

Ordering number : EN5383

Monolithic Digital IC



LB1910

FDD Spindle Motor Driver

Overview

The LB1910 is a 3-phase disc drive motor driver that is optimal for use as a 3.5-inch FDD spindle motor driver.

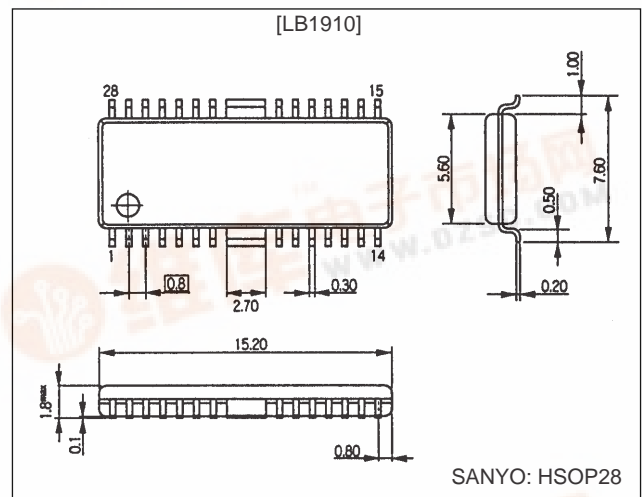
Functions and Features

- Three-phase full-wave linear driver
- Digital speed control circuit
- Start and stop circuits (active low)
- RPM switching H: 300 rpm
L: 360 rpm
- Current limiter circuit
- Built-in index comparator
- Thermal shutdown circuit

Package Dimensions

unit: mm

3222-HSOP28



Specifications

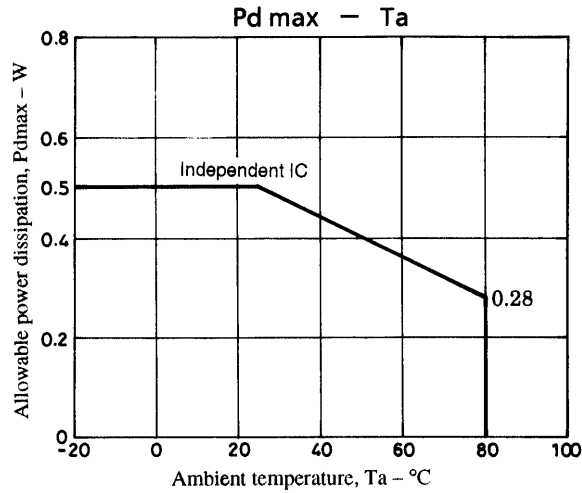
Absolute Maximum Ratings at Ta = 25°C

Parameter	Symbol	Conditions	Ratings	Unit
Maximum supply voltage	V _{CC} max		7.0	V
Maximum output current	I _O max1	t ≤ 0.5 s	1.0	A
Maximum steady-state output current	I _O max2		0.7	A
Allowable power dissipation	P _d max	Independent IC	0.5	W
Operating temperature	T _{opr}		-20 to +80	°C
Storage temperature	T _{stg}		-40 to +150	°C

Allowable Operating Ranges at Ta = 25°C

Parameter	Symbol	Conditions	Ratings	Unit
Recommended supply voltage	V _{CC}		4.2 to 6.5	V

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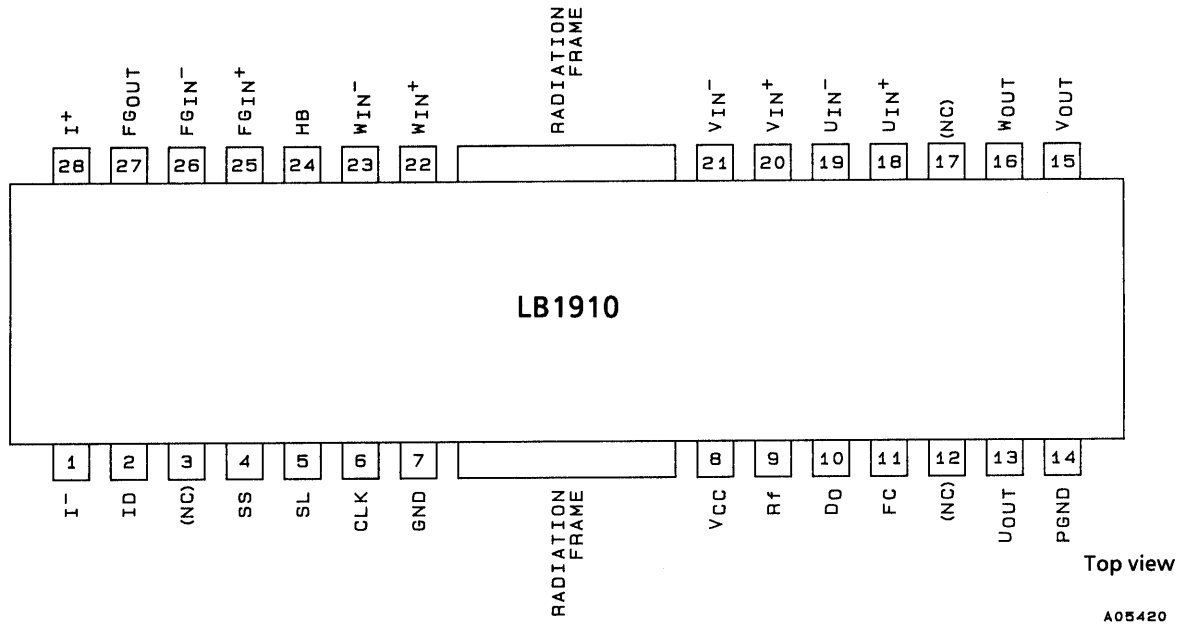
Electrical Characteristics at Ta = 25°C, VCC = 5 V

Parameter	Symbol	Conditions	min	typ	max	Unit
Current drain	I _{CCO}	S/S = 5 V (standby)			10	μA
	I _{CC}	S/S = 0 V (steady state)		12	18	mA
SL bias current	I _{SL}	V _{SL} = 0 V			10	μA
SL input low-level voltage	V _{SLL}		0		1.0	V
SL input high-level voltage	V _{SLH}		3.5		V _{CC}	V
S/S bias current	I _{S/S}			180	270	μA
S/S low-level voltage	V _{S/SL}		0		0.8	V
S/S high-level voltage	V _{S/SH}		3.5		V _{CC}	V
Hall amplifier input bias current	I _{HB}				10	μA
Common-mode input voltage range	V _h		1.5		V _{CC} – 1.0	V
Differential input voltage range	V _{dif}		50		200	mVp-p
Hall bias output voltage	V _H	I _H = 5 mA		0.8		V
Leakage current	I _{HL}	S/S = 5 V			±10	μA
Output saturation voltage	V _{sat}	I _o = 0.7 A, sink + source		1.3	1.8	V
Output leakage current	I _{OL}				1.0	mA
Current limiter	V _{lim}		0.27	0.3	0.33	V
Control amplifier voltage gain	G _C			-7		dB
Voltage gain difference between phases	ΔG _C				±1	dB
V/I conversion source current	I ⁺		9	14	19	μA
V/I conversion sink current	I ⁻		-9	-14	-19	μA
V/I conversion current ratio	I ⁺ /I ⁻		0.8	1.0	1.2	
DSC buffer input current	I _{DSC}				1.0	μA
FG Schmitt hysteresis	ΔV _{sh}	*		50		mV
Speed discriminator counts	N			1041.5		
Discriminator operating frequency	F _D	*			1.1	MHz
Oscillator frequency range	F _{OSC}	*			1.1	MHz
Index output low-level voltage	V _{IDL}	I _O = 2 mA			0.4	V
Index output leakage current	I _{IDL}				±10	μA
FG amplifier voltage gain	G _{FG}	*		48		dB
FG amplifier input offset	V _{FG O}				±10	mV
FG amplifier internal reference voltage	V _{FG B}		2.2	2.5	2.8	V
Thermal shutdown temperature	TSD	*	150	180		°C
Hysteresis	ΔTSD	*		40		°C

Note: * Items marked with an asterisk are design target values and are not measured.

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Pin Assignment



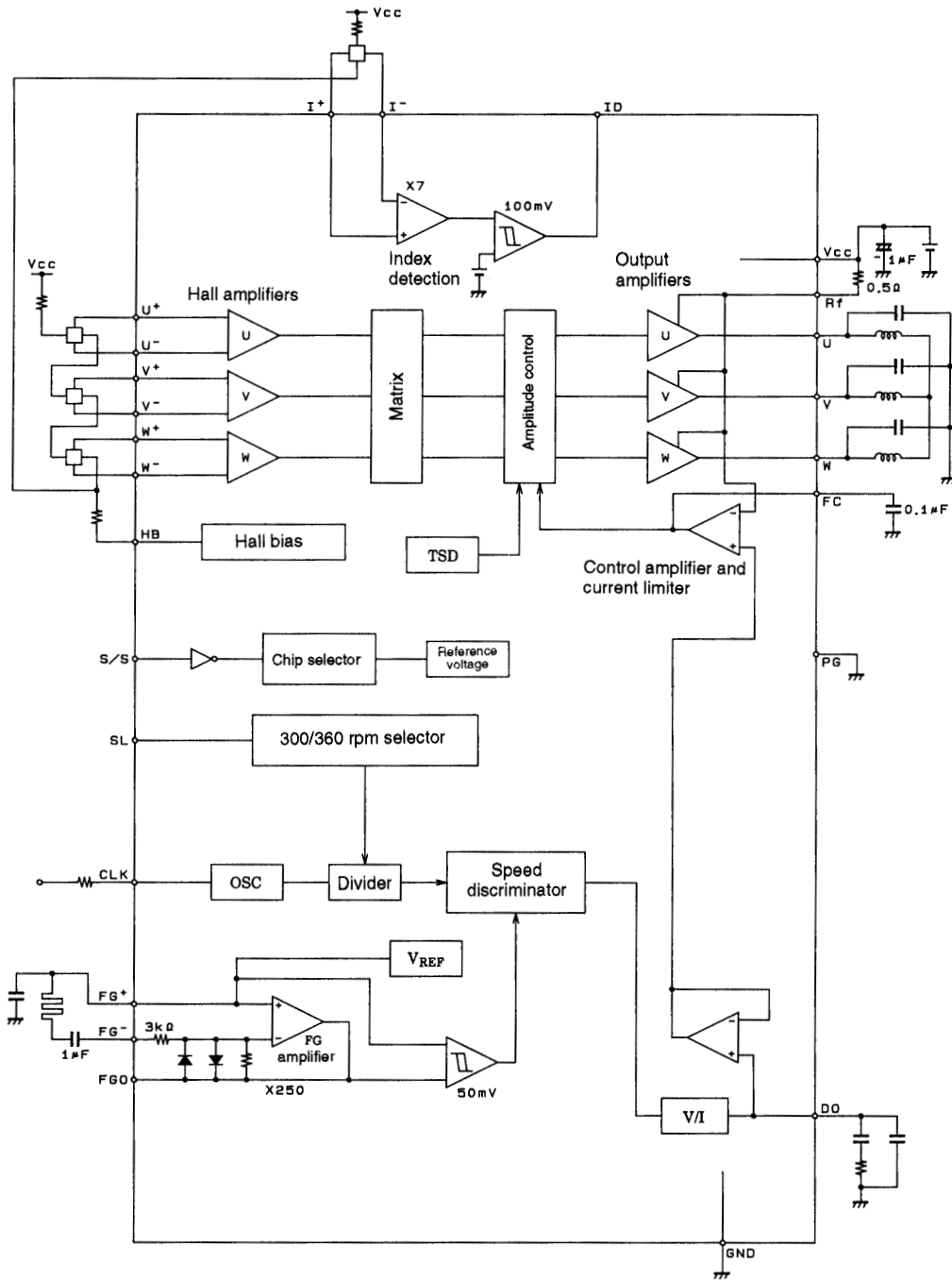
Truth Table

	Source → sink	Hall input		
		U	V	W
1	V phase → W phase	H	H	L
2	V phase → U phase	L	H	L
3	W phase → U phase	L	H	H
4	W phase → V phase	L	L	H
5	U phase → V phase	H	L	H
6	U phase → W phase	H	L	L

Note: Hall input high levels are defined as: $U_{IN^+} > U_{IN^-}$
 $V_{IN^+} > V_{IN^-}$
 $W_{IN^+} > W_{IN^-}$

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Block Diagram



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Pin Functions

Pin No.	Symbol	Pin voltage	Equivalent circuit diagram	Function
18 19 20 21 22 23	U_{IN}^+ U_{IN}^- V_{IN}^+ V_{IN}^- W_{IN}^+ W_{IN}^-	1.5 V min $V_{CC} - 1.0$ V max	<p style="text-align: right;">A05421</p>	U phase Hall element input V phase Hall element input W phase Hall element input
24	HB	0.8 V typ ($I_H = 5$ mA)	<p style="text-align: right;">A05422</p>	Minus side connection for providing the Hall bias current This pin becomes open in the stopped state, thus cutting the Hall bias current.
25 26 27	FG_{IN}^+ FG_{IN}^- FG_{OUT}	2.5 V	<p style="text-align: right;">A05423</p>	<ul style="list-style-type: none"> • FG amplifier plus input • A 2.5-V reference voltage is generated internally. • FG amplifier minus input • FG amplifier output
28 1	I^+ I^-		<p style="text-align: right;">A05424</p>	Index input
2	ID	L: 0.4 V max H: 4.5 V min	<p style="text-align: right;">A05425</p>	Index output

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Pin No.	Symbol	Pin voltage	Equivalent circuit diagram	Function
4	SS	L: 0.8 V max H: 3.5 V min	<p style="text-align: right;">A05426</p>	Start/stop mode switching This is an active-low input.
5	SL	L: 1.0 V max H: 3.5 V min	<p style="text-align: right;">A05427</p>	Rotational speed switching
6	CLK	L: 1.0 V max H: $V_{CC} - 1.0$ V min	<p style="text-align: right;">A05428</p>	Reference clock input A 1-MHz input frequency corresponds to speeds of 300 and 360 rpm.
7	GND			<ul style="list-style-type: none"> • Ground • This pin, pin 14, and the frame must all be grounded together.
8	V_{CC}			Power supply This voltage must be stabilized so that ripple and noise do not enter the IC.
9	Rf			Output current detection The output current is detected as a voltage by connecting the resistor Rf between this pin and V_{CC} . The current limiter operates by detecting the voltage on this pin.
10	Do		<p style="text-align: right;">A05429</p>	Speed discriminator
11	Fc			Frequency characteristics compensation Current control system loop oscillation is prevented by connecting a capacitor between this pin and ground.

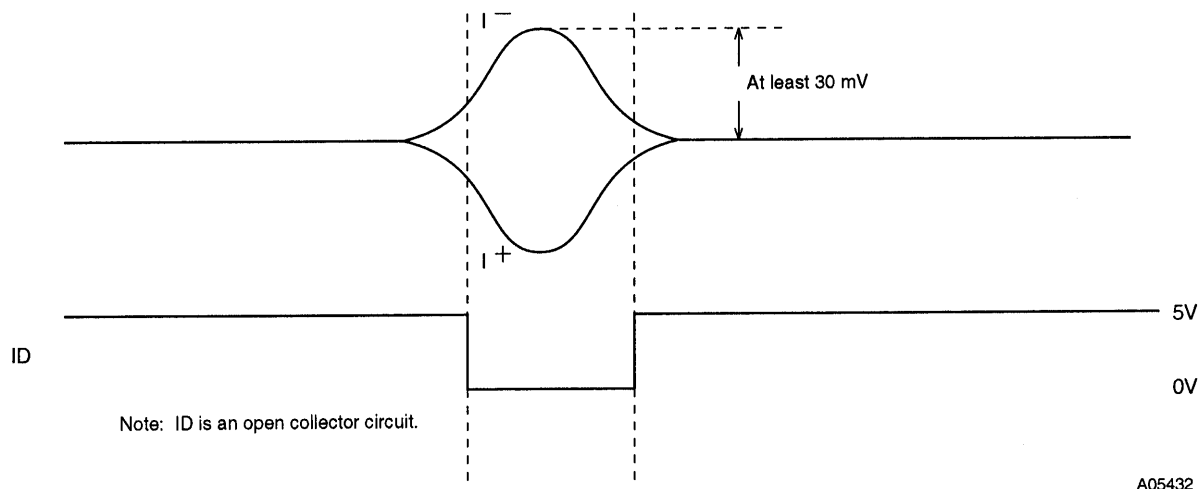
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Pin No.	Symbol	Pin voltage	Equivalent circuit diagram	Function
13 15 16	U_{OUT} V_{OUT} W_{OUT}			U phase output V phase output W phase output
14	PGND			Output transistor ground connection

Index Pulse Timing Chart



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