







Objective specification

900 MHz transmit modulator and 2.2 GHz fractional–N synthesizer

SA9025

DESCRIPTION

This specification defines the requirements for a transmitter modulator and fractional–N synthesizer IC to be used in cellular telephones which employ the North American Dual Mode Cellular System (IS–136).

FEATURES

- Low current from 3.75V supply
- Low phase noise
- Main loop with internal charge pump and fractional compensation
- 3–line serial interface bus
- Power down for the synthesizers
- Speedup mode for faster switching

APPLICATIONS

- Cellular phones
- Portable battery-powered radio equipment.

GENERAL DESCRIPTION

The SA9025 BICMOS device integrates:

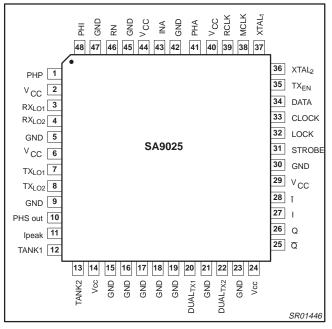
- Main channel synthesizer
- Auxiliary synthesizer
- Transmit offset synthesizer and oscillator
- I/Q modulator
- Power control

QUICK REFERENCE DATA

•	Reference	and	clock	buffers
	11010101100	ana	010010	balloio

• Control logic for programming and power down modes

PIN CONFIGURATION





SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
V _{CC}	Supply voltage	V _{CC}	3.6	3.75	3.9	V
I _{CC}	Supply current		-	TBD	-	mA
I _{CC_save}	Total supply current in power–down mode		-	TBD	_	mA
f _{VCO}	Input frequency		800	-	2200	MHz
f _{AUX}	Input frequency		10	-	500	MHz
f _{XTAL}	Crystal reference input frequency		10	-	40	MHz
f _{PC}	Maximum phase comparator frequency	Main and Aux loops	-	-	5	MHz
T _{amb}	Operating ambient temperature		-40	-	+85	°C

ORDERING INFORMATION

TYPE NUMBER	PACKAGE			
	NAME DESCRIPTION VERS			
SA9025	LQFP48 Plastic low profile quad flat package; 48 leads; body 7x7x1.4 mm S		SOT313-2	

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900 MHz transmit modulator and 2.2 GHz fractional–N synthesizer

CONNECTIONS

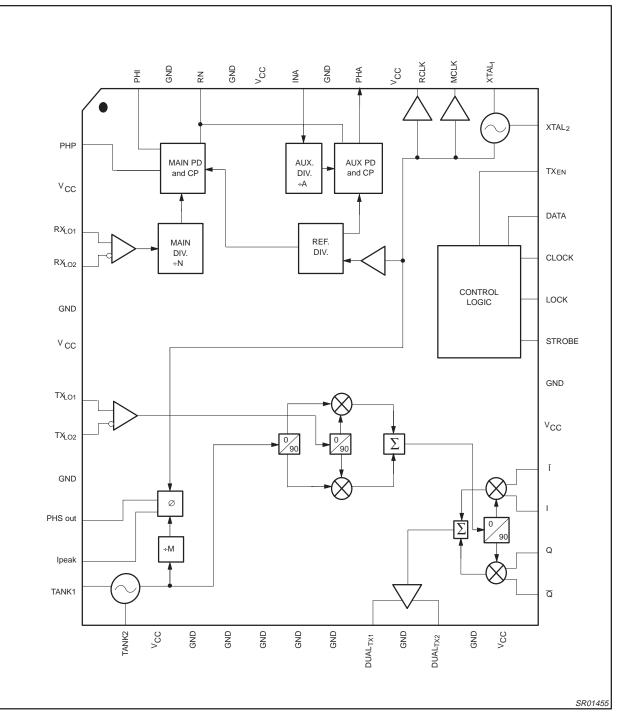


Figure 2. SA9025 Block Diagram

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PIN DESCRIPTIONS

PIN NO.	PIN	DESCRIPTION
1	PHP	Proportional charge pump output
2	V _{CC}	Digital supply voltage
3	RX _{LO1}	Differential LO input
4	RX _{LO2}	Differential LO input
5	GND	Digital Ground
6	V _{CC}	Tank supply voltage
7	TX _{LO1}	Differential Transmit LO Input
8	TX _{LO2}	Differential Transmit LO Input
9	GND	Tank Ground
10	PHS OUT	Charge pump output (transmit offset)
11	I _{PEAK}	PHS out current set resistor
12	TANK1	VCO differential tank
13	TANK2	VCO differential tank
14	V _{CC}	Tx supply voltage
15	GND	Tx Ground
16	GND	Tx Ground
17	GND	Tx Ground
18	GND	Tx Ground
19	GND	Tx Ground
20	DUALTX1	Dual mode RF output
21	GND	Tx Ground
22	DUALTX2	Dual mode RF output
23	GND	Tx Ground

24	V _{CC}	Tx supply voltage
25	Q	Inverting quadrature input
26	Q	Non-Inverting quadrature input
27	Ī	Non-inverting in phase modulation input
28	Ī	Inverting in phase modulation input
29	V _{CC}	Tx supply voltage
30	GND	Tx Ground
31	STROBE	Data input latch enable
32	LOCK	Lock detect
33	CLOCK	Serial clock input
34	DATA	Serial data input
35	ΤΧ _{ΕΝ}	Transmit enable
36	XTAL ₂	Crystal Oscillator emitter input
37	XTAL ₁	Crystal Oscillator base Input
38	MCLK	Buffered oscillator output
39	RCLK	Buffered oscillator output
40	V _{CC}	REF supply voltage
41	PHA	Auxiliary charge pump output
42	GND	REF Ground
43	INA	RX _{IF} input
44	V _{CC}	CP supply voltage
45	GND	CP Ground
46	RN	CP current set resistor
47	GND	CP Ground
48	PHI	Integral charge pump output

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OPERATING MODES & POWER DOWN CONTROL

There are two power saving modes of operation which the SA9025 can be put into, dependent on the status of the system. The intention of these different modes is to disable circuity that is not in use at the time in order to reduce power consumption. During sleep mode, only circuitry which is required to provide a master clock to

the digital portion of the system is enabled. During receive mode, circuitry which is used to perform the receive function and provide a master clock is enabled. In transmit mode all the functions of the chip are enabled which are required to perform transmit, receive and provide master clock.

SA9025	POWER MODE	TRUTH TAB	LE			
	Sleep Mode		Receive Mode		Transmit Mode	
Enabled	yes	no	yes	no	yes	no
Crystal Oscillator	1		1		1	
Phase detector and charge pump (transmit offset)		1		1	1	
VCO		1		1	1	
SSB Up-converter		1		1	1	
MCLK Buffer	1		1		1	
RCLK Buffer		1	1		1	
+M offset loop divider		1		1	1	
TX _{LO} Buffer		1		1	1	
RX _{LO} Buffer		1	1		1	
I/Q Modulator		1		1	1	
Variable Gain Amp.		1		1	1	
Control Logic	✓		1		1	
Main Divider		1	1		1	
Reference Divider		1	1		1	
Auxiliary Divider		1	1		1	
Main Phase Detector and charge pump		1	1		1	
Auxiliary Phase Detector and charge pump		1	1		1	
Lock Detect		√	1		1	

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ABSOLUTE MAXIMUM RATINGS

SYMBOL	PARAMETER	VAL	.UE	UNIT
		MIN.	MAX.	
V _{CC}	Supply voltage	-0.3	+4.5	V
V _{IN}	Voltage applied to any other pin	-0.3	V _{CC} +0.3	V
P _N	Power dissipation, $T_A = 25^{\circ}C$ (still air)		980	mW
T _{JMAX}	Operation junction temperature		TBD	°C
P _{MAX}	Power input/output		+10/+14	dBm
I _{MAX}	DC current into any I/O pin	-10	+10	mA
T _{STG}	Storage temperature	-65	+150	°C
To	Operating temperature	-40	+85	°C

DC ELECTRICAL CHARACTERISTICS

 V_{CC} = +3.75 V; T_A = 25°C; unless otherwise stated.

SYMBO	DADAMETED			LIMITS		
L	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNITS
V _{CC}	Power supply range		3.6	3.75	3.9	V
		Sleep mode		2		
		Standby mode		17		
I _{CC}	Supply current	Operating: full power analog		95		mA
		Operating: full power digital				
		DUAL ¹		52		
I/Ī	In-phase differential input	quiescent		V _{CC} /2		V
Q / <u>Q</u>	Quadrature phase differential input	quiescent		V _{CC} /2		V
V _{IL}	Clock, Data, Strobe, TX _{EN}	Input logic low	-0.3		$0.3 \times V_{CC}$	V
V _{IH}	Clock, data, strobe, TX _{EN}	Input logic high	$0.7 \times V_{CC}$		V _{CC} +0.3	V
T _A	Ambient temperature range		-40	+25	+85	°C
Digital Ou	itputs Lock	-				
V _{OL}	Output voltage LOW	$I_{O} = 2mA$			0.4	V
V _{OH}	Output voltage HIGH	I _O = -2mA	$V_{CC} - 0.4$			V
Charge P	ump Current Setting Resistor Input; RN,	R _{Ipeak}	•			
RN	External resistor to ground		6	7.5	24	kΩ
R _{lpeak}	External resistor to ground			4.7		kΩ
V _{RN}	Regulated voltage	RN = 7.5 kΩ		1.23		V
V _{Ipeak}	Regulated voltage	R _{ipeak} = 4.7 kΩ		1.3		V
I _{peak}	PHSOUT programming	$R_{ipeak} = 4.7 \ k\Omega$		0.26		mA
PHSgain	PHSOUT gain	$R_{ipeak} = 4.7 \text{ k}\Omega$		24xl _{peak}		mA
Κφ	PD phase gain	Transmit offset PLL in phase lock		4.33		mA/rad
Charge P	ump Outputs (including fractional comp	ensation pump, not PHS) RN = 7.5	δkΩ			
I _{OPH}	Charge pump output current error versus expected current.		-15		15	%
IMATCH	Sink to source current matching	$V_{PHX} = V_{CC}/2$	-5		5	%
	Current output variation versus V _{PHX}	V _{PHX} in compliance range	-10		10	%
	Charge pump off, leakage current	$V_{PHX} = V_{CC}/2$	-10	±1	10	nA
V _{PH}	Charge pump voltage compliance ³		0.7		V _{CC} – 0.8	V
	ump Outputs (only PHS) $R_{ipeak} = 4.7 \text{ k}\Omega$				-	
I _{OPH}	Charge pump output current error versus expected current.		-15		15	%
IMATCH	Sink to source current matching	$V_{PHS} = V_{CC}/2$	-10		10	%

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	Current output variation versus V _{PH}	V _{PHS} in compliance range	-25	25	%
V _{PH}	Charge pump voltage compliance		0.5	V _{CC} -0.5	V

AC ELECTRICAL CHARACTERISTICS

 V_{CC} = +3.75 V; T_A = 25°C; unless otherwise stated.

SYMBOL	DADAMETED	TEST CONDITIONS	LIMITS			UNITS	
STMBUL	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX		
Modulator							
TX _{LO 1/2}	Transmit LO input (AC-coupled; 50Ω single-ended, 100Ω differential)	Input power Frequency range	-13 900		-10 1100	dBm MHz	
VSWR				2:1			
TANK1/2	VCO tank differential inputs	Frequency range	90		180	MHz	
÷М	PLL offset divider	Maximum input frequency	180			MHz	
XTAL ₁	Osc. transistor base	Osc. frequency	10		40	MHz	
XTAL ₂	Osc. transistor emitter	Osc. frequency	10		40	MHz	
XO	Negative resistance			-100		Ω	
RCLK, MCLK	Reference buffer output Frequency range Output levels Harmonic content	Z _{LOAD} = 5kΩ 7 pF	10 0.7	1.0	40 1.4 –10	MHz V _{P–P} dBc	
ΤΧ _{ΕΝ}	Transmit enable	Transmit enable Transmit disable		$TX_{EN} = 1$ $TX_{EN} = 0$		Logic	
Q/Q /]	Baseband in-phase differential inputs	Maximum frequency Diff. mod. level Diff. input impedance DC bias point	1.8 0.8 10.0 1.8	0.9 V _{CC} /2	1.0 2.55	MHz V _{P-P} kΩ V	
TX _{RF}	TX _{RF} operating range		820		920	MHz	
DUAL _{TX}	DUAL output SE=1, TX _{EN} =1 (with external matching) (50Ω)	AMPS/DAMPS	820		853	MHz	
DUAL _{TX}	Differential output, (DUAL _{TX}) open-collector, matched to 200Ω differential impedance	Output level (avg. min., I and Q quad., 0dB VGA) Gain flatness	+9.0	+11.0	+13.0	dBm dB	
DUAL _{TX}	Linearity worst case intermod. products (0dB VGA OR +9 dBm, whichever is less, I & Q in-phase)	3rd-order 5th-order 7th-order		-42 -55 -65	-34 -45 -53	dBc	
DUAL _{TX}	Carrier suppression (I & Q in quadrature)	VGA = 0dB VGA = -38dB		-45 -33	-35	dBc	
DUAL _{TX}	Sideband suppression (I & Q in quadrature)			-45	-35	dBc	
		2 to 284 MHz			-45		
		824 to 849 MHz			-47	dBc	
DUAL _{TX}	Spurious output	849 to 869 MHz			-45]	
		869 to 894 MHz			-104	dBm	
		894 to 8490 MHz			-45	dBc	
		TX _{LO}			-21		
		Upper Side Band			-21		
DUAL _{TX}	TX _{LO} up-conversion products	$TX_{LO} \pm 3 \times TX_{OFFSET}$			-36	dBc	
		Harmonics ≤ 10th			-21		
DUAL _{TX}	Broad-band noise (0dB VGA or +9 dBm, whichever is less)	869 to 894 MHz			-123	dBm/Hz	
DUAL _{TX}	Adjacent channel noise power	@ 30 kHz			-95	dBc/Hz	
DUALTX	Alternate channel noise power	@ 60 kHz			-101	dBc/Hz	

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		Main Divider			
<i>f</i> _{MMAX}	Input frequency range		800	2200	MHz
	Input harmonics	No multi–clocking	-10		dBc
RX _{LO 1/2}	Synthesizer LO input (AC-coupled; external shunt 50Ω single-ended, 100Ω differential)	Input power	-20	0	dBm
	· · · · ·	Reference Divider	· · ·		
f _{RMAX}	Input frequency RANGE		10	40	MHz
	Input harmonics	No multi–clocking	-10		dBc
	· · · · · ·	Auxiliary Divider	· · · ·		-
<i>f</i> AMAX	Input frequency RANGE		10	500	MHz
	Input harmonics	No multi-clocking	-10		dBc
V _{INA}	Input signal amplitude		0.200		V _{P-P}
		Serial Interface			
<i>f</i> _{CLOCK}	Clock frequency			10	MHz
t _{SU}	Set-up time: DATA to CLOCK, CLOCK to STROBE		30		ns
t _H	Hold time: CLOCK to DATA		30		ns
		CLOCK	30		
t _{SW}	Pulse width	STROBE (B - D words)	30		ns
	Puise wiath	A word	$\frac{1}{f_{\text{REF}} \cdot \text{NREF}} + t_{\text{W}}$		115

Transmit mode @ 33% duty cycle.
 The relative output current variation is defined thus: Δl_{out}/l_{out}=2x(l₂-l₁)/|(l₂+l₁)|; with V₁=0.7V, V₂=V_{CC}-0.8V (see figure 3)
 Power supply current measured with f_{RX} = 2100.54 MHZ, f_{REF} = 19.44 MHZ, f_{INA}= 109.92 MHZ, main phase detector bias resistor = 7.5 kΩ. Main phase detector reference frequency = 240 kHZ, auxiliary phase detector frequency = 240 kHZ.
 Maximum and minimum levels guaranteed by design and random testing for temperature range of -40 to +85°C.
 Power is rated at I/Q input level of 0.9V_{PP}.

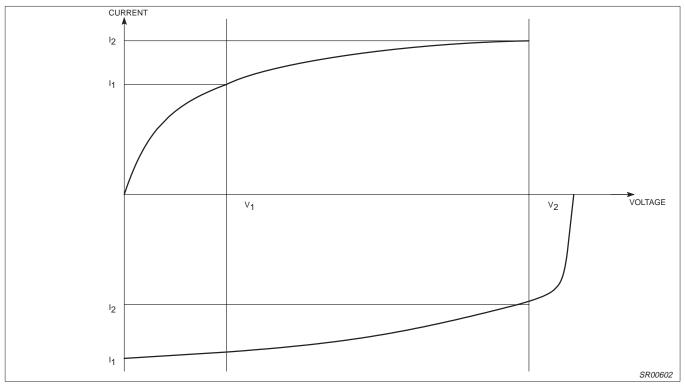


Figure 3. Output Current Definition

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Functional Description Main Channel Synthesizer & Auxiliary Synthesizer

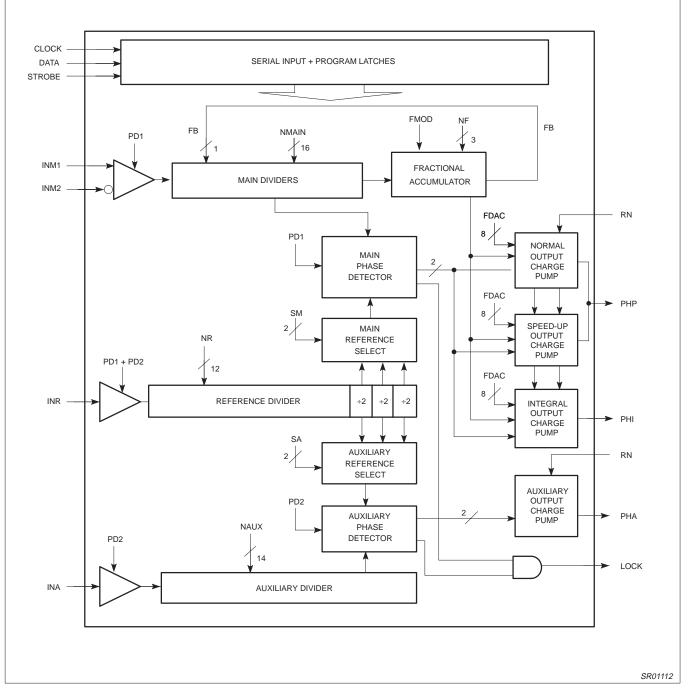


Figure 4. Synthesizer Block Diagram

Serial Programming Input

The serial input is a 3-wire input (CLOCK, DATA, STROBE) used to program all counter ratios, DACs, selection and enable bits. The programming data is structured into 24-bit words; each word includes 2 or 3 address bits. Figure [5] shows the timing diagram of the serial input. When STROBE = L, the clock driver is enabled and on positive edges of the CLOCK, the signal on DATA input is

clocked into a shift register. When STROBE = H, the clock is disabled and the data in the shift register remains stable.

Depending on the 2 or 3 address bits, data is latched into different working or temporary registers. In order to fully program the synthesizer, 3 words must be sent: A, B and C. The D word programs all other functions within the SA9025. Those functions are

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power control, +M (offset loop), SE (Tx offset loop synthesizer enable), DUAL mode, Sleep Mode 1 and Sleep Mode 2.

The data for FDAC is stored by the B word into a temporary register. When the A word is loaded, the data in this temporary register is loaded together with the A word into the work registers to avoid false temporary main synthesizer output caused by changes in fractional compensation.

The A word contains new data for the main divider. The A word is loaded into the working registers only when a main divider synchronization signal is active to avoid phase jumps when reprogramming the main divider. The synchronization pulse is generated by the main divider when it has reached its terminal count, at which time a main divider output pulse is also sent to the main phase detector. This disables the loading of the A word each main divider cycle during maximum of (NREF / f_{REF}) seconds. Therefore, to be sure that the A word will be correctly loaded, the STROBE signal must be high for at least (NREF / f_{REF}) seconds. When programming the A word, the main charge pumps on output PHP and PHI are set into the speed–up mode as soon as the A word is latched into the working registers and remain so as long as STROBE is held high.

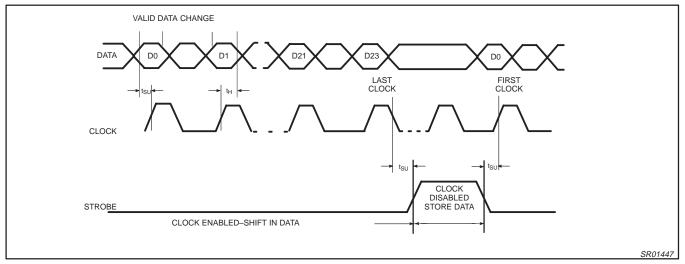


Figure 5. Serial Input Timing Sequence

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Table 1. Function Table

Symbol	Bits	Function
FMOD	1	Fractional-N modulus selection flag: '0' = modulo 8 '1' = modulo 5
NF	3	Fractional-N increment
NMAIN	16	Main divider ratio; 512 to 65,535 allowed
NREF	10	Reference divider ratio; 4 to 1,023 allowed, RSM, RSA = "0 0"
RSM	2	Reference select for main phase detector
RSA	2	Reference select for auxiliary phase detector
FDAC	8	Fractional compensation charge pump current DAC
NAUX	14	Auxiliary divider ratio; 128 to 16,384 allowed
СР	2	Charge pump current ratio select (see table 1)
LD	2	Lock detect output select (see table 2)
PD1	1	PD1 = 0 for power down; shuts off power to main divider and main chargepumps, anded with PD2 to turn off ref. divider.
PD2	1	PD2 = 0 for power down; shuts off power to auxiliary divider, and auxiliary charge pumps; anded with PD1 to turn off ref. divider.
PC	8	Power control (see note 3)
М	2	÷M, M = 6, 7, 8, 9 (see note 4)
SE	1	Transmit offset synthesizer on/off
ТМ	1	Transmit mode: '0' = DUAL
AD	1	Mode control, 1 = digital; 0 = analog
SM1	1	Sleep mode 1
SM2	1	Sleep mode 2

 Data bits are shifted in on the the leading clock edge, with the least significant bit (LSB) first and the most significant bit (MSB) last.

- On the rising edge of the strobe and with the address decoder output = 1, the contents of the input shift register are transferred to the working registers. The strobe rising edge comes one half clock period after the clock edge on which the MSB of a word is shifted in.
- 3. The PC bits are used for the power control function. Eight (8) bits of data allows for appropriate resolution of the power control. 00000000 = 0 dB: 11111111 = -45.9 dB (= 255 × 0.18).
- 4. The M bits are used to program the ÷M counter for integer values between 6 and 9. 00 = 6, 01 = 7, 10 = 8, 11 = 9.
- 5. The TM bit is used to put the SA9025 into DUAL mode operation. In DUAL mode (TM = 0).
- 6. The AD bit allows a reduction in the linearity of the DUAL output driver while in AMPS mode.
- 7. The SM1 bit is used to shut down the TX_{LO} buffers. SM1 = 1, buffers on; SM1 = 0, buffers off.
- 8. The SM2 bit is used to shut down the RCLK buffer. SM2 = 1, buffer on; SM2 = 0, buffer off.
- 9. The SE bit turns on and off the offset loop synthesizer circuits. SE = 1, synthesizer on; SE = 0, synthesizer off.
- 10. The LOCK bits determine what signal is present on the LOCK pin as follows:

Table 2.

	Lock Detect Output Select*
LOCK	LOCK Pin Function
00	Main, auxiliary and offset lock condition
01	Main and auxiliary lock condition
10	Main lock detect condition
11	Auxiliary lock condition

*When a section is in power down mode, the lock indicator for that section is high.

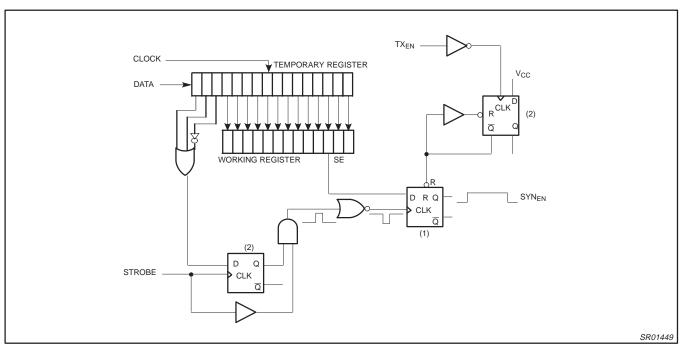


Figure 6. Transmit Offset Synthesizer Reset Circuit

In Figure 6, the falling edge of the strobe and address, inverted, toggles the Q output of flip-flop (1) to a '1' state, enabling the phase detector, VCO, divide by M, TX_{IF} buffer and SSB up-converter. Approximately 80µs after the synthesizer is locked, the TX_{EN} signal (enabled = 1) turns on the modulator and variable gain amplifier. The rising edge of TX_{EN} has no effect on SYN_{EN}, however, the falling (rising inverted) edge toggles the \overline{Q} output of D flip-flop (2) to a '0' state. This disables the synthesizer, modulator and variable gain amplifier. To insure that slow edges on TX_{EN} do not cause improper operation, the TX_{EN} is a Schmitt trigger design.

The address decoder for program word 'D' ANDed together with the strobe is used to load the contents of the temporary register into the working registers. D flip-flop (3) is used to prevent multiple strobe and address pulses in the event the address decoder output toggles on garbage bits during the time the strobe remains in a '1' state.

The temporary register is common to the transmit offset synthesizer, main channel synthesizer and auxiliary synthesizer.

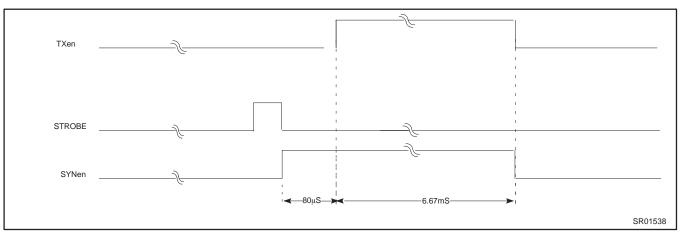


Figure 7. Transmit Offset Synthesizer Timing Diagram

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Data format Format of programmed data

LAST IN		MSB	Ś	SERIAL PROGRA	MMING FORMAT	Γ	FIRST IN LSB
p23	p22	p21	p20	/	/	р1	p0

A word, length 24 bits

Last i	n					MSB														LSB	Fir	st IN
Addre	SS	fmod	Frac	tional	-N					Mai	n Divi	der ra	tio– N	Imain							Sp	oare
0	0	Fmod	NF2	NF1	NF0	NF0 N15 N14 N13 N12 N11 N10 N9 N8 N7 N6 N5 N4 N3 N2 N								N1	N0	sk1	sk2					
Defa	Default: 0 1 0 0 1 0 0 1 0 0 1 0 0 1 0 0 1 1 0 1 1 0 1 1 0 1 1 0 1 1 1 0 1 1 1 0 1 1 1 0 1 1 1 0 1 1 1 0 1 1 1 0 1 1 1 0 1 1 1 0 1 1 1 0 1 1 1 0 1 1 1 0 1 1 1 0 1 1 0 1 1 0 1 1 0 1 1 0 1 1 0 1 1 0 1 1 0 1 1 0 1 1 0 1 1 1<								0	0	0	0	0									
A wor	d sele	ct			Fixed	to 00.																
Fracti	Fractional Modulus select FI						8, 1=	modu	ılo 5.													
Fracti	onal-l	N Increr	nent		NF2	0 Fractio	onal N	I Incre	ement	value	s 000	to 11	1.									
N–Div	N-Divider NO					I15, Maii	n divio	der va	lues 5	512 to	6553	5 allov	ved fo	or divio	der ra	tio.						

B word, length 24 bits

ADDR	RESS		F	REFE	REN	CED	DIVID	ER I	NREI	F		R	SM	RS	6A		FRA	CTION	AL CC	MPEN	SATIO	N DAC	;
0	1	R9	R8	R7	R6	R5	R4	R3	R2	R1	1 R0 RSM RSM RSA RSA RSA Fdac Fdac Fdac Fdac Fdac A 3										Fdac 2	Fdac 1	Fdac 0
Defa	ault:	0	0	0	1	0	1	0	0	0	1	0	0	0	0	х	x	х	х	х	х	х	х
	B word select Fixed to 01																-						
	R–Divider R0R9, Reference divider value							alue	s 4 to 1	1023 al	lowed fo	or divide	er ratio	n.									
Cha	Charge pump current Ratio CP1, CP0: Charge pump current								irren	t ratio,	see tab	ole of ch	arge pi	ump cu	irrents.								
М	Main comparison RSM Comparison divider se select									seleo	ct for m	iain pha	ase dete	ector.									
Aux	Aux comparison select RSA Comparison divider s								selec	t for au	uxiliary	phase c	letector	r.									
(Fractional Fdac70, Fractional compens Compensation							nsati	on cha	irge pu	mp curr	ent DA	C, valu	es 0 to	255. F	DAC =	77 for	best op	D MOD8	3.			

C word, length 24 bits

ADDR	ESS					AU)	(ILIAF	RY DIV	/IDER	NAU	Х					0	P	LC	оск	F	PD	SP	ARE
1	0	A13	A12	A11	A10	A9	A8	A7	A6	A5	A4	A3	A2	A1	A0	CP1	CP0	LD1	LD0	PD1	PD2	PD3	LOD
Default 0 0 0 0 1 1 1 0 0 1 </td <td>1</td> <th>0</th> <td>1</td> <td>1</td> <td>0</td> <td>0</td> <td>TX_{EN}</td> <td>тх_{ел}</td> <td>0</td> <td>0</td>									1	0	1	1	0	0	TX _{EN}	тх _{ел}	0	0					
C word select Fixed to 10																							
A–Divider A0A13, Auxiliary divider values 128 to 16384 allow									wed f	or div	ider ra	tio.											
Charge pump current Ratio CP1, CP0: Charge pump current ratio, see table f									ole fo	char	ge pu	mp cu	irrents										
Lock detect output LD1 LD0 0 Combined main, aux. & offset loop lock detect signal 0 Combined main and aux. lock detect signal present at 10 Main lock detect signal present at the LOCK pin. 11 1 Auxiliary loop lock detect signal present at the LOCK when a section is in power down mode, the lock indicator for the lock indi													nt aṫ th CK pir	ne LOO	CK pir	ı. '							
Power down PD1=1: power to N–divider, reference divider, main charge pumps, PD1=(PD2=1: power to Aux divider, reference divider, Aux charge pump, PD2=0										:0 to po 0 to pov	wer dowr ver down	ז. ו.											

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Table 3.

Main and auxiliary chargepump currents

CP1	CP0	I _{PHA}	I _{PHP}	I _{PHP-SU}	I _{PHI_SU}
0	0	1.5xlset	3xlset	15xlset	36xlset
0	1	0.5xlset	1xlset	5xlset	12xlset
1	0	1.5xlset	3xlset	15xlset	0
1	1	0.5xlset	1xlset	5xlset	0

NOTES

I_{SET} = Vset/RN; bias current for charge pumps.
 CP1 is used to disable the PHI pump.
 Iphp_su is the total current out of PHP in speedup mode.

D word, length 24 bits

A	ddres	s			Po	ower (Contro	bl			N divi		SE	тм	AD	Sle Mo			Te	est pa	_curre	ent	
1	1 1 0 PC7 PC6 PC5 PC4 PC3 PC2 PC1 F										M1	M0	SE	ΤM	AD	SM1	SM2	pai5	pai4	pai3	pai2	pai1	pai0
	Default: X X X X X X X X								х	0	0	0	0	0	0	0	0	0	0	0	0	0	
	D0 word select Fixed to 110.										•												
	Output Power Control PC7(msb)PC0(Isb) Provides out								output	power	attenua	ation fo	or DUA	L mod	e amplif	ier out	puts in	0.18 d	B steps	, Fx =	45.9 dE	3.	
	M Divider 00 = 6, 01 = 7, 10 = 8, 11 = 9																						
0	Offset Ic	op pow	ver dow	n	SE O	ffset lo	op synt	hesize	r powe	r down	, SE =	1 powe	r on, S	SE = 0	power	down (s	sleep n	node).					
	DUAL	mode	select		TM =	0 DUA	Lmode																
AN	AMPS/DAMPS mode select AD = 1 DAMPS mode. AD = 0 AMPs mode																						
٦	TX buffers power down SM1 TX Local oscillator buffers p SM2 RCLK buffer power down. S																wer do	own.					
Test: pa_current:pai TX test bits for controlling the current									rent in	the pov	wer am	p. Sho	uld be	0 durii	ng norm	nal ope	ration.						

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MODES OF OPERATION

There are two power saving modes of operation which the circuit can be put into, dependent on the status of the system. The intention of these different modes is to disable circuitry that is not in use at the time in order to reduce power consumption. During sleep mode, only circuitry which is required to provide a master clock to the digital portion of the system is enabled. During receive mode, circuitry which is used to perform the receive function and provide a master clock is enabled. In transmit mode all the functions of the circuit are enabled which are required to perform transmit, receive and provide master clock. When the circuit is powered for the first time, it is in DUAL MODE SLEEP.

Mode	Dua	al Mode Al	MPS	
Mode Setting and BlockStatus (X = ON)	Sleep	RX	ТХ	Logic
ΤΧ _{ΕΝ}	0	0	1	
PD1	0	1	1	
PD2	0	1	1	
SE->SYNen	0	0	1	
ТМ	0	0	0	
SM1	0	0	1	
SM2	0	1	1	
Main loop, Ndivider, RXLO buffer		Х	Х	PD1
Aux loop, Adivider		Х	Х	PD2
Rdivider		Х	Х	PD1 .OR. PD2
Offset VCO, Mdivider			Х	SE (+delay) See SE->SYN _{EN} diagram
RCL buffer		Х	Х	SM2
MCL buffer, reference input	Х	Х	Х	1 (always ON)
DUAL _{TX} PA			Х	(.not. TM) .and. TX _{EN} .and. SM1
TXLO buffer, SSB up-converter			Х	SM1
I/Q MODULATOR, VGA			Х	TXEN .AND. SM1
Control Logic	Х	Х	Х	1 (always ON)

Mode Programming

Main Divider

The input signal on RX_{LO} is amplified to a logic level by a balanced input comparator giving a common mode rejection. This input stage is enabled by serial control bit PD1 = 1. Disabling means that all currents in the comparator are switched off. The main divider is built up to be a 16-bit counter.

The loading of the work registers FMOD, NF and NMAIN is synchronized with the state of the main counter to avoid extra phase disturbance when switching over to another main divider ratio as is explained in the Serial Programming Input chapter.

At the completion of a main divider cycle, a main divider output pulse is generated which will drive the main phase comparator. Also, the fractional accumulator is incremented with NF. The accumulator works modulo Q. Q is preset by the serial control bit FMOD to 8 when FMOD = '0'. Each time the accumulator overflows, the total divide ratio will be NMAIN + 1 for the next cycle. The mean division ratio over Q main divider cycles will then be:

$$NQ = NMAIN + \frac{NF}{Q}$$

Synchronization is provided to avoid a random phase on the phase detector upon the loading of a new ratio and when powering up the loop.

Auxiliary Divider

The input signal on INA is amplified to logic level by a single-ended input buffer, which accepts low level AC-coupled input signals. This input stage is enabled if the serial control bit PD2 = '1'. Disabling means that all currents in the buffer and prescaler are switched off. The auxiliary divider is programmed with 14 bits and has continuous integer division ratios over the range of 128 to 16,384.

Reference Divider (Figure 8)

The input can be driven by a differential crystal input or an external TCXO. This input stage is enabled by the OR function of the serial input bits PD1 and PD2. Disabling means that all currents are switched off. The reference divider consists of a programmable divide by N_{REF} (N_{REF} = 4 to 1,023) followed by a 3-bit binary counter. The 2 bit SM determines which of the four output pulses is selected as the main phase detector signal. To obtain the best time spacing for the main and auxiliary reference signals, a different output will be used for the auxiliary phase detector, reducing the possibility of unwanted interactions.

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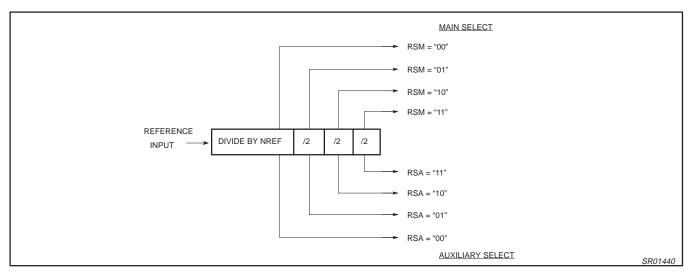


Figure 8. Reference Variable Divider

Phase Detectors (Figure 9)

The auxiliary and main phase detectors each consist of a 2 D-type flip-flop phase and frequency detector. Each flip-flop is set by the negative edge of the divider terminal count output pulse. The reset inputs are activated after a delay when both flip-flops have been set. This avoids non-linearity or dead-band around zero phase error. The flip-flops drive on-chip charge pumps. A pull-up current from the charge pump indicates the VCO frequency shall be increased while a pull-down pulse indicates the VCO frequency shall be decreased.

Current Settings

The IC has two current setting pins, RN and I_{PEAK}. The active charge pump currents and the fractional compensation currents are linearly dependent on the current in the current setting pins. This current, I_{SET}, is set by an external resistor connected between the current setting pin and V_{SS}.

Auxiliary Output Charge Pumps

The auxiliary charge pumps on pin PHA are driven by the auxiliary phase detector and the current value is determined by the external resistor attached to pin RN.

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900 MHz transmit modulator and 2.2 GHz fractional–N synthesizer

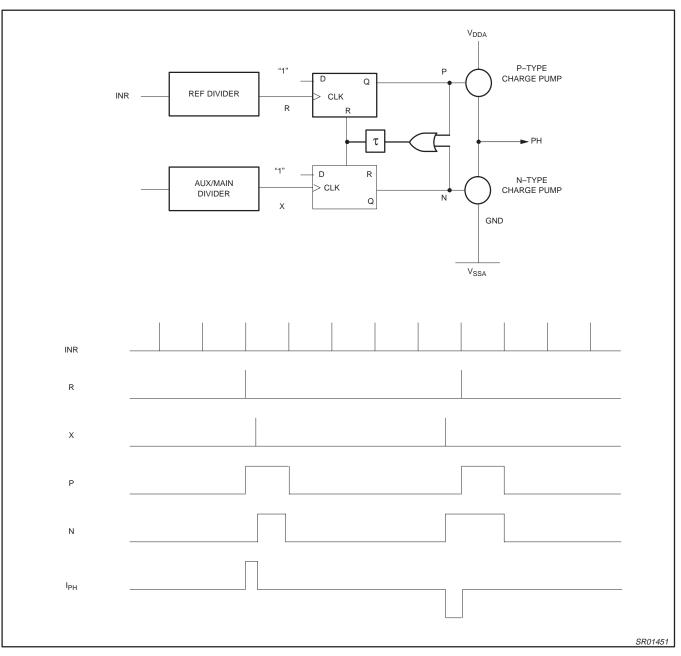


Figure 9. Phase Detector Structure With Timing

Main Output Charge Pumps and Fractional Compensation Currents

The main charge pumps on pin PHP and PHI are driven by the main phase detector. The current value is determined by the current at pin RN. The fractional compensation current is linearly dependent on the main charge pump current and its level relative to the main charge pumps is set by an 8-bit programmable DAC. The timing for the fractional compensation is derived from the main divider. The current level based on the value of FRD, FDAC and I_{SET}. Figure 10 shows the waveforms (not to scale) for a typical base.

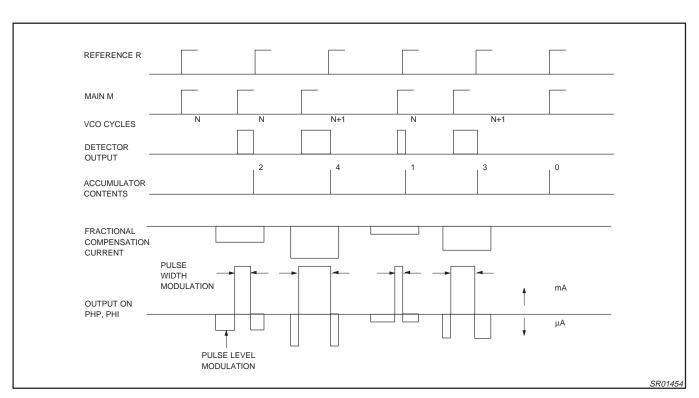


Figure 10. Waveforms for NF = 2; Fraction = 0.4

Figure 10 shows that for a proper fractional compensation, the area of the fractional compensation current pulse must be equal to the area of the charge pump ripple output.

The fractional compensation current is derived from the main charge pump in that it will follow all the current scaling through external resistor setting, programming or speedup operation.

For a given pump,

$$|\text{comp} = \frac{|\text{pump}|}{128} \times \frac{\text{Fdac}}{5 \times 128} \times \text{FRD}$$

Where:

Icomp is the compensation current, Ipump is the pump current, Fdac is the fractional DAC value and FRD is the fractional accumulator value.

The theoretical value for Fdac would then be: 128 for Fmod = 1 (modulo 5) and 80 for Fmod = 0 (modulo 8).

When the serial input A word is loaded, the output circuits are in the "speedup mode" as long as the STROBE is H, otherwise the "normal mode" is active.

Lock Detect

The output LOCK maintains a logic '1' when the auxiliary phase detector ANDed with the main phase detector indicates a lock condition. The lock condition for the main and auxiliary synthesizers is defined as a phase difference of less than ± 1 cycle on the reference inputs XTAL1,2. The LOCK condition is also fulfilled when the relative counter is disabled (PD_{main} = '0' or PD_{aux} = '0') for the main or auxiliary counter, respectively. Lock indication when PD_{main} = PD_{aux} = '0'.

Functional Description of Offset Loop, Modulator and Power Control

Transmit Offset Synthesizer

The transmit offset phase locked loop portion of the SA9025 design consists of the following functional blocks: reference oscillator, limiters, phase detector, ÷M, IF VCO and passive loop filter. Harmonic contents of this signal are attenuated by an LP filter. The output of the IF VCO is also divided by N and compared with the reference oscillator in the phase detector.

Reference Oscillator

This Oscillator is used to generate the reference frequency together with an external crystal and varicap. The output is internally routed to three buffers and a phase comparator. It is possible to run the oscillator as an amplifier from an external reference signal (TCXO).

Phase Detector and Charge Pump

The phase comparator is used to compare the output of the divider with the reference. It provides an output proportional to the phase difference between the divided down VCO and the reference. This output is then filtered and used as the control voltage input to the VCO. The phase detector is a Gilbert multiplier cell type, having a linear output from 0 to π ($\pi/2 \pm \pi/2$), followed by a charge pump. The charge pump peak output current is programmable to 6.4mA via the use of an external resistor.

A preliminary design analysis has been performed with the following loop parameters:

A lock detect signal is provided and ANDed together with lock detect signals from both the main channel synthesizer and auxiliary

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synthesizer. While in standby mode, the lock detect signal will be forced to a valid lock state so that the lock detect signal will indicate when the main and auxiliary phase detectors have achieved phase lock.

Divide by M

The \pm M is a 2-bit programmable divider which can be configured for ney integer divide from 6 to 9. The divider is used to convert the VCO output down to the reference frequency before feeding it into the phase comparator.

VCO

This oscillator is used to generate the transmit IF frequency between 90MHz and 180MHz. The VCO tank is configured using a parallel inductor tuning varactor diode. DC blocking capacitors are used to isolate the varactor control voltage from the VCO tank DC bias voltages.

SSB Up-converter and TX_{IF} Buffer

The TX_{IF} buffer provides isolation between the SSB Up-converter and the VCO output. The Single Sideband Up-converter (SSB) is an active Gilbert cell multiplier (matched pair), combined with two quadrature phase shift networks and a low pass filter. The SSB up-converter is used to reject the unwanted upper sideband that would normally occur during the up-conversion process.

I/Q Modulator

The quadrature modulator is an active Gilbert cell multiplier (matched pair) with cross coupled outputs. These outputs are then provided to the variable gain amplifier. When the in-phase input I = cos (ω t) and the quadrature-phase input Q = sin (ω t) (i.e., Q lags I by 90°), the resulting output should be upper single sideband.

Variable Gain Amplifiers

The variable gain amplifiers are used to control the output level of the device, with a power control range of 45.9dB. The output stages are differential, matched from 200Ω to 50Ω .

Power Control

The power control range should be greater than or equal to 45.9dB, having a monotonically decreasing slope, with 0dB = +11.5 dBm nominal. Eight bits are available for power control programming. The top 6 bits (PC7 to PC2) provide coarse attenuation with .6dB step size accuracy. The bottom 2 bits provide fine attenuation with .18 dB step size accuracy.

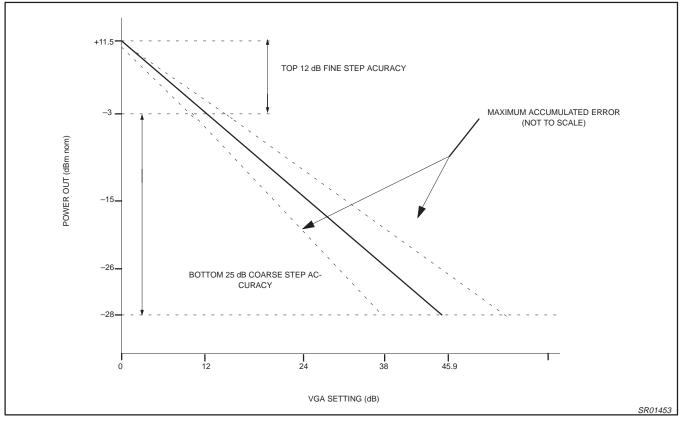


Figure 11. Power Control

Oscillator Buffers

There are three buffers for the reference signal, two of which are used to provide external reference signals. The internal reference signal is used for the main and auxiliary synthesizer reference. The second buffer (MCLK) is used as a master clock for external digital circuitry which is always on, while the third buffer (RCLK) is used as a clock for external digital circuitry which is not used in sleep mode.

LO Buffers

The LO buffers are used to provide isolation for the VCO and between the transmitter up-converter and channel synthesizer.

Objective specification

900 MHz transmit modulator and 2.2 GHz fractional–N synthesizer

LQFP48: plastic low profile quad flat package; 48 leads; body 7 x 7 x 1.4 mm SOT313-2 X 36 25 Α 37 24 Z_E Т Q е έH_E (A_3) ♦wM ,¥^{₽[₽]} pin 1 index 48 13 detail X 12 $|z_D|$ = v (M) A е ⊕wM bp ► B HD -**=** v 🕅 B 2.5 5 m m 0 scale

DIMENSIONS (mm are the original dimensions)

UNIT	A max.	Α1	A ₂	Α3	р ^р	с	D ⁽¹⁾	E ⁽¹⁾	е	HD	Η _E	L	Lp	Q	v	×	У	Z _D ⁽¹⁾	ZE ⁽¹⁾	θ
mm	1.60	0.20 0.05	1.45 1.35	0.25	0.27 0.17	0.18 0.12	7.1 6.9	7.1 6.9	0.5	9.15 8.85	9.15 8.85	1.0	0.75 0.45	0.69 0.59	0.2	0.12	0.1	0.95 0.55	0.95 0.55	7° 0°

Note

1. Plastic or metal protrusions of 0.25 mm maximum per side are not included.

OUTLINE		EUROPEAN	ISSUE DATE		
VERSION	IEC	JEDEC	EIAJ	PROJECTION	ISSUE DATE
SOT313-2					-93-06-15- 94-12-19

SA9025

	DEFINITIONS										
Data Sheet Identification	Product Status	Definition									
Objective Specification	Formative or in Design	This data sheet contains the design target or goal specifications for product development. Specifications may change in any manner without notice.									
Preliminary Specification	Preproduction Product	This data sheet contains preliminary data, and supplementary data will be published at a later date. Philips Semiconductors reserves the right to make changes at any time without notice in order to improve design and supply the best possible product.									
Product Specification	Full Production	This data sheet contains Final Specifications. Philips Semiconductors reserves the right to make changes at any time without notice, in order to improve design and supply the best possible product.									

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