19-1003; Rev 2; 6/05

EVALUATION KIT AVAILABLE



#### **General Description**

The MAX1213 is a monolithic, 12-bit, 170Msps analogto-digital converter (ADC) optimized for outstanding dynamic performance at high-IF frequencies up to 300MHz. The product operates with conversion rates up to 170Msps while consuming only 788mW.

At 170Msps and an input frequency up to 250MHz, the MAX1213 achieves a spurious-free dynamic range (SFDR) of 72.9dBc. Its excellent signal-to-noise ratio (SNR) of 65.8dB at 10MHz remains flat (within 2dB) for input tones up to 250MHz. This ADC yields an excellent low-noise floor of -68dBFS, which makes it ideal for wideband applications such as cable head-end receivers and power-amplifier predistortion in cellular base-station transceivers.

The MAX1213 requires a single 1.8V supply. The analog input is designed for either differential or single-ended operation and can be AC- or DC-coupled. The ADC also features a selectable on-chip divide-by-2 clock circuit, which allows the user to apply clock frequencies as high as 340MHz. This helps to reduce the phase noise of the input clock source. A low-voltage differential signal (LVDS) sampling clock is recommended for best performance. The converter's digital outputs are LVDS compatible and the data format can be selected to be either two's complement or offset binary.

The MAX1213 is available in a 68-pin QFN package with exposed paddle (EP) and is specified over the industrial (-40°C to +85°C) temperature range.

See the *Pin-Compatible Versions* table for a complete selection of 8-bit, 10-bit, and 12-bit high-speed ADCs in this family.

#### **Applications**

Base-Station Power-Amplifier Linearization

Cable Head-End Receivers

Wireless and Wired Broadband Communication

Communications Test Equipment

Radar and Satellite Subsystems

#### \_Features

- ♦ 170Msps Conversion Rate
- Low Noise Floor of -68dBFS
- Excellent Low-Noise Characteristics SNR = 65.8dB at f<sub>IN</sub> = 65MHz SNR = 64.5dB at f<sub>IN</sub> = 250MHz
- Excellent Dynamic Range
  SFDR = 76.5dBc at f<sub>IN</sub> = 65MHz
  SFDR = 72.9dBc at f<sub>IN</sub> = 250MHz
- 59.5dB NPR for f<sub>NOTCH</sub> = 28.8MHz and a Noise Bandwidth of 50MHz
- Single 1.8V Supply
- 788mW Power Dissipation at fSAMPLE = 170MHz and fIN = 65MHz
- On-Chip Track-and-Hold Amplifier
- Internal 1.23V-Bandgap Reference
- On-Chip Selectable Divide-by-2 Clock Input
- ♦ LVDS Digital Outputs with Data Clock Output
- MAX1213 EV Kit Available

#### **Ordering Information**

PART	TEMP RANGE	PIN-PACKAGE				
MAX1213EGK -40°C to +85°C 68 QFN-EP*						
*EP = Exposed paddle.						

#### **Pin-Compatible Versions**

		-
PART	RESOLUTION (BITS)	SPEED GRADE (Msps)
MAX1121	8	250
MAX1122	10	170
MAX1123	10	210
MAX1124	10	250
MAX1213	12	170
MAX1214	12	210
MAX1215	12	250
IVIAA 12 15	12	200

Pin Configuration appears at end of data sheet.

#### 

Maxim Integrated Products 1

For pricing, delivery, and ordering information, please contact Maxim/Dallas Direct! at 1-888-629-4642, or visit Maxim's website at www.maxim-ic.com.

#### **ABSOLUTE MAXIMUM RATINGS**

AV <sub>CC</sub> to AGND	0.3V to +2.1V
OV <sub>CC</sub> to OGND	0.3V to +2.1V
AVCC to OVCC	0.3V to +2.1V
AGND to OGND	0.3V to +0.3V
INP, INN to AGND	0.3V to (AV <sub>CC</sub> + 0.3V)
REFIO, REFADJ to AGND	0.3V to (AV <sub>CC</sub> + 0.3V)
All Digital Inputs to AGND	0.3V to (AV <sub>CC</sub> + 0.3V)
All Digital Outputs to OGND	0.3V to (OV <sub>CC</sub> + 0.3V)
ESD on All Pins (Human Body Model)	±2000V

Thermal Resistance (multilayer board)

θjc	0.8°C/W
θja	24°C/W
Operating Temperature Range	40°C to +85°C
Junction Temperature	+150°C
Storage Temperature Range	60°C to +150°C
Maximum Current into Any Pin	50mA
Lead Temperature (soldering, 10s)	+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

#### **ELECTRICAL CHARACTERISTICS**

 $(AV_{CC} = OV_{CC} = 1.8V, AGND = OGND = 0, f_{SAMPLE} = 170MHz$ , differential sine-wave clock input drive, 0.1µF capacitor on REFIO, internal reference, digital output pins differential R<sub>L</sub> = 100 $\Omega$  ±1%, T<sub>A</sub> = T<sub>MIN</sub> to T<sub>MAX</sub>, unless otherwise noted. Typical values are at T<sub>A</sub> = +25°C.) (Note 1)

PARAMETER SYMBOL CONDITIONS				ТҮР	MAX	UNITS
DC ACCURACY						
Resolution			12			Bits
Integral Nonlinearity (Note 2)	INL	$f_{IN} = 10MHz$ , $T_A = +25^{\circ}C$	-2	±0.75	+2	LSB
Differential Nonlinearity (Note 2)	DNL	$T_A = +25^{\circ}C$ , No missing codes	-0.8	±0.3	+0.8	LSB
Transfer Curve Offset	Vos	$T_{A} = +25^{\circ}C$ (Note 2)	-3.3		+3.3	mV
Offset Temperature Drift				40		µV/°C
ANALOG INPUTS (INP, INN)						
Full-Scale Input Voltage Range	VFS	$T_A = +25^{\circ}C$ (Note 2)	1320	1454	1590	mV <sub>P-P</sub>
Full-Scale Range Temperature Drift				130		ppm/°C
Common-Mode Input Range	V <sub>CM</sub>	Internally self-biased	-	1.365 ±0.1	5	V
Input Capacitance	CIN			2.5		рF
Differential Input Resistance	R <sub>IN</sub>		3.00	4.2	6.25	kΩ
Full-Power Analog Bandwidth	FPBW			700		MHz
<b>REFERENCE (REFIO, REFADJ)</b>						
Reference Output Voltage	VREFIO	$T_A = +25^{\circ}C$ , REFADJ = AGND	1.18	1.23	1.30	V
Reference Temperature Drift		90			ppm/°C	
REFADJ Input High Voltage	ADJ Input High Voltage V <sub>REFADJ</sub> Used to disable the internal reference AV <sub>CC</sub> - 0.1					V
SAMPLING CHARACTERISTICS						
Maximum Sampling Rate	<b>f</b> SAMPLE	170			MHz	
Minimum Sampling Rate	<b>f</b> SAMPLE	E 20			MHz	
Clock Duty Cycle		Set by clock-management circuit		40 to 60		%
Aperture Delay	t <sub>AD</sub>	Figures 4, 11		620		ps
Aperture Jitter	taj	Figure 11		0.2		psrms

#### **ELECTRICAL CHARACTERISTICS (continued)**

 $(AV_{CC} = OV_{CC} = 1.8V, AGND = OGND = 0, f_{SAMPLE} = 170MHz$ , differential sine-wave clock input drive, 0.1µF capacitor on REFIO, internal reference, digital output pins differential  $R_L = 100\Omega \pm 1\%$ ,  $T_A = T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted. Typical values are at  $T_A = +25^{\circ}C$ .) (Note 1)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
CLOCK INPUTS (CLKP, CLKN)			•				
Differential Clock Input Amplitude (N		(Note 3)	200	500		mV <sub>P-P</sub>	
Clock Input Common-Mode Inter		Internally self-biased		1.15 ±0.2	ō	V	
Clock Differential Input Resistance	R <sub>CLK</sub>			11 ±25%		kΩ	
Clock Differential Input Capacitance	Ссік			5		pF	
DYNAMIC CHARACTERISTICS (a	t -1dBFS)						
		$f_{IN} = 10MHz, T_A \ge +25^{\circ}C$	64.5	66.2			
Signal-to-Noise	SNR	$f_{IN} = 65MHz, T_A \ge +25^{\circ}C$	64.5	65.8		dB	
Ratio	SINH	$f_{IN} = 200MHz$		65		uБ	
		$f_{IN} = 250 MHz$		64.5			
		$f_{IN} = 10MHz, T_A \ge +25^{\circ}C$	64	65.9			
Signal-to-Noise and Distortion	SINAD	$f_{IN} = 65MHz, T_A \ge +25^{\circ}C$	63.5	65.2	65.2		
		f <sub>IN</sub> = 200MHz 63.9			dB		
		$f_{IN} = 250 MHz$	63.5				
		$f_{IN} = 10MHz, T_A \ge +25^{\circ}C$	73	83			
Spurious-Free	SFDR	$f_{IN} = 65MHz, T_A \ge +25^{\circ}C$	69	76.5		dBc	
Dynamic Range	SFDN	f <sub>IN</sub> = 200MHz		70.7		ивс	
		$f_{IN} = 250 MHz$		72.9			
		$f_{IN} = 10MHz, T_A \ge +25^{\circ}C$		-85	-73		
Worst Harmonics		$f_{IN} = 65MHz, T_A \ge +25^{\circ}C$		-76.5	-69	dBc	
(HD2 or HD3)		$f_{IN} = 200MHz$		-70.7		UDC	
$f_{\rm IN} = 250 \text{MHz}$		$f_{IN} = 250 MHz$		-72.9			
Two-Tone Intermodulation Distortion	TTIMD	f <sub>IN1</sub> = 99MHz at -7dBFS,      -78        f <sub>IN2</sub> = 101MHz at -7dBFS      -78			dBc		
Noise Power Ratio	NPR	f <sub>NOTCH</sub> = 28.8MHz ±1MHz, noise BW = 50MHz, A <sub>IN</sub> = -9.1dBFS 59.5			dB		
LVDS DIGITAL OUTPUTS (D0P/N	–D11P/N, OF	RP/N)	·				
Differential Output Voltage	IV <sub>OD</sub> I	$R_{L} = 100\Omega \pm 1\%$	250		400	mV	
Output Offset Voltage	OVOS	$R_L = 100\Omega \pm 1\%$	1.125		1.310	V	

#### **ELECTRICAL CHARACTERISTICS (continued)**

 $(AV_{CC} = OV_{CC} = 1.8V, AGND = OGND = 0, f_{SAMPLE} = 170MHz$ , differential sine-wave clock input drive, 0.1µF capacitor on REFIO, internal reference, digital output pins differential  $R_L = 100\Omega \pm 1\%$ ,  $T_A = T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted. Typical values are at  $T_A = +25^{\circ}C$ .) (Note 1)

PARAMETER	CONDITIONS	MIN	ТҮР	MAX	UNITS	
LVCMOS DIGITAL INPUTS (CLKI	DIV, T/B)	·				
Digital Input Voltage Low					2 x AV <sub>CC</sub>	V
Digital Input Voltage High	VIH	0.8 x AV <sub>CC</sub>				V
TIMING CHARACTERISTICS						
CLK-to-Data Propagation Delay	<b>t</b> PDL	Figure 4		1.75		ns
CLK-to-DCLK Propagation Delay	<b>t</b> CPDL	Figure 4		4.95		ns
DCLK-to-Data Propagation Delay	tpdl - tcpdl	Figure 4 (Note 3)	2.8	3.2	3.6	ns
LVDS Output Rise Time	t <sub>RISE</sub>	20% to 80%, $C_L = 5pF$		460		ps
LVDS Output Fall Time	tfall	20% to 80%, $C_L = 5pF$		460		ps
Output Data Pipeline Delay	<sup>t</sup> LATENCY	Figure 4		11		Clock cycles
POWER REQUIREMENTS	•					
Analog Supply Voltage Range	AVCC		1.70	1.80	1.90	V
Digital Supply Voltage Range	OVCC		1.70	1.80	1.90	V
Analog Supply Current	IAVCC	f <sub>IN</sub> = 65MHz 375		425	mA	
Digital Supply Current	lovcc	f <sub>IN</sub> = 65MHz 63		75	mA	
Analog Power Dissipation	PDISS	f <sub>IN</sub> = 65MHz 788		900	mW	
Power-Supply Rejection Ratio	PSRR	Offset		1.8		mV/V
(Note 4)	FORR	Gain		1.5		%FS/V

Note 1:  $\geq$ +25°C guaranteed by production test, <+25°C guaranteed by design and characterization.

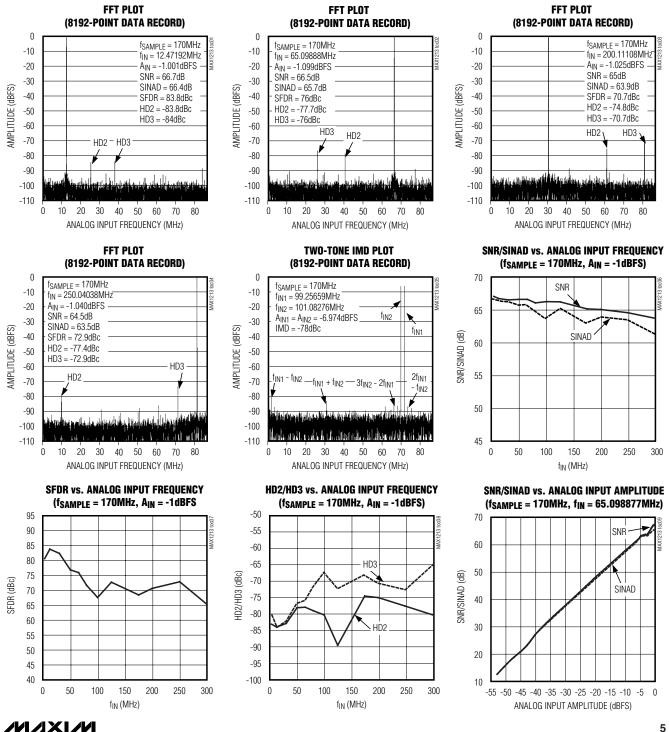
Note 2: Static linearity and offset parameters are computed from a best-fit straight line through the code transition points. The fullscale range (FSR) is defined as 4095 x slope of the line.

**Note 3:** Parameter guaranteed by design and characterization:  $T_A = T_{MIN}$  to  $T_{MAX}$ .

Note 4: PSRR is measured with both analog and digital supplies connected to the same potential.

#### Typical Operating Characteristics

(AV<sub>CC</sub> = OV<sub>CC</sub> = 1.8V, AGND = OGND = 0, f<sub>SAMPLE</sub> = 170MHz, A<sub>IN</sub> = -1dBFS; see each TOC for detailed information on test conditions, differential input drive, differential sine-wave clock input drive, 0.1µF capacitor on REFIO, internal reference, digital output pins differential  $R_L = 100\Omega$ ,  $T_A = +25^{\circ}C$ .)

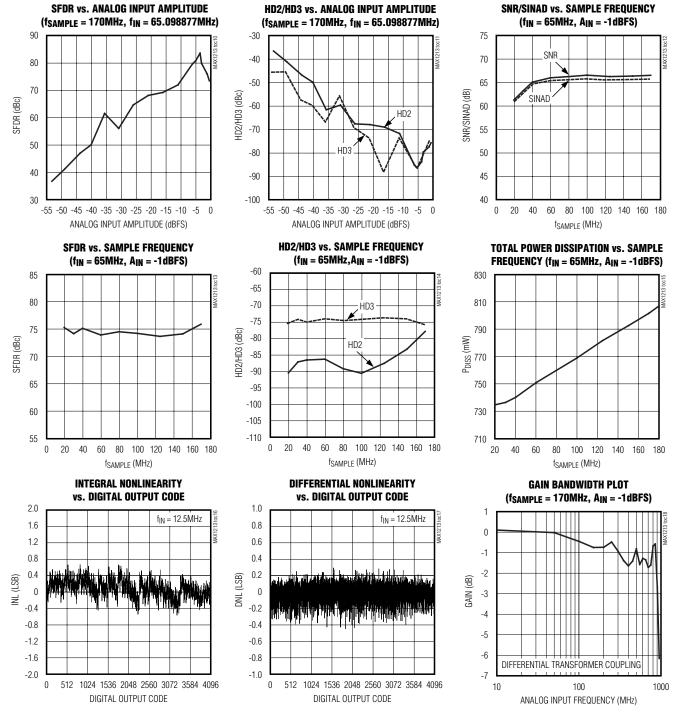


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#### \_Typical Operating Characteristics (continued)

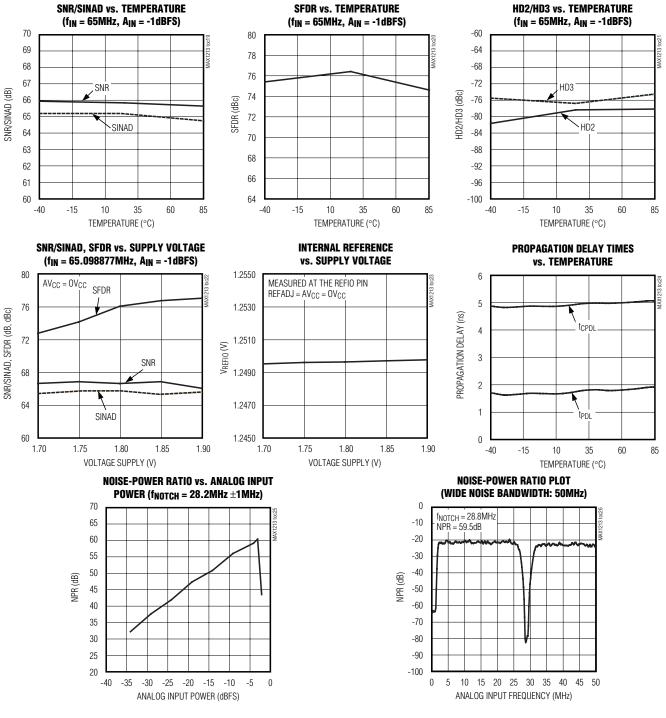
 $(AV_{CC} = OV_{CC} = 1.8V, AGND = OGND = 0, f_{SAMPLE} = 170MHz, A_{IN} = -1dBFS;$  see each TOC for detailed information on test conditions, differential input drive, differential sine-wave clock input drive, 0.1µF capacitor on REFIO, internal reference, digital output pins differential R<sub>L</sub> = 100 $\Omega$ , T<sub>A</sub> = +25°C.)





#### **Typical Operating Characteristics (continued)**

 $(AV_{CC} = OV_{CC} = 1.8V, AGND = OGND = 0, f_{SAMPLE} = 170MHz, A_{IN} = -1dBFS;$  see each TOC for detailed information on test conditions, differential input drive, differential sine-wave clock input drive, 0.1µF capacitor on REFIO, internal reference, digital output pins differential R<sub>L</sub> = 100 $\Omega$ , T<sub>A</sub> = +25°C.)



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**MAX1213** 

		Pin Description			
PIN	NAME	FUNCTION			
1, 6, 11–14, 20, 25, 62, 63, 65	AV <sub>CC</sub>	Analog Supply Voltage. Bypass each pin with a parallel combination of 0.1 $\mu$ F and 0.22 $\mu$ F capacitors for best decoupling results.			
2, 5, 7, 10, 15, 16, 18, 19, 21, 24, 64, 66, 67	AGND	Analog Converter Ground			
3	REFIO	Reference Input/Output. With REFADJ pulled high, this I/O port allows an external reference source to be connected to the MAX1213. With REFADJ pulled low, the internal 1.23V bandgap reference is active.			
4	REFADJ	Reference Adjust Input. REFADJ allows for FSR adjustments by placing a resistor or trim potentiometer between REFADJ and AGND (decreases FSR) or REFADJ and REFIO (increases FSR). If REFADJ is connected to AV <sub>CC</sub> , the internal reference can be overdriven with an external source connected to REFIO. If REFADJ is connected to AGND, the internal reference is used to determine the FSR of the data converter.			
8	INP	Positive Analog Input Terminal. Internally self-biased to 1.365V.			
9	INN	Negative Analog Input Terminal. Internally self-biased to 1.365V.			
17	CLKDIV	Clock Divider Input. This LVCMOS-compatible input controls which speed the converter's digital outputs are updated with. CLKDIV has an internal pulldown resistor. CLKDIV = 0: ADC updates digital outputs at one-half the input clock rate. CLKDIV = 1: ADC updates digital outputs at input clock rate.			
22	22 CLKP True Clock Input. This input ideally requires an LVPECL-compatible input level to maintain converter's excellent performance. Internally self-biased to 1.15V.				
23	CLKN	Complementary Clock Input. This input ideally requires an LVPECL-compatible input level to maintain the converter's excellent performance. Internally self-biased to 1.15V.			
26, 45, 61	OGND	Digital Converter Ground. Ground connection for digital circuitry and output drivers.			
27, 28, 41, 44, 60	OV <sub>CC</sub>	Digital Supply Voltage. Bypass with a 0.1µF capacitor for best decoupling results.			
29	DON	Complementary Output Bit 0 (LSB)			
30	D0P	True Output Bit 0 (LSB)			
31	D1N	Complementary Output Bit 1			
32	D1P	True Output Bit 1			
33	D2N	Complementary Output Bit 2			
34	D2P	True Output Bit 2			
35	D3N	Complementary Output Bit 3			
36	D3P	True Output Bit 3			

### \_Pin Description (continued)

PIN	NAME	FUNCTION					
37	D4N	Complementary Output Bit 4					
38	D4P	True Output Bit 4					
39	D5N	Complementary Output Bit 5					
40	D5P	True Output Bit 5					
42	DCLKN	Complementary Clock Output. This output provides an LVDS-compatible output level and can be used to synchronize external devices to the converter clock.					
43	DCLKP	True Clock Output. This output provides an LVDS-compatible output level and can be used to synchronize external devices to the converter clock.					
46	D6N	Complementary Output Bit 6					
47	D6P	True Output Bit 6					
48	D7N	Complementary Output Bit 7					
49	D7P	True Output Bit 7					
50	D8N	Complementary Output Bit 8					
51	D8P	True Output Bit 8					
52	D9N	Complementary Output Bit 9					
53	D9P	True Output Bit 9					
54	D10N	Complementary Output Bit 10					
55	D10P	True Output Bit 10					
56	D11N	Complementary Output Bit 11 (MSB)					
57	D11P	True Output Bit 11 (MSB)					
58	ORN	Complementary Output for Out-of-Range Control Bit. If an out-of-range condition is detected, bit ORN flags this condition by transitioning low.					
59	ORP	True Output for Out-of-Range Control Bit. If an out-of-range condition is detected, bit ORP flags this condition by transitioning high.					
_	EP	Exposed Paddle. The exposed paddle is located on the backside of the chip and must be connected to analog group for optimum performance.					

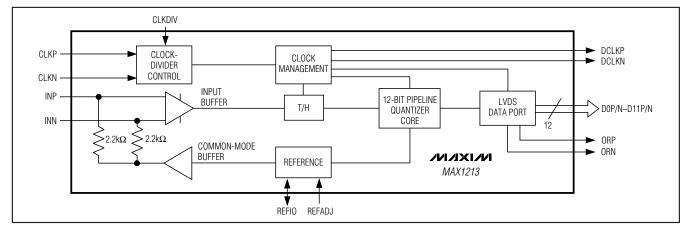


Figure 1. Simplified MAX1213 Block Diagram

#### Detailed Description— \_\_\_\_Theory of Operation

The MAX1213 uses a fully differential pipelined architecture that allows for high-speed conversion, optimized accuracy, and linearity while minimizing power consumption and die size.

Both positive (INP) and negative/complementary analog input terminals (INN) are centered around a common-mode voltage of 1.365V, and accept a differential analog input voltage swing of  $\pm V_{FS}$  / 4 each, resulting in a typical differential full-scale signal swing of 1.454V<sub>P-P</sub>. Inputs INP and INN are buffered prior to entering each T/H stage and are sampled when the differential sampling clock signal transitions high.

Each pipeline converter stage converts its input voltage to a digital output code. At every stage, except the last, the error between the input voltage and the digital output code is multiplied and passed along to the next pipeline stage. Digital error correction compensates for ADC comparator offsets in each pipeline stage and ensures no missing codes. The result is a 12-bit parallel digital output word in user-selectable two's complement or offset binary output formats with LVDS-compatible output levels. See Figure 1 for a more detailed view of the MAX1213 architecture.

#### Analog Inputs (INP, INN)

INP and INN are the fully differential inputs of the MAX1213. Differential inputs usually feature good rejection of even-order harmonics, which allows for enhanced AC performance as the signals are progressing through the analog stages. The MAX1213 analog inputs are self-biased at a common-mode voltage of 1.365V and allow a differential input voltage swing of 1.454VP-P (Figure 2). Both inputs are self-biased

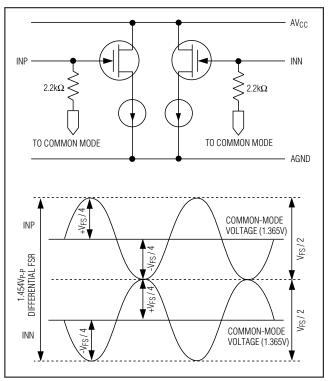


Figure 2. Simplified Analog Input Architecture and Allowable Input Voltage Range

through  $2k\Omega$  resistors, resulting in a typical differential input resistance of  $4k\Omega$ . It is recommended to drive the analog inputs of the MAX1213 in AC-coupled configuration to achieve best dynamic performance. See the *Transformer-Coupled*, *Differential Analog Input Drive* section for a detailed discussion of this configuration.



**MAX1213** 

#### **On-Chip Reference Circuit**

The MAX1213 features an internal 1.23V bandgap reference circuit (Figure 3), which in combination with an internal reference-scaling amplifier determines the FSR of the MAX1213. Bypass REFIO with a 0.1 $\mu$ F capacitor to AGND. To compensate for gain errors or increase the ADC's FSR, the voltage of this bandgap reference can be indirectly adjusted by adding an external resistor (e.g., 100k $\Omega$  trim potentiometer) between REFADJ and AGND or REFADJ and REFIO. See the *Applications Information* section for a detailed description of this process.

To disable the internal reference, connect REFADJ to  $AV_{CC}$ . In this configuration, an external, stable reference must be applied to REFIO to set the converter's full scale. To enable the internal reference, connect REFADJ to AGND.

#### **Clock Inputs (CLKP, CLKN)**

Designed for a differential LVDS clock input drive, it is recommended to drive the clock inputs of the MAX1213 with an LVDS- or LVPECL-compatible clock to achieve the best dynamic performance. The clock signal source must be a high-quality, low-phase noise with fast edge rates to avoid any degradation in the noise performance of the ADC. The clock inputs (CLKP, CLKN) are internally biased to 1.15V, accept a typical differential signal swing of 0.5VP-P, and are usually driven in AC-coupled configuration. See the *Differential, AC-Coupled PECL-Compatible Clock Input* section for more circuit details on how to drive CLKP and CLKN appropriately. Although not recommended, the clock inputs also accept a single-ended input signal.

The MAX1213 also features an internal clock-management circuit (duty-cycle equalizer) that ensures that the clock signal applied to inputs CLKP and CLKN is processed to provide a 50% duty-cycle clock signal that desensitizes the performance of the converter to variations in the duty cycle of the input clock source. Note that the clock duty-cycle equalizer cannot be turned off externally and requires a minimum clock frequency of >20MHz to work appropriately and according to data sheet specifications.

#### Data Clock Outputs (DCLKP, DCLKN)

The MAX1213 features a differential clock output, which can be used to latch the digital output data with an external latch or receiver. Additionally, the clock output can be used to synchronize external devices (e.g., FPGAs) to the ADC. DCLKP and DCLKN are differential outputs with LVDS-compatible voltage levels. There is a 4.95ns delay time between the rising (falling) edge of CLKP (CLKN) and the rising edge of DCLKP (DCLKN). See Figure 4 for timing details.

#### **Divide-by-2 Clock Control (CLKDIV)**

The MAX1213 offers a clock control line (CLKDIV), which supports the reduction of clock jitter in a system. Connect CLKDIV to OGND to enable the ADC's internal divide-by-2 clock divider. Data is now updated at one-half the ADC's input clock rate. CLKDIV has an internal pulldown resistor and can be left open for applications that require this divide-by-2 mode. Connecting CLKDIV to OV<sub>CC</sub> disables the divide-by-2 mode.

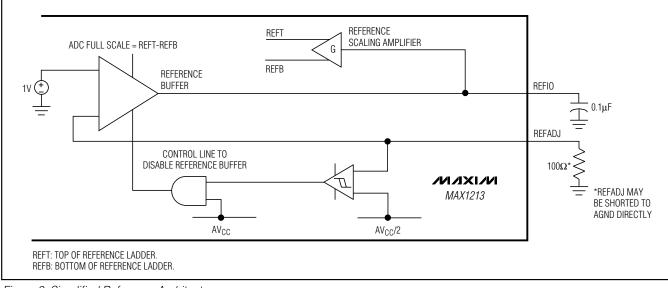


Figure 3. Simplified Reference Architecture

# **MAX1213**

# **1.8V, 12-Bit, 170Msps ADC for Broadband Applications**

#### **System Timing Requirements**

Figure 4 depicts the relationship between the clock input and output, analog input, sampling event, and data output. The MAX1213 samples on the rising (falling) edge of CLKP (CLKN). Output data is valid on the next rising (falling) edge of the DCLKP (DCLKN) clock, but has an internal latency of 11 clock cycles.

# Digital Outputs (D0P/N–D11P/N, DCLKP/N, ORP/N) and Control Input $\overline{T}/B$

Digital outputs D0P/N–D11P/N, DCLKP/N, and ORP/N are LVDS compatible, and data on D0P/N–D11P/N is presented in either binary or two's-complement format (Table 1). The T/B control line is an LVCMOS-compatible input, which allows the user to select the desired output format. Pulling T/B low outputs data in two's complement and pulling it high presents data in offset binary format on the 12-bit parallel bus. T/B has an internal pulldown resistor and may be left unconnected in applications using only two's complement output for-

mat. All LVDS outputs provide a typical voltage swing of 0.325V around a common-mode voltage of roughly 1.15V, and must be differentially terminated at the far end of each transmission line pair (true and complementary) with 100 $\Omega$ . The LVDS outputs are powered from a separate power supply, which can be operated between 1.7V and 1.9V.

The MAX1213 offers an additional differential output pair (ORP, ORN) to flag out-of-range conditions, where out-of-range is above positive or below negative full scale. An out-of-range condition is identified with ORP (ORN) transitioning high (low).

**Note:** Although a differential LVDS output architecture reduces single-ended transients to the supply and ground planes, capacitive loading on the digital outputs should still be kept as low as possible. Using LVDS buffers on the digital outputs of the ADC when driving larger loads may improve overall performance and reduce system-timing constraints.

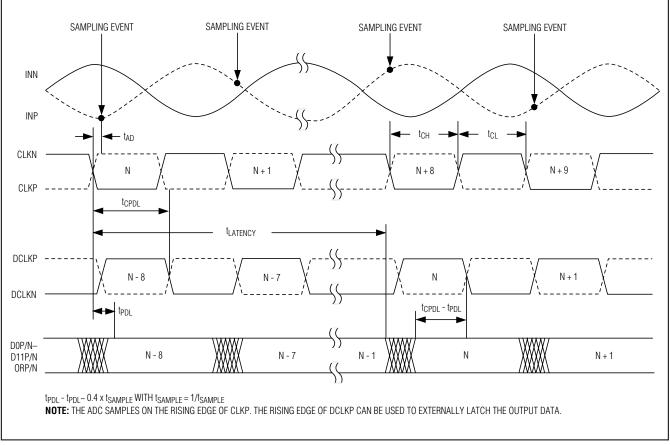


Figure 4. System and Output Timing Diagram

#### Table 1. MAX1213 Digital Output Coding

INP ANALOG INPUT VOLTAGE LEVEL	INN ANALOG INPUT VOLTAGE LEVEL	OUT-OF-RANGE ORP (ORN)	BINARY DIGITAL OUTPUT CODE (D11P/N-D0P/N)	TWO'S COMPLEMENT DIGITAL OUTPUT CODE (D11P/N-D0P/N)
$> V_{CM} + V_{FS} / 4$	< V <sub>CM</sub> - V <sub>FS</sub> / 4	1 (0)	1111 1111 1111 (exceeds +FS, OR set)	0111 1111 1111 (exceeds +FS, OR set)
V <sub>CM</sub> + V <sub>FS</sub> / 4	V <sub>CM</sub> - V <sub>FS</sub> / 4	0(1)	1111 1111 1111 (+FS)	0111 1111 1111 (+FS)
V <sub>CM</sub>	V <sub>CM</sub>	0(1)	1000 0000 0000 or 0111 1111 1111 (FS/2)	0000 0000 0000 or 1111 1111 1111 (FS/2)
V <sub>CM</sub> - V <sub>FS</sub> / 4	$V_{CM}$ + $V_{FS}$ / 4	0(1)	0000 0000 0000 (-FS)	1000 0000 0000 (-FS)
< V <sub>CM</sub> + V <sub>FS</sub> / 4	$+ V_{FS} / 4 > V_{CM} - V_{FS} / 4$		00 0000 0000 (exceeds -FS, OR set)	10 0000 0000 (exceeds -FS, OR set)

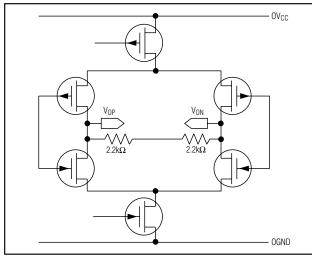


Figure 5. Simplified LVDS Output Architecture

#### \_Applications Information

#### FSR Adjustments Using the Internal Bandgap Reference

The MAX1213 supports a full-scale adjustment range of 10% ( $\pm$ 5%). To decrease the full-scale signal range, an external resistor value ranging from 13k $\Omega$  to 1M $\Omega$  may be added between REFADJ and AGND. A similar approach can be taken to increase the ADC's full-scale range (FSR). Adding a variable resistor, potentiometer, or predetermined resistor value between REFADJ and REFIO increases the FSR of the data converter. Figure 6a shows the two possible configurations and their impact on the overall full-scale range adjustment of the MAX1213. Do not use resistor values of less than 13k $\Omega$  to avoid instability of the internal gain regulation loop for the bandgap reference. See Figure 6b for the results of the adjustment range for a selection of resistors used to trim the full-scale range of the MAX1213.



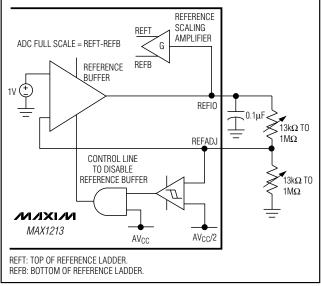


Figure 6a: Circuit Suggestions to Adjust the ADC's Full-Scale Range

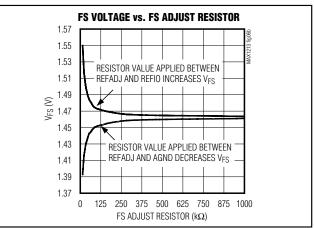


Figure 6b: FS Adjustment Range vs. FS Adjustment Resistor

# MAX1213

# **1.8V, 12-Bit, 170Msps ADC for Broadband Applications**

#### Differential, AC-Coupled, LVPECL-Compatible Clock Input

The MAX1213 dynamic performance depends on the use of a very clean clock source. The phase noise floor of the clock source has a negative impact on the SNR performance. Spurious signals on the clock signal source also affect the ADC's dynamic range. The preferred method of clocking the MAX1213 is differentially with LVDS- or LVPECL-compatible input levels. The fast data transition rates of these logic families minimize the clock-input circuitry's transition uncertainty, thereby improving the SNR performance. To accomplish this, a 50 $\Omega$  reverse-terminated clock signal source with low phase noise is AC-coupled into a fast differential receiver such as the MC100LVEL16D (Figure 7). The receiver produces the necessary LVPECL output levels to drive the clock inputs of the data converter.

#### Transformer-Coupled, Differential Analog Input Drive

In general, the MAX1213 provides the best SFDR and THD with fully differential input signals and it is not re-

commended to drive the ADC inputs in single-ended configuration. In differential input mode, even-order harmonics are usually lower since INP and INN are balanced, and each of the ADC inputs only requires half the signal swing compared to a single-ended configuration. Wideband RF transformers provide an excellent solution to convert a single-ended signal to a fully differential signal, required by the MAX1213 to reach its optimum dynamic performance.

A secondary-side termination of a 1:1 transformer (e.g., Mini-Circuit's ADT1-1WT) into two separate  $24.9\Omega \pm 1\%$  resistors (use tight resistor tolerances to minimize effects of imbalance; 0.5% would be an ideal choice) placed between top/bottom and center tap of the transformer is recommended to maximize the ADC's dynamic range. This configuration optimizes THD and SFDR performance of the ADC by reducing the effects of transformer parasitics. However, the source impedance combined with the shunt capacitance provided by a PC board and the ADC's parasitic capacitance limit the ADC's full-power input bandwidth to approximately 600MHz.

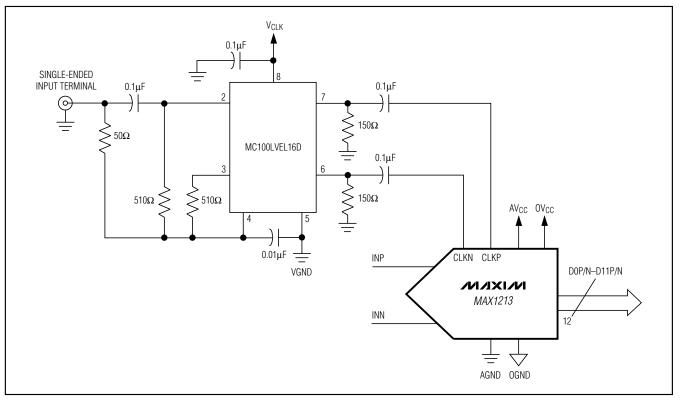


Figure 7. Differential, AC-Coupled, PECL-Compatible Clock Input Configuration

To further enhance THD and SFDR performance at high-input frequencies (>100MHz), a second transformer (Figure 8) should be placed in series with the single-ended-to-differential conversion transformer. This transformer reduces the increase of even-order harmonics at high frequencies.

**Single-Ended, AC-Coupled Analog Inputs** Although not recommended, the MAX1213 can be used in single-ended mode (Figure 9). Analog signals can be AC-coupled to the positive input INP through a  $0.1\mu$ F capacitor and terminated with a  $49.9\Omega$  resistor to AGND. The negative input should be reverse terminated with 24.9 $\Omega$  resistors and AC-grounded with a  $0.1\mu$ F capacitor.

#### Grounding, Bypassing, and Board Layout Considerations\_

The MAX1213 requires board layout design techniques suitable for high-speed data converters. This ADC provides separate analog and digital power supplies. The analog and digital supply voltage pins accept input voltage ranges of 1.7V to 1.9V. Although both supply types can be combined and supplied from one source, it is recommended to use separate sources to cut down on performance degradation caused by digital switching currents, which can couple into the analog supply network. Isolate analog and digital supplies (AV<sub>CC</sub> and OV<sub>CC</sub>) where they enter the PC board with separate networks of ferrite beads and capacitors to their corresponding grounds (AGND, OGND).

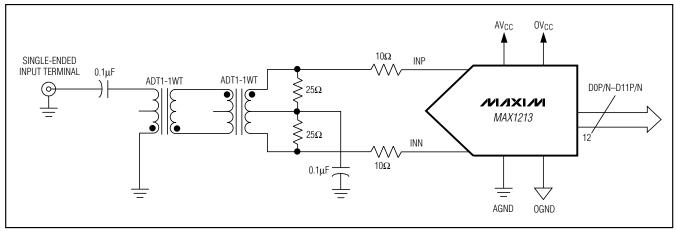


Figure 8. Analog Input Configuration with Back-to-Back Transformers and Secondary-Side Termination

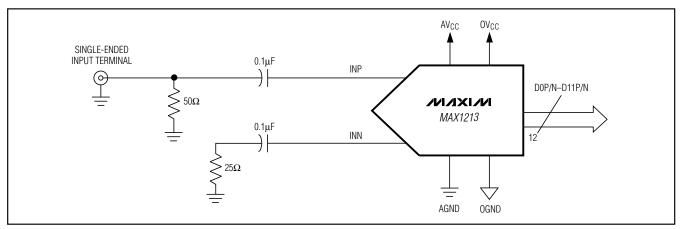


Figure 9. Single-Ended AC-Coupled Analog Input Configuration

**MAX1213** 

To achieve optimum performance, provide each supply with a separate network of a  $47\mu$ F tantalum capacitor and parallel combinations of  $10\mu$ F and  $1\mu$ F ceramic capacitors. Additionally, the ADC requires each supply pin to be bypassed with separate 0.1 $\mu$ F ceramic capacitors (Figure 10). Locate these capacitors directly at the ADC supply pins or as close as possible to the MAX1213. Choose surface-mount capacitors, whose preferred location should be on the same side as the converter to save space and minimize the inductance. If close placement on the same side is not possible, these bypassing capacitors may be routed through vias to the bottom side of the PC board.

Multilayer boards with separated ground and power planes produce the highest level of signal integrity. Consider the use of a split ground plane arranged to match the physical location of analog and digital ground on the ADC's package. The two ground planes should be joined at a single point such that the noisy digital ground currents do not interfere with the analog ground plane. The dynamic currents that may need to travel long distances before they are recombined at a common-source ground, resulting in large and undesirable ground loops, are a major concern with this approach. Ground loops can degrade the input noise by coupling back to the analog front end of the converter, resulting in increased spurious activity, leading to decreased noise performance.

Alternatively, all ground pins could share the same ground plane, if the ground plane is sufficiently isolated from any noisy, digital systems ground. To minimize the coupling of the digital output signals from the analog input, segregate the digital output bus carefully from the analog input circuitry. To further minimize the effects of digital noise coupling, ground return vias can be positioned throughout the layout to divert digital switching currents away from the sensitive analog sections of the ADC. This approach does not require split ground planes, but can be accomplished by placing substantial ground connections between the analog front end and the digital outputs.

The MAX1213 is packaged in a 68-pin QFN-EP package **(package code: G6800-4)**, providing greater design flexibility, increased thermal dissipation, and optimized AC performance of the ADC. The exposed paddle (EP) must be soldered down to AGND.

In this package, the data converter die is attached to an EP lead frame with the back of this frame exposed at the package bottom surface, facing the PC board side of the package. This allows a solid attachment of the package to the board with standard infrared (IR) flow soldering techniques.

Thermal efficiency is one of the factors for selecting a package with an exposed pad for the MAX1213. The exposed pad improves thermal and ensures a solid ground connection between the DAC and the PC board's analog ground layer.

Considerable care must be taken when routing the digital output traces for a high-speed, high-resolution data converter. It is recommended running the LVDS output traces as differential lines with  $100\Omega$  matched impedance from the ADC to the LVDS load device.

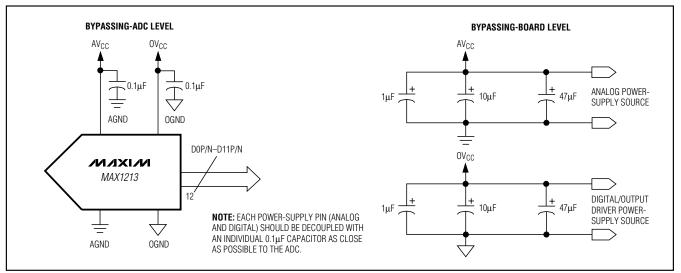


Figure 10. Grounding, Bypassing, and Decoupling Recommendations for MAX1213

#### **Static Parameter Definitions**

#### **Integral Nonlinearity (INL)**

Integral nonlinearity is the deviation of the values on an actual transfer function from a straight line. This straight line can be either a best straight-line fit or a line drawn between the end points of the transfer function, once offset and gain errors have been nullified. However, the static linearity parameters for the MAX1213 are measured using the histogram method with an input frequency of 10MHz.

#### **Differential Nonlinearity (DNL)**

Differential nonlinearity is the difference between an actual step width and the ideal value of 1LSB. A DNL error specification of less than 1LSB guarantees no missing codes and a monotonic transfer function. The MAX1213's DNL specification is measured with the histogram method based on a 10MHz input tone.

#### \_Dynamic Parameter Definitions

#### **Aperture Jitter**

Figure 11 depicts the aperture jitter  $(t_{AJ})$ , which is the sample-to-sample variation in the aperture delay.

#### **Aperture Delay**

Aperture delay  $(t_{AD})$  is the time defined between the rising edge of the sampling clock and the instant when an actual sample is taken (Figure 11).

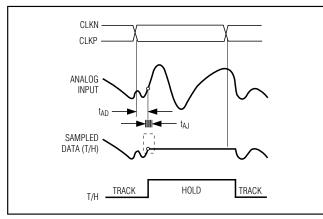


Figure 11. Aperture Jitter/Delay Specifications

#### Signal-to-Noise Ratio (SNR)

For a waveform perfectly reconstructed from digital samples, the theoretical maximum SNR is the ratio of the full-scale analog input (RMS value) to the RMS quantization error (residual error). The ideal, theoretical minimum analog-to-digital noise is caused by quantization error only and results directly from the ADC's resolution (N bits):

$$SNR_{[max]} = 6.02 \times N + 1.76$$

In reality, other noise sources such as thermal noise, clock jitter, signal phase noise, and transfer function nonlinearities are also contributing to the SNR calculation and should be considered when determining the signal-to-noise ratio in ADC.

#### Signal-to-Noise Plus Distortion (SINAD)

SINAD is computed by taking the ratio of the RMS signal to all spectral components excluding the fundamental and the DC offset. In the case of the MAX1213, SINAD is computed from a curve fit.

#### Spurious-Free Dynamic Range (SFDR)

SFDR is the ratio of RMS amplitude of the carrier frequency (maximum signal component) to the RMS value of the next-largest noise or harmonic distortion component. SFDR is usually measured in dBc with respect to the carrier frequency amplitude or in dBFS with respect to the ADC's full-scale range.

#### Intermodulation Distortion (IMD)

IMD is the ratio of the RMS sum of the intermodulation products to the RMS sum of the two fundamental input tones. This is expressed as:

$$\mathsf{IMD} = 20 \times \log \left( \frac{\sqrt{\mathsf{V_{IM1}}^2 + \mathsf{V_{IM2}}^2 + \dots + \mathsf{V_{IM3}}^2 + \mathsf{V_{IM1}}^2}}{\sqrt{\mathsf{V_1}^2 + \mathsf{V_2}^2}} \right)$$

The fundamental input tone amplitudes (V<sub>1</sub> and V<sub>2</sub>) are at -7dBFS. The intermodulation products are the amplitudes of the output spectrum at the following frequencies:

- Second-order intermodulation products:  $f_{IN1} + f_{IN2}$ ,  $f_{IN2} f_{IN1}$
- Third-order intermodulation products: 2 x f<sub>IN1</sub> f<sub>IN2</sub>, 2 x f<sub>IN2</sub> - f<sub>IN1</sub>, 2 x f<sub>IN1</sub> + f<sub>IN2</sub>, 2 x f<sub>IN2</sub> + f<sub>IN1</sub>
- Fourth-order intermodulation products: 3 x f<sub>IN1</sub> f<sub>IN2</sub>, 3 x f<sub>IN2</sub> - f<sub>IN1</sub>, 3 x f<sub>IN1</sub> + f<sub>IN2</sub>, 3 x f<sub>IN2</sub> + f<sub>IN1</sub>
- Fifth-order intermodulation products:  $3 \times f_{IN1} 2 \times f_{IN2}$ ,  $3 \times f_{IN2} - 2 \times f_{IN1}$ ,  $3 \times f_{IN1} + 2 \times f_{IN2}$ ,  $3 \times f_{IN2} + 2 \times f_{IN1}$

#### **Full-Power Bandwidth**

A large -1dBFS analog input signal is applied to an ADC and the input frequency is swept up to the point where the amplitude of the digitized conversion result has decreased by 3dB. The -3dB-point is defined as full-power input bandwidth frequency of the ADC.

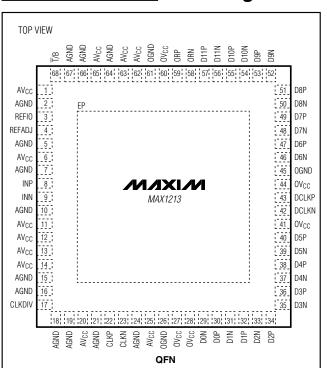


#### Noise Power Ratio (NPR)

NPR is commonly used to characterize the return path of cable systems where the signals are typically individual guadrature amplitude-modulated (QAM) carriers with a frequency spectrum similar to noise. Numerous such carriers are operated in a continuous spectrum, generating a noise-like signal, which covers a relatively broad bandwidth. To test the MAX1213 for NPR, a "noise-like" signal is passed through a high-order bandpass filter to produce an approximately square spectral pedestal of noise with about the same bandwidth as the signals being simulated. Following the bandpass filter, the signal is passed through a narrow band-reject filter to produce a deep notch at the center of the noise pedestal. Finally, this signal is applied to the MAX1213 and its digitized results analyzed. The RMS noise power of the signal inside the notch is compared with the RMS noise level outside the notch using an FFT. Note that the NPR test requires sufficiently long data records to guarantee a suitable number of samples inside the notch. NPR for the MAX1213 was determined for 50MHz noise bandwidth signals, simulating a typical cable signal environment (see the Typical Operating Characteristics for test details and results) with a notch frequency of 28.8MHz.

#### Pin-Compatible Lower Speed/Resolution Versions

Applications that require lower resolution and/or higher speed can refer to other family members of the MAX1213. Adjusting an application to a lower resolution has been simplified by maintaining an identical pinout for all members of this high-speed family. See the *Pin-Compatible Versions* table for a selection of different resolution and speed grades.

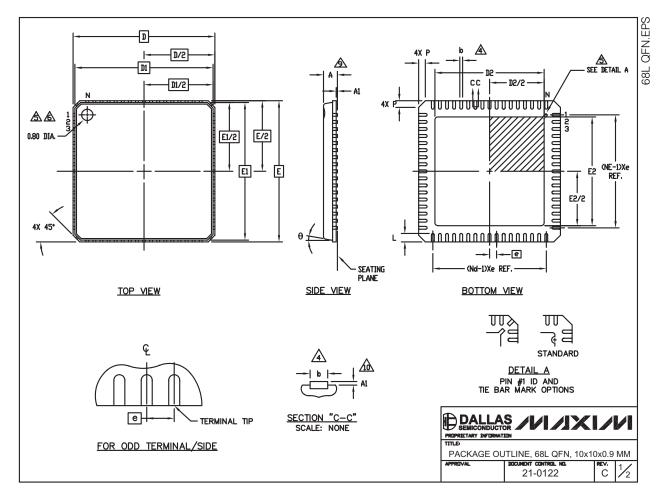


#### **Pin Configuration**

#### Package Information

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information go to **www.maxim-ic.com/packages**.)

#### For the MAX1213, the package code is G6800-4.



#### **Package Information (continued)**

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(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information go to www.maxim-ic.com/packages.)

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Ne    17    3      0    0    12'      P    0    0.42      0    0.42    0.60      II.    MEETS JEDEC MD-220.      EXPOSED PAD VARIATIONS      D2    E2      PKG CDDE    MIN    NDM      MIN    NDM    MAX      G6800-2    7.55    7.70      7.55    7.70    7.85	Ne      17      3        0      0      12'        P      0      0.42      0.60        II.      MEETS JEDEC MD-220.	Nd		17			3	i		
0    12'      P    0    0.42    0.60      EXPOSED    PAD    VARIATIONS      D2    E2      PKG    CIDE    MIN    NDM    MAX      G6800-2    7.55    7.70    7.85    7.55    7.70	0    12'    Image: Constraint of the second s	Ne		17			3			
P      0      0.42      0.60      11. MEETS JEDEC MD-220.        EXPOSED PAD VARIATIONS        D2      E2        PKG CDDE      MIN      NDM      MAX        G6800-2      7.55      7.70      7.85	P    0    0.42    0.60    11. MEETS JEDEC MD-220.      EXPOSED PAD VARIATIONS      D2    E2      PKG CDDE    MIN    NDM    MAX      G6800-2    7.55    7.70    7.85    7.55    5.80    5.95      G6800-4    5.65    5.80    5.95    5.65    5.80    5.95	θ	0		12	•		7		
D2      E2        PKG CDDE      MIN      NDM      MAX        G6800-2      7.55      7.70      7.85      7.55	D2      E2        PKG CDDE      MIN      NDM      MAX      MIN      NDM      MAX        G6800-2      7.55      7.70      7.85      7.55      7.70      7.85        G6800-4      5.65      5.80      5.95      5.65      5.80      5.95	Ρ	0	0.42	0.6	60				
G6800-2 7.55 7.70 7.85 7.55 7.70 7.85	G6800-2 7.55 7.70 7.85 7.55 7.70 7.85 G6800-4 5.65 5.80 5.95 5.65 5.80 5.95 ■ Section 10 Section 1				D2			E2	1	
	G6800-4 5.65 5.80 5.95 5.65 5.80 5.95									-
G6800-4 5.65 5.80 5.95 5.65 5.80 5.95										-
		G6	5800-4	5.65	5.80	5.95	5.65	5.80	5.95	

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