Monolithic Digital IC

SANYO

No.1571B

LB1649

unit

0.9 1.05 1.20

6.5 7.2 7.5

Continued on next page.

Dual Bidirectional Motor Driver

The LB1649 is a dual bidirectional motor driver. Since each channel has a 2-input logic circuit and performs bidirectional driving and braking functions, it is capable of direct driving 2pcs. of motor of various types rated at 6 to 24V. The output voltage can be varied by using external zener diodes. It is especially suited for dual motor drive (reel motor, loading motor, cassette motor in VTR) and for stepping motor drive.

Features

- . With power transistors for motor drive contained, capable of withstanding dash current of 1A max.
- . Performs braking function at the motor stop mode.
- . Contains elements to absorb motor dash current.
- . Input connectable direct to MOS LSI.
- . Minimum number of external parts required.
- . Wide operating voltage range.

Input Threshold Voltage

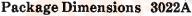
Output Voltage

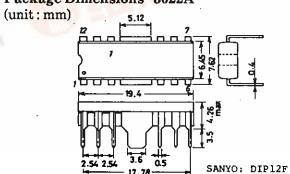
Absolute Maximum Ratings at Ta=25°C

Maximum Supply Voltage	V _{CC} max	25	V
Input Voltage	VIN	25	V
Output Current	I,	±1	A
Allowable Power Dissipation	n Pdmax		W
Operating Temperature	Topr		C
Storage Temperature	Tstg	-55 to +125 °	C COM
Allowable Operating Condition	ns at Ta=25°C	www.DZs	it
Supply Voltage	v _{cc.}	7 to 25	V
Electrical Characteristics at	Ta=25°C, V _{CC} =12V, per channel	min typ max	unit
Current Dissipation 1	CC Braking mode, R _L =∞ per channel	7.0 10.0	mA
Output Leakage Current 1	OL Braking mode, R _L =∞	40 120	JιΑ

 $R_L = \infty$

 $R_L = 60 \text{ohms}, V_Z = 7.4 \text{V}$

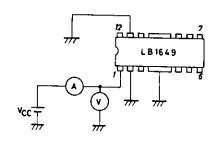




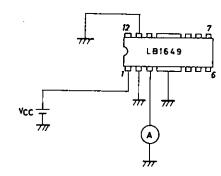
Continued from preceding	page.	min	tvo	max	unit
Output Tr Saturation	V _{sat 1} I _{OUT} =300mA			2.3	
Voltage (Upper)	V _{sat1} I _{OUT} =300mA I _{OUT} =500mA		2.0	2.4	V
Output Tr Saturation	V _{sat2} I _{OUT} =300mA		0.3	0.55	V
Voltage (Lower)	V _{sat2} I _{OUT} =300mA I _{OUT} =500mA		0.5	0.7	V

Test Circuits (per channel)

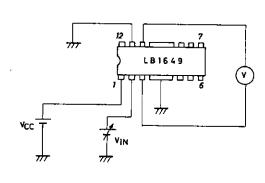




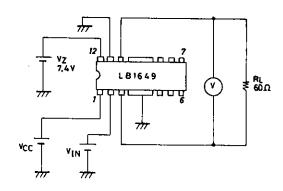
(2) I_{OL}



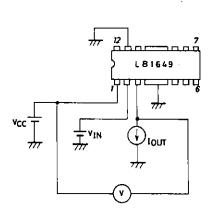
(3) v_{th}



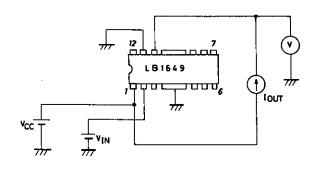
(4) V_O



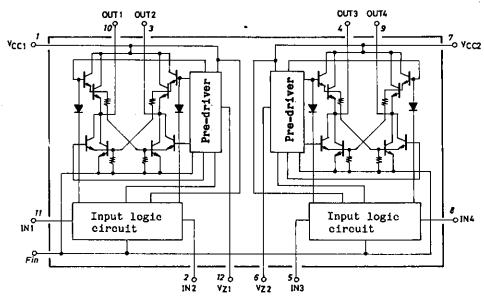
(5) V_{sati}



(6) V_{sat2}



Equivalent Circuit Block Diagram



Truth Table of Logic Circuit

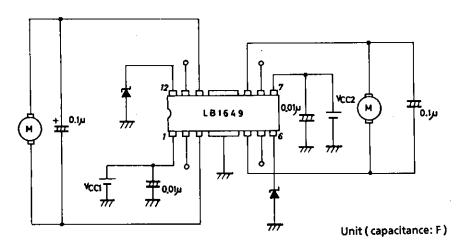
IN1	IN2	OUT1	OUT2	IN3	IN4	OUT3	OUT4
0	0	L	L	0	0	L	L
1	0	H	L	1	0	H	L
0	1	L	H	Ô	1	L	H
1	1	L	L	1	1	L	L

Note) A capacitor of 0.01 μF or greater must be connected across $V_{\rm CC}1$,2 and GND.

INPUT OUT PUT				мо	DE			
IN1	IN2,3	IN4	OUT 1	OUT2	OUT3	OUT4	M1	M2
0	0	0	L	L	L	L	Brake	Brake
1	0	0	H	L	L	L	Forward/Reverse	Brake
O	1	1	L	H	L	L	Reverse/Forward	Brake
1	1	0	L	L	H	L	Brake	Forward/Reverse
0	0	1	L	L	L	H	Brake	Reverse/Forward
1	1	1	L	L	L	L	Brake	Brake

The remaining input states 1,0,1 and 0,1,0 are not inhibited.

Sample Application Circuit



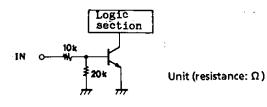
Input Circuit

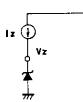
The input circuit is shown right.

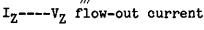
 $\mathbf{V}_{\mathbf{Z}}$ pin

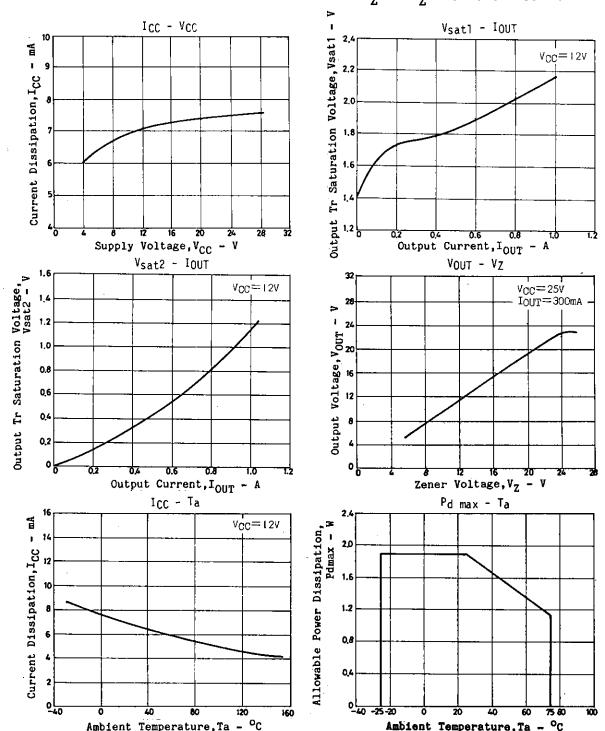
Zener voltage	V _Z pin Voltage value		
≥5.6V	small		
<5.6V	large*		

*Susceptible to V_{Z} pin flow-out current change.









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