Monolithic Digital IC

SANYO

No.3345

LB1687

unit

3-Phase Brushless Motor Driver

Applications

The LB1687 is a 3-phase brushless motor driver IC ideally suited for use in VTR capstan motor, drum motor drive applications.

Features and Functions

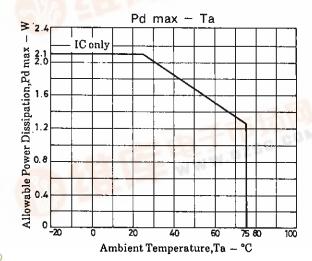
- (1) 120° voltage linear type
- (2) Soft switching type eliminating noises caused by current switching and making the values of external capacitors smaller (comparable to those of chip capacitors)
- (3) On-chip FG amplifier
- (4) On-chip thermal shutdown circuit
- (5) The FG signal can be used to detect the rotational speed of a motor so that the hall amp gain is changed in two steps, thus reducing torque ripple and noise.
- (6) Motor drivable at voltage down to motor supply voltage 5V

Absolute Maximum Ratings at Ta = 25°C

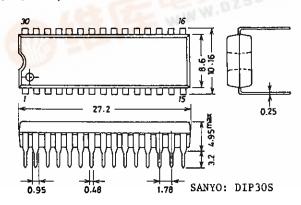
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	Maximum Supply Voltage	V _{CC} max1	20	V
		V _{CC} max2	7.0	V
	Output Supply Voltage	$V_{OUT.V.W.}$	22	V
	Output Current	I_{OUT}	1.5	Α
	Allowable Power Dissipation	Pd max	2.1	W
	Operating Temperature	Topr	-20 to +75	°C
	Storage Temperature	Tstg	-55 to + 125	°C

Allowable Operating Conditions at Ta = 25°C

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Supply Voltage	V _{CC} 1	5 to 18	V
	V_{CC}^2	4.3 to 6.5	V



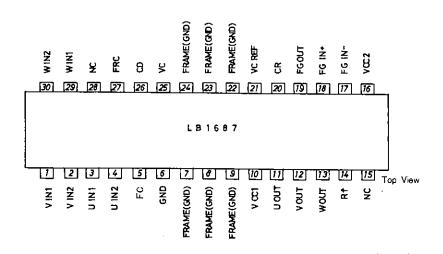
Package Dimensions 3061 (unit: mm)



Electrical Characteristics at Ta = 2 [Power Supply]	$25^{\circ}\text{C}, V_{\text{CC}}1 = 1$	$12V, V_{CC}2 = 5V$	min	typ	max	unit
Supply Current 1	I _{CC} 1	$V_C = 0$, $R_L = \infty$		17	30	mA
Supply Current 2	I _{CC} 2	$V_C = 0$		6.5	9.5	mA
[Output]		C				
Output Saturation Voltage	$V_{O(sat)}1$	$I_{OUT} = 0.5 A, sink + source$		1.6	2.2	V
-	V _{O(sat)} 2	I _{OUT} =1.0A,sink+source		2.0	3.0	V
Output TRS Voltage	$V_{O(sus)}$	I _{OUT} = 20mA (See note.)	20			V
Output Quiescent Voltage	V_{QQ}	$V_C = 0$	5.8	6.1	6.4	V
[Hall Input-Output]	- 4	·				
Hall Amp Input Offset Voltage	V _H offset		- 5		+5	mV
Hall Amp Input Bias Current	I _H bias			1	5	μΑ
Hall Amp Common-Mode	V_H ch		1.3		3.7	v
Input Voltage Range						
Hall Input-Output Voltage Gain	$G_{ m VHO}$ 1			56		dB
	$G_{ m VHO}2$			43		dΒ
[Control-Output]						
Control-Output Drive Gain	G_{VCO}		38	41	44	dB
Control-Output CH Difference	ΔG_{VCO}		-2		+2	dB
[FG Amplifier]		•				
FG Amp Input Offset Voltage	VFG offset		-8		+8	mV
Open-Loop Voltage Gain	$G_{ m VFG}$	f = 1kHz		60		dB
Source Output Saturation Voltage	V_{FGOU}	$I_O = 2mA$	3.7			V
Sink Output Saturation Voltage	V_{FGOD}	$I_O = -2mA$			1.3	V
Common-Mode Signal	CHR	(See note.)		80		dB
Rejection Ratio						
FG Amp Common-Mode	$ m V_{FGCH}$		0		3.5	V
Input Voltage Range						
Phase Margin		(See note.)		20		deg.
[Motor Detection]						Ū
Motor Detection Amp			35	50	65	mV
Hysteresis Width						
CR Pin Threshold Voltage		V _{CR} changes from LOW to HIGH.	2.35	2.5	2.65	V
Thermal Shutdown Temperature	T_{SD}	(See note.)	150	180	210	°C
Thermal Shutdown Hysteresis	ΔT_{SD}	(See note.)		15		°C

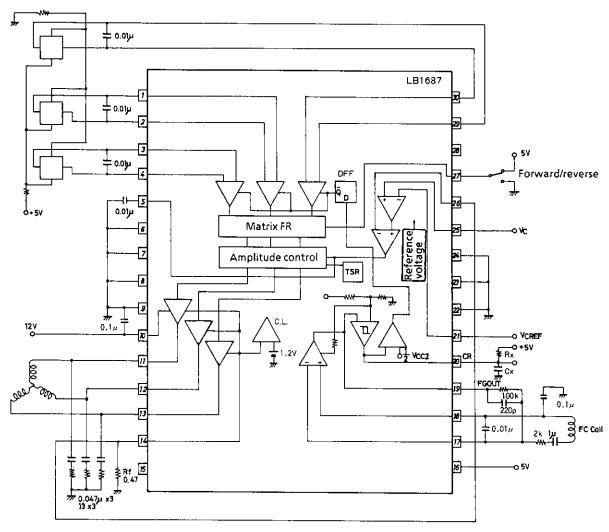
Note: Values shown are design targets only. No measurements have been taken.

Pin Assignment



Equivalent Circuit Block Diagram

Unit (resistance: Ω , capacitance: F)



Truth Table

	Source			Input			Forward/Reverse Control	
			Sink	U	U V W	W	F/RC	
1	W phase	→	V phase	Н	Н	L	L	
	V phase	→	W phase				Н	
2	W phase	→	U phase	Н	L	L	L	
	U phase	→	W phase				Н	
3	V phase	→	W phase	L		,		L
	W phase	→	V phase		L	Н	Н	
4	U phase	→	V phase	L	Н	L	L	
	V phase	→	U phase				Н	
5	V phase	→	U phase	7,1	L	Н	L	
	U phase	→	V phase	Ħ			Н	
6	U phase	→	W phase	L	Н	Н	L	
	W phase	→	U phase				Н	

Input:

H: High level. One of the inputs should have a potential at least 0.2V higher than the other.

L: Low level. One of the inputs should have a potential at least 0.2V lower than the other.

Forward/reverse control:

 $\mbox{H}: 2.0 \mbox{ to } \mbox{V}_{CC} \mbox{2} \\ \mbox{L}: 0 \mbox{ to } 0.3 \mbox{V}$

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