

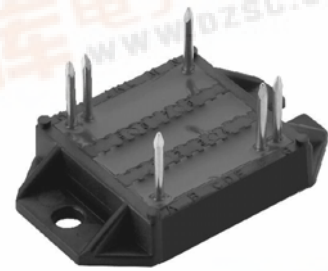
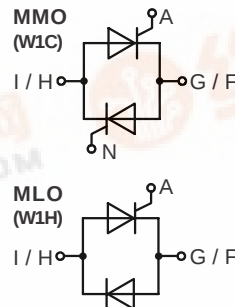
AC Controller Modules

$$I_{RMS} = 112 \text{ A}$$

$$V_{RRM} = 800-1400 \text{ V}$$

Preliminary Data

V_{RSM} V_{DSM} V	V_{RRM} V_{DRM} V	Type	
800	800	MMO 110-08io7	MLO 110-08io7
1200	1200	MMO 110-12io7	MLO 110-12io7
1400	1400	MMO 110-14io7	MLO 110-14io7



Symbol	Conditions		Maximum Ratings	
I_{RMS}	$T_C = 85^\circ\text{C}$, 50 - 400 Hz, module		112	A
I_{TRMS}	$T_C = 85^\circ\text{C}$; (180° sine)		81	A
I_{TAVM}			51	A
I_{TSM}	$T_{VJ} = 45^\circ\text{C}$	$t = 10 \text{ ms}$ (50 Hz), sine	1000	A
	$V_R = 0$	$t = 8.3 \text{ ms}$ (60 Hz), sine	1070	A
	$T_{VJ} = 125^\circ\text{C}$	$t = 10 \text{ ms}$ (50 Hz), sine	870	A
	$V_R = 0$	$t = 8.3 \text{ ms}$ (60 Hz), sine	930	A
I^2t	$T_{VJ} = 45^\circ\text{C}$	$t = 10 \text{ ms}$ (50 Hz), sine	5000	A ² s
	$V_R = 0$	$t = 8.3 \text{ ms}$ (60 Hz), sine	4810	A ² s
	$T_{VJ} = 125^\circ\text{C}$	$t = 10 \text{ ms}$ (50 Hz), sine	3780	A ² s
	$V_R = 0$	$t = 8.3 \text{ ms}$ (60 Hz), sine	3630	A ² s
$(di/dt)_{cr}$	$T_{VJ} = 125^\circ\text{C}$ $f = 50 \text{ Hz}$, $t_p = 200 \mu\text{s}$	repetitive, $I_T = 50 \text{ A}$	100	A/ μs
	$V_D = \frac{2}{3} V_{DRM}$ $I_G = 0.45 \text{ A}$ $di_G/dt = 0.45 \text{ A}/\mu\text{s}$	non repetitive, $I_T = I_{TAVM}$	500	A/ μs
$(dv/dt)_{cr}$	$T_{VJ} = 125^\circ\text{C}$; $V_{DR} = \frac{2}{3} V_{DRM}$ $R_{GK} = \infty$; method 1 (linear voltage rise)		1000	V/ μs
P_{GM}	$T_{VJ} = 125^\circ\text{C}$	$t_p = 30 \mu\text{s}$	10	W
	$I_T = I_{TAVM}$	$t_p = 300 \mu\text{s}$	5	W
P_{GAVM}			0.5	W
V_{RGM}			10	V
T_{VJ}			-40...+150	°C
T_{VJM}			150	°C
T_{stg}			-40...+125	°C
V_{ISOL}	50/60 Hz, RMS	$t = 1 \text{ min}$	2500	V~
	$I_{ISOL} \leq 1 \text{ mA}$	$t = 1 \text{ s}$	3000	V~
M_d	Mounting torque (M4)		1.5...2.0/14...18 Nm/lb.in.	
Weight	typ.		18	g

Features

- Thyristor controller for AC (circuit W1C acc. to IEC) for mains frequency
- Isolation voltage 3000 V~
- Planar glass passivated chips
- Low forward voltage drop
- Lead suitable for PC board solering

Applications

- Switching and control of single and three phase AC circuits
- Light and temperature control
- Softstart AC motor controller
- Solid state switches

Advantages

- Easy to mount with two screws
- Space and weight savings
- Improved temperature and power cycling
- High power density
- Small and light weight

Symbol	Conditions	Characteristic Values
I_D, I_R	$T_{VJ} = 125^\circ\text{C}; V_R = V_{RRM}; V_D = V_{DRM}$	≤ 5 mA
V_T	$I_T = 150$ A; $T_{VJ} = 25^\circ\text{C}$	≤ 1.57 V
V_{T0}	For power-loss calculations only	0.85 V
r_T		5.6 m Ω
V_{GT}	$V_D = 6$ V $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = -40^\circ\text{C}$	≤ 1.5 V ≤ 1.9 V
I_{GT}	$V_D = 6$ V $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = -40^\circ\text{C}$	≤ 100 mA ≤ 200 mA
V_{GD}	$T_{VJ} = 125^\circ\text{C}; V_D = \frac{2}{3} V_{DRM}$	≤ 0.2 V
I_{GD}		≤ 1 mA
I_L	$T_{VJ} = 25^\circ\text{C}; t_p = 10$ μs $I_G = 0.45$ A; $di_G/dt = 0.45$ A/ μs	≤ 200 mA
I_H	$T_{VJ} = 25^\circ\text{C}; V_D = 6$ V; $R_{GK} = \infty$	≤ 100 mA
t_{gd}	$T_{VJ} = 25^\circ\text{C}; V_D = \frac{1}{2} V_{DRM}$ $I_G = 0.45$ A; $di_G/dt = 0.45$ A/ μs	≤ 2 μs
R_{thJC}	per thyristor; DC per module	0.8 K/W 0.4 K/W
R_{thCH}	per thyristor; sine 180° el per module	typ. 0.12 K/W typ. 0.06 K/W
d_s	Creeping distance on surface	11.2 mm
d_A	Creepage distance in air	17.0 mm
a	Max. allowable acceleration	50 m/s ²

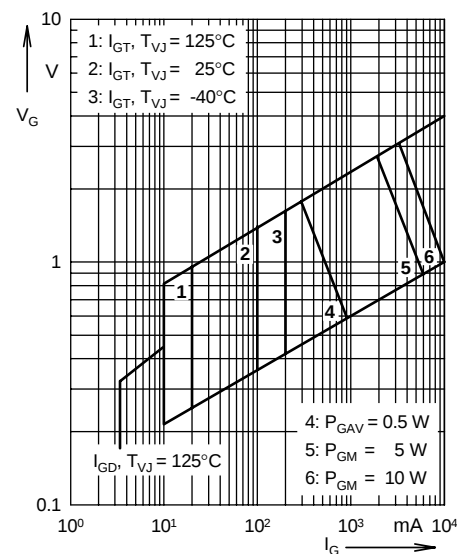


Fig. 1 Gate trigger characteristics

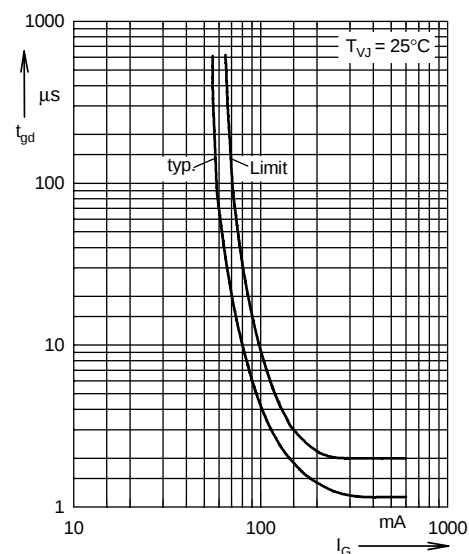


Fig. 2 Gate trigger delay time

Dimensions in mm (1 mm = 0.0394")

