

TPA6111A2

SLOS313B-DECEMBER 2000-REVISED JUNE 2004

150-mW STEREO AUDIO POWER AMPLIFIER

FEATURES

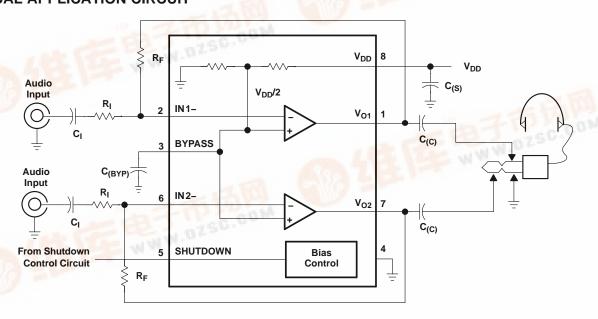
- 150-mW Stereo Output
- PC Power Supply Compatible
 - Fully Specified for 3.3-V and 5-V Operation
 - Operation to 2.5 V
- Pop Reduction Circuitry
- Internal Midrail Generation
- Thermal and Short-Circuit Protection
- Surface-Mount Packaging
 - PowerPAD™ MSOP
 - SOIC
- Pin Compatible With TPA122, LM4880, and LM4881 (SOIC)

DESCRIPTION

The TPA6111A2 is a stereo audio power amplifier packaged in either an 8-pin SOIC or an 8-pin PowerPADTM MSOP package capable of delivering 150 mW of continuous RMS power per channel into $16-\Omega$ loads. Amplifier gain is externally configured by means of two resistors per input channel and does not require external compensation for settings of 0 to 20 dB.

THD+N, when driving a 16- Ω load from 5 V, is 0.03% at 1 kHz, and less than 1% across the audio band of 20 Hz to 20 kHz. For 32- Ω loads, the THD+N is reduced to less than 0.02% at 1 kHz, and is less than 1% across the audio band of 20 Hz to 20 kHz. For 10-k Ω loads, the THD+N performance is 0.005% at 1 kHz, and less than 0.5% across the audio band of 20 Hz to 20 kHz.

TYPICAL APPLICATION CIRCUIT



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.





These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

AVAILABLE OPTIONS

	PACKAGED DEVI	CES	Meon
T _A	SMALL OUTLINE ⁽¹⁾ (D)	MSOP ⁽¹⁾ (DGN)	MSOP SYMBOLIZATION
-40°C to 85°C	TPA6111A2D	TPA6111A2DGN	TI AJA

 The D and DGN package is available in left-ended tape and reel only (e.g., TPA6111A2DR, TPA6111A2DGNR).

Terminal Functions

TERMINA	AL	1/0	DESCRIPTION
NAME	NO.	1/0	DESCRIPTION
BYPASS	3	I	Tap to voltage divider for internal mid-supply bias supply. Connect to a 0.1-μF to 1-μF low ESR capacitor for best performance.
GND	4	I	GND is the ground connection.
IN1-	2	I	IN1– is the inverting input for channel 1.
IN2-	6	I	IN2– is the inverting input for channel 2.
SHUTDOWN	5	I	Puts the device in a low quiescent current mode when held high
V_{DD}	8	I	V _{DD} is the supply voltage terminal.
V _{O1}	1	0	V _{O1} is the audio output for channel 1.
V _{O2}	7	0	V _{O2} is the audio output for channel 2.

ABSOLUTE MAXIMUM RATINGS

over operating free-air temperature range (unless otherwise noted) (1)

		UNIT
V_{DD}	Supply voltage	6 V
VI	Input voltage	-0.3 V to V _{DD} + 0.3 V
	Continuous total power dissipation	internally limited
T_J	Operating junction temperature range	-40°C to 150°C
T _{stg}	Storage temperature range	-65°C to 150°C
	Lead temperature 1,6 mm (1/16 inch) from case for 10 seconds	260°C

⁽¹⁾ Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

DISSIPATION RATING TABLE

PACKAGE	$T_A \le 25^{\circ}C$ POWER RATING	DERATING FACTOR ABOVE T _A = 25°C	T _A = 70°C POWER RATING	T _A = 85°C POWER RATING
D	725 mW	5.8 mW/°C	464 mW	377 mW
DGN	2.14 W ⁽¹⁾	17.1 mW/°C	1.37 W	1.11 W

(1) See the Texas Instruments document, PowerPAD Thermally Enhanced Package Application Report (literature number SLMA002), for more information on the PowerPAD package. The thermal data was measured on a PCB layout based on the information in the section entitled Texas Instruments Recommended Board for PowerPAD on page 33 of the before-mentioned document.



RECOMMENDED OPERATING CONDITIONS

		MIN	MAX	UNIT
V_{DD}	Supply voltage	2.5	5.5	٧
T _A	Operating free-air temperature	-40	85	°C
V _{IH}	High-level input voltage (SHUTDOWN)	60% x V _{DD}		V
V _{IL}	Low-level input voltage (SHUTDOWN)		25% x V _{DD}	V

DC ELECTRICAL CHARACTERISTICS

at V_{DD} = 3.3 V, T_A = 25°C (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Voo	Output offset voltage				10	mV
PSRR	Power supply rejection ratio	V _{DD} = 3.2 V to 3.4 V		70		dB
I _{DD}	Supply current	SHUTDOWN (pin 5) = 0 V		1.5	3	mA
I _{DD(SD)}	Supply current in shutdown mode	SHUTDOWN (pin 5) = V _{DD}		1	10	μΑ
Z _i	Input impedance			> 1		$M\Omega$

AC OPERATING CHARACTERISTICS

 V_{DD} = 3.3 V, T_A = 25°C, R_L = 16 Ω

	PARAMETER	TEST CONDITIONS	MIN TYP MA	XX UNIT
Po	Output power (each channel)	THD ≤ 0.1%, f = 1 kHz	60	mW
THD+N	Total harmonic distortion + noise	$P_0 = 40 \text{ mW}, 20 \text{ Hz} - 20 \text{ kHz}$	0.4%	
B _{OM}	Maximum output power BW	G = 20 dB, THD < 5%	> 20	kHz
	Phase margin	Open loop	96°	
	Supply ripple rejection	f = 1 kHz, C _(BYP) = 0.47 μF	71	dB
	Channel/channel output separation	f = 1 kHz, P _O = 40 mW	89	dB
SNR	Signal-to-noise ratio	P _O = 50 mW, A _V = 1	100	dB
V _n	Noise output voltage	A _V = 1	11	μV(rms)

DC ELECTRICAL CHARACTERISTICS

at $V_{DD} = 5.5 \text{ V}$, $T_A = 25^{\circ}\text{C}$

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Voo	Output offset voltage				10	mV
PSRR	Power supply rejection ratio	V _{DD} = 4.9 V to 5.1 V		70		dB
I _{DD}	Supply current	SHUTDOWN (pin 5) = 0 V		1.6	3.2	mA
I _{DD(SD)}	Supply current in shutdown mode	SHUTDOWN (pin 5) = V _{DD}		1	10	μΑ
I _{IH}	High-level input current (SHUTDOWN)	$V_{DD} = 5.5 \text{ V}, V_{I} = V_{DD}$			1	μΑ
$ I_{1L} $	Low-level input current (SHUTDOWN)	$V_{DD} = 5.5 \text{ V}, V_{I} = 0 \text{ V}$			1	μΑ
Z _i	Input impedance			> 1		$M\Omega$



AC OPERATING CHARACTERISTICS

 $V_{DD} = 5 \text{ V}, T_A = 25^{\circ}\text{C}, R_L = 6 \Omega$

	PARAMETER	TEST CONDITIONS	MIN TY	P MAX	UNIT
Po	Output power (each channel)	THD ≤ 0.1%, f = 1 kHz	15	50	mW
THD+N	Total harmonic distortion + noise	P _O = 100 mW, 20 Hz – 20 kHz	0.6	%	
Вом	Maximum output power BW	G = 20 dB, THD < 5%	> 2	20	kHz
	Phase margin	Open loop	9	6°	
	Supply ripple rejection ratio	$f = 1 \text{ kHz}, C_{(BYP)} = 0.47 \mu F$	(61	dB
	Channel/channel output separation	f = 1 kHz, P _O = 100 mW	9	90	dB
SNR	Signal-to-noise ratio	P _O = 100 mW, A _V = 1	10	00	dB
V _n	Noise output voltage	A _V = 1	11	.7	μV(rms)

AC OPERATING CHARACTERISTICS

 $V_{DD} = 3.3 \text{ V}, T_A = 25^{\circ}\text{C}, R_L = 32 \Omega$

	PARAMETER	TEST CONDITIONS	MIN TYP	MAX	UNIT
Po	Output power (each channel)	THD ≤ 0.1%, f = 1 kHz	35		mW
THD+N	Total harmonic distortion + noise	P _O = 40 mW, 20 Hz – 20 kHz	0.4%		
B _{OM}	Maximum output power BW	G = 20 dB, THD < 2%	> 20		kHz
	Phase margin	Open loop	96°		
	Supply ripple rejection	f = 1 kHz, C _(BYP) = 0.47 μF	71		dB
	Channel/channel output separation	f = 1 kHz, P _O = 25 mW	75		dB
SNR	Signal-to-noise ratio	$P_{O} = 90 \text{ mW}, A_{V} = 1$	100		dB
V _n	Noise output voltage	A _V = 1	11		μV(rms)

AC OPERATING CHARACTERISTICS

 V_{DD} = 5 V, T_A = 25°C, R_L = 32 Ω

	PARAMETER	TEST CONDITIONS	MIN TYP	MAX	UNIT
Po	Output power (each channel)	THD ≤ 0.1%, f = 1 kHz	90		mW
THD+N	Total harmonic distortion + noise	P _O = 20 mW, 20 Hz – 20 kHz	2%		
B _{OM}	Maximum output power BW	G = 20 dB, THD < 2%	> 20		kHz
	Phase margin	Open loop	97°		
	Supply ripple rejection	$f = 1 \text{ kHz}, C_{(BYP)} = 0.47 \mu F$	61		dB
	Channel/channel output separation	f = 1 kHz, P _O = 65 mW	98		dB
SNR	Signal-to-noise ratio	$P_{O} = 90 \text{ mW}, A_{V} = 1$	104		dB
V _n	Noise output voltage	A _V = 1	11.7		μV(rms)



TYPICAL CHARACTERISTICS

Table of Graphs

			FIGURE
THD+N	Total harmonia distartian plus paisa	vs Frequency	1, 3, 5, 6, 7, 9, 11, 13,
I UD+N	Total harmonic distortion plus noise	vs Output power	2, 4, 8, 10, 12, 14
	Supply ripple rejection ratio	vs Frequency	15, 16
V _n	Output noise voltage	vs Frequency	17, 18
	Crosstalk	vs Frequency	19–24
	Shutdown attenuation	vs Frequency	25, 26
	Open-loop gain and phase margin	vs Frequency	27, 28
	Output power	vs Load resistance	29, 30
I _{DD}	Supply current	vs Supply voltage	31
SNR	Signal-to-noise ratio	vs Voltage gain	32
	Power dissipation/amplifier	vs Load power	33, 34

TOTAL HARMONIC DISTORTION + NOISE vs FREQUENCY

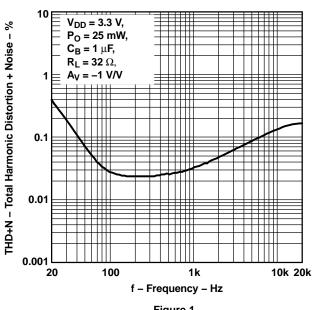


Figure 1.

TOTAL HARMONIC DISTORTION + NOISE vs OUTPUT POWER

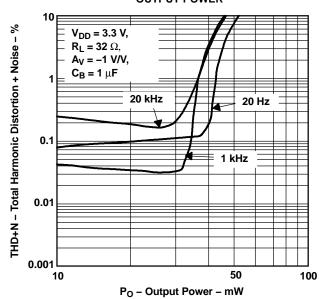


Figure 2.



TOTAL HARMONIC DISTORTION + NOISE vs FREQUENCY

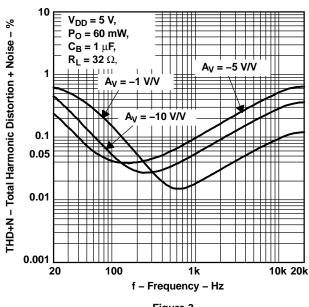
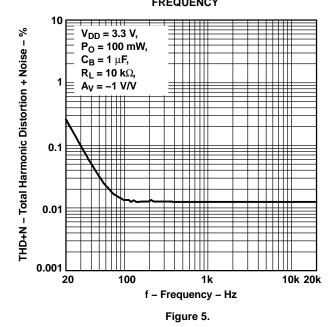


Figure 3.

TOTAL HARMONIC DISTORTION + NOISE vs FREQUENCY



TOTAL HARMONIC DISTORTION + NOISE vs OUTPUT POWER

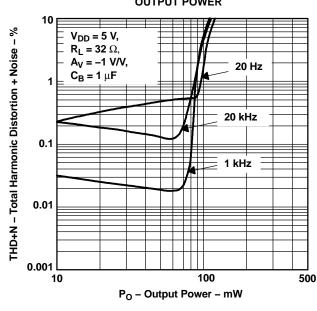


Figure 4.

TOTAL HARMONIC DISTORTION + NOISE vs FREQUENCY

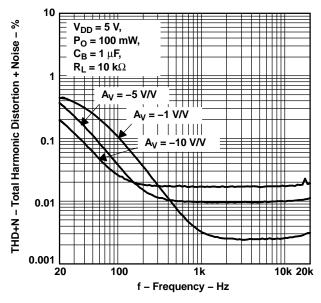
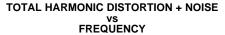


Figure 6.





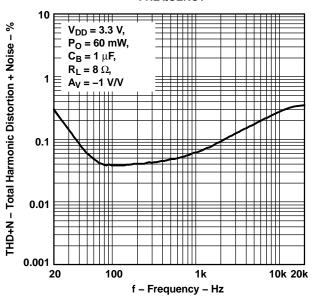


Figure 7.

TOTAL HARMONIC DISTORTION + NOISE vs FREQUENCY

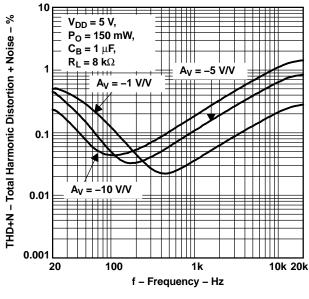


Figure 9.

TOTAL HARMONIC DISTORTION + NOISE vs OUTPUT POWER

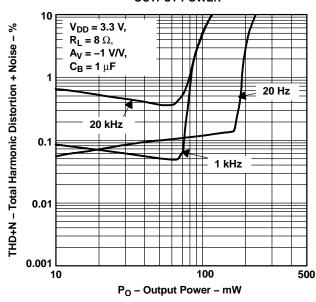


Figure 8.

TOTAL HARMONIC DISTORTION + NOISE vs OUTPUT POWER

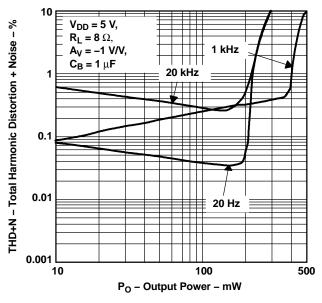
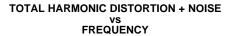


Figure 10.





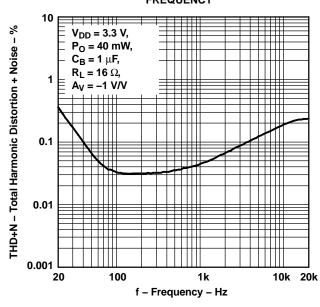


Figure 11.

TOTAL HARMONIC DISTORTION + NOISE vs OUTPUT POWER

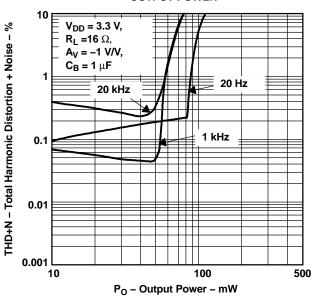
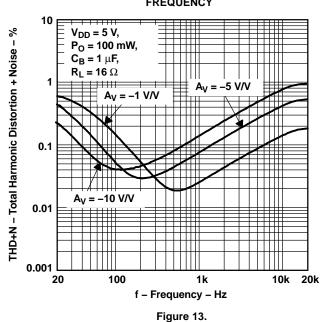


Figure 12.

TOTAL HARMONIC DISTORTION + NOISE vs FREQUENCY



TOTAL HARMONIC DISTORTION + NOISE

VS

OUTPUT POWER

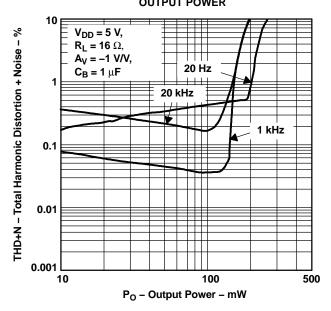
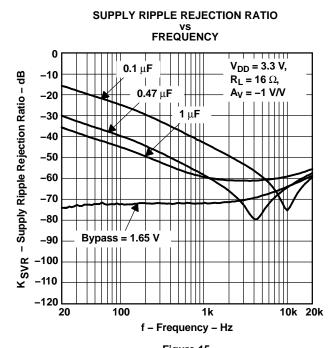
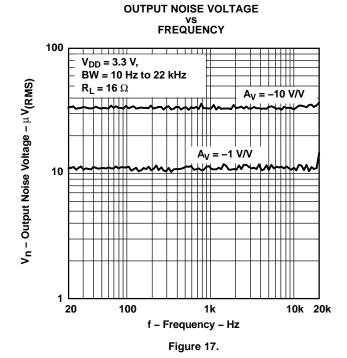


Figure 14.









SUPPLY RIPPLE REJECTION RATIO vs FREQUENCY

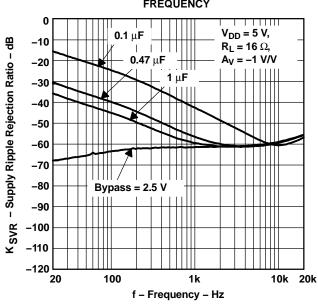


Figure 16.

OUTPUT NOISE VOLTAGE vs FREQUENCY

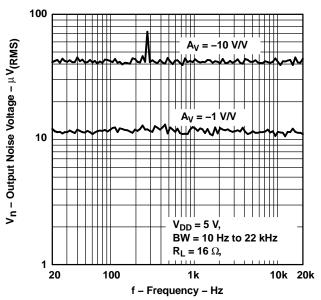
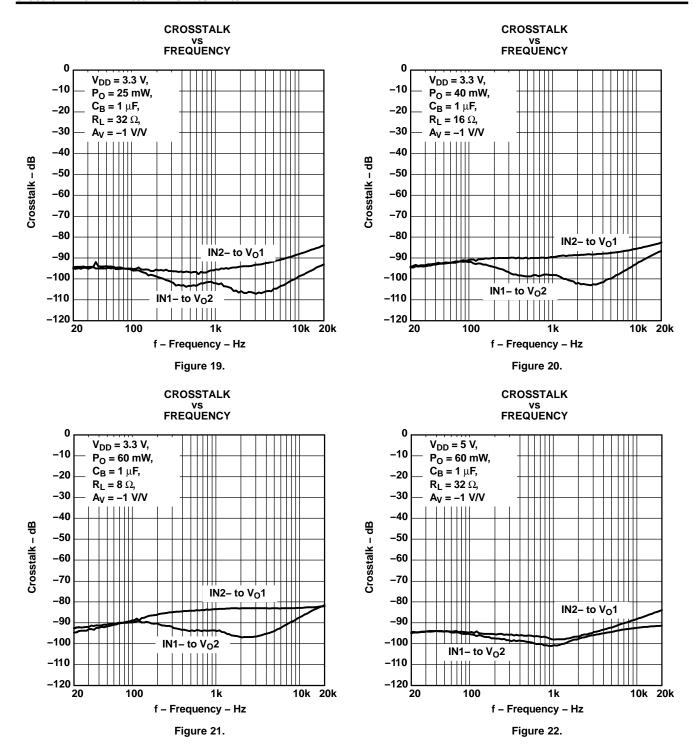
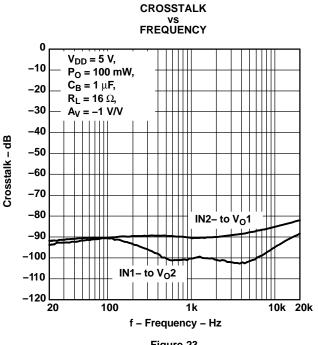


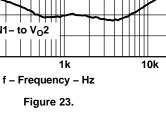
Figure 18.

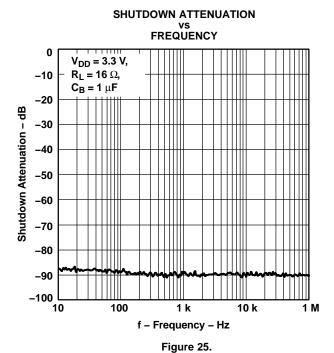


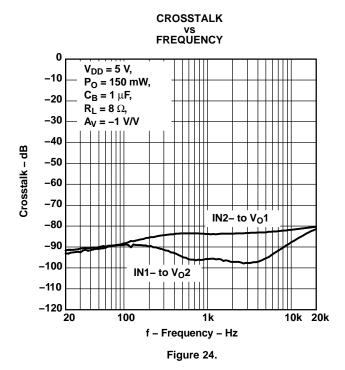


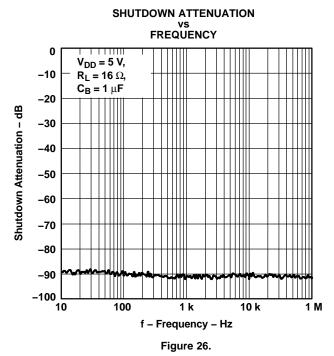










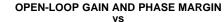




-150

-180

10 M



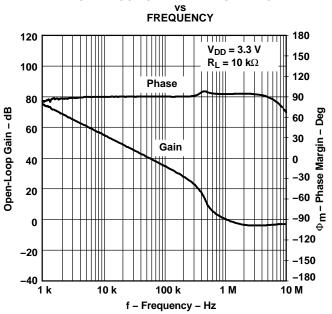


Figure 27.

vs FREQUENCY 180 120 $V_{DD} = 5 V$ 150 $R_L = 10 \text{ k}\Omega$ 100 Gain 120 80 90 Open-Loop Gain - dB 60 60 30 Phase 40 0 20 -60 -E -90 ⊕ 0 -120 -20

OPEN-LOOP GAIN AND PHASE MARGIN

Figure 28.

1 M

100 k

f - Frequency - Hz

-40

1 k

10 k

OUTPUT POWER vs LOAD RESISTANCE

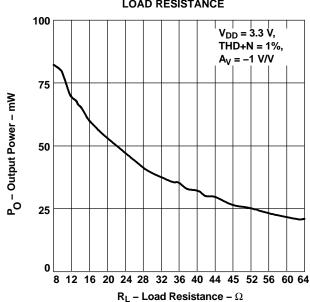


Figure 29.

OUTPUT POWER vs LOAD RESISTANCE

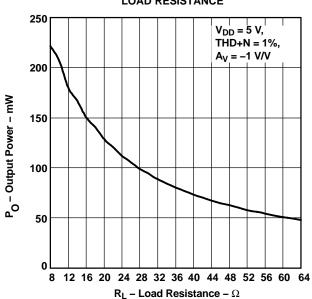
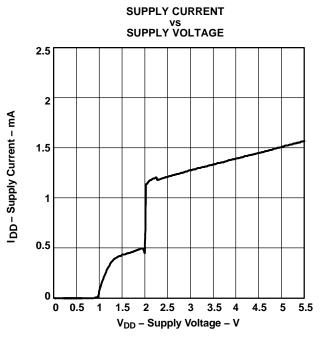


Figure 30.





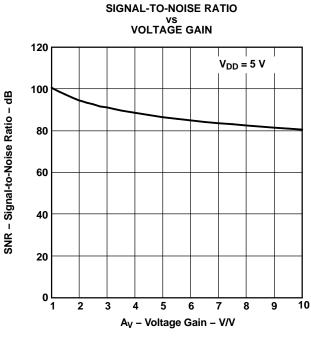
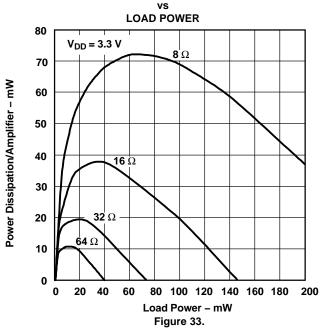


Figure 31.

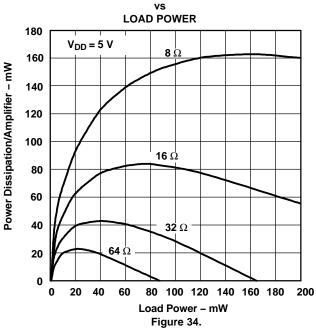
Figure 32.

POWER DISSIPATION/AMPLIFIER





POWER DISSIPATION/AMPLIFIER





APPLICATION INFORMATION

GAIN SETTING RESISTORS, R_F and R_i

The gain for the TPA6111A2 is set by resistors R_F and R_I according to Equation 1.

$$Gain = -\left(\frac{R_F}{R_I}\right) \tag{1}$$

Given that the TPA6111A2 is a MOS amplifier, the input impedance is high. Consequently, input leakage currents are not generally a concern, although noise in the circuit increases as the value of R_F increases. In addition, a certain range of R_F values is required for proper start-up operation of the amplifier. Taken together it is recommended that the effective impedance seen by the inverting node of the amplifier be set between 5 k Ω and 20 k Ω . The effective impedance is calculated in Equation 2.

Effective Impedance =
$$\frac{R_F R_I}{R_F + R_I}$$
 (2)

As an example, consider an input resistance of 20 k Ω and a feedback resistor of 20 k Ω . The gain of the amplifier would be -1 and the effective impedance at the inverting terminal would be 10 k Ω , which is within the recommended range.

For high-performance applications, metal film resistors are recommended because they tend to have lower noise levels than carbon resistors. For values of R_F above 50 $k\Omega$, the amplifier tends to become unstable due to a pole formed from R_F and the inherent input capacitance of the MOS input structure. For this reason, a small compensation capacitor of approximately 5 pF should be placed in parallel with R_F . In effect, this creates a low-pass filter network with the cutoff frequency defined in Equation 3.

$$f_{c(lowpass)} = \frac{1}{2\pi R_F C_F}$$
 (3)

For example, if R_F is 100 k Ω and C_F is 5 pF, then $f_{c(lowpass)}$ is 318 kHz, which is well outside the audio range.

INPUT CAPACITOR, Ci

In the typical application, input capacitor C_l is required to allow the amplifier to bias the input signal to the proper dc level for optimum operation. In this case, C_i and R_l form a high-pass filter with the corner frequency determined in Equation 4.

$$f_{c(highpass)} = \frac{1}{2\pi R_{I}C_{I}}$$
 (4)

The value of C_l is important to consider, as it directly affects the bass (low-frequency) performance of the circuit. Consider the example where R_l is 20 k Ω and the specification calls for a flat bass response down to 20 Hz. Equation 4 is reconfigured as Equation 5.

$$C_{l} = \frac{1}{2\pi R_{l} f_{c(highpass)}}$$
 (5)

In this example, C_l is 0.40 μ F, so one would likely choose a value in the range of 0.47 μ F to 1 μ F. A further consideration for this capacitor is the leakage path from the input source through the input network (R_l , C_l) and the feedback resistor (R_F) to the load. This leakage current creates a dc offset voltage at the input to the amplifier that reduces useful headroom, especially in high-gain applications (> 10). For this reason a low-leakage tantalum or ceramic capacitor is the best choice. When polarized capacitors are used, the positive side of the capacitor should face the amplifier input in most applications, as the dc level there is held at $V_{DD}/2$, which is likely higher than the source dc level. Note that it is important to confirm the capacitor polarity in the application.

APPLICATION INFORMATION (continued)

POWER SUPPLY DECOUPLING, C(S)

The TPA6111A2 is a high-performance CMOS audio amplifier that requires adequate power supply decoupling to ensure that the output total harmonic distortion (THD) is as low as possible. Power supply decoupling also prevents oscillations for long lead lengths between the amplifier and the speaker. The optimum decoupling is achieved by using two capacitors of different types that target different types of noise on the power supply leads. For higher frequency transients, spikes, or digital hash on the line, a good low equivalent-series-resistance (ESR) ceramic capacitor, typically 0.1 μ F, placed as close as possible to the device V_{DD} lead, works best. For filtering lower frequency noise signals, a larger aluminum electrolytic capacitor of 10 μ F or greater placed near the power amplifier is recommended.

MIDRAIL BYPASS CAPACITOR, C(BYP)

The midrail bypass capacitor, $C_{(BYP)}$, serves several important functions. During start-up, $C_{(BYP)}$ determines the rate at which the amplifier starts up. This helps to push the start-up pop noise into the subaudible range (so low it cannot be heard). The second function is to reduce noise produced by the power supply caused by coupling into the output drive signal. This noise is from the midrail generation circuit internal to the amplifier. The capacitor is fed from a 230-k Ω source inside the amplifier. To keep the start-up pop as low as possible, the relationship shown in Equation 6 should be maintained.

$$\frac{1}{\left(C_{(BYP)} \times 230 \text{ k}\Omega\right)} \le \frac{1}{\left(C_{I}R_{I}\right)} \tag{6}$$

As an example, consider a circuit where $C_{(BYP)}$ is 1 μ F, C_{I} is 1 μ F, and R_{I} is 20 $k\Omega$. Inserting these values into Equation 6 results in: $6.25 \le 50$ which satisfies the rule. Recommended values for bypass capacitor $C_{(BYP)}$ are 0.1 μ F, ceramic or tantalum low-ESR, for the best THD and noise performance.

OUTPUT COUPLING CAPACITOR, C(C)

In the typical single-supply single-ended (SE) configuration, an output coupling capacitor (C_C) is required to block the dc bias at the output of the amplifier, thus preventing dc currents in the load. As with the input coupling capacitor, the output coupling capacitor and impedance of the load form a high-pass filter governed by Equation 7.

$$f_{C} = \frac{1}{2\pi R_{L} C_{(C)}} \tag{7}$$

The main disadvantage, from a performance standpoint, is that the typically small load impedances drive the low-frequency corner higher. Large values of $C_{(C)}$ are required to pass low frequencies into the load. Consider the example where a $C_{(C)}$ of 68 μF is chosen and loads vary from 32 Ω to 47 $k\Omega$. Table 1 summarizes the frequency response characteristics of each configuration.

Table 1. Common Load Impedances vs Low Frequency
Output Characteristics in SE Mode

R _L	C _C	LOWEST FREQUENCY	
32 Ω	68 µF	73 Hz	
10,000 Ω	68 µF	0.23 Hz	
47,000 Ω	68 µF	0.05 Hz	

As Table 1 indicates, headphone response is adequate and drive into line level inputs (a home stereo for example) is good.



The output coupling capacitor required in single-supply SE mode also places additional constraints on the selection of other components in the amplifier circuit. With the rules described earlier still valid, add the following relationship:

$$\frac{1}{\left(C_{(BYP)} \times 230 \text{ k}\Omega\right)} \leq \frac{1}{\left(C_{I}R_{I}\right)} \ll \frac{1}{R_{L}C_{(C)}}$$
(8)

USING LOW-ESR CAPACITORS

Low-ESR capacitors are recommended throughout this application. A real capacitor can be modeled simply as a resistor in series with an ideal capacitor. The voltage drop across this resistor minimizes the beneficial effects of the capacitor in the circuit. The lower the equivalent value of this resistance, the more the real capacitor behaves like an ideal capacitor.

5-V VERSUS 3.3-V OPERATION

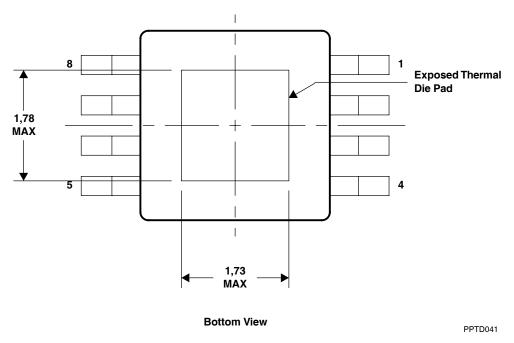
The TPA6111A2 was designed for operation over a supply range of 2.5 V to 5.5 V. This data sheet provides full specifications for 5-V and 3.3-V operation, since these are considered to be the two most common standard voltages. There are no special considerations for 3.3-V versus 5-V operation as far as supply bypassing, gain setting, or stability. The most important consideration is that of output power. Each amplifier in the TPA6111A2 can produce a maximum voltage swing of $V_{DD}-1$ V. This means, for 3.3-V operation, clipping starts to occur when $V_{O(PP)}=2.3$ V as opposed when $V_{O(PP)}=4$ V while operating at 5 V. The reduced voltage swing subsequently reduces maximum output power into the load before distortion begins to become significant.



THERMAL INFORMATION

The DGN PowerPAD™ package incorporates an exposed thermal die pad that is designed to be attached directly to an external heat sink. When the thermal die pad is soldered directly to the printed circuit board (PCB), the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal die pad can be attached directly to a ground plane or special heat sink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).

For additional information on the PowerPAD package and how to take advantage of its heat dissipating abilities, refer to Technical Brief, *PowerPAD Thermally Enhanced Package*, Texas Instruments Literature No. SLMA002 and Application Brief, *PowerPAD Made Easy*, Texas Instruments Literature No. SLMA004. Both documents are available at www.ti.com. See Figure 1 for DGN package exposed thermal die pad dimensions.



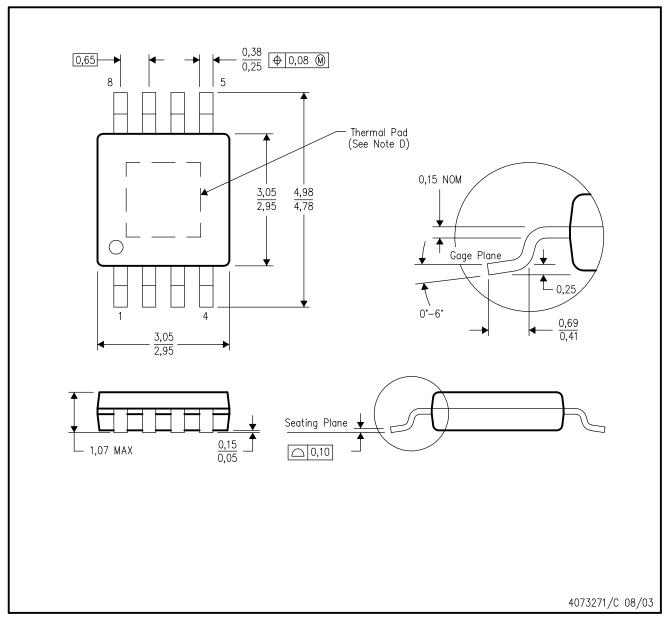
NOTE: All linear dimensions are in millimeters.

Figure 1. DGN Package Exposed Thermal Die Pad Dimensions

PowerPAD is a trademark of Texas Instruments.

DGN (S-PDSO-G8)

PowerPAD™ PLASTIC SMALL-OUTLINE PACKAGE



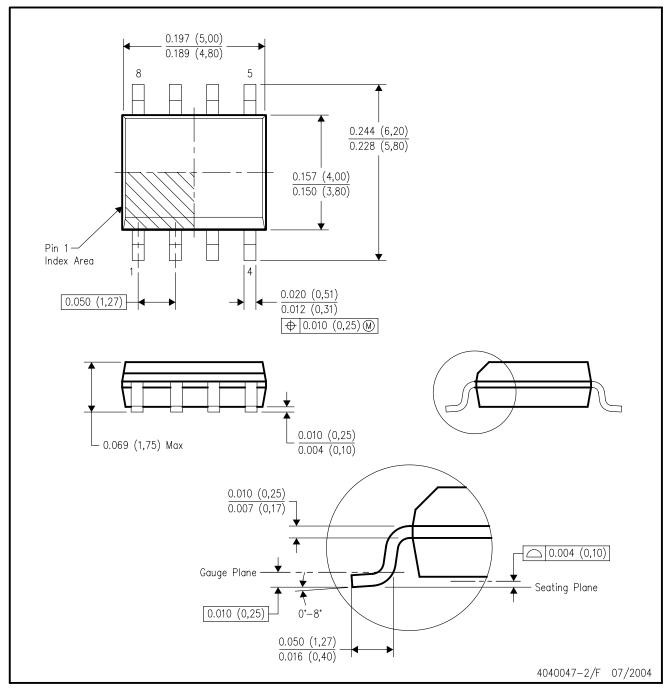
NOTES:

- A. All linear dimensions are in millimeters.
- B. This drawing is subject to change without notice.
- C. Body dimensions do not include mold flash or protrusion.
- D. This package is designed to be soldered to a thermal pad on the board. Refer to Technical Brief, PowerPad Thermally Enhanced Package, Texas Instruments Literature No. SLMA002 for information regarding recommended board layout. This document is available at www.ti.com https://www.ti.com.
- E. Falls within JEDEC MO-187

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D (R-PDSO-G8)

PLASTIC SMALL-OUTLINE PACKAGE



NOTES:

- A. All linear dimensions are in inches (millimeters).
- B. This drawing is subject to change without notice.
- C. Body dimensions do not include mold flash or protrusion not to exceed 0.006 (0,15).
- D. Falls within JEDEC MS-012 variation AA.



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