


Hybrid Power Module

Integrated Power Stage for 460 VAC Motor Drives

These modules integrate a 3-phase inverter in a single convenient package. They are designed for 2.0, 3.0, and 5.0 hp motor drive applications. The inverter incorporates advanced insulated gate bipolar transistors (IGBT) matched with fast soft free-wheeling diodes to give optimum performance. The top connector pins are designed for easy interfacing to the user's control board.

- Short Circuit Rated 10 μ s @ 125°C, 720 V
- Pin-to-Baseplate Isolation Exceeds 2500 Vac (rms)
- Compact Package Outline
- Access to Positive and Negative DC Bus
- UL  Recognized

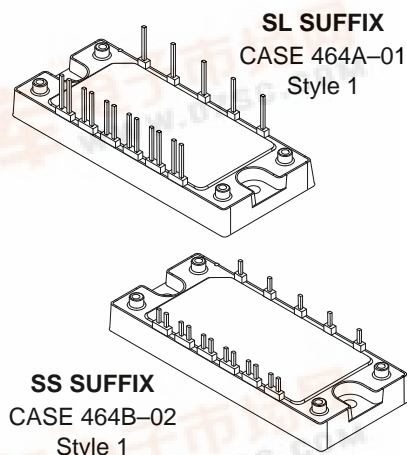
ORDERING INFORMATION

Device	Current Rating	Package
MHPM6B10N120SL	10	464A-01
MHPM6B15N120SL	15	Style 1
MHPM6B25N120SL	25	
MHPM6B10N120SS	10	464B-02
MHPM6B15N120SS	15	Style 1
MHPM6B25N120SS	25	

MHPM6B10N120 MHPM6B15N120 MHPM6B25N120 SERIES

Motorola Preferred Devices

10, 15, 25 A, 1200 V
HYBRID POWER MODULES



MAXIMUM DEVICE RATINGS (T_J = 25°C unless otherwise noted)

Rating	Symbol	Value	Unit
IGBT Reverse Voltage	V _{CES}	1200	V
Gate-Emitter Voltage	V _{GES}	± 20	V
Continuous IGBT Collector Current (T _C = 80°C)	I _{Cmax}	10 15 25	A
Repetitive Peak IGBT Collector Current (1)	I _{C(pk)}	20 30 50	A
Continuous Diode Current (T _C = 25°C)	I _{Fmax}	10 15 25	A
Continuous Diode Current (T _C = 80°C)	I _{F80}	8.3 11 14	A
Repetitive Peak Diode Current (1)	I _{F(pk)}	20 30 50	A
IGBT Power Dissipation per die (T _C = 95°C)	P _D	41 50 65	W
Diode Power Dissipation per die (T _C = 95°C)	P _D	16 22 27	W

(1) 3.0 ms = 1.0% duty cycle

Preferred devices are Motorola recommended choices for future use and best overall value.



MHPM6B10N120 MHPM6B15N120 MHPM6B25N120 SERIES

MAXIMUM DEVICE RATINGS ($T_J = 25^\circ\text{C}$ unless otherwise noted)

Rating	Symbol	Value	Unit
Junction Temperature Range	T_J	– 40 to +150	$^\circ\text{C}$
Short Circuit Duration ($V_{CE} = 720\text{ V}$, $T_J = 125^\circ\text{C}$)	t_{sc}	10	μs
Isolation Voltage, Pin to Baseplate	V_{ISO}	2500	Vac
Operating Case Temperature Range	T_C	– 40 to +95	$^\circ\text{C}$
Storage Temperature Range	T_{stg}	– 40 to +150	$^\circ\text{C}$
Mounting Torque — Heat Sink Mounting Holes	—	1.4	Nm

ELECTRICAL CHARACTERISTICS ($T_J = 25^\circ\text{C}$ unless otherwise noted)

Characteristic	Symbol	Min	Typ	Max	Unit
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DC AND SMALL SIGNAL CHARACTERISTICS

Gate-Emitter Leakage Current ($V_{CE} = 0\text{ V}$, $V_{GE} = \pm 20\text{ V}$)	I_{GES}	—	—	± 20	μA
Collector-Emitter Leakage Current ($V_{CE} = 1200\text{ V}$, $V_{GE} = 0\text{ V}$)	I_{CES}	—	5.0	100	μA
Gate-Emitter Threshold Voltage ($V_{CE} = V_{GE}$, $I_C = 1.0\text{ mA}$)	$V_{GE(th)}$	5.0	6.0	7.0	V
Collector-Emitter Breakdown Voltage ($I_C = 10\text{ mA}$, $V_{GE} = 0\text{ V}$)	$V_{(BR)CES}$	1200	—	—	V
Collector-Emitter Saturation Voltage ($I_C = I_{Cmax}$, $V_{GE} = 15\text{ V}$) $T_J = 125^\circ\text{C}$	$V_{CE(SAT)}$	1.7 —	2.35 2.69	2.9 —	V
Forward Transconductance 10A120 15A120 25A120	g_{fe}	— — —	8.3 14 19	— — —	mho
Diode Forward Voltage ($I_F = I_{Fmax}$, $V_{GE} = 0\text{ V}$) $T_J = 125^\circ\text{C}$	V_F	1.7 —	2.35 1.9	3.1 —	V
Input Capacitance ($V_{CE} = 10\text{ V}$, $V_{GE} = 0\text{ V}$, $f = 1.0\text{ MHz}$) 10A120 15A120 25A120	C_{ies}	— — —	1880 2620 4770	— — —	pF
Input Gate Charge ($V_{CE} = 600\text{ V}$, $I_C = I_{Cmax}$, $V_{GE} = 15\text{ V}$) 10A120 15A120 25A120	Q_T	— — —	65 87 150	— — —	nC

INDUCTIVE SWITCHING CHARACTERISTICS ($T_J = 25^\circ\text{C}$)

Recommended Gate Resistor ($R_{G(on)} = R_{G(off)}$) 10A120 15A120 25A120	R_G	— — —	82 82 68	— — —	Ω
Turn-On Delay Time ($V_{CE} = 600\text{ V}$, $I_C = I_{Cmax}$, $V_{GE} = 15\text{ V}$) 10A120 15A120 25A120	$t_{d(on)}$	— — —	174 240 330	— — —	ns
Rise Time ($V_{CE} = 600\text{ V}$, $I_C = I_{Cmax}$, $V_{GE} = 15\text{ V}$) 10A120 15A120 25A120	t_r	— — —	84 105 150	— — —	ns
Turn-Off Delay Time ($V_{CE} = 600\text{ V}$, $I_C = I_{Cmax}$, $V_{GE} = 15\text{ V}$) 10A120 15A120 25A120	$t_{d(off)}$	— — —	640 780 1060	— — —	ns
Fall Time ($V_{CE} = 600\text{ V}$, $I_C = I_{Cmax}$, $V_{GE} = 15\text{ V}$) 10A120 15A120 25A120	t_f	— — —	39 48 70	47 58 84	ns
Turn-On Energy ($V_{CE} = 600\text{ V}$, $I_C = I_{Cmax}$, $V_{GE} = 15\text{ V}$) 10A120 15A120 25A120	E_{on}	— — —	1.5 2.7 4.6	1.8 3.3 5.6	mJ

MHPM6B10N120 MHPM6B15N120 MHPM6B25N120 SERIES

Characteristic	Symbol	Min	Typ	Max	Unit
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INDUCTIVE SWITCHING CHARACTERISTICS ($T_J = 25^\circ\text{C}$) – continued

Turn-Off Energy ($V_{CE} = 600\text{ V}$, $I_C = I_{Cmax}$, $V_{GE} = 15\text{ V}$)	10A120 15A120 25A120	E_{off}	— — —	1.1 1.7 3.0	1.4 2.1 3.5	mJ
Diode Reverse Recovery Time ($I_F = I_{Fmax}$, $V = 600\text{ V}$)	10A120 15A120 25A120	t_{rr}	— — —	95 110 124	— — —	ns
Peak Reverse Recovery Current ($I_F = I_{Fmax}$, $V = 600\text{ V}$)	10A120 15A120 25A120	I_{rrm}	— — —	8.0 9.7 11.5	— — —	A
Diode Stored Charge ($I_F = I_{Fmax}$, $V = 600\text{ V}$)	10A120 15A120 25A120	Q_{rr}	— — —	550 600 740	— — —	nC

INDUCTIVE SWITCHING CHARACTERISTICS ($T_J = 125^\circ\text{C}$)

Characteristic	Symbol	Min	Typ	Max	Unit
Turn-On Delay Time ($V_{CE} = 600\text{ V}$, $I_C = I_{Cmax}$, $V_{GE} = 15\text{ V}$)	$t_{d(on)}$	— — —	160 220 310	— — —	ns
Rise Time ($V_{CE} = 600\text{ V}$, $I_C = I_{Cmax}$, $V_{GE} = 15\text{ V}$)	t_r	— — —	93 110 160	— — —	ns
Turn-Off Delay Time ($V_{CE} = 600\text{ V}$, $I_C = I_{Cmax}$, $V_{GE} = 15\text{ V}$)	$t_{d(off)}$	— — —	680 850 1140	— — —	ns
Fall Time ($V_{CE} = 600\text{ V}$, $I_C = I_{Cmax}$, $V_{GE} = 15\text{ V}$)	t_f	— — —	51 60 76	— — —	ns
Turn-On Energy ($V_{CE} = 600\text{ V}$, $I_C = I_{Cmax}$, $V_{GE} = 15\text{ V}$)	E_{on}	— — —	2.0 3.6 6.1	— — —	mJ
Turn-Off Energy ($V_{CE} = 600\text{ V}$, $I_C = I_{Cmax}$, $V_{GE} = 15\text{ V}$)	E_{off}	— — —	1.5 2.4 4.2	— — —	mJ
Diode Reverse Recovery Time ($I_F = I_{Fmax}$, $V = 600\text{ V}$)	t_{rr}	— — —	160 210 250	— — —	ns
Peak Reverse Recovery Current ($I_F = I_{Fmax}$, $V = 600\text{ V}$)	I_{rrm}	— — —	11.0 14.1 17.4	— — —	A
Diode Stored Charge ($I_F = I_{Fmax}$, $V = 600\text{ V}$)	Q_{rr}	— — —	995 1770 2460	— — —	nC

THERMAL CHARACTERISTICS (Each Die)

Thermal Resistance — IGBT	10A120 15A120 25A120	$R_{\theta JC}$	— — —	1.1 0.89 0.68	1.3 1.1 0.85	$^\circ\text{C/W}$
Thermal Resistance — Diode	10A120 15A120 25A120	$R_{\theta JC}$	— — —	2.8 2.0 1.6	3.5 2.5 2.0	$^\circ\text{C/W}$

MHPM6B10N120 MHPM6B15N120 MHPM6B25N120 SERIES

TYPICAL CHARACTERISTICS

(see also application information)

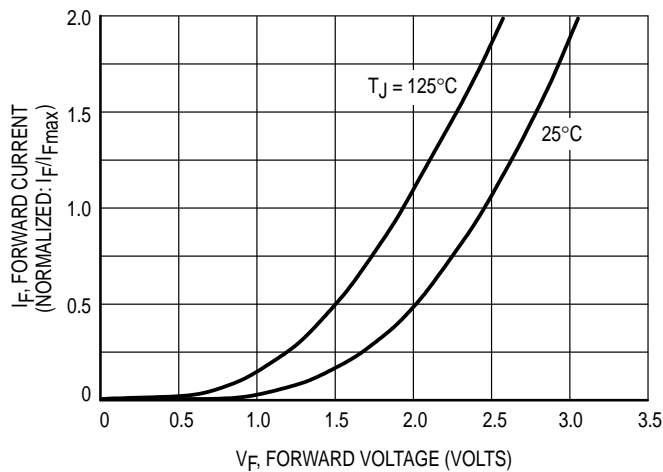


Figure 1. Forward Characteristics — Free-Wheeling Diode

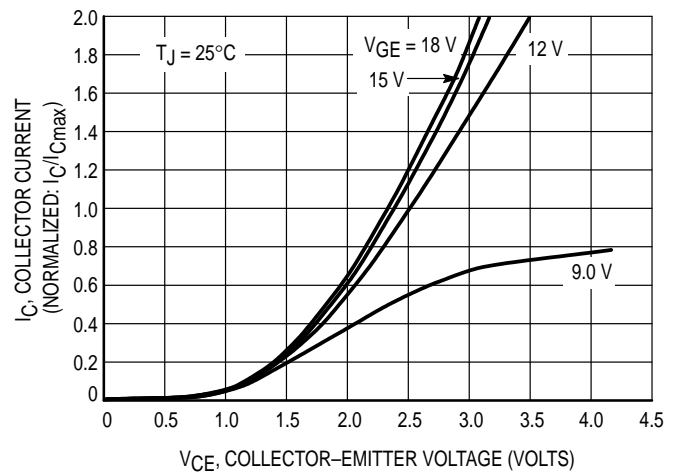


Figure 2. Forward Characteristics, $T_J = 25^\circ\text{C}$

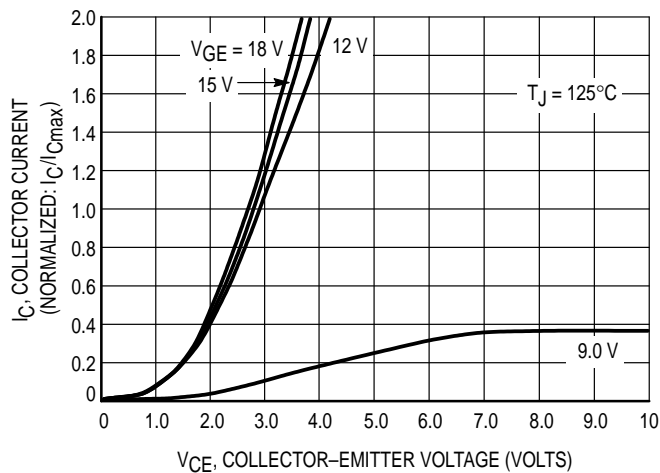


Figure 3. Forward Characteristics, $T_J = 125^\circ\text{C}$

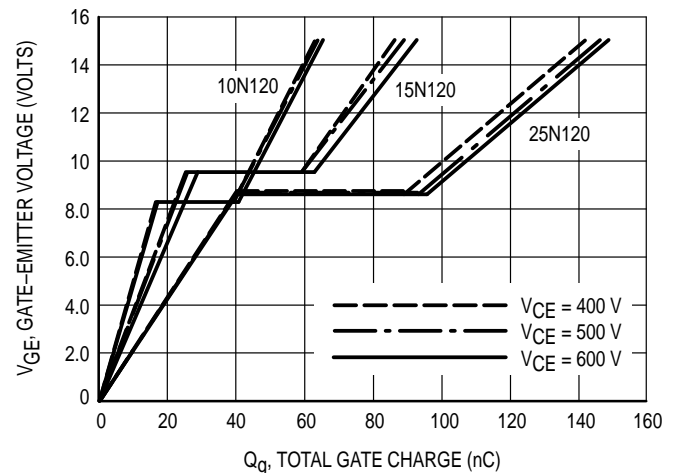


Figure 4. Gate-Emitter Voltage versus Total Gate Charge

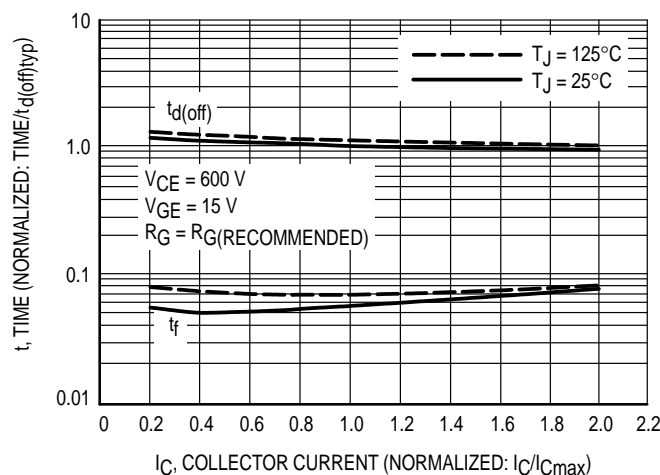


Figure 5. Inductive Switching Times versus Collector Current

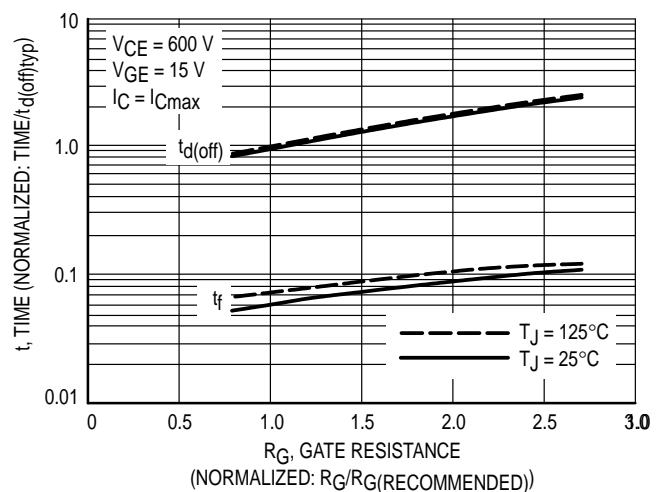


Figure 6. Inductive Switching Times versus Gate Resistance

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TYPICAL CHARACTERISTICS

(see also application information)

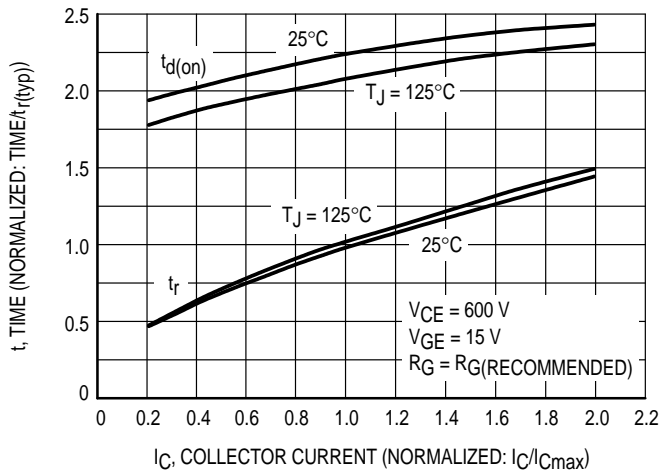


Figure 7. Inductive Switching Times versus Collector Current

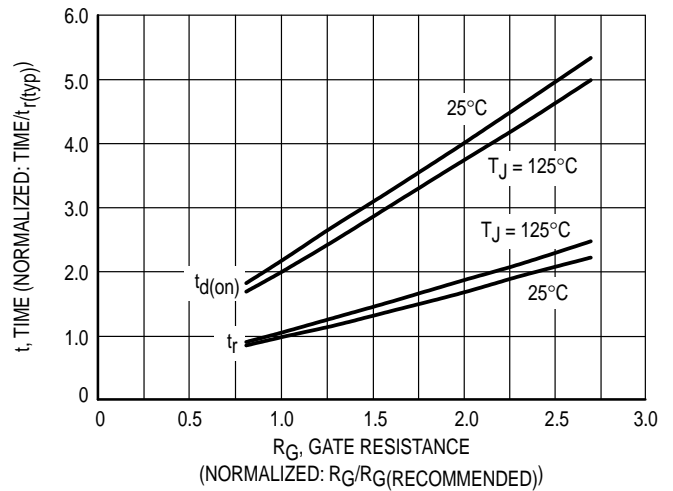


Figure 8. Inductive Switching Times versus Gate Resistance

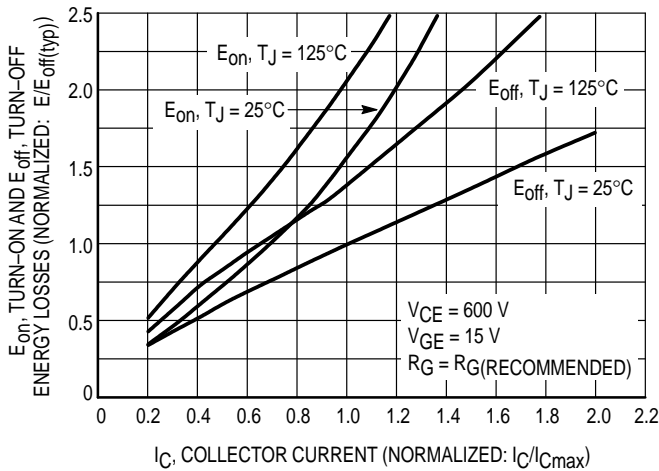


Figure 9. Turn-On and Turn-Off Energy Losses versus Collector Current

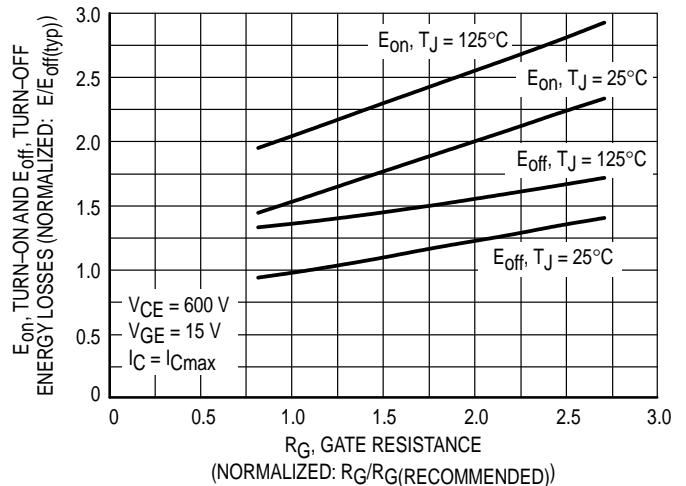


Figure 10. Turn-On and Turn-Off Energy Losses versus Gate Resistance

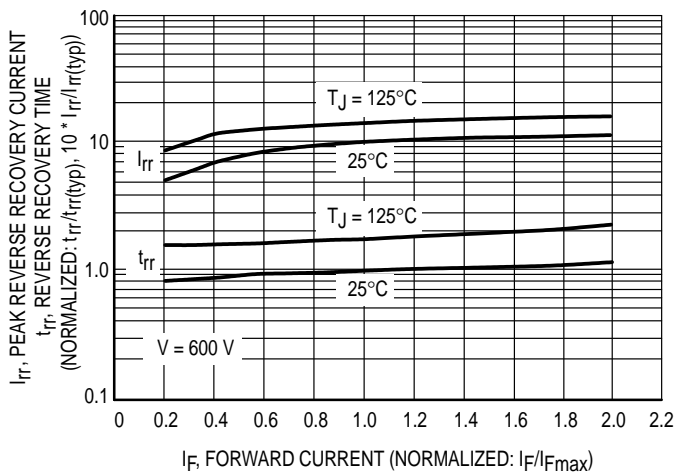


Figure 11. Reverse Recovery Characteristics — Free-Wheeling Diode

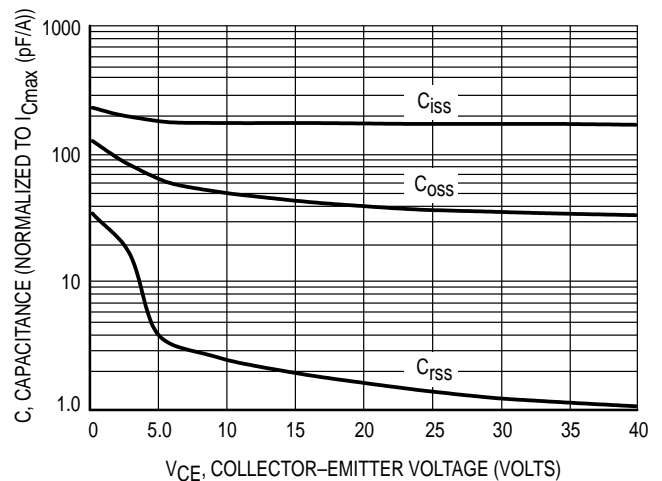


Figure 12. Capacitance Variation

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TYPICAL CHARACTERISTICS

(see also application information)

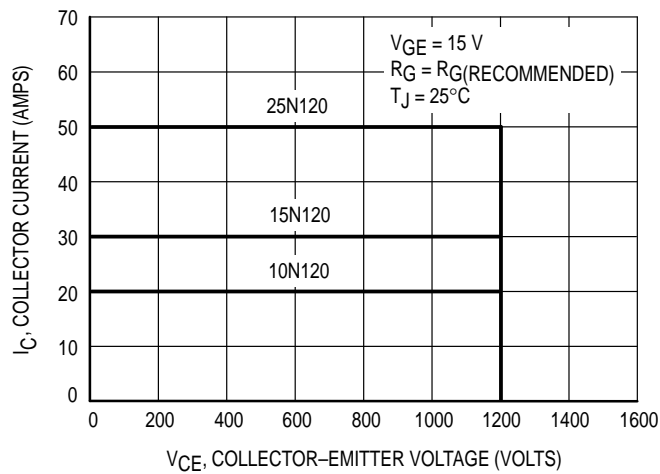


Figure 13. Reverse Biased Safe Operating Area (RBSOA)

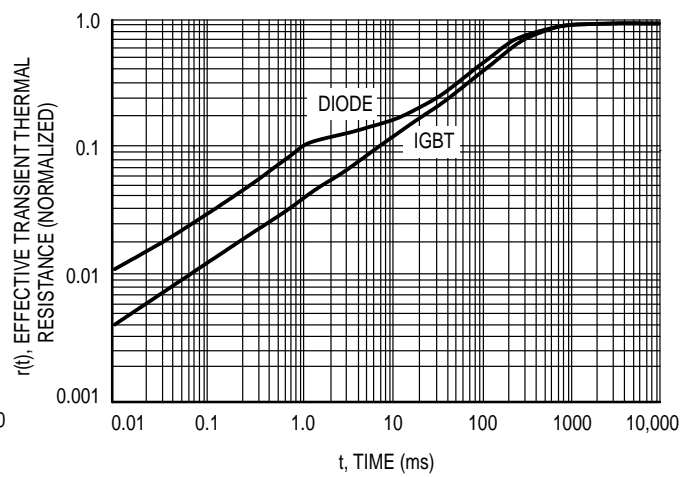


Figure 14. Thermal Response

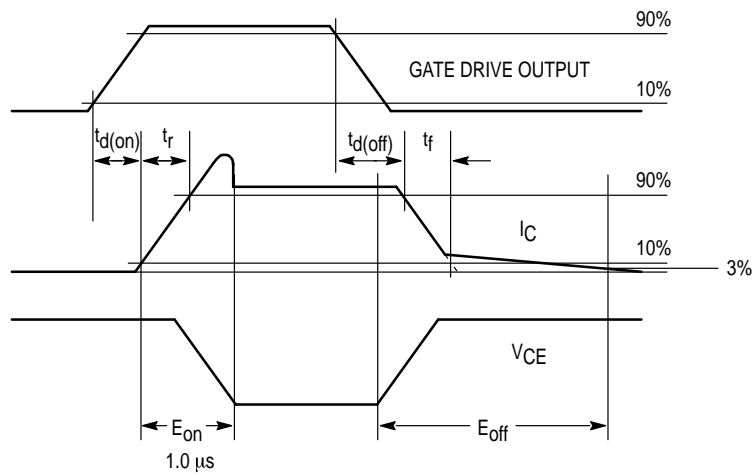


Figure 15. Timing Definitions

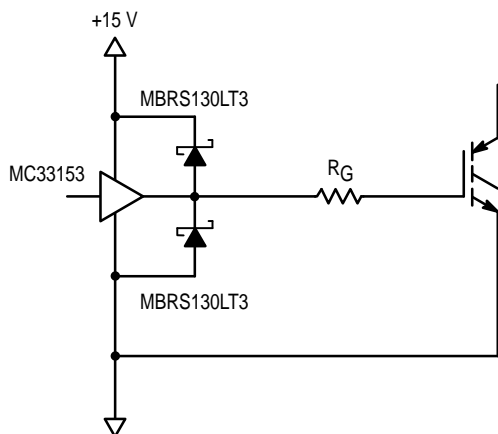


Figure 16. Common Gate Drive Circuit

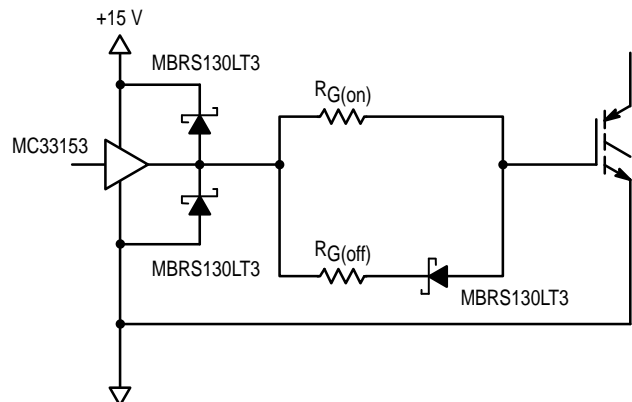


Figure 17. Recommended Gate Drive Circuit

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APPLICATION INFORMATION

These modules are designed to be used as the power stage of a three-phase AC induction motor drive. They may be used for up to 460 VAC applications. Switching frequencies up to 15 kHz were considered in the design.

Gate resistance recommendations have been listed. These choices were based on the common gate drive circuit shown in Figure 16. However, significant improvements in E_{off} may be gained by either of two methods: use of a negative gate bias, or use of the gate drive shown in Figure 17. Separate turn-on and turn-off gate resistors give the best results; in this case, $R_{G(off)}$ should be chosen as small as possible while limiting current to prevent damage to the gate drive IC. Designers should also note that turn-on and turn-off delay times are measured from the rising and falling edges of the gate drive output, not the gate voltage waveform.

Since all three modules use similar technology, most of the graphs showing typical performance have been normalized. Actual values are listed for each size in the table, "Electrical Characteristics." Data on the graphs reflect performance using the common gate drive circuit shown in Figure 16.

The first three curves, showing DC characteristics, are normalized for I_{Cmax} . The devices all perform similarly at rated current. The curves extend to $I_{C(pk)}$, the maximum allowable instantaneous current.

The next two graphs, turn-off and turn-on times versus I_C , are also normalized for I_{Cmax} . In addition, the time scales are normalized. Turn-off times are normalized to $t_{d(off)}$ at 25°C at rated current with recommended R_G , while turn-on times are normalized to t_r at 25°C at rated current with recommended R_G .

The graphs showing switching times as a function of R_G are similarly normalized. R_G has been normalized to the rec-

ommended value listed under "Electrical Characteristics." The time axes are normalized exactly as for the corresponding graphs showing variation with I_C .

Similar transformations have been made for the next two figures, showing E_{on} and E_{off} . Energies have been normalized to E_{off} at 25°C at I_{Cmax} with the recommended R_G . I_C has been normalized to I_{Cmax} , and R_G has been normalized to the recommended value.

Reverse recovery characteristics are also normalized. I_C has again been normalized to I_{Cmax} . Reverse recovery time t_{rr} has been normalized to t_{rr} at 25°C at I_{Cmax} . Peak reverse recovery current I_{rrm} has been normalized to I_{rrm} at 25°C at I_{Cmax} , then multiplied by 10.

Capacitance has been normalized to device rated I_{Cmax} . Since all modules are rated for the same voltage, the voltage scale on Figure 11 does not need to be normalized.

Typical transient thermal impedance is shown for a diode and for an IGBT. All diodes behave quite similarly, as do all IGBTs.

The last two graphs, V_{GE} versus Q_G and $RBSOA$, are not normalized.

Many issues beyond the ratings must be considered in a system design. Dynamic characteristics can all be affected by external circuit parameters. For example, excessive bus inductance can dramatically increase voltage overshoot during switching, increasing the switching energy. The choice of gate drive IC can have quite a large effect on rise and fall times, corresponding to differences in switching energies. In many cases, this can be compensated by simply changing the gate resistor accordingly — a gate driver with a lower drive capability requires a smaller gate resistor. Ultimately, the module must be tested in the final system to characterize its performance.

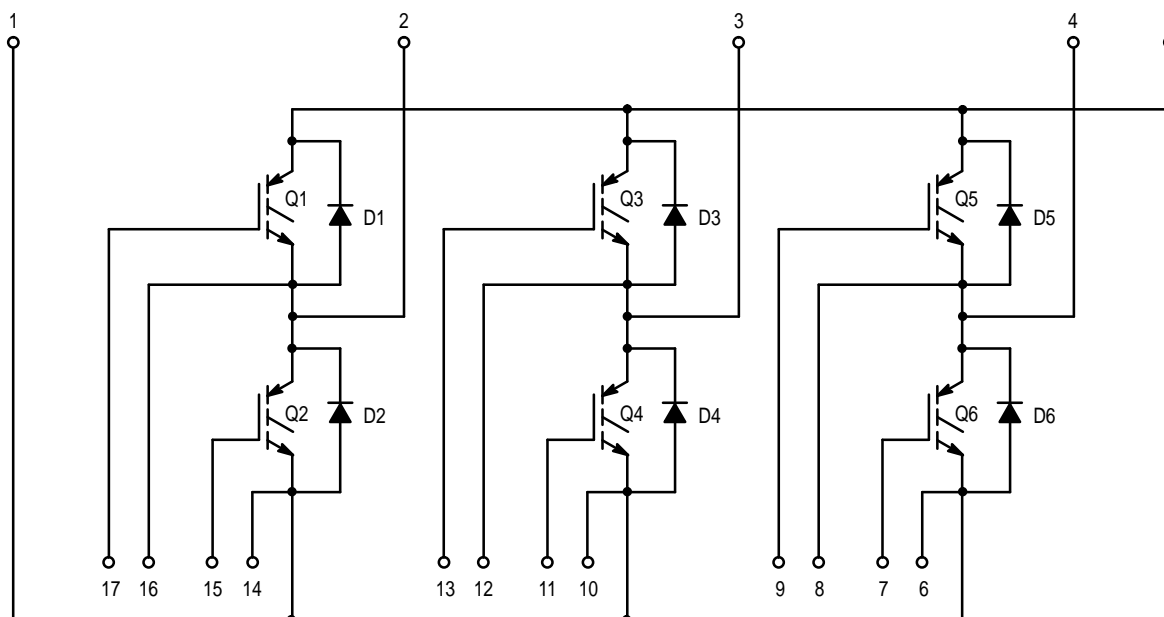


Figure 18. Schematic of Module, Showing Pin-Out

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RECOMMENDED PCB LAYOUT MODULE SIDE VIEW OF BOARD (Typical Dimensions in mm)

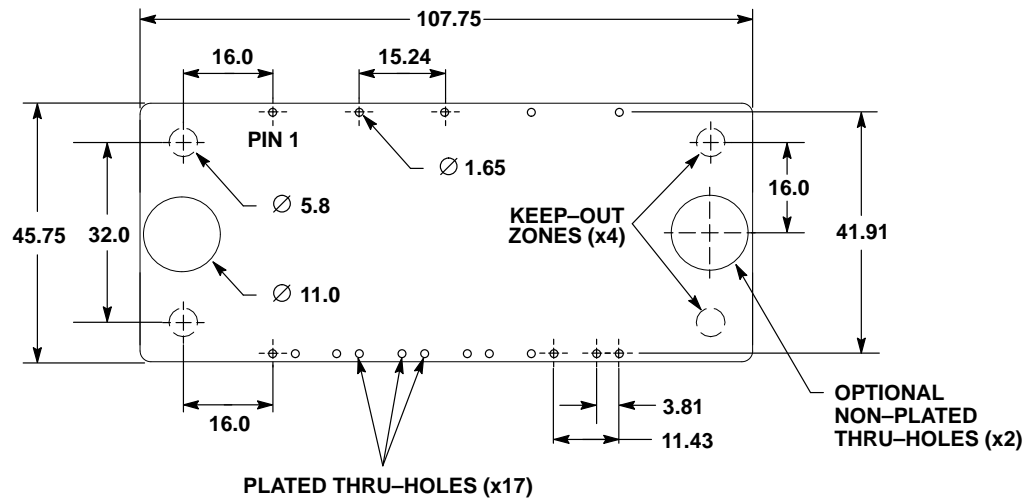
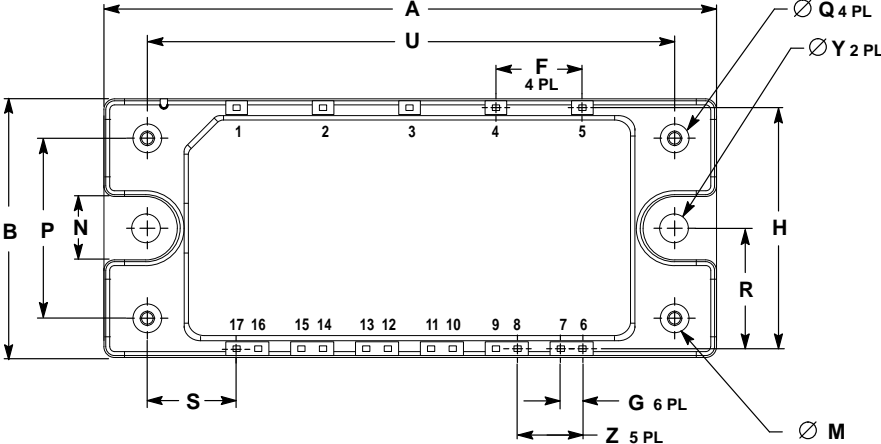


Figure 19. Package Footprint

NOTES:

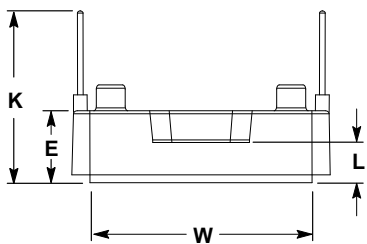
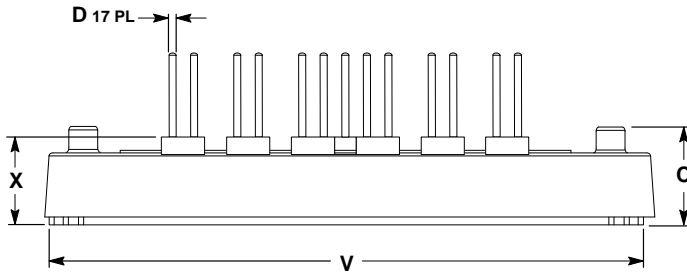
1. Package is symmetrical.
2. Dimension of plated thru-holes indicates finished hole size after plating.
3. Non-plated thru-holes shown for optional access to heat sink mounting screws.

MHPM6B10N120 MHPM6B15N120 MHPM6B25N120 SERIES
PACKAGE DIMENSIONS



- NOTES:
1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
2. CONTROLLING DIMENSION: MILLIMETER.
3. LEAD LOCATION DIMENSIONS (ie: G, S, R, H, F,...) ARE TO THE CENTER OF THE LEAD.

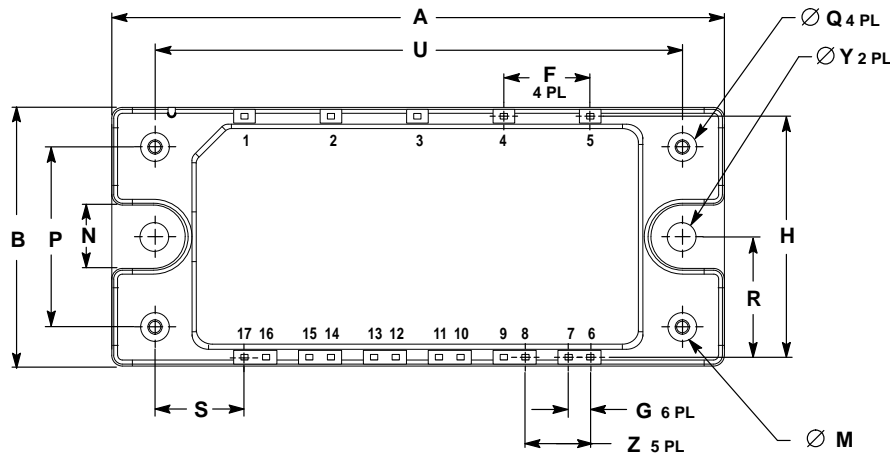
DIM	MILLIMETERS		INCHES	
	MIN	MAX	MIN	MAX
A	—	107.75	—	4.242
B	—	45.75	—	1.801
C	16.37	17.64	0.644	0.694
D	0.77	1.53	0.030	0.060
E	12.49	13.51	0.492	0.532
F	14.86	15.62	0.585	0.615
G	3.43	4.19	0.135	0.165
H	41.53	42.29	1.635	1.665
K	29.99	31.01	1.181	1.221
L	6.29	7.31	0.248	0.288
M	1.59	2.61	0.063	0.103
N	10.49	11.51	0.413	0.453
P	31.49	32.51	1.240	1.280
Q	2.00	2.60	0.079	0.103
R	20.57	21.33	0.810	0.840
S	15.62	16.38	0.615	0.645
U	92.49	93.51	3.641	3.681
V	104.17	105.44	4.101	4.151
W	37.49	38.51	1.476	1.516
X	15.37	16.64	0.605	0.655
Y	5.25	5.75	0.207	0.227
Z	11.05	11.81	0.435	0.465



CASE 464A-01
ISSUE A

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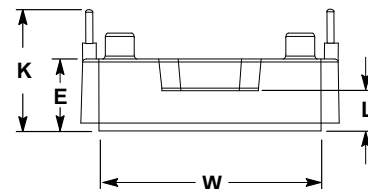
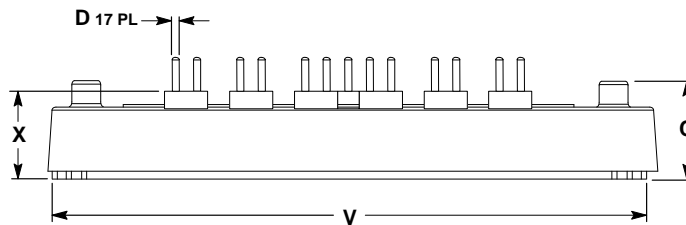
PACKAGE DIMENSIONS




NOTES:

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DIM	MILLIMETERS		INCHES	
	MIN	MAX	MIN	MAX
A	—	107.75	—	4.242
B	—	45.75	—	1.801
C	16.37	17.64	0.644	0.694
D	0.77	1.53	0.030	0.060
E	12.49	13.51	0.492	0.532
F	14.86	15.62	0.585	0.615
G	3.43	4.19	0.135	0.165
H	41.53	42.29	1.635	1.665
K	19.81	20.60	0.780	0.881
L	6.29	7.31	0.248	0.288
M	1.59	2.61	0.063	0.103
N	10.49	11.51	0.413	0.453
P	31.49	32.51	1.240	1.280
Q	2.00	2.60	0.079	0.103
R	20.57	21.33	0.810	0.840
S	15.62	16.38	0.615	0.645
U	92.49	93.51	3.641	3.681
V	104.17	105.44	4.101	4.151
W	37.49	38.51	1.476	1.516
X	15.37	16.64	0.605	0.655
Y	5.25	5.75	0.207	0.227
Z	11.05	11.81	0.435	0.465



CASE 464B-02
ISSUE A

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