





MULTIPOINT-LVDS QUAD DIFFERENTIAL LINE DRIVER

FEATURES

- Differential Line Drivers for 30- Ω to 55- Ω Loads and Data Rates⁽¹⁾ Up to 200 Mbps, Clock Frequencies up to 100 MHz
- Supports Multipoint Bus Architectures
- Meets the Requirements of TIA/EIA-899
- Operates from a Single 3.3-V Supply
- Characterized for Operation from -40°C to 85°C
- 16-Pin SOIC (JEDEC MS-012) and 16-Pin TSSOP (JEDEC MS-153) Packaging

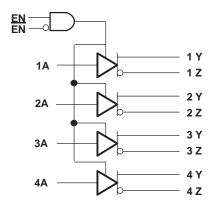
APPLICATIONS

- AdvancedTCA[™] (ATCA[™]) Clock Bus Driver
- Clock Distribution
- Backplane or Cabled Multipoint Data Transmission in Telecommunications, Automotive, Industrial, and Other Computer Systems
- Cellular Base Stations
- Central-Office and PBX Switching
- Bridges and Routers
- Low-Power High-Speed Short-Reach Alternative to TIA/EIA-485

DESCRIPTION

The SN65MLVD047A is a quadruple line driver that complies with the TIA/EIA-899 standard, Electrical Characteristics of Multipoint-Low-Voltage Differential Signaling (M-LVDS). The output current of this M-LVDS device has been increased, in comparison to standard LVDS compliant devices, in order to support doubly terminated transmission lines and heavily loaded backplane bus applications. Backplane applications generally require impedance matching termination resistors at both ends of the bus. The effective impedance of a doubly terminated bus can be as low as 30 Ω due to the bus terminations, as well as the capacitive load of bus interface devices. SN65MLVD047A drivers allow for operation with loads as low as 30 Ω . The SN65MLVD047A devices allow for multiple drivers to be present on a single bus. SN65MLVD047A drivers are high impedance when disabled or unpowered. Driver edge rate control is incorporated to support operation. The M-LVDS standard allows up to 32 nodes (drivers and/or receivers) to be connected to the same media in a backplane when multiple bus stubs are expected from the main transmission line to interface devices. The SN65MLVD047A provides 9-kV ESD protection on all bus

LOGIC DIAGRAM (POSITIVE LOGIC)



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

(1)The data rate of a line, is the number of voltage transitions that are made per second expressed in the units bps (bits per second). AdvancedTCA and ATCA are trademarks of the PCI Industrial Computer Manufacturers Group.



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These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

ORDERING INFORMATION

| PART NUMBER | PACKAGE MARKING | PACKAGE/CARRIER |
|-----------------|-----------------|----------------------------|
| SN65MLVD047AAD | MLVD047A | 16-Pin SOIC/Tube |
| SM65MLVD047ADR | MLVD047A | 16-Pin SOIC/Tape and Reel |
| SN65MLVD047APW | BUL | 16-Pin TSSOP/Tube |
| SM65MLVD047APWR | BUL | 16-Pin TSSOP/Tape and Reel |

NOTE: For the most current package and ordering information, see the Package Option Addendum at the end of this document, or see the TI website at www.ti.com.

PACKAGE DISSIPATION RATINGS

| PACKAGE | PCB JEDEC STANDARD | T _A ≤ 25°C POWER RATING | DERATING FACTOR ABOVE T _A = 25°C(1) | T _A = 85°C POWER RATING |
|-----------|-----------------------|---------------------------------------|---|---------------------------------------|
| D(16) | Low-K(2) | 898 mW | 7.81 mW/°C | 429 mW |
| D\\((4.0) | Low-K(2) | 592 mW | 5.15 mW/°C | 283 mw |
| PW(16) | High-K ⁽³⁾ | 945 mW | 8.22 mW/°C | 452 mw |

⁽¹⁾ This is the inverse of the junction-to-ambient thermal resistance when board mounted and with no air flow.

ABSOLUTE MAXIMUM RATINGS

over operating free-air temperature range unless otherwise noted(1)

| | | | UNITS |
|-------------------------------------|-------------------------------------|----------|---------------|
| Supply voltage range(2), V | CC | | –0.5 V to 4 V |
| Input voltage range, V _I | A, EN, EN | | –0.5 V to 4 V |
| Output voltage range, VO | Y, Z | | –1.8 V to 4 V |
| | Human Body Model(3) | Y and Z | ±9 kV |
| | | All pins | ±4 kV |
| Electrostatic discharge | Charged-Device Model ⁽⁴⁾ | All pins | ±1500 V |
| | Machine Model ⁽⁵⁾ | All pins | 200 V |
| Junction temperature, TJ | | | 140°C |

⁽¹⁾ Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

⁽²⁾ In accordance with the Low-K thermal metric difinitions of EIA/JESD51-3.

⁽³⁾ In accordance with the High-K thermal metric difinitions of EIA/JESD51-7.

⁽²⁾ All voltage values, except differential I/O bus voltages, are with respect to the circuit ground terminal.

⁽³⁾ Tested in accordance with JEDEC Standard 22, Test Method A114-B.

⁽⁴⁾ Tested in accordance with JEDEC Standard 22, Test Method C101-A.

⁽⁵⁾ Tested in accordance with JEDEC Standard 22, Test Method A115-A.



RECOMMENDED OPERATING CONDITIONS (see Figure 1)

| | MIN | NOM | MAX | UNIT |
|--|------|-----|-----|------|
| Supply voltage, V _{CC} | 3 | 3.3 | 3.6 | V |
| High-level input voltage, VIH | 2 | | VCC | V |
| Low-level input voltage, V _{IL} | 0 | | 0.8 | V |
| Voltage at any bus terminal (separate or common mode) V _Y or V _Z | -1.4 | | 3.8 | V |
| Differential load resistance, R _L | 30 | | 55 | Ω |
| Signaling rate, 1/tul | | | 200 | Mbps |
| Clock frequency, f | | | 100 | MHz |
| Junction temperature, T _J | -40 | | 125 | °C |

THERMAL CHARACTERISTICS

| PARAMETER | TEST CONDITIONS | | MIN TYP | MAX | UNIT |
|---|--|-----|---------|-------|-------|
| | Low-K board ⁽¹⁾ , no airflow | D | 128 | | |
| | Low-K board ⁽¹⁾ , no airflow | | 194.2 | | |
| Junction-to-ambient thermal resistance, ⊖JA | Low-K board ⁽¹⁾ , 150 LFM | PW | 146.8 | | °C/W |
| | Low-K board ⁽¹⁾ , 250 LFM | PVV | 133.1 | | |
| | High-K board ⁽²⁾ , no airflow | | 121.6 | | |
| lunction to beaud thousand reciptores O. | High-K board ⁽²⁾ | D | 51.1 | | °C/W |
| Junction-to-board thermal resistance, Θ _{JB} | High-K board(=) | | 85.3 | | -C/VV |
| Junction-to-case thermal resistance, Θ _{IC} | D PW | | 45.4 | | °C/W |
| Junction-to-case thermal resistance, GJC | | | 34.7 | | C/VV |
| Device power dissipation, PD | $ \begin{array}{l} {\sf EN=V_{CC},\overline{EN}=GND,R_L=50\Omega,} \\ {\sf Input100MHz50\%dutycyclesquarewaveto} \\ {\sf alldatainputs,T_A=85^\circ C} \end{array} $ | | | 288.5 | mW |

⁽¹⁾ In accordance with the Low-K thermal metric difinitions of EIA/JESD51-3.

ELECTRICAL CHARACTERISTICS

over recommended operating conditions unless otherwise noted

| | PARAMETER | | TEST CONDITIONS | | TYP(1) | MAX | UNIT |
|----|------------------|-----------------|--|--|--------|-----|------|
| | - Cumple ourrent | Driver enabled | EN = V_{CC} , \overline{EN} = GND, R_L = 50 Ω , All data inputs = V_{CC} or GND | | 59 | 70 | A |
| ıC | C Supply current | Driver disabled | $EN = GND$, $\overline{EN} = V_{CC}$, $R_L = No load$, All data inputs = V_{CC} or GND | | 2 | 4 | mA |

⁽¹⁾ All typical values are at 25°C and with a 3.3-V supply voltage.

⁽²⁾ In accordance with the High-K thermal metric difinitions of EIA/JESD51-7.



ELECTRICAL CHARACTERISTICS

over recommended operating conditions unless otherwise noted

| | PARAMETER | TEST CONDITIONS | MIN(1) | TYP(2) | MAX | UNIT |
|----------------------------------|--|---|----------------------|--------|---------------------|------|
| LVTTL (EN, | EN, 1A:4A) | | • | | ' | |
| IIIII | High-level input current | V _{IH} = 2 V or V _{CC} | 0 | | 10 | μΑ |
| I _{IL} | Low-level input current | V _{IL} = GND or 0.8 V | 0 | | 10 | μΑ |
| Ci | Input capacitance | $V_I = 0.4 \sin(30E6\pi t) + 0.5 V(3)$ | | 5 | | pF |
| M-LVDS (1Y | /1Z:4Y/4Z) | | | | | |
| $ v_{YZ} $ | Differential output voltage magnitude | | 480 | | 650 | mV |
| $\Delta V_{YZ} $ | Change in differential output voltage magnitude between logic states | See Figure 2 | -50 | | 50 | mV |
| Vos(ss) | Steady-state common-mode output voltage | | 0.8 | | 1.2 | V |
| ΔV _{OS(SS)} | Change in steady-state common-mode output voltage between logic states | See Figure 3 | -50 | | 50 | mV |
| VOS(PP) | Peak-to-peak common-mode output voltage | | | | 150 | mV |
| VY(OC) | Maximum steady-state open-circuit output voltage | Con Figure 7 | 0 | | 2.4 | V |
| VZ(OC) | Maximum steady-state open-circuit output voltage | See Figure 7 | 0 | | 2.4 | V |
| V _{P(H)} | Voltage overshoot, low-to-high level output | Can Figure 5 | | | 1.2 V _{SS} | V |
| V _{P(L)} | Voltage overshoot, high-to-low level output | See Figure 5 | -0.2 V _{SS} | | | V |
| I _{OS} | Differential short-circuit output current magnitude | See Figure 4 | | | 24 | mA |
| loz | High-impedance state output current | $-1.4 \text{ V} \le (\text{V} \text{ or V} \text{Z}) \le 3.8 \text{ V},$ Other output = 1.2 V | -15 | | 10 | μΑ |
| IO(OFF) | Power-off output current | $-1.4 \text{ V} \le (\text{V} \text{Y or V} \text{Z}) \le 3.8 \text{ V},$ Other output = 1.2 V, $\text{V}_{CC} = 1.5 \text{ V}$ | -10 | | 10 | μА |
| C _Y or C _Z | Output capacitance | V_Y or V_Z = 0.4 sin(30E6πt) + 0.5 V, (3) Other outputs at 1.2 V, driver disabled | | 3 | | pF |
| CYZ | Differential output capacitance | V _{YZ} = 0.4 sin(30E6πt) V, (3) Driver disabled | | | 2.5 | pF |
| C _{Y/Z} | Output capacitance balance, (CY/CZ) | | 0.99 | | 1.01 | |

⁽¹⁾ The algebraic convention, in which the least positive (most negative) limit is designated as minimum is used in this data sheet.
(2) All typical values are at 25°C and with a 3.3-V supply voltage.
(3) HP4194A impedance analyzer (or equivalent)



SWITCHING CHARACTERISTICS

over recommended operating conditions unless otherwise noted

| | PARAMETER | TEST CONDITIONS | MIN | TYP(1) | MAX | UNIT |
|--------------------|--|--|-----|--------|-----|------|
| ^t pLH | Propagation delay time, low-to-high-level output | | 1 | 1.5 | 2.4 | ns |
| tpHL | Propagation delay time, high-to-low-level output | | 1 | 1.5 | 2.4 | ns |
| t _r | Differential output signal rise time | | 1 | | 1.9 | ns |
| tf | Differential output signal fall time | See Figure 5 | 1 | | 1.9 | ns |
| tsk(o) | Output skew(2) | | | | 100 | ps |
| t _{sk(p)} | Pulse skew (tpHL - tpLH) | | | 22 | 100 | ps |
| tsk(pp) | Part-to-part skew(3) | | | | 600 | ps |
| tjit(per) | Period jitter, rms (1 standard deviation) ⁽⁴⁾ | See Figure 8, All data inputs 100 MHz clock input | | 0.2 | 1 | ps |
| tjit(c-c) | Cycle-to-cycle jitter(4) | See Figure 8, All data inputs 100 MHz clock input | | 5 | 36 | ps |
| tjit(pp) | Peak-to-peak jitter(3)(5) | See Figure 8, All data inputs 200 Mbps 2 ¹⁵ –1 PRBS input | | 46 | 158 | ps |
| ^t pZH | Enable time, high-impedance-to-high-level output | See Figure 6 | | | 9 | ns |
| tpZL | Enable time, high-impedance-to-low-level output | See Figure 6 | | | 9 | ns |
| t _{pHZ} | Disable time, high-level-to-high-impedance output | See Figure 6 | | | 10 | ns |
| tpLZ | Disable time, low-level-to-high-impedance output | See Figure 6 | | | 10 | ns |

⁽¹⁾ All typical values are at 25°C and with a 3.3-V supply voltage.

 ⁽²⁾ t_{sk(o)}, output skew is the magnitude of the time difference in propagation delay times between any specified terminals of a device.
 (3) t_{sk(pp)} is the magnitude of the difference in propagation delay times between any specified terminals of two devices when both devices operate with the same supply voltages, at the same temperature, and have identical packages and test circuits.
 (4) Stimulus jitter has been subtracted from the measurements.

⁽⁵⁾ Peak-to-peak jitter includes jitter due to pulse skew $(t_{sk(p)})$.



PARAMETER MEASUREMENT INFORMATION

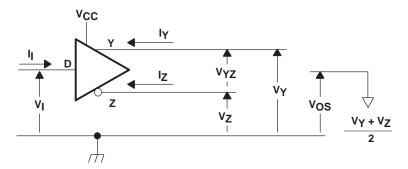
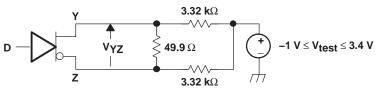
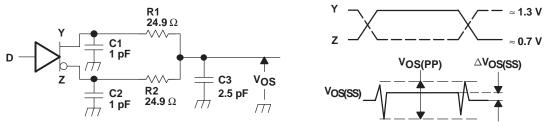


Figure 1. Driver Voltage and Current Definitions



NOTE: All resistors are 1% tolerance.

Figure 2. Differential Output Voltage Test Circuit



- NOTES:A. All input pulses are supplied by a generator having the following characteristics: t_{Γ} or $t_{\tilde{f}} \le 1$ ns, pulse frequency = 500 kHz, duty cycle = $50 \pm 5\%$.
 - B. C1, C2 and C3 include instrumentation and fixture capacitance within 2 cm of the D.U.T. and are ±20%.
 - C. R1 and R2 are metal film, surface mount, ±1%, and located within 2 cm of the D.U.T.
 - D. The measurement of VOS(PP) is made on test equipment with a -3 dB bandwidth of at least 1 GHz.

Figure 3. Test Circuit and Definitions for the Common-Mode Output Voltage

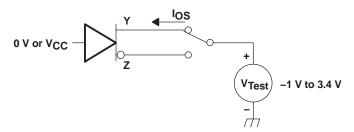
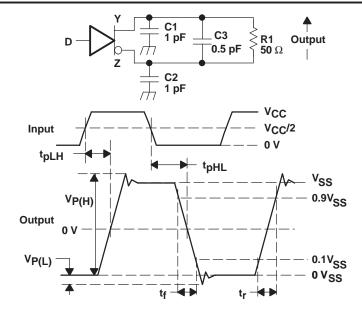


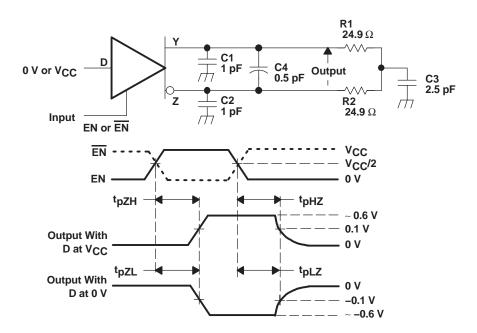
Figure 4. Short-Circuit Test Circuit





- NOTES:A. All input pulses are supplied by a generator having the following characteristics: t_{Γ} or $t_{f} \le 1$ ns, frequency = 500 kHz, duty cycle = $50 \pm 5\%$.
 - B. C1, C2, and C3 include instrumentation and fixture capacitance within 2 cm of the D.U.T. and are ±20%.
 - C. R1 is a metal film, surface mount, and 1% tolerance and located within 2 cm of the D.U.T.
 - D. The measurement is made on test equipment with a -3 dB bandwidth of at least 1 GHz.

Figure 5. Driver Test Circuit, Timing, and Voltage Definitions for the Differential Output Signal



- NOTES:A. All input pulses are supplied by a generator having the following characteristics: t_{Γ} or $t_{\tilde{f}} \le 1$ ns, frequency = 500 kHz, duty cycle = 50 ± 5%.
 - B. C1, C2, C3, and C4 includes instrumentation and fixture capacitance within 2 cm of the D.U.T. and are $\pm 20\%$.
 - C. R1 and R2 are metal film, surface mount, and 1% tolerance and located within 2 cm of the D.U.T.
 - D. The measurement is made on test equipment with a -3 dB bandwidth of at least 1 GHz.

Figure 6. Driver Enable and Disable Time Circuit and Definitions



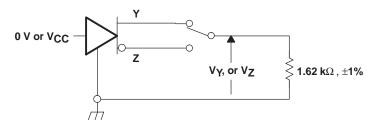
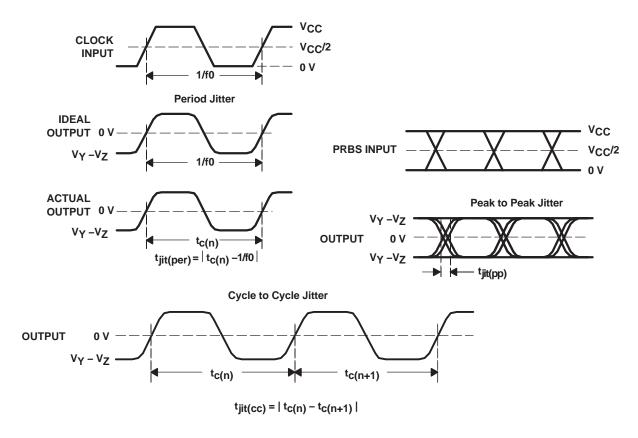


Figure 7. Driver Maximum Steady State Output Voltage



NOTES:A. All input pulses are supplied by an Agilent 8304A Stimulus System.

- B. The measurement is made on a TEK TDS6604 running TDSJIT3 application software
- C. Period jitter and cycle-to-cycle jitter are measured using a 100 MHz 50 \pm 1% duty cycle clock input.
- D. Peak-to-peak jitter is measured using a 200 Mbps 2¹⁵–1 PRBS input.

Figure 8. Driver Jitter Measurement Waveforms

DEVICE INFORMATION PIN ASSIGNMENTS

| 1A 2 15 1Y 1A 2 15 1Y 2A 3 14 2Y 2A 3 14 2Y VCC 4 13 2Z VCC 4 13 2Z GND 5 12 3Z GND 5 12 3Z 3A 6 11 3Y 3A 6 11 3Y 4A 7 10 4Y 4A 7 10 4Y | | D PACKAGE (TOP VIEW) | | | PW PACKAGE (TOP VIEW) | |
|---|----|--------------------------------------|----------------------|------------------------------|--------------------------------------|--|
| | 1A | 2 15 3 14 4 13 5 12 6 11 | 1Y 2Y 2Z 3Z 3Z 3Y 4Y | 1A 2A VCC GND 3A | 2 15 3 14 4 13 5 12 6 11 | 1Z 1Y 2Y 2Z 3Z 3Z 3Y 4Y 4Y |



DEVICE FUNCTION TABLE

| | INPUTS | OUT | PUTS | |
|------|-----------|-----------|------|---|
| D | EN | EN | Υ | Z |
| L | Н | L | L | Н |
| Н | Н | L | Н | L |
| OPEN | Н | L | L | Н |
| X | L or OPEN | X | Z | Z |
| X | X | H or OPEN | Z | Z |

DRIVER OUTPUT

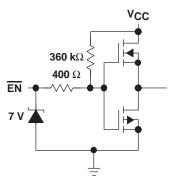
H = high level, L = low level, Z = high impedance, X = Don't care

EQUIVALENT INPUT AND OUTPUT SCHEMATIC DIAGRAMS

DRIVER INPUT AND POSITIVE DRIVER ENABLE

D or EN $\frac{400 \,\Omega}{360 \,\mathrm{k}\Omega}$

NEGATIVE DRIVER ENABLE





TYPICAL CHARACTERISTICS

RMS SUPPLY CURRENT INPUT FREQUENCY 80 $V_{CC} = 3.3 V$ $T_A = 25^{\circ}C$ EN = VCC, 75 ICC - Supply Current - mArms $\overline{\mathsf{EN}} = \mathsf{GND},$ $R_L = 50 \Omega$, **All Inputs** 70 65 60 55 50 25 100 125 f - Input Frequency - MHz

Figure 9

DIFFERENTIAL OUTPUT VOLTAGE MAGNITUDE

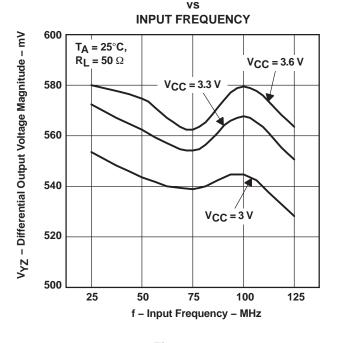


Figure 11

RMS SUPPLY CURRENT FREE-AIR TEMPERATURE

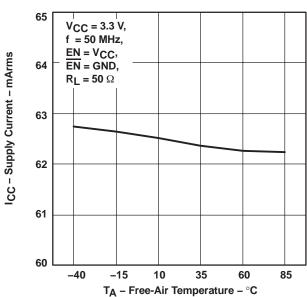


Figure 10

DRIVER PROPAGATION DELAY TIME

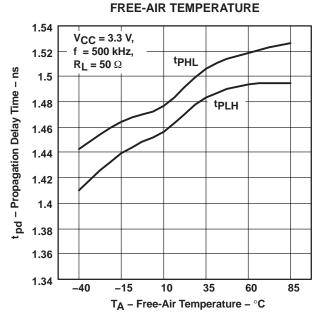


Figure 12



TYPICAL CHARACTERISTICS

DRIVER TRANSITION TIME FREE-AIR TEMPERATURE 1.8 t_r or t_f – Rising or Falling Transition Time – ns $V_{CC} = 3.3 V$ f = 500 kHz, $R_L = 50 \Omega$ 1.7 tf 1.6 t_{r} 1.5 1.4 1.3 1.2 -40 -15 10 35 60 85

Figure 13

 T_A – Free-Air Temperature – $^{\circ}C$

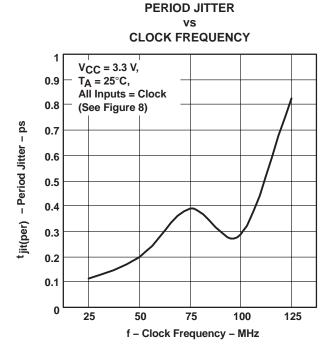


Figure 15

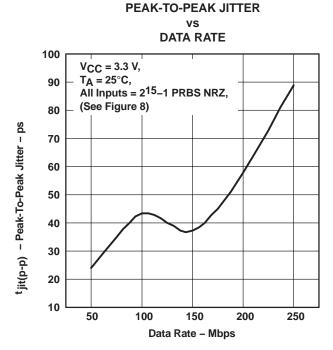


Figure 14

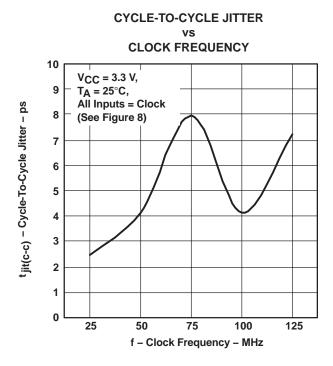


Figure 16



APPLICATION INFORMATION

SYNCHRONIZATION CLOCK IN ADVANCEDTCA

Advanced Telecommunications Computing Architecture, also known as AdvancedTCA, is an open architecture to meet the needs of the rapidly changing communications network infrastructure. M–LVDS bused clocking is recommended by the ATCA.

The ATCA specification includes requirements for three redundant clock signals. An 8-KHz and a 19.44-MHz clock signal, as well as an user-defined clock signal are included in the specification. The SN65MLVD047A quad driver supports distribution of these three ATCA clock signals, supporting operation beyond 100 MHz, which is the highest clock frequency included in the ATCA specification. A pair of SN65MLVD047A devices can be used to support the ATCA redundancy requirements.

MULTIPOINT CONFIGURATION

The SN65MLVD047A is designed to meet or exceed the requirement of the TIA/EIA-899 (M-LVDS) standard, which allows multipoint communication on a shared bus.

Multipoint is a bus configuration with multiple drivers and receivers present. An example is shown in Figure 17. The figure shows transceivers interfacing to the bus, but a combination of drivers, receivers, and transceivers is also possible. Termination resistors need to be placed on each end of the bus, with the termination resistor value matched to the loaded bus impedance.

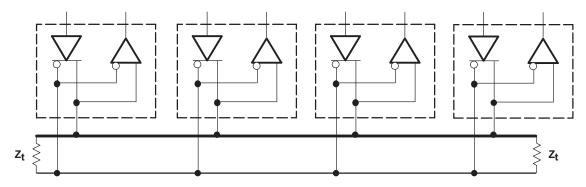


Figure 17. Multipoint Architecture

MULTIDROP CONFIGURATION

Multidrop configuration is similar to multipoint configuration, but only one driver is present on the bus. A multidrop system can be configured with the driver at one end of the bus, or in the middle of the bus. When a driver is located at one end, a single termination resistor is located at the far end, close to the last receiver on the bus. Alternatively, the driver can be located in the middle of the bus, to reduce the maximum flight time. With a centrally located driver, termination resistors are located at each end of the bus. In both cases the termination resistor value should be matched to the loaded bus impedance. Figure 18 shows examples of both cases.



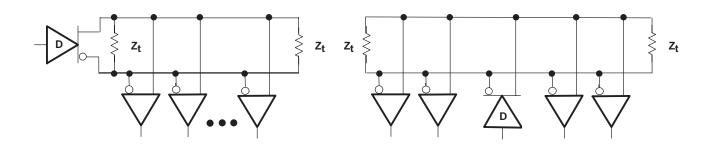


Figure 18. Multidrop Architectures With Different Driver Locations

UNUSED CHANNEL

The SN65MLVD047A is designed to meet or exceed the requirement of the TIA/EIA–899 (M–LVDS) standard, which allows multipoint communication on a standard bus. A 360-k Ω pull-down resistor is built in every LVTTL input. The unused driver inputs and outputs may be left floating.



6-Dec-2006



UMENTS

PACKAGING INFORMATION

| Orderable Device | Status ⁽¹⁾ | Package Type | Package Drawing | Pins | Package Qty | e Eco Plan ⁽²⁾ | Lead/Ball Finish | MSL Peak Temp ⁽³⁾ |
|-------------------|-----------------------|-----------------|--------------------|------|----------------|---------------------------|------------------|------------------------------|
| SN65MLVD047AD | ACTIVE | SOIC | D | 16 | 40 | Green (RoHS & no Sb/Br) | CU NIPDAU | Level-1-260C-UNLIM |
| SN65MLVD047ADG4 | ACTIVE | SOIC | D | 16 | 40 | Green (RoHS & no Sb/Br) | CU NIPDAU | Level-1-260C-UNLIM |
| SN65MLVD047ADR | ACTIVE | SOIC | D | 16 | 2500 | Green (RoHS & no Sb/Br) | CU NIPDAU | Level-1-260C-UNLIM |
| SN65MLVD047ADRG4 | ACTIVE | SOIC | D | 16 | 2500 | Green (RoHS & no Sb/Br) | CU NIPDAU | Level-1-260C-UNLIM |
| SN65MLVD047APW | ACTIVE | TSSOP | PW | 16 | 90 | Green (RoHS & no Sb/Br) | CU NIPDAU | Level-1-260C-UNLIM |
| SN65MLVD047APWG4 | ACTIVE | TSSOP | PW | 16 | 90 | Green (RoHS & no Sb/Br) | CU NIPDAU | Level-1-260C-UNLIM |
| SN65MLVD047APWR | ACTIVE | TSSOP | PW | 16 | 2000 | Green (RoHS & no Sb/Br) | CU NIPDAU | Level-1-260C-UNLIM |
| SN65MLVD047APWRG4 | ACTIVE | TSSOP | PW | 16 | 2000 | Green (RoHS & no Sb/Br) | CU NIPDAU | Level-1-260C-UNLIM |

⁽¹⁾ The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined.

Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

Pb-Free (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

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TAPE AND REEL INFORMATION





| Α | 0 | Dimension designed to accommodate the component width |
|----|---|---|
| В | 0 | Dimension designed to accommodate the component length |
| | | Dimension designed to accommodate the component thickness |
| ٧ | ٧ | Overall width of the carrier tape |
| ГР | 1 | Pitch between successive cavity centers |

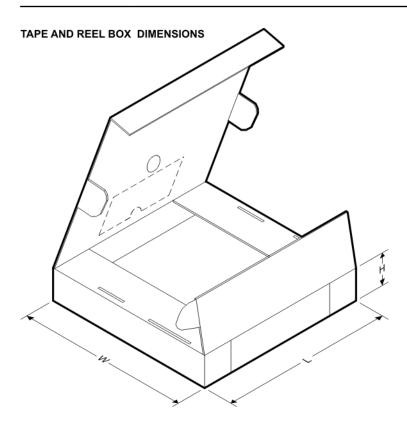
QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal

| Device | | Package Drawing | | | Reel Diameter (mm) | Reel Width W1 (mm) | A0 (mm) | B0 (mm) | K0 (mm) | P1 (mm) | W (mm) | Pin1 Quadrant |
|----------------|------|--------------------|----|------|--------------------------|--------------------------|---------|---------|---------|------------|-----------|------------------|
| SN65MLVD047ADR | SOIC | D | 16 | 2500 | 330.0 | 16.4 | 6.5 | 10.3 | 2.1 | 8.0 | 16.0 | Q1 |





*All dimensions are nominal

| ĺ | Device | Package Type | Package Drawing | Pins | SPQ | Length (mm) | Width (mm) | Height (mm) |
|---|----------------|--------------|-----------------|------|------|-------------|------------|-------------|
| I | SN65MLVD047ADR | SOIC | D | 16 | 2500 | 346.0 | 346.0 | 33.0 |

PW (R-PDSO-G**)

14 PINS SHOWN

PLASTIC SMALL-OUTLINE PACKAGE



NOTES: A. All linear dimensions are in millimeters.

B. This drawing is subject to change without notice.

C. Body dimensions do not include mold flash or protrusion not to exceed 0,15.

D. Falls within JEDEC MO-153

D (R-PDSO-G16)

PLASTIC SMALL-OUTLINE PACKAGE



NOTES:

- A. All linear dimensions are in inches (millimeters).
- B. This drawing is subject to change without notice.
- Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed .006 (0,15) per end.
- Body width does not include interlead flash. Interlead flash shall not exceed .017 (0,43) per side.
- E. Reference JEDEC MS-012 variation AC.



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