can write the 8-bit data into the Display Data RAM without address setting.

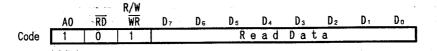




(g) Read Display Data

This instruction read out the 8-bit data from Display Data RAM which addressed by the column and page address. In case of the Read Modify Write Mode is Off, the column address increase "1" automatically after each read out, therefore, the MPU can read out the 8-bit data from the Display Data RAM continuously without address setting.

One time of dummy read must be required after column address set as explain in (4-3).



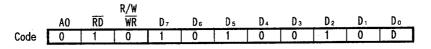
(h) ADC Select

This instruction set the correspondence of column address in the Display Data RAM and segment driver output. (See Fig. 1.) Therefore, the order of segment output can be changed by the software, and no restriction of the LSI placement against the LCD panel.

| | A0 | RD | R∕₩ ₩R | D7 | De | D₅ | D₄ | D3 | D2 | Dı | Do |
|------|----|------------------|-----------|----|----------------|----|--------------------|----|----|----|----|
| Code | 0 | 1 | 0 | 1 | 0 | 1 | 0 | 0 | 0 | 0 | D |
| | D | 0 : C1 1 : Cc | | | out ise Out | | (Invers (Normal | | | | |

(i) Static Drive On/Off

This instruction executes the all common output terns on and whole display on obligatory.

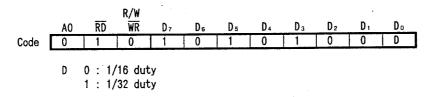


D 0 : Static Drive Off (Normal Operation) 1 : Static Drive On (Whole Display Turns On)

When the Display Off mode is selected (Display Off) in Static Drive On status, the internal circuits put on the power save mode.

(j) Duty Select

This instruction set the LCD driving duty ratio.

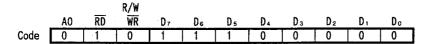


(k) Read Modify Write

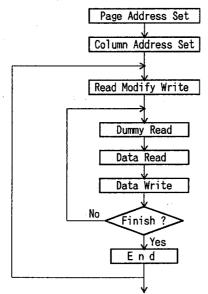
After this instruction is executed, the column address increase "1" automatically when Display Data Write Instruction execution, but the address is not changed when the Display Data Read Instruction execution.

This status continues during End instruction execution. When the End instruction is entered the column address back to the address where Read Modify Write instruction entering.

By this function, the load of MPU for example cyclic data writing operation like as cursor blink etc., can be reduced.

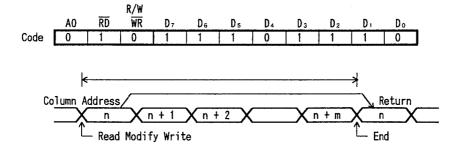


- Note) During the Read Modify Write mode, any instruction except Column Address Set can be executed.
- (1) Sequence of cursor display



(m) End

This instruction release the Read Modify Write mode and the column address back to the address where the read modify write mode setting.



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(n) Reset

This instruction executes the following initialization.

Initialization

① Set the 1st line in the Display Start Line Register.

② Set the page 3 in the Page Register.

In this time, there are no influence to the Display Data RAM.

R/₩ D۵ A0 RD WR De D، D, D-D₂ D D. Ò 0 0 0 0 Code Ô 1

The reset signal input to the $\overline{\text{RST}}$ terminal must be required for the initialization when the power terms on.

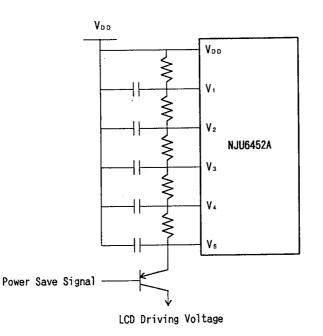
(Note) The initialization when the power turns on can not be executed by Reset instruction.

(o) Power Save(Dual Command)

When both of Display Off and Static Drive On are executed, the internal circuits put on the power save mode and the current consumption is reduced as same as stand by current. The internal status in this mode are as follows;

- Stop the LCD driving. Segment and Common drivers output V_{DD} level.
- ② Stop the oscillation or inhibit the external clock input. Then the terminal OSC₂ becomes floating status.
- (3) Keeping the display data and operating mode.

The power save mode is released by Display on or static drive off instruction. To reduce the total power consumption, the current flow on the bleeder resistance must be cut by the transistor etc. during the power save mode as shown below.





(4) MPU Interface

(4-1) 68 or 80 type MPU interface selection.

The NJU6452A can interface both of 68 or 80 type MPU bus directly by setting the RST level after reset instruction entered as shown Table. 2.

The data transfer is executed between $D_{\circ} \sim D_{7}$ of NJU6452A and the MPU data bus.

Duaring the CS signal is "H", the NJU6452A rereased from the the MPU and becomes stand-by mode. But the reset instruction can be input though the internal status of NJU6451A.

Table, 2.

| Level of RST | Type of MPU | AO | Е | R/W | D ₀ ~ D ₇ |
|--------------|-------------|-----|----|-----|---|
| "H" | 68 type | 1 Î | Î | î | Î |
| ″L″ | 80 type | Î | RD | ŴŔ | 1 |

(4-2) Discrimination of the data bus signal.

The NJU6452A discriminates the data bus signal by combination of AO, $E(\overline{RD})$, and $R/W(\overline{WR})$ signals as shown Table. 3.

Table. 3.

| Common | 68 type | 80 t | уре | Function | | | |
|--------|---------|------|-----|-------------------------------|--|--|--|
| AO | R/W | RD | ŴŔ | FUNCTION | | | |
| 1 | 1 | 0 | 1 | Display Data Read out | | | |
| 1 | 0 | 1 | 0 | Display Data Write | | | |
| 0 | 1 | 0 | 1 | Status Read | | | |
| 0 | 0 | 1 | 0 | Command Input to the Register | | | |

(4-3) Access to the Display Data RAM and Internal Register.

The NJU6452A is operating as one of Pipe-line processor by the bus-holder connecting to the internal data bus to adjust the operation frequency between MPU and the Display Data RAM or Internal Register.

For example, when the MPU write the data into the Display Data RAM, the data is held in the bus-holder at once then write into the Display Data RAM by next data write cycle.

Therefore high speed data transmission between MPU and NJU6452A is available because of the limitation of access time of NJU6452A locking from MPU is just determined by the cycle time only which ignored the access time of t_{ACC} and t_{DS} of Display Data RAM.

If the cycle time can not be kept in the MPU operation, NOP operation cycle must be insert which equivalent to the waiting operation.

Please note that the read out data is a address data when the read out execution just after the address setting. Therefore, one dummy read is required after address setting or write cycle as shown in Fig. 2.

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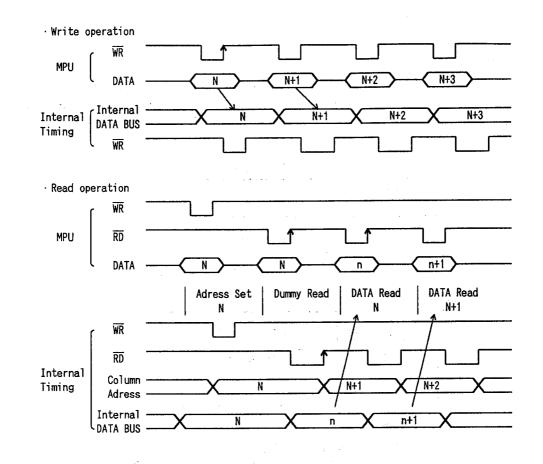


Fig.2 MPU Interface Timing

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ABSOLUTE MAXIMUM RATINGS

(Ta=25°C)

| PARAMETER | SYMBOL | RATINGS | UNIT |
|-----------------------|--------------------|--------------------|------|
| Supply Voltage (1) | Voo . | - 0.3 ~ + 7.0 | V |
| Supply Voltage (2) | $V_1 \sim V_5$ (3) | Voo-13.5 ~ Voo+0.3 | V |
| Input Voltage | VIN | - 0.3 ~ Voo+0.3 | V |
| Operating Temperature | Topr | - 30 ~ + 80 | °C |
| Storage Temperature | Tstg | - 55 ~ + 125 | °C |

Note 1) If the LSI are used on condition above the absolute maximum ratings, the LSI may be destroyed. Using the LSI within electrical characteristics is strongly recommended for normal operation. Use beyond the electric characteristics conditions will cause malfunction and poor reliability.

Note 2) All voltage values are specified as $V_{ss} = 0$ V.

Note 3) The relation : $V_{DD} \ge V_1 \ge V_2 \ge V_3 \ge V_4 \ge V_5$ must be maintained.

ELECTRICAL CHARACTERISTICS

(V₀₀=5V±10%, V₅₅=0V, Ta=-20~+75°C)

| PARAM | ETER | SYMBOL | CONDI | TIONS | MIN | түр | MAX | UNIT | Note |
|---------------|-----------|----------------|--------------------------|--------------------------|-----------------------|------|-----------|------|------|
| Operating | Recommend | v | | • . | 4.5 | 5.0 | 5.5 | v | |
| Voltage(1) | Available | Voo | | | 2.4 | | 6.0 | | 4 |
| | Recommend | v | · · | | Voo-13.5 | | Voo-3.5 | | |
| Operating | Available | V₅ | | | V ₀₀ -13.5 | | | v | |
| Voltage(2) | Available | V2 | VLCD=VDD-V5 | , | Voo-0.6xV | LCD | Voo |] ` | |
| | Available | ۷ ₃ | VLCD=VDD-V5 | and the second | Vs · | Voo | -0.4xVLCD | | |
| | 1 | VIHT | CS, AO, D₀~ | D7, E, R/W | 2.0 | | VDD | | |
| Input | I | VILT | | Terminals | Vss | | 0.8 | v | |
| Voltage | 2 | Vıнс | CL, FR, RST | | 0.8xVpp | | VDD |] ' | |
| | 2 | VILC | | Terminals | Vss | | 0.2xV00 | | |
| | | Vонт | Do~D7 | Iон=-3.0mA | 2.4 | - | | | |
| Output | | VOLT | Terminals | IoL= 3.0mA | | | 0.4 | | |
| Voltage | 4 | Vonci | FR Terminal | Iон=-2.0mA | 2.4 | | | v | |
| | 1 | VOLCI | rn terminat | IoL= 2.0mA | | | 0.4 | · · | |
| Input Leaka | ge | ILI | AO, E, R/W, | CS, CL, RST | -1.0 | | 1.0 | uA | |
| | Current | Ιιο | D₀∼D7, FR T | erminals | -3.0 | | 3.0 | ů. | 5 |
| Dation On a | | B | Ta=25°C | V₅=V _{DD} -5.0V | | 5.0 | 7.5 | kΩ | 6 |
| Driver On-r | esistance | Ron | | V5=V00-3.5V | | | | K 32 | |
| Stand-by Cu | rrent | Ισοα | CS=CL=Vpc | | | 0.05 | 1.0 | uA | |
| Occuption - 0 | | IDDI | Display V₅=V fc∟=2kHz | 00-5.0V, | | 2.0 | 5.0 | uA | |
| Operating C | urrent | Ioo2 | Accessing, t | cyc=200kHz | | 300 | 500 | UA | 7 |
| Reset time | | t, | RST Terminal | | 1.0 | | 1000 | us | |

Note 4) NJU6452A can operate wide operating range, but it is not guarantee immediate voltage changing during the accessing of the MPU.



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- Note 5) Apply to the High-impedance state of DO to D7 and FR terminals.
- Note 6) R_{ON} is the resistance values between power supply terminals(V_1, V_2, V_3, V_4) and each output terminals of common and segment supplied by 0.1V.
- Note 7) The IDD2 is specified under the condition of cyclic(tcyc)inverted data input continuously. The operating current during the accessing is proportionate to the frequency of tcyc. In the no accessing it is as same as IDD1.

BUS TIMING CHARACTERISTICS

| PARA | ΜΕΤΕ | R | SYMBOL | MIN | MAX | CONDITION | UNIT |
|--|---------|--|------------------|------|----------------|-----------|------|
| Address Set l | Jp Time | 40 D/W | t _{aw6} | 20 | | | |
| Address Hold Time System Cycle Time | | Terminals | t _{AH6} | 10 | | | |
| | | | teres . | 1000 | | 2 A 19 | |
| Enable · | Read | | tew | 100 | 44 - 1 - 1 - 1 | a and an | |
| Pulse Width | Write | AO, R/W Terminals E Terminal D₀~D7 Terminals | LEW | 80 | | | ns |
| Data Set Up Time | | | t _{os6} | 80 | | | 115 |
| Data Hold Time | | Do~D7 | tons | 10 | | | |
| Access Time | | Terminals | tACC6 | ** | 90 | С.=100рF | |
| Output Disab | le Time | | t _{CH6} | 10 | 60 | or~ioobi. | |

· Read / Write operation sequence (68 Type MPU) ($V_{p_p}=5.0V \pm 10\%, V_{s_s}=0V, Ta=-20 \sim +75^{\circ}C$)

Note 8) Input signal rise time(tr) and fall time(tr) are less than 15ns.

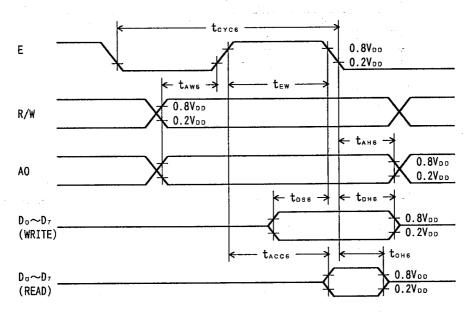


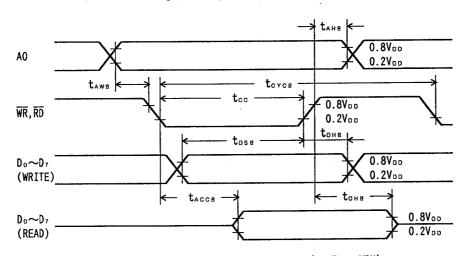
fig.3 Bus Read / Write operation sequence (68 Type MPU)

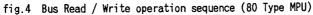


| PARAMETE | SYMBOL | MIN | MAX | CONDITION | UNIT | |
|---|-----------|-------------------|------|-----------|----------------|------|
| Address Set Up Time | AO | tAWB | . 20 | | and the second | ···· |
| Address Hold Time | Terminal | t _{ahb} | 10 | | | |
| System Cycle Time RW, WR | | teres | 1000 | | | |
| Control Pulse Width | Terminals | t _{cc} . | 200 | | | |
| Data Set Up Time | | tosa | 80 | | | ns |
| Data Hold Time Do~D7 RD Access Time Terminals Output Disable Time | | -D7 tons | 10 | | | |
| | | t _{ACC8} | | 90 | - CL=100pF | |
| | | tснв | 10 | .60 | | |

· Read / Write operation sequence (80 Type MPU) $(V_{DD}=5.0V\pm10\%, V_{SS}=0V, Ta=-20\sim+75^{\circ}C)$

Note 9) Input signal rise time(tr) and fall time(tr) are less than 15ns.





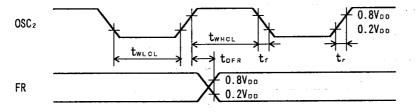


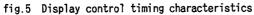
 \cdot Display control timing characteristics (Both of 68 and 80 type MPU)

| Input Timing | (V _{op} =5.0V±10%,V _{ss} =0V,Ta=-20~+75°C) | | | | | | |
|--------------------------------|--|------|-----|-----|-----------|------|--|
| PARAMETER | SYMBOL | MIN | ТҮР | MAX | CONDITION | UNIT | |
| "L" level Pulse Width | twici | 35 | | | | us | |
| "H" level Pulse Width | twhel | 35 | | | | | |
| Rise Time | tr | | 30 | 150 | | | |
| Fall Time | tr | 1 | 30 | 150 | | ns | |
| FR Delay Time (NJU6452A Slave) | tofr | -2.0 | | 2.0 | | us | |

Output Timing

| PARAMETER | SYMBOL | MIN | ТҮР | MAX | CONDITION | UNIT |
|---------------------------------|--------|-----|-----|-----|-----------|------|
| FR Delay Time (NJU6452A Master) | tofr | | 0.2 | 0.4 | CL=100pF | us |

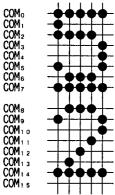


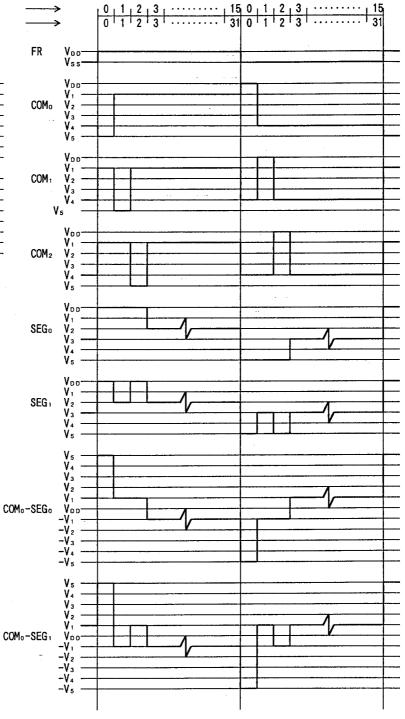


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LCD DRIVING WAVEFORM

1/5 BIAS, 1/16 DUTY 1/6 BIAS, 1/32 DUTY



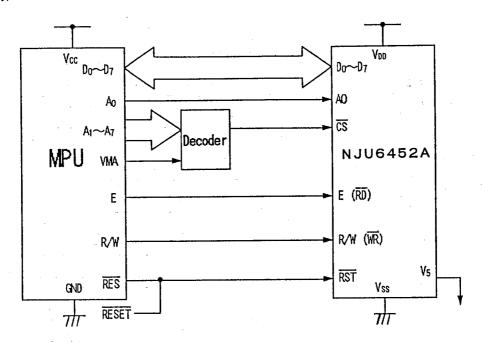




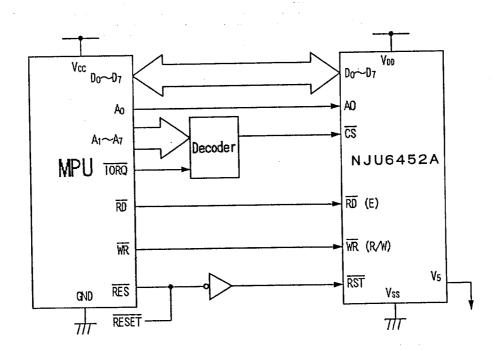


APPLICATION CIRCUITS 1

· 68 type MPU Interface



· 80 type MPU Interface

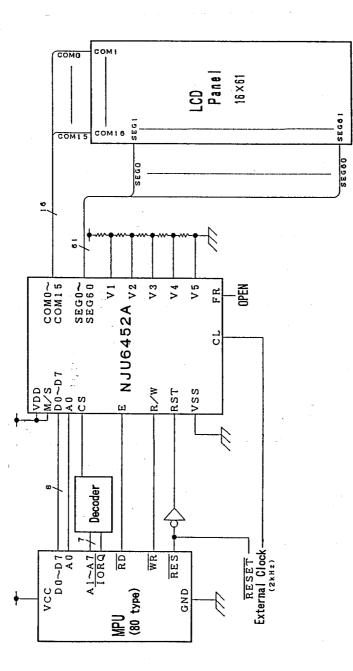


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APPLICATION CIRCUITS 2

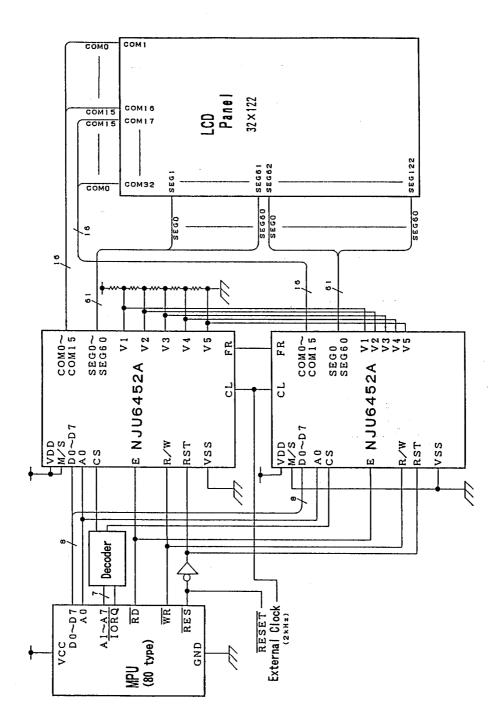
(1) 16 x 61 dots Driving Application Circuits (NJU6452A Single Operation)



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(2) 32 x 122 dots Driving Application Circuits

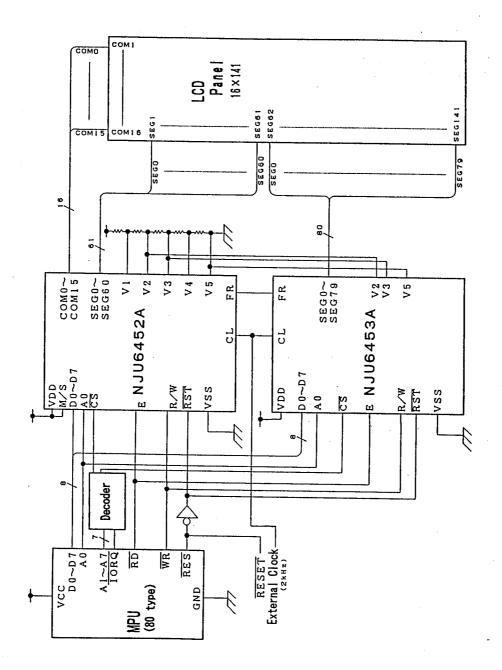
(Common and Segment Drivers Extension by using two of NJU6452A)



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(3) 16 x 141 dots Driving Application Circuits

(Segment Drivers Extension by using NJU6453A)



MEMO

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- Now Janan Padia Ca Std -