

# SIEMENS

## Hall Sensor

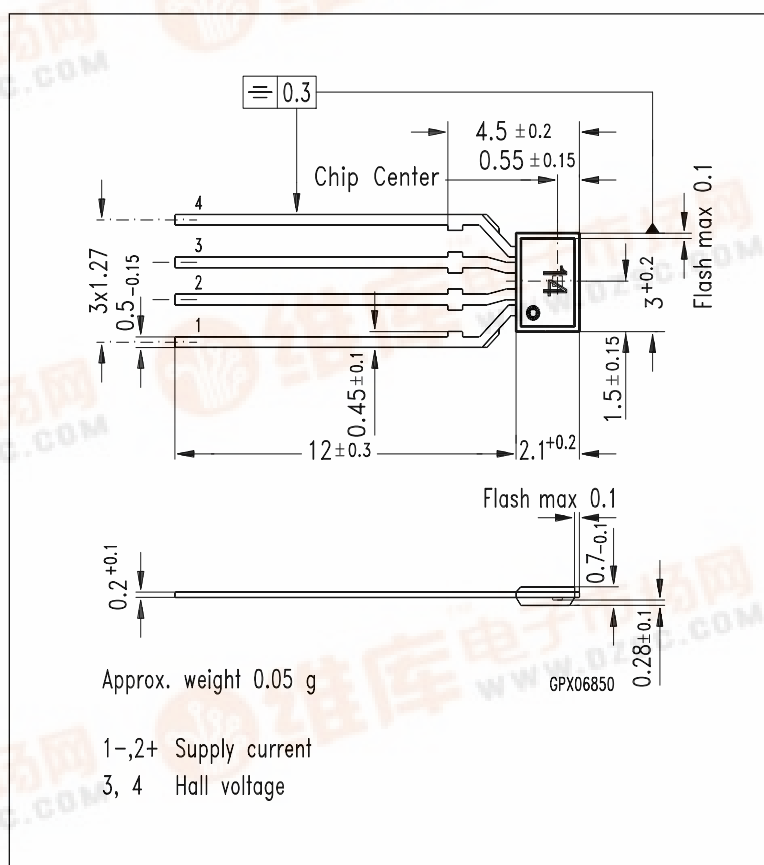
## KSY 14

### Features

- High sensitivity
- High operating temperature
- Small linearity error
- Low offset voltage
- Low TC of sensitivity and internal resistance
- Ultra-flat plastic miniature package
- Low inductive zero component
- Package thickness 0.7 mm
- Connections from one side of the package

### Typical applications

- Current and power measurement
- Magnetic field measurement
- Control of brushless DC motors
- Rotation and position sensing
- Measurement of diaphragm
- Movement for pressure sensing



Dimensions in mm

Type	Marking	Ordering Code
KSY 14	14	Q62705-K227

The KSY 14 is an ion-implanted Hall sensor generator in a mono-crystalline GaAs material, built into an extremely flat plastic package (SOH). It is outstanding for a high magnetic sensitivity and low temperature coefficients. The  $0.35 \times 0.35 \text{ mm}^2$  chip is mounted onto a non-magnetic leadframe.

## Maximum ratings

Parameter	Symbol	Value	Unit
Operating temperature	$T_A$	– 40...+ 175	°C
Storage temperature	$T_{stg}$	– 50...+ 180	°C
Supply current	$I_1$	7	mA
Thermal conductivity soldered, in air	$G_{thA}$ $G_{thC}$	$\geq 1.5$ $\geq 2.2$	mW/K mW/K

## Characteristics ( $T_A = 25\text{ °C}$ )

Nominal supply current	$I_{1N}$	5	mA
Open-circuit sensitivity	$K_{B0}$	190...260	V/AT
Open-circuit Hall voltage $I_1 = I_{1N}$ , $B = 0.1\text{ T}$	$V_{20}$	95...130	mV
Ohmic offset voltage $I_1 = I_{1N}$ , $B = 0\text{ T}$	$V_{R0}$	$\leq \pm 20$	mV
Linearity of Hall voltage $B = 0...0.5\text{ T}$ $B = 0...1\text{ T}$	$F_L$	$\leq \pm 0.2$ $\leq \pm 0.7$	% %
Input resistance $B = 0\text{ T}$	$R_{10}$	900...1200	$\Omega$
Output resistance $B = 0\text{ T}$	$R_{20}$	900...1200	$\Omega$
Temperature coefficient of the open-circuit Hall voltage $I_1 = I_{1N}$ , $B = 0.1\text{ T}$	$TC_{V20}$	$\sim -0.03...-0.07$	%/K
Temperature coefficient of the internal resistance $B = 0\text{ T}$	$TC_{R10, R20}$	$\sim 0.1...0.18$	%/K
Change of offset voltage within the temperature range	$ \Delta V_{R0} ^{1)}$	$\leq 2$	mV
Inductive zero component $I_{1N} = 0$	$A_2^{2)}$	0.16	cm <sup>2</sup>
Noise figure	$F$	$\sim 10$	dB

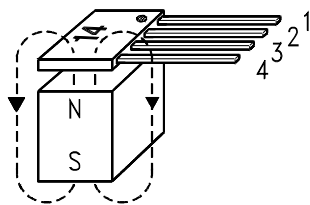
1) AQL: 0.65

2) With time varying induction there exists an inductive voltage  $V_{ind}$  between the Hall voltage terminals (supply current  $I_1 = 0$ ):  
 $V_{ind} = A_2 \times dB/dt \times 10^{-4}$  with  $V(V)$ ,  $A_2\text{ (cm}^2\text{)}$ ,  $B(T)$ ,  $t(s)$

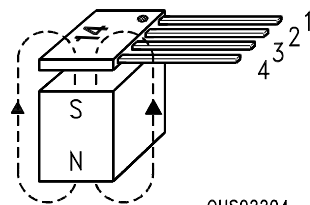
## Connection of a Hall sensor with a power source

Since the voltage on the component must not exceed 10 V, the connection to the constant current supply should only be done via a short circuit by-pass. The by-pass circuit-breaker shall not be opened before turning on the power source, in order to avoid damage to the Hall sensor due to power peaks.

## Polarity of Hall voltage



Pin 1	$I_1$	-
Pin 2	$I_1$	+
Pin 3	$U_{20}$	-
Pin 4	$U_{20}$	+



OHS02204

Pin 1	$I_1$	-
Pin 2	$I_1$	+
Pin 3	$U_{20}$	+
Pin 4	$U_{20}$	-