## Dual 14 BIT， 65 MSPS $^{\text {TM }}$ <br> Analog－to－Digital Converter

## FEATURES

－Dual ADC
－ 14 Bit Resolution
－ 65 MSPS Sample Rate
－High SNR $=74 \mathrm{dBFs}$ at $70 \mathrm{MHz} \mathrm{f}_{\mathrm{IN}}$
－High SFDR $=84 \mathrm{dBc}$ at $70 \mathrm{MHz} \mathrm{f}_{\mathrm{IN}}$
－2．3 VPP Differential Input Voltage
－Internal／External Voltage Reference
－3．3 V Single－Supply Voltage

## DESCRIPTION

The ADS5553 is a high－performance，dual channel， 14 bit， 65 MSPS analog－to－digital converter（ADC）．To provide a complete solution，each channel includes a high－bandwidth linear sample－and－hold stage（S\＆H）and an internal reference．Designed for applications demanding high dynamic performance in a small space，the ADS5553 has excellent power consumption of 0.9 W at 3.3 V single－supply voltage．This allows an even higher system integration density．The provided internal reference simplifies system design requirements，yet an external reference can be used optionally to suit the accuracy and low drift requirements of the application．The outputs are parallel CMOS compatible．
The ADS5553 is available in a 80 lead TQFP PowerPAD package and is specified over the full temperature range of $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ ．


Please be aware that an important notice concerning availability，standard warranty，and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet．

## PACKAGE/ORDERING INFORMATION ${ }^{(1)}$

| PRODUCT | PACKAGE-LEAD | PACKAGE <br> DESIGNATOR | SPECIFIED <br> TEMPERATURE <br> RANGE | PACKAGE <br> MARKING | ORDERING <br> NUMBER | TRANSPORT <br> MEDIA, QUANTITY |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ADS5553 | HTQFP-80(2) <br> PowerPAD | PFP | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | ADS5553I | ADS5553IPFP | Tray, 96 |
|  | ADS5553IPFPR | Tape and Reel, 1000 |  |  |  |  |

(1) For the most current product and ordering information, see the Package Option Addendum located at the end of this data sheet.
(2) Thermal pad size: $6.17 \mathrm{~mm} \times 6.17 \mathrm{~mm}(\mathrm{~min}), 7,5 \mathrm{~mm} \times 7,5 \mathrm{~mm}(\mathrm{max}) . \theta_{\mathrm{ja}}=21^{\circ} \mathrm{C} / \mathrm{W}$ (no airflow) or $15^{\circ} \mathrm{C} / \mathrm{W}$ (with 200 LPFM airflow), $\theta_{\mathrm{jc}}=13.5^{\circ} \mathrm{C} / \mathrm{W}$, and $\theta_{\mathrm{jp}}$ (to the bottom PowerPad) $=2^{\circ} \mathrm{C} / \mathrm{W}$ when used with 2 oz. copper trace and pad soldered directly to a JEDEC standard four layer 3 in $\times 3$ in PCB.

## ABSOLUTE MAXIMUM RATINGS

over operating free-air temperature range unless otherwise noted ${ }^{(1)}$

| Supply <br> Voltage |  |  |  |
| :--- | :---: | :---: | :---: |
|  | $\mathrm{AV}_{\mathrm{DD}}$ to $\mathrm{A}_{\mathrm{GND}}$, <br> $\mathrm{DRV}_{\mathrm{DD}}$ to $\mathrm{DR}_{\mathrm{GND}}$ | -0.3 to 3.7 | V |
|  | $\mathrm{~A}_{\mathrm{GND}}$ to $\mathrm{DR}_{\mathrm{GND}}$ | $\pm 0.1$ | V |
| Analog input to $\mathrm{A}_{\mathrm{GND}}{ }^{(2)}$ | -0.3 to 3.6 | V |  |
| Logic input to $\mathrm{DR}_{\mathrm{GND}}$ | -0.3 to $\mathrm{DRV}_{\mathrm{DD}}+0.3$ | V |  |
| Digital data output to $\mathrm{DR}_{\mathrm{GND}}$ | -0.3 to $\mathrm{DRV}_{\mathrm{DD}}+0.3$ | V |  |
| Operating temperature range | -40 to 85 | ${ }^{\circ} \mathrm{C}$ |  |
| Junction temperature | 105 | ${ }^{\circ} \mathrm{C}$ |  |
| Storage temperature range | -65 to 150 | ${ }^{\circ} \mathrm{C}$ |  |

(1) Stresses above these ratings may cause permanent damage. Exposure to absolute maximum conditions for extended periods may degrade device reliability. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those specified is not implied.
(2) For more details, see the Input Voltage Overstress section in this data sheet.


This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

## RECOMMENDED OPERATING CONDITIONS

| PARAMETER | MIN | TYP | MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: |
| Supplies |  |  |  |  |
| Analog supply voltage, $\mathrm{AV}_{\mathrm{DD}}$ | 3 | 3.3 | 3.6 | V |
| Output driver supply voltage, DRVDD | 3 | 3.3 | 3.6 | V |
| Analog Input |  |  |  |  |
| Differential input range |  | 2.3 |  | $\mathrm{V}_{\mathrm{PP}}$ |
| Input common-mode voltage, $V_{C M}{ }^{(1)}$ | 1.45 | 1.55 | 1.65 | V |
| Digital Output |  |  |  |  |
| Maximum output load |  | 10 |  | pF |
| Clock Input |  |  |  |  |
| ADCLK input sample rate (sine wave) $1 / \mathrm{t}_{\mathrm{C}}$ | 10 |  | 65 | MSPS |
| Clock amplitude, sine wave, differential(2) |  | 3 |  | $V_{\text {PP }}$ |
| Clock duty cycle ${ }^{(3)}$ |  | 50\% |  |  |
| Open free-air temperature range | -40 |  | 85 | ${ }^{\circ} \mathrm{C}$ |

(1) Input common-mode should be connected to CM.
(2) See Figure 20 for more information.
(3) See Figure 21 for more information.

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## ELECTRICAL CHARACTERISTICS

Typ, min, and max values at $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$, full temperature range is $\mathrm{T}_{\mathrm{MIN}}=-40^{\circ} \mathrm{C}$ to $\mathrm{T}_{\mathrm{MAX}}=85^{\circ} \mathrm{C}$, sampling rate $=65 \mathrm{MSPS}, 50 \%$ clock duty cycle, $\mathrm{AV}_{\mathrm{DD}}=\mathrm{DRV} \mathrm{DD}^{2}=3.3 \mathrm{~V},-1-\mathrm{dBFS}$ differential input, $3-\mathrm{V}_{\mathrm{PP}}$ differential clock, and internal reference, unless otherwise noted

(1) $100-\mu \mathrm{A}$ per input
${ }^{(2)}$ Includes error due to references. The total gain error will become smaller (see gain error in the Dynamic Linearity and Accuracy section of this table) if an external reference is used.
(3) Gain error left assuming ideal references: $\mathrm{V}_{\text {REFP }}-\mathrm{V}_{\text {REFM }}=1.15 \mathrm{~V}$

## ELECTRICAL CHARACTERISTICS

Typ, min, and max values at $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$, full temperature range is $\mathrm{T}_{\text {MIN }}=-40^{\circ} \mathrm{C}$ to $\mathrm{T}_{\text {MAX }}=85^{\circ} \mathrm{C}$, sampling rate $=65 \mathrm{MSPS}, 50 \%$ clock duty cycle, $\mathrm{AV}_{\mathrm{DD}}=\mathrm{DRV}_{\mathrm{DD}}=3.3 \mathrm{~V},-1-\mathrm{dBFS}$ differential input, $3-\mathrm{V}_{\mathrm{PP}}$ differential clock, and internal reference, unless otherwise noted

| PARAMETER | CONDITIONS |  | MIN | TYP | MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Second-harmonic, HD2 | $\mathrm{f}_{\mathrm{IN}}=10 \mathrm{MHz}$ |  |  | 93 |  | dBc |
|  | $\mathrm{f}_{\mathrm{IN}}=46 \mathrm{MHz}$ |  |  | 93 |  |  |
|  | $\mathrm{f}_{\mathrm{IN}}=70 \mathrm{MHz}$ | Room temp | 80 | 86 |  |  |
|  |  | Full temp range | 78 | 85 |  |  |
|  | $\mathrm{f}_{\mathrm{IN}}=100 \mathrm{MHz}$ |  |  | 86 |  |  |
|  | $\mathrm{f}_{\mathrm{IN}}=150 \mathrm{MHz}$ |  |  | 82 |  |  |
|  | $\mathrm{f}_{\mathrm{IN}}=225 \mathrm{MHz}$ |  |  | 79 |  |  |
| Third-harmonic, HD3 | $\mathrm{f}_{\mathrm{IN}}=10 \mathrm{MHz}$ |  |  | 85 |  | dBc |
|  | $\mathrm{f}_{\mathrm{IN}}=46 \mathrm{MHz}$ |  |  | 84 |  |  |
|  | $\mathrm{f}_{\mathrm{IN}}=70 \mathrm{MHz}$ | Room temp | 80 | 84 |  |  |
|  |  | Full temp range | 78 | 83 |  |  |
|  | $\mathrm{f}_{\mathrm{IN}}=100 \mathrm{MHz}$ |  |  | 83 |  |  |
|  | $\mathrm{fiN}^{\mathrm{IN}}=150 \mathrm{MHz}$ |  |  | 81 |  |  |
|  | $\mathrm{fiN}^{\text {I }}$ = 225 MHz |  |  | 75 |  |  |
| Worst-harmonic/spur (other than HD2 and HD3) | $\mathrm{f}_{\mathrm{IN}}=10 \mathrm{MHz}$ | Room temp |  | 86 |  | dBc |
|  | $\mathrm{fiN}_{\mathrm{IN}}=70 \mathrm{MHz}$ | Room temp |  | 85 |  |  |
| Signal-to-noise + distortion, SINAD | $\mathrm{f}_{\mathrm{IN}}=10 \mathrm{MHz}$ |  |  | 74 |  | dBFS |
|  | $\mathrm{fin}^{\mathrm{N}}=46 \mathrm{MHz}$ |  |  | 73.5 |  |  |
|  | $\mathrm{f}_{\mathrm{IN}}=70 \mathrm{MHz}$ | $25^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | 71.8 | 73.4 |  |  |
|  |  | Full temp range | 71 | 73 |  |  |
|  | $\mathrm{f}_{\mathrm{IN}}=100 \mathrm{MHz}$ |  |  | 73 |  |  |
|  | $\mathrm{fin}_{\mathrm{IN}}=150 \mathrm{MHz}$ |  |  | 71.8 |  |  |
|  | $\mathrm{f}_{\mathrm{IN}}=225 \mathrm{MHz}$ |  |  | 69.5 |  |  |
| Total harmonic distortion, THD | $\mathrm{f}_{\mathrm{IN}}=10 \mathrm{MHz}$ |  |  | 83 |  | dBc |
|  | $\mathrm{f}_{\mathrm{IN}}=46 \mathrm{MHz}$ |  |  | 82 |  |  |
|  | $\mathrm{f}_{\mathrm{IN}}=70 \mathrm{MHz}$ | Room temp |  | 82 |  |  |
|  |  | Full temp range |  | 82 |  |  |
|  | $\mathrm{f}_{\mathrm{IN}}=100 \mathrm{MHz}$ |  |  | 81 |  |  |
|  | $\mathrm{f}_{\mathrm{IN}}=150 \mathrm{MHz}$ |  |  | 81 |  |  |
|  | $\mathrm{f}_{\mathrm{IN}}=225 \mathrm{MHz}$ |  |  | 74 |  |  |
| Effective number of bits, ENOB | $\mathrm{f}_{\mathrm{IN}}=70 \mathrm{MHz}$ |  |  | 11.9 |  | Bits |
| Two-tone intermodulation distortion, IMD3 | $\begin{aligned} & \mathrm{f}=10.1 \mathrm{MHz}, 15.1 \mathrm{MHz} \\ & (-7 \mathrm{dBFS} \text { each tone) } \end{aligned}$ |  |  | 94 |  | dBc |
|  | $\mathrm{f}=48 \mathrm{MHz}, 53 \mathrm{MHz}$(-7 dBFS each tone) |  |  | 84 |  |  |
|  | $\begin{aligned} & \text { f = } 147 \mathrm{MHz}, 152 \mathrm{MHz} \\ & (-7 \mathrm{dBFS} \text { each tone) } \end{aligned}$ |  |  | 75 |  |  |
| Crosstalk | $\mathrm{f}_{\mathrm{IN}}=70 \mathrm{MHz}^{(4)}$ |  |  | -100 | -95 | dBc |

${ }^{(4)}$ Inject one tone at -1 dBFS on one channel and measure the ampltitude on the other channel, then repeat for the other channel

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## ELECTRICAL CHARACTERISTICS

Typ, min, and max values at $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$, full temperature range is $\mathrm{T}_{\mathrm{MIN}}=-40^{\circ} \mathrm{C}$ to $\mathrm{T}_{\mathrm{MAX}}=85^{\circ} \mathrm{C}$, sampling rate $=65 \mathrm{MSPS}, 50 \%$ clock duty cycle, $\mathrm{AV}_{\mathrm{DD}}=\mathrm{DRV} \mathrm{DD}^{2}=3.3 \mathrm{~V},-1-\mathrm{dBFS}$ differential input, $3-\mathrm{V}_{\mathrm{PP}}$ differential clock, and internal reference, unless otherwise noted

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Power Supply |  |  |  |  |  |
| Total supply current, ICC | $\mathrm{V}_{\text {IN }}=$ full-scale, $\mathrm{f}_{\text {IN }}=70 \mathrm{MHz}$ |  | 270 | 288 | mA |
| Analog supply current, ${ }_{\text {IAVDD }}$ | $\mathrm{V}_{\text {IN }}=$ full-scale, $\mathrm{f}_{\text {IN }}=70 \mathrm{MHz}$ |  | 220 | 230 | mA |
| Output buffer supply current, I I ${ }_{\text {dRVDD }}$ | $\mathrm{V}_{\mathrm{IN}}=$ full-scale, $\mathrm{f}_{\mathrm{IN}}=70 \mathrm{MHz}$, with 10 pF load on digital outputs to ground |  | 50 | 58 | mA |
| Power dissipation | Analog only, $\mathrm{f}_{\mathrm{I}}=70 \mathrm{MHz}$ |  | 725 | 760 | mW |
|  | Digital power with $10-\mathrm{pF}$ load on digital outputs to ground, $\mathrm{f}_{\mathrm{N}}=70 \mathrm{MHz}$ |  | 165 | 190 |  |
| Power dissipation with external reference | Total power with $10-\mathrm{pF}$ load on digital outputs to ground, $\mathrm{f}_{\mathrm{I}}=70 \mathrm{MHz}$ |  | 780 | 820 | mW |
| Standby power | With clocks running (both channels off and outputs disabled) |  | 220 | 250 | mW |

## DIGITAL CHARACTERISTICS

Typ, min, and max values at $T_{A}=25^{\circ} \mathrm{C}$, full temperature range is $\mathrm{T}_{\mathrm{MIN}}=-40^{\circ} \mathrm{C}$ to $\mathrm{T}_{\mathrm{MAX}}=85^{\circ} \mathrm{C}$, and $A V_{D D}=D R V_{D D}=3.3 \mathrm{~V}$, unless otherwise noted

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Digital Inputs |  |  |  |  |  |
| High-level input voltage |  | 2.4 |  |  | V |
| Low-level input voltage |  |  |  | 0.8 | V |
| High-level input current |  |  |  | 10 | $\mu \mathrm{A}$ |
| Low-level input current |  |  |  | 10 | $\mu \mathrm{A}$ |
| Input capacitance |  |  | 4 |  | pF |
| Digital Outputs ${ }^{(1)}$ |  |  |  |  |  |
| Low-level output voltage | $\mathrm{C}_{\text {LOAD }}=10 \mathrm{pF}^{(2)}$ |  | 0.3 | 0.4 | V |
| High-level output voltage | $\mathrm{C}_{\text {LOAD }}=10 \mathrm{pF}^{(2)}$ | 2.8 | 3 |  | V |
| Output capacitance |  |  | 3 |  | pF |

${ }^{(1)}$ For optimal performance, all digital output lines (D0:D13), including the output clock, should see a similar load.
${ }^{(2)}$ Equivalent capacitance to ground of (load + parasitics of transmission lines).

## SLWS158 - FEBRUARY 2005

TIMING CHARACTERISTICS


NOTE: It is recommended that the loading at CLKOUT and all data lines are accurately matched to ensure that the above timing matches closely with the specified values.

Figure 1. Timing Diagram

## TIMING CHARACTERISTICS ${ }^{(3)}$

Over full temperature range ( $\mathrm{T}_{\mathrm{MIN}}=-40^{\circ} \mathrm{C}$ to $\mathrm{T}_{\mathrm{MAX}}=+85^{\circ} \mathrm{C}$ ), sampling rate $=65 \mathrm{MSPS}, 50 \%$ clock duty cycle, and $A V_{D D}=D R V_{D D}=3.3 \mathrm{~V}$, unless otherwise noted

| PARAMETER | DESCRIPTION | MIN | TYP | MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Switching Specification |  |  |  |  |  |
| Aperture delay, $\mathrm{t}_{\mathrm{A}}$ | Input CLK falling edge to data sampling point |  | 1 |  | ns |
| Aperture delay matching, $\mathrm{t}_{\mathrm{A}}$ | Channel-to-channel aperture delay matching |  | 50 |  | ps |
| Aperture jitter (uncertainty) | Uncertainty in sampling instant |  | 300 |  | fs |
| Latency |  |  | 16.5 |  | Clock Cyles |
| Data setup time, $\mathrm{t}_{\text {su }}$ | Data valid ${ }^{(1)}$ to $50 \%$ of CLKOUT rising edge | 4.3 | 6 |  | ns |
| Data hold time, th | $50 \%$ of CLKOUT rising edge to data becoming invalid ${ }^{(1)}$ | 2 | 2.8 |  | ns |
| Data start time, tstart | $50 \%$ of clock input to beginning of valid data ${ }^{(1)}$ |  | 2.5 | 4.5 | ns |
| Data stop time, $\mathrm{t}_{\text {END }}$ | $50 \%$ of clock input to end of valid data ${ }^{(1)}$ | 9 | 10.6 |  | ns |
| Data rise time, $\mathrm{t}_{\mathrm{r}}$ | Data rise time measured from $20 \%$ to $80 \%$ of DRV $_{\text {DD }}$ |  | 6.6 |  | ns |
| Data fall time, $\mathrm{t}_{\mathrm{f}}$ | Data fall time measured from $80 \%$ to $20 \%$ of $\mathrm{DRV}_{\text {DD }}$ |  | 5.5 |  | ns |
| Data setup time, $\mathrm{t}_{\text {su }}$ | Data valid ${ }^{(1)}$ to $50 \%$ of CLKOUT rising edge, $\mathrm{f}_{\mathrm{S}}=40 \mathrm{MSPS}$ | 8.5 | 11 |  | ns |
| Data hold time, $\mathrm{th}_{\mathrm{h}}$ | $50 \%$ of CLKOUT rising edge to data becoming invalid ${ }^{(1)}$, $\mathrm{f}_{\mathrm{S}}=40 \mathrm{MSPS}$ | 2.6 | 4 |  | ns |
| Data start time, ${ }_{\text {tstart }}$ | $50 \%$ of clock input to beginning of valid data ${ }^{(1)}, \mathrm{F}_{S}=40 \mathrm{MSPS}$ |  | -2.5 | 1 | ns |
| Data stop time, tend | $50 \%$ of clock input to end of valid data ${ }^{(1)}$, $\mathrm{F}_{S}=40 \mathrm{MSPS}$ | 11.5 | 13 |  | ns |
| Data rise time, $\mathrm{tr}_{r}$ | Data rise time measured from $20 \%$ to $80 \%$ of $\mathrm{DRV}_{\mathrm{DD}}$, $\mathrm{f}_{\mathrm{S}}=40 \mathrm{MSPS}$ |  | 7.5 |  | ns |
| Data fall time, $\mathrm{t}_{\mathrm{f}}$ | Data fall time measured from $80 \%$ to $20 \%$ of $\mathrm{DRV}_{\mathrm{DD}}$, $\mathrm{f}_{\mathrm{S}}=40 \mathrm{MSPS}$ |  | 7.3 |  | ns |
| Output enable (OE) to data output delay | Time required for outputs to have stable timings with respect to the input clock ${ }^{(2)}$ after OE is activated |  |  | 1000 | Clock Cycles |

${ }^{(1)}$ Data valid refers to 2 V for logic high and 0.8 V for logic low.
${ }^{(2)}$ : Data outputs are available within a clock from assertion of OE; however it takes 1000 clock cycles to ensure stable timing with respect to input clock.
${ }^{(3)}$ : Timing parameters are ensured by design and characterization and not tested in production.

PIN CONFIGURATION


SLWS158 - FEBRUARY 2005

## PIN ASSIGNMENTS

| TERMINAL <br> NAME | NO. | NO. OF PINS | I/O | DESCRIPTION |
| :---: | :---: | :---: | :---: | :---: |
| $\mathrm{AV}_{\text {DD }}$ | $\begin{gathered} 8,9,11 \\ 13,21,26, \\ 27,73,75 \\ 80 \end{gathered}$ | 10 | I | Analog power supply |
| $A_{G N D}$ | $\begin{gathered} 2,5,12, \\ 16,19,22, \\ 25,74,76, \\ 79 \end{gathered}$ | 10 | I | Analog ground |
| CLKMA | 4 | 1 | I | Channel A differential input clock (negative) |
| CLKMB | 18 | 1 | 1 | Channel B differential input clock (negative) |
| CLKOUTA | 53 | 1 | 0 | Channel A clock out in sync with data |
| CLKOUTB |  | 1 | 0 | Channel B clock out in sync with data |
| CLKPA | 3 | 1 | 1 | Channel A differential input clock (positive) |
| CLKPB | 17 | 1 | 1 | Channel B differential input clock (positive) |
| CMA | 1 | 1 | 0 | Channel A common-mode output voltage |
| CMB | 20 | 1 | 0 | Channel B common-mode output voltage |
| D0A (LSB)-D13A (MSB) | $\begin{aligned} & 54-56 \\ & 59-64, \\ & 67-71 \end{aligned}$ | 14 | O | Channel A parallel data |
| D0B (LSB)-D13B (MSB) | $\begin{aligned} & 28-32 \\ & 35-40 \\ & 43-45 \end{aligned}$ | 14 | 0 | Channel B parallel data |
| DRV ${ }_{\text {DD }}$ | $\begin{gathered} 34,42, \\ 49,57,65 \end{gathered}$ | 4 | I | Output driver power supply |
| $\mathrm{DR}_{\mathrm{GND}}$ | $\begin{aligned} & 33,41, \\ & 58,66 \end{aligned}$ | 4 | I | Output driver ground |
| INMA | 77 | 1 | I | Channel A differential analog input (negative) |
| INMB | 23 | 1 | I | Channel B differential analog input (negative) |
| INPA | 78 | 1 | I | Channel A differential analog input (positive) |
| INPB | 24 | 1 | I | Channel B differential analog input (positive) |
| IREF | 10 | 1 | I | Current set, $56-\mathrm{k} \Omega$ resistor to GND |
| OEA | 52 | 1 | I | Channel A output enable (active high) |
| OEB | 48 | 1 | 1 | Channel B output enable (active high) |
| OVRA | 72 | 1 | 0 | Channel A over-range indicator bit |
| OVRB | 46 | 1 | O | Channel B over-range indicator bit |
| REFMA | 6 | 1 | 1 | Channel A reference voltage (negative); $0.1 \mu \mathrm{~F}$ to GND |
| REFMB | 14 | 1 | I | Channel B reference voltage (negative); $0.1 \mu \mathrm{~F}$ to GND |
| REFPA | 7 | 1 | 1 | Channel A reference voltage (positive); $0.1 \mu \mathrm{~F}$ to GND |
| REFPB | 15 | 1 | 1 | Channel B reference voltage (positive); $0.1 \mu \mathrm{~F}$ to GND |
| PDN | 50 | 1 | I | Power down active high. See Table 2 |
| REFSEL | 51 | 1 | I | Reference select. $1 \rightarrow$ EXT. REF; $0 \rightarrow$ INT. REF |

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## DEFINITION OF SPECIFICATIONS

## Analog Bandwidth

The analog input frequency at which the power of the fundamental is reduced by 3 dB with respect to the low frequency value.

## Aperture Delay

The delay between the falling edge of the input sampling clock and the actual time at which the sampling occurs.

## Aperture Uncertainty (Jitter)

The sample-to-sample variation in aperture delay.

## Clock Pulse Width/Duty Cycle

The duty cycle of a clock signal is the ratio of the time the clock signal remains at a logic high (clock pulse width) to the period of the clock signal. Duty cycle is typically expressed as a percentage. A perfect differential sine wave clock results in a 50\% duty cycle.

## Maximum Conversion Rate

The maximum sampling rate at which certified operation is given. All parametric testing is performed at this sampling rate unless otherwise noted.

## Minimum Conversion Rate

The minimum sampling rate at which the ADC functions.

## Differential Nonlinearity (DNL)

An ideal ADC exhibits code transitions at analog input values spaced exactly 1LSB apart. The DNL is the deviation of any single step from this ideal value, measured in units of LSBs.

## Integral Nonlinearity (INL)

The INL is the deviation of the ADC's transfer function from a best fit line determined by a least squares curve fit of that transfer function, measured in units of LSBs.

## Gain Error

The gain error is the deviation of the ADC's actual input full-scale range from its ideal value. The gain error is given as a percentage of the ideal input full-scale range. Gain error does not account for variations in the internal reference voltages (see the Electrical Specifications section for limits on the variation of $\mathrm{V}_{\text {REFP }}$ and $\mathrm{V}_{\text {REFM }}$ ).

## Offset Error

The offset error is the difference, given in number of LSBs, between the ADC's actual average idle channel output code and the ideal average idle channel output code. This quantity is often mapped into mV .

## Temperature Drift

The temperature drift coefficient (with respect to gain error and offset error) specifies the change per degree celcius of the parameter from $\mathrm{T}_{\text {MIN }}$ to $\mathrm{T}_{\text {MAX }}$. It is calcuated by dividing the maximum deviation of the parameter across the $\mathrm{T}_{\text {MIN }}$ to $\mathrm{T}_{\text {MAX }}$ range by the difference $\mathrm{T}_{\text {MAX }}-\mathrm{T}_{\text {MIN }}$.

## Signal-to-Noise Ratio

SNR is the ratio of the power of the fundamental ( $\mathrm{P}_{\mathrm{S}}$ ) to the noise floor power $\left(\mathrm{P}_{\mathrm{N}}\right)$, excluding the power at DC and the first eight harmonics.

$$
S N R=10 \log _{10} \frac{P_{S}}{P_{N}}
$$

SNR is either given in units of dBc ( dB to carrier) when the absolute power of the fundamental is used as the reference, or dBFS (dB to full scale) when the power of the fundamental is extrapolated to the converter's full-scale range.

## Signal-to-Noise and Distortion (SINAD)

SINAD is the ratio of the power of the fundamental ( $\mathrm{P}_{\mathrm{S}}$ ) to the power of all the other spectral components including noise ( $\mathrm{P}_{\mathrm{N}}$ ) and distortion ( $\mathrm{P}_{\mathrm{D}}$ ), but excluding DC.

$$
\text { SINAD }=10 \log _{10} \frac{P_{S}}{P_{N}+P_{D}}
$$

SINAD is either given in units of dBc ( dB to carrier) when the absolute power of the fundamental is used as the reference, or dBFS ( dB to full scale) when the power of the fundamental is extrapolated to the converter's full-scale range.

## Effective Number of Bits (ENOB)

The ENOB is a measure of a converter's performance as compared to the theoretical limit based on quantization noise.

$$
\mathrm{ENOB}=\frac{\text { SINAD }-1.76}{6.02}
$$

## DEFINITION OF SPECIFICATIONS

## Total Harmonic Distortion (THD)

THD is the ratio of the power of the fundamental ( Ps ) to the power of the first eight harmonics ( $\mathrm{P}_{\mathrm{D}}$ ).

$$
\mathrm{THD}=10 \log _{10} \frac{\mathrm{P}_{\mathrm{S}}}{\mathrm{P}_{\mathrm{D}}}
$$

THD is typically given in units of dBc ( dB to carrier).

## Spurious-Free Dynamic Range (SFDR)

The ratio of the power of the fundamental to the highest other spectral component (either spur or harmonic). SFDR is typically given in units of dBc ( dB to carrier).

## Two-Tone Intermodulation Distortion

IMD3 is the ratio of the power of the fundamental (at frequencies $f_{1}$ and $f_{2}$ ) to the power of the worst spectral component at either frequency $2 f_{1}-f_{2}$ or $2 f_{2}-f_{1}$. IMD3 is either given in units of dBc ( dB to carrier) when the absolute power of the fundamental is used as the reference, or dBFS ( dB to full scale) when the power of the fundamental is extrapolated to the converter's full-scale range. INSTRUMENTS
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## TYPICAL CHARACTERISTICS

Typical values are at $T_{A}=25^{\circ} \mathrm{C}, A V_{D D}=D R V_{D D}=3.3 \mathrm{~V}$, differential input amplitude $=-1 \mathrm{dBFS}$, sampling rate $=65 \mathrm{MSPS}$, unless otherwise noted


Figure 2

## SPECTRAL PERFORMANCE



Figure 4

SPECTRAL PERFORMANCE


Figure 6

SPECTRAL PERFORMANCE


Figure 3

SPECTRAL PERFORMANCE


Figure 5

SPECTRAL PERFORMANCE


Figure 7 INSTRUMENTS

## TYPICAL CHARACTERISTICS

Typical values are at $T_{A}=25^{\circ} \mathrm{C}, A V_{D D}=D R V_{D D}=3.3 \mathrm{~V}$, differential input amplitude $=-1 \mathrm{dBFS}$, sampling rate $=65 \mathrm{MSPS}$, unless otherwise noted


Figure 8


Figure 10


Figure 12

SPECTRAL PERFORMANCE


Figure 9


Figure 11


Figure 13

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## TYPICAL CHARACTERISTICS

Typical values are at $T_{A}=25^{\circ} \mathrm{C}, A V_{D D}=D R V_{D D}=3.3 \mathrm{~V}$, differential input amplitude $=-1 \mathrm{dBFS}$, sampling rate $=65 \mathrm{MSPS}$, unless otherwise noted


Figure 14
AC PERFORMANCE
vS
INPUT AMPLITUDE


Figure 16
AC PERFORMANCE
vs
INPUT AMPLITUDE


Figure 18

WCDMA CARRIER


Figure 15
AC PERFORMANCE
VS
INPUT AMPLITUDE


Figure 17
POWER DISSIPATION
VS
SAMPLING RATE


Figure 19 INSTRUMENTS www.ti.com

## TYPICAL CHARACTERISTICS

Typical values are at $T_{A}=25^{\circ} \mathrm{C}, A V_{D D}=D R V_{D D}=3.3 \mathrm{~V}$, differential input amplitude $=-1 \mathrm{dBFS}$, sampling rate $=65 \mathrm{MSPS}$, unless otherwise noted


Figure 20


Figure 22
AC PERFORMANCE
vs
ANALOG SUPPLY VOLTAGE


Figure 24

AC PERFORMANCE
DUTY CYCLE


Figure 21


Figure 23
AC PERFORMANCE
vs
DIGITAL SUPPLY VOLTAGE


Figure 25
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## ADS5553

Typical values are at $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}, A \mathrm{~V}_{\mathrm{DD}}=\mathrm{DRV}_{\mathrm{DD}}=3.3 \mathrm{~V}$, differential input amplitude $=-1 \mathrm{dBFS}$, sampling rate $=65 \mathrm{MSPS}$, unless otherwise noted


Figure 26.


Figure 27.

## APPLICATION INFORMATION

## THEORY OF OPERATION

The ADS5553 is a low-power, dual 14 bit, 65 MSPS, CMOS, switched capacitor, pipeline ADC that operates from a single 3.3 V supply. The conversion process is initiated by a falling edge of the external input clock. Once the signal is captured by the input S\&H, the input sample is sequentially converted by a series of small resolution stages, with the outputs combined in a digital correction logic block. Both the rising and the falling clock edges are used to propagate the sample through
the pipeline every half clock cycle. This process results in a data latency of 16.5 clock cycles, after which the output data is available as a 14 bit parallel word, coded in binary two's complement format.

## INPUT CONFIGURATION

The analog input for the ADS5553 consists of a differential sample-and-hold architecture implemented using a switched capacitor technique, shown in Figure 28.


All switches are on in sampling phase which is approximately one half of a clock period.
Figure 28. Analog Input Stage
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This differential input topology produces a high level of ac performance for high sampling rates. It also results in a high usable input bandwidth, especially important for high intermediate-frequency (IF) or undersampling applications. The ADS5553 requires each of the analog inputs (INP, INM) to be externally biased around the common-mode level of the internal circuitry (CM, pins 1 and 20). For a full-scale differential input, each of the differential lines of the input signal swings symmetrically between $\mathrm{CM}+0.575 \mathrm{~V}$ and $\mathrm{CM}-0.575 \mathrm{~V}$. This means that each input is driven with a signal of up to $\mathrm{CM} \pm 0.575$ V , so that each input has a maximum differential signal of 1.15 VPP for a total differential input signal swing of 2.3 $\mathrm{V}_{\mathrm{PP}}$. The maximum swing is determined by the two reference voltages, the top reference (REFPA, pin 7 and REFPB, pin 15) and the bottom reference (REFMA, pin 6 and REFMB, pin 18).
The ADS5553 obtains optimum performance when the analog inputs are driven differentially. The circuit shown in Figure 29 shows one possible configuration using an RF transformer.


Figure 29. Transformer Input to Convert Single-Ended Signal to Differential Signal

The single-ended signal is fed to the primary winding of an RF transformer. Since the input signal must be biased around the common-mode voltage of the internal circuitry, the common-mode voltage ( $\mathrm{V}_{\mathrm{CM}}$ ) from the ADS5553 is connected to the center-tap of the secondary winding. To ensure a steady low-noise $\mathrm{V}_{\mathrm{CM}}$ reference, best performance is obtained when the CM output (pins 1 and 20) is filtered to ground with a $10 \Omega$ series resistor and parallel $0.1 \mu \mathrm{~F}$ and $0.001 \mu \mathrm{~F}$ low-inductance capacitors as shown in Figure 29.
Output $\mathrm{V}_{\mathrm{CM}}$ (pins 1 and 20 ) is designed to directly drive the ADC input. When providing a custom CM level, be aware that the input structure of the ADC sinks a common-mode current in the order of $200 \mu \mathrm{~A}(100 \mu \mathrm{~A}$
per input). Equation (1) describes the dependency of the common-mode current and the sampling frequency:

$$
\begin{equation*}
20+\frac{400 \mu \mathrm{~A} \times \mathrm{f}_{\mathrm{s}}(\text { in } \mathrm{MSPS})}{125 \mathrm{MSPS}} \tag{1}
\end{equation*}
$$

This equation helps to design the output capability and impedance of the driving circuit accordingly.
When it is necessary to buffer or apply a gain to the incoming analog signal, it is possible to combine single-ended operational amplifiers with an RF transformer, or to use a differential input/output amplifier without a transformer, to drive the input of the ADS5553. Texas Instruments offers a wide selection of single-ended operational amplifiers (including the THS3201, THS3202, OPA847, and OPA695) that can be selected depending on the application. An RF gain block amplifier, such as Texas Instruments THS9001, can also be used with an RF transformer for high input frequency applications. The THS4503/6 are recommended differential input/output amplifiers. Table 1 lists the recommended amplifiers.
When using single-ended operational amplifiers (such as the THS3201, THS3202, OPA847, or OPA695) to provide gain, a three-amplifier circuit is recommended with one amplifier driving the primary of an RF transformer and one amplifier in each of the legs of the secondary driving the two differential inputs of the ADS5553. These three amplifier circuits minimize even-order harmonics. For high frequency inputs, an RF gain block amplifier can be used to drive a transformer primary; in this case, the transformer secondary connections can drive the input of the ADS5553 directly, as shown in Figure 29 or with the addition of the filter circuit shown in Figure 30.

Figure 30 illustrates how $\mathrm{R}_{\mathbb{N}}$ and $\mathrm{C}_{\mathbb{N}}$ can be placed to isolate the signal source from the switching inputs of the ADC and to implement a low-pass RC filter to limit the input noise in the ADC. It is recommended that these components be included in the ADS5553 circuit layout when any of the amplifier circuits discussed previously are used. The components allow fine-tuning of the circuit performance. Any mismatch between the differential lines of the ADS5553 input produces a degradation in performance at high input frequencies, mainly characterized by an increase in the even-order harmonics. In this case, special care should be taken to keep as much electrical symmetry as possible between both inputs.
Another possible configuration for lower-frequency signals is the use of differential input/output amplifiers that can simplify the driver circuit for applications
requiring dc coupling of the input. Flexible in their configurations (see Figure 31), such amplifiers can be used for single-ended-to-differential conversion, signal amplification.

Table 1. Recommended Amplifiers to Drive the Input of the ADS5553

| INPUT SIGNAL FREQUENCY | RECOMMENDED AMPLIFIER | TYPE OF AMPLIFIER | USE WITH TRANSFORMER? |
| :---: | :---: | :---: | :---: |
| DC to 20 MHz | THS4503/6 | Differential In/Out Amp | No |
| DC to 50 MHz | OPA847 | Operational Amp | Yes |
| 10 MHz to 120 MHz | OPA695 | Operational Amp | Yes |
|  | THS3201 | Operational Amp | Yes |
|  | THS3202 | Operational Amp | Yes |



Figure 30. Converting a Single-Ended Input Signal to a Differential Signal Using an RF Transformer


Figure 31. Using the THS4503 With the ADS5553

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## INPUT VOLTAGE OVER-STRESS

The ADS5553 can handle absolute maximum voltages of 3.6 V DC on the input pins INP and INM. For DC inputs between 3.6 V and 3.8 V , a $25 \Omega$ resistor is required in series with the input pins. For inputs above 3.8 V , the device can handle only transients, which need to have less than $5 \%$ duty cycle of overstress. The input pins connect internally to an ESD diode to $A V_{D D}$, as well as a switched capacitor circuit. The sampling capacitor of the switched capacitor circuit connects to the input pins through a switch in the sample phase. In this phase, an input larger then 2.65 V would cause the switched capacitor circuit to present an equivalent load of a forward biased diode to 2.65 V , in series with a $60 \Omega$ impedance. Also, beyond the voltage on $A V_{D D}$, the ESD diode to $A V_{D D}$ starts to become forward biased.
In the phase where the sampling switch is off, the diode loading from the input switched capacitor circuit is disconnected from the pin, while the ESD loading to $A V_{D D}$ is still present.

CAUTION:
A violation of any of the previously stated conditions could damage the device (or reduce its lifetime) either due to electromigration or gate oxide integrity. Care should be taken not to expose the device to input over-voltage for extended periods of time as it may degrade device reliability.

## POWER SUPPLY SEQUENCE

The preferred mode of power supply sequencing is to power up $A V_{D D}$ first, followed by $D R V_{D D}$. Raising both supplies simultaneously is also a valid power supply sequence. In the event that $D R V_{D D}$ powers up before $A V_{D D}$ in the system, $A V_{D D}$ must power up within 10 ms of $D R V_{D D}$.

## POWER DOWN

The device enters power down in one of two ways: either by reducing the clock speed to between dc and 1 MHz or by selecting any of the modes in Table 2. If reducing the clock speed, power-down may be initiated for any clock frequency below 10 MHz . The actual frequency at which the device powers down varies from device to device.

Table 2. Powerdown Mode Selection

| PDN <br> (Pin 50) | OEA <br> (Pin 52) | OEB <br> (Pin 48) | Out A | Out B | ADC A | ADC B |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | Off | Off | On | On |
| 0 | 0 | 1 | Off | On | On | On |
| 0 | 1 | 0 | On | Off | On | On |
| $\mathbf{0}$ | $\mathbf{1}$ | $\mathbf{1}$ | On | On | On | On |
| 1 | 0 | 0 | Off | Off | Off | Off |
| 1 | 0 | 1 | Off | On | Off | On |
| 1 | 1 | 0 | On | Off | On | Off |
| 1 | 1 | 1 | On | On | On | On |

## REFERENCE CIRCUIT

The ADS5553 has built-in internal reference generation, requiring no external circuitry on the printed circuit board (PCB). For optimum performance, it is best to connect both REFP and REFM to ground with a $1 \mu \mathrm{~F}$ decoupling capacitor in series with a $20 \Omega$ resistor, as shown in Figure 32. In addition, an external 56.2-k $\Omega$ resistor should be connected from IREF (pin 10) to AGND to set the proper current for the operation of the ADC, as shown in Figure 32. No capacitor should be connected between pin 31 and ground; only the $56.2 \mathrm{k} \Omega$ resistor should be used.


Figure 32. REFP, REFM, and IREF Connections for Optimum Performance

SLWS158 - FEBRUARY 2005

## CLOCK INPUT

The ADS5553 clock input can be driven with either a differential clock signal or a single-ended clock input, with little or no difference in performance between both configurations. The common-mode voltage of the clock inputs is set internally to CM using internal $5-\mathrm{k} \Omega$ resistors that connect CLKP and CLKM to CM , as shown in Figure 33.


Figure 33. Clock Inputs
When driven with a single-ended CMOS clock input, it is best to connect CLKM to ground with a $0.01 \mu \mathrm{~F}$ capacitor, while CLKP is ac-coupled with a $0.01 \mu \mathrm{~F}$ capacitor to the clock source, as shown in Figure 34.


Figure 34. AC-Coupled, Single-Ended Clock Input
The ADS5553 clock input can also be driven differentially, reducing susceptibility to common-mode noise. In this case, it is best to connect both clock inputs to the differential input clock signal with $0.01 \mu \mathrm{~F}$ capacitors, as shown in Figure 35.


Figure 35. AC-Coupled, Differential Clock Input
For high input frequency sampling, it is recommended to use a clock source with low jitter. Additionally, the internal ADC core uses both edges of the clock for the conversion process. This means that, ideally, a $50 \%$ duty cycle should be provided. Figure 24 shows the performance variation of the ADC versus clock duty cycle.
Bandpass filtering of the source can help produce a $50 \%$ duty cycle clock and reduce the effect of jitter. When using a sinusoidal clock, the clock jitter further improves as the amplitude is increased. In that sense, using a differential clock allows for the use of larger amplitudes without exceeding the supply rails and absolute maximum ratings of the ADC clock input. Figure 23 shows the performance variation of the device versus input clock amplitude. For detailed clocking schemes based on transformer or PECL-level clocks, see the ADS5553EVM user's guide (SLWU010), available for download from www.ti.com.
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## OUTPUT INFORMATION

Each of the two ADCs provide 14 data outputs in two's complement format (D13 to D0, with D13 being the MSB and DO the LSB), a data-ready signal (CLKOUT), and an out-of-range indicator (OVR) that equals 1 when the output reaches the full-scale limits.
In addition, output enable control (pins 48 and 52) are provided to tri-state the outputs. See Table 2 for details.
The output circuitry of the ADS5553 has been designed to minimize the noise produced by the transients of the data switching and in particular its coupling to the ADC analog circuitry. Output DO senses the load capacitance and adjusts the drive capability of all the output pins of the ADC to maintain the same output slew rate described in the timing diagram of Figure 1, as long as all outputs (including CLKOUT) have a similar load as the one at DO. This circuit also reduces the sensitivity of the output timing versus supply voltage or temperature. External series resistors with the output are not necessary.

## PowerPAD PACKAGE

The PowerPAD package is a thermally enhanced standard size IC package designed to eliminate the use of bulky heatsinks and slugs traditionally used in thermal packages. This package can be easily mounted using standard printed circuit board (PCB) assembly techniques, and can be removed and replaced using standard repair procedures.
The PowerPAD package is designed so that the leadframe die pad (or thermal pad) is exposed on the bottom of the IC. This provides an extremely low thermal resistance path between the die and the exterior of the package. The thermal pad on the bottom of the IC can then be soldered directly to the printed circuit board (PCB), using the PCB as a heatsink.

## Assembly Process

1. Prepare the PCB top-side etch pattern including etch for the leads as well as the thermal pad as illustrated in the Mechanical Data section.
2. Place a 5 -by-5 array of thermal vias in the thermal pad area. These holes should be 13 mils in diameter. The small size prevents wicking of the solder through the holes.
3. It is recommended to place a small number of 25 mil diameter holes under the package, but outside the thermal pad area to provide an additional heat path.
4. Connect all holes (both those inside and outside the thermal pad area) to an internal copper plane (such as a ground plane).
5. Do not use the typical web or spoke via connection pattern when connecting the thermal vias to the ground plane. The spoke pattern increases the thermal resistance to the ground plane.
6. The top-side solder mask should leave exposed the terminals of the package and the thermal pad area.
7. Cover the entire bottom side of the PowerPAD vias to prevent solder wicking.
8. Apply solder paste to the exposed thermal pad area and all of the package terminals.
For more detailed information regarding the PowerPAD package and its thermal properties, see either the SLMA004B Application Brief PowerPAD Made Easy or the SLMA002 Technical Brief PowerPAD Thermally Enhanced Package.

## PACKAGING INFORMATION

| Orderable Device | Status ${ }^{(1)}$ | Package <br> Type | Package <br> Drawing | Pins Package <br> Qty | Eco Plan ${ }^{(2)}$ | Lead/Ball Finish | MSL Peak Temp ${ }^{(3)}$ |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ADS5553IPFP | ACTIVE | HTQFP | PFP | 80 | 96 |  <br> no Sb/Br) | CU NIPDAU | Level-3-260C-168 HR |
| ADS5553IPFPG4 | ACTIVE | HTQFP | PFP | 80 | 96 |  <br> no Sb/Br) | CU NIPDAU | Level-3-260C-168 HR |
| ADS5553IPFPR | ACTIVE | HTQFP | PFP | 80 | 1000 <br> no Sb/Br) | CU NIPDAU | Level-3-260C-168 HR |  |
| ADS5553IPFPRG4 | ACTIVE | HTQFP | PFP | 80 | 1000 |  <br> no Sb/Br) | CU NIPDAU | Level-3-260C-168 HR |

${ }^{(1)}$ The marketing status values are defined as follows:
ACTIVE: Product device recommended for new designs.
LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.
NRND: Not recommended for new designs. Device is in production to support existing customers, but Tl does not recommend using this part in a new design.
PREVIEW: Device has been announced but is not in production. Samples may or may not be available.
OBSOLETE: TI has discontinued the production of the device.
${ }^{(2)}$ Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS) or Green (RoHS \& no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.
TBD: The $\mathrm{Pb}-\mathrm{Free} / \mathrm{Green}$ conversion plan has not been defined.
Pb -Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed $0.1 \%$ by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.
Green (RoHS \& no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants ( Br or Sb do not exceed $0.1 \%$ by weight in homogeneous material)
${ }^{(3)}$ MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

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PFP (S—PQFP-G80) PowerPAD ${ }^{\text {TM }}$ PLASTIC QUAD FLATPACK


NOTES: A. All linear dimensions are in millimeters.
B. This drawing is subject to change without notice.
C. Body dimensions do not include mold flash or protrusion
D. This package is designed to be soldered to a thermal pad on the board. Refer to Technical Brief, PowerPad Thermally Enhanced Package, Texas Instruments Literature No. SLMA002 for information regarding recommended board layout. This document is available at www.ti.com <http: //www.ti.com>.
E. Falls within JEDEC MS-026

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