Monolithic Digital IC



No.3347

B 1689 D

3-Phase Brushless Motor Driver

Applications

The LB1689D is a 3-phase brushless motor driver IC ideally suited for use in VTR capstan motor, drum motor drive applications.

Features and Functions

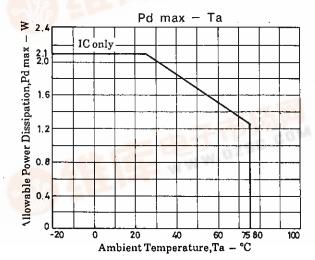
- (1) 120° voltage linear type
- (2) Soft switching type eliminating noises caused by current switching and making the values of external capacitors smaller (comparable to those of chip capacitors)
- (3) On-chip FG amplifier
- (4) On-chip thermal shutdown circuit
- (5) The FG signal can be used to detect the rotational speed of a motor so that the hall amp gain is changed in two steps, thus reducing torque ripple and noise.

Absolute Maximum Ratings at $Ta = 25^{\circ}C$

Absolute Maximum Ratings at	Ta = 25°C		unit
Maximum Supply Voltage	V _{CC} max1	20	V
	V _{CC} max2	7.0	V
Output Supply Voltage	V _{OUT.V.W.}	22	V
Output Current	I_{OUT}	1.5	Α
Allowable Power Dissipation	Pd max	2.1	W
Operating Temperature	Topr	-20 to +75	°C
Storage Temperature	Tstg	-55 to + 125	°C

Allowable Operating Conditions at Ta = 25°C

· •	8		
Supply Voltage	$V_{CC}1$	8.5 to 18	V
	$ m V_{CC}2$	4.3 to 6.5	V



Package Dimensions 3061 (unit: mm)

SANYO: DIP30S

Electrical Characteristics at Ta=2	25°C,V _{CC} 1=1	12V,V _{CC} 2=5V	min	typ	max	unit
[Power Supply]	_					
Supply Current 1	I _{CC} 1	$V_C = 0, R_L = \infty$		17	30	mA
Supply Current 2	$I_{CC}2$	$V_C = 0$		6.5	9.5	mA
[Output]						
Output Saturation Voltage	$V_{O(sat)}1$	$I_{OUT} = 0.5A$, sink + source		1.6	2.2	V
	$V_{O(sat)}2$	$I_{OUT} = 1.0A$, sink + source		2.0	3.0	V
Output TRS Voltage	$V_{O(sus)}$	$I_{OUT} = 20 \text{mA}$ (See note.)	20			V
Output Quiescent Voltage	v_{oq}	$V_C = 0$	5.8	6.1	6.4	V
[Hall Input-Output]	_					
Hall Amp Input Offset Voltage	$ m V_{H}$ offset		-5		+5	mV
Hall Amp Input Bias Current	I _H bias			1	5	μA
Hall Amp Common-Mode	V _H ch		1.3		3.7	·v
Input Voltage Range	••				• • • • • • • • • • • • • • • • • • • •	
Hall Input-Output Voltage Gain	G _{VHO} 1			56		dΒ
	G _{VHO} 2			43		dB
[Control-Output]	* *****	•				
Control-Output Drive Gain	G_{VCO}		38	41	44	dB
Control-Output CH Difference	ΔG_{VCO}		-2	•-	+2	dB
[FG Amplifier]	- 100		_		, -	
FG Amp Input Offset Voltage	VFG offset		-8		+8	mV
Open-Loop Voltage Gain	G_{VFG}	f=1kHz	Ŭ	60	. 0	dB
Source Output Saturation Voltage		$I_0 = 2mA$	3.7	•		V
Sink Output Saturation Voltage	$V_{\text{FG OD}}$	$I_0 = -2mA$	0		1.3	v
Common-Mode Signal	CHR	(See note.)		80	1.0	dB
Rejection Ratio	01111	(See Hote.)		00		uВ
FG Amp Common-Mode	V_{FGCH}		0		3.5	V
Input Voltage Range						
Phase Margin		(See note.)		30		deg.
[Motor Detection]		•				6
Motor Detection Amp			35	50	65	mV
Hysteresis Width					•	
CR Pin Threshold Voltage		V _{CR} changes from LOW to HIGH.	2.35	2.5	2.65	V .
Thermal Shutdown Temperature	T_{SD}	(See note.)	150	180	210	°C
Thermal Shutdown Hysteresis	ΔT_{SD}	(See note.)		15		°C
	- 00	V		~ ~		•

Note: Values shown are design targets only. No measurements have been taken.

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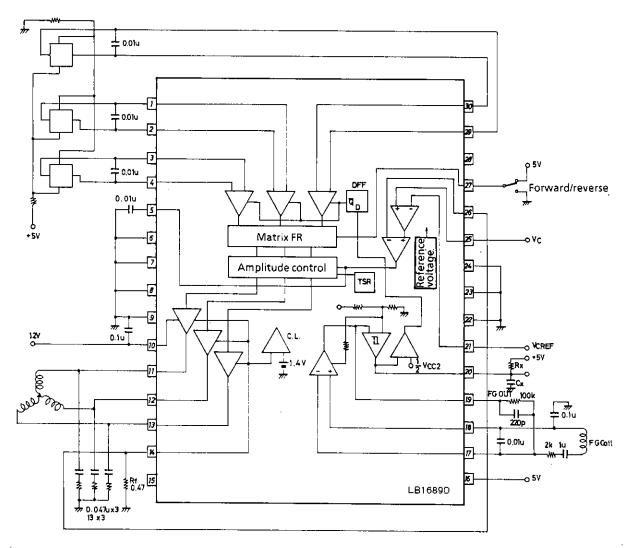
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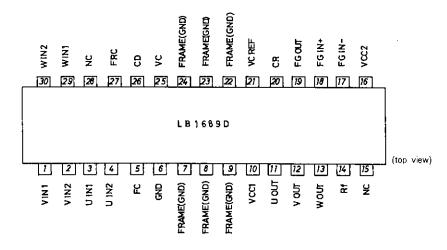
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Equivalent Circuit Block Diagram



Unit (resistance: Ω , capacitance: F)

Pin Assignment



Note: All FRAME pins are connected to GND.

LB1689D

Pin Description

Pin Name	Pin No.	Description
$U_{IN}1, U_{IN}2 \ V_{IN}1, V_{IN}2 \ W_{IN}1, W_{IN}2$	3, 4 1, 2 29, 30	U phase hall element input pin. 'H' of logic: $V_{IN}1>V_{IN}2$ V phase hall element input pin. 'H' of logic: $V_{IN}1>V_{IN}2$ W phase hall element input pin. 'H' of logic: $V_{IN}1>V_{IN}2$
U _{OUT} V _{OUT} W _{OUT}	11 12 13	U phase output pin V phase output pin W phase output pin
V _{CC} 1	10	Power supply pin for applying output
V _{CC} 2	16	Power supply pin for applying voltage to each section other than output section. This voltage must be stabilized to be free from ripple, noise, etc.
Rf	14	Output current detect pin. By connecting Rf across this pin and GND pin, output current is detected as voltage. The result is used to control the overcurrent protection circuit.
CD	26	Pin for fetching current (voltage) detected with Rf. Takes feedback from Rf to reduce output voltage gain. Ground when not in use.
FC	5	Frequency characteristic correction
V _C	25	Speed-phase control pin Control is of voltage-controlled type that controls output voltage.
V _{CREF}	21	Control reference voltage
GND	6	GND for other than output Minimum potential of output transistor is at Rf pin.
F/RC	27	Forward/reverse control pin By setting this pin to 'H' (more than 2.0V)/'L' (less than 0.3V), truth value is changed to perform forward/reverse rotation.
FGin-, FGin+	17, 18	FG signal input pin
FG _{OUT}	19	FG amp output pin
CR	20	This pin voltage can be used to change the hall input-output gain. Connection of an external resistor and capacitor makes it possible to detect the rotational speed of a motor and change the hall input gain in two steps.

Truth Table

	Source				Input		Forward/Reverse Control
			Sink	Ŭ	v	W	F/RC
1	W phase	→	V phase	н	Н	L	L
	V phase	→	W phase	F1			Н
2	W phase	→	U phase	H L	,	L L	L
Z	U phase	→	W phase		L		Н
3 V	V phase	→	W phase	L	L	Н	L
Ş	W phase	→	V phase				Н
4	U phase	→	V phase	L H	1 ,,	,	L
*	V phase	→	U phase		L	Н	
5	V phase	→	U phase	н	H L	н	L
J	U phase	→	V phase				Н
6	U phase	→	W phase	L	г н	Н	L
	W phase	→	U phase				Н

Input:

- H: High level. One of the inputs should have a potential at least 0.2V higher than the other.
- L: Low level. One of the inputs should have a potential at least 0.2V lower than the other.

Forward/reverse control:
H:2.0 to V_{CC}2
L: 0 to 0.3V