

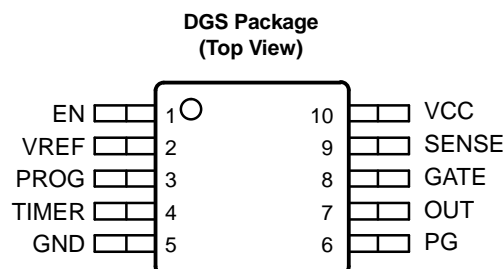
## POSITIVE HIGH-VOLTAGE POWER-LIMITING HOTSWAP CONTROLLER

### FEATURES

- Programmable Power Limiting and Current Limiting for Complete SOA Protection
- Wide Operating Range: +9 V to +80 V
- Latched Operation (TPS2490) and Automatic Retry (TPS2491)
- High-side Drive for Low- $R_{DS(on)}$  External N-channel MOSFET
- Programmable Fault Timer to Protect the MOSFET and Eliminate Nuisance Shutdowns
- Power Good Open-Drain Output for Down-stream DC/DC Coordination
- Enable can be used as a Programmable Undervoltage Lockout or Logic Control
- Small, Space-saving 10-pin MSOP Package

### APPLICATIONS

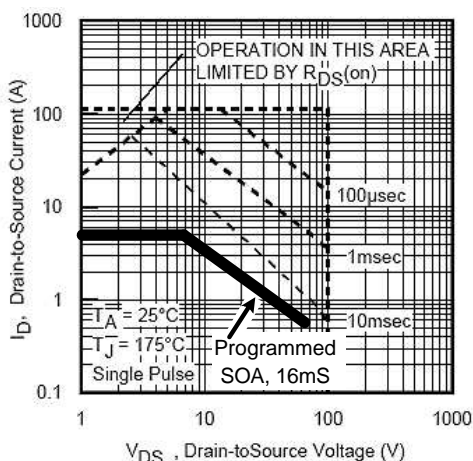
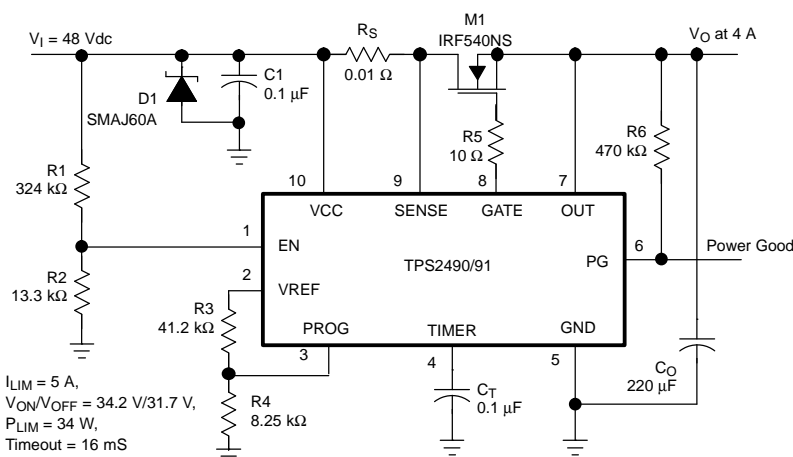
- Server Backplanes
- Storage Area Networks (SAN)
- Medical Systems
- Plug-in Modules
- Base Stations



### DESCRIPTION

The TPS2490 and TPS2491 are easy-to-use, positive high voltage, 10-pin Hot Swap Power Manager™ devices that safely drive an external N-channel MOSFET switch. The power limit and current limit (both are adjustable and independent of each other) ensure that the external MOSFET operates inside a selected safe operating area (SOA) under the harshest operating conditions. Applications include inrush current limiting, electronic circuit breaker protection, controlled load turn-on, interfacing to down-stream dc-to-dc converters, and power feed protection. These devices are available in a small, space-saving 10-pin MSOP package and significantly reduce the number of external devices, saving precious board space. The TPS2490/91 is supported by application notes, an evaluation module, and a design tool.

### Typical Application and Corresponding SOA



Hot Swap Power Manager is a trademark of Texas Instruments.



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

**ORDERING INFORMATION**

TA	FUNCTION	PACKAGE	PART NUMBER <sup>(1)</sup>	SYMBOL
-40°C to 85°C	Latched	VSSOP-10	TPS2490DGS	BIY
	Retry	(MSOP)	TPS2491DGS	BIX

(1) Add an R suffix to the device type for tape and reel packaging.

**ABSOLUTE MAXIMUM RATINGS<sup>(1)</sup>**

over operating free-air temperature range (unless otherwise noted)

		UNIT
Input voltage range, VCC, SENSE, EN, OUT	-0.3 to 100	V
Output voltage range, GATE, PG	-0.3 to 100	V
Input voltage range, PROG	-0.3 to 6	V
Output voltage range, TIMER, VREF	-0.3 to 6	V
Sink current, PG	10	mA
Source current, VREF	0 to 2	mA
Sink Current, PROG	2	mA
ESD - human body model	2	kV
ESD - charged device model	500	V
Maximum junction temperature, T <sub>J</sub>	150	°C
Storage temperature, T <sub>ST</sub>	-65 to 150	°C
Lead temperature 1.6 mm (1/16 inch) from case for 10 seconds	260	°C

(1) Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability

**RECOMMENDED OPERATING CONDITIONS**

	MIN	NOM	MAX	UNIT
V <sub>VCC</sub> Input voltage range	9		80	V
V <sub>PROG</sub> Input voltage range	0		4	V
I <sub>VREF</sub> Operating current range (sourcing), V <sub>REF</sub>	0		1	mA
T <sub>J</sub> Operating junction temperature	-40		125	°C
T <sub>A</sub> Operating free-air temperature	-40		85	°C

**DISSIPATION RATING TABLE**

PACKAGE	T <sub>A</sub> <25°C POWER RATING mW	DERATING FACTOR ABOVE T <sub>A</sub> = 25°C (mW/°C)	T <sub>A</sub> = 70°C POWER RATING (mW)	T <sub>A</sub> = 85°C POWER RATING (mW)
VSSOP-10 (MSOP)	376	3.76	207	150

## ELECTRICAL CHARACTERISTICS

unless otherwise noted, minimum and maximum limits apply across the recommended operating junction temperature and voltage range,  $V_{\text{TIMER}} = 0 \text{ V}$ , and all outputs unloaded; typical specifications are at  $T_J = 25^\circ\text{C}$ ,  $V_{\text{VCC}} = 48 \text{ V}$ ,  $V_{\text{TIMER}} = 0 \text{ V}$ , and all outputs unloaded; positive currents are into pins.

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
<b>SUPPLY CURRENT (VCC)</b>						
Enabled		$V_{\text{EN}} = \text{Hi}$ , $V_{\text{SENSE}} = V_{\text{OUT}} = V_{\text{VCC}}$		450	1000	$\mu\text{A}$
Disabled		$V_{\text{EN}} = \text{Lo}$ , $V_{\text{SENSE}} = V_{\text{VCC}} = V_{\text{OUT}} = 0$		90	250	$\mu\text{A}$
<b>CURRENT SENSE INPUT (SENSE)</b>						
$I_{\text{SENSE}}$	Input bias current	$V_{\text{SENSE}} = V_{\text{VCC}}$ , $V_{\text{OUT}} = V_{\text{VCC}}$		7.5	20	$\mu\text{A}$
<b>REFERENCE VOLTAGE OUTPUT (VREF)</b>						
$V_{\text{REF}}$	Reference voltage	$0 < I_{\text{VREF}} < 1 \text{ mA}$	3.9	4	4.1	V
<b>POWER LIMITING INPUT (PROG)</b>						
$I_{\text{PROG}}$	Input bias current, device enabled, sourcing or sinking	$0 < V_{\text{PROG}} < 4 \text{ V}$ , $V_{\text{EN}} = 48 \text{ V}$			5	$\mu\text{A}$
$R_{\text{PROG}}$	Pulldown resistance, device disabled	$I_{\text{PROG}} = 200 \mu\text{A}$ , $V_{\text{EN}} = 0 \text{ V}$		375	600	$\Omega$
<b>POWER LIMITING AND CURRENT LIMITING (SENSE)</b>						
$V_{\text{CL}}$	Current sense threshold $V_{(\text{VCC-SENSE})}$ with power limiting trip	$V_{\text{PROG}} = 2.4 \text{ V}$ , $V_{\text{OUT}} = 0 \text{ V}$ or $V_{\text{PROG}} = 0.9 \text{ V}$ , $V_{\text{OUT}} = 30 \text{ V}$ , $V_{\text{VCC}} = 48 \text{ V}$	17	25	33	mV
$V_{\text{SENSE}}$	Current sense threshold $V_{(\text{VCC-sense})}$ without power limiting trip	$V_{\text{PROG}} = 4 \text{ V}$ , $V_{\text{SENSE}} = V_{\text{OUT}}$	45	50	55	mV
$t_{\text{F\_TRIP}}$	Large overload response time to GATE low <sup>(1)</sup>	$V_{\text{PROG}} = 4 \text{ V}$ , $V_{\text{OUT}} = V_{\text{SENSE}}$ , $V_{(\text{VCC-SENSE})}: 0 \rightarrow 200 \text{ mV}$ , $C_{(\text{GATE-OUT})} = 2 \text{ nF}$ , $V_{(\text{GATE-OUT})} = 1 \text{ V}$			1.2	$\mu\text{S}$
<b>TIMER OPERATION (TIMER)</b>						
Charge current (sourcing)		$V_{\text{TIMER}} = 0 \text{ V}$	15.0	25.0	34.0	$\mu\text{A}$
		$V_{\text{TIMER}} = 0 \text{ V}$ , $T_J = 25^\circ\text{C}$	20.0	25.0	30.0	$\mu\text{A}$
Discharge current (sinking)		$V_{\text{TIMER}} = 5 \text{ V}$	1.50	2.5	3.70	$\mu\text{A}$
		$V_{\text{TIMER}} = 5 \text{ V}$ , $T_J = 25^\circ\text{C}$	2.10	2.5	3.10	$\mu\text{A}$
TIMER upper threshold voltage			3.9	4	4.1	V
TIMER lower reset threshold voltage		TPS2491 only	0.96	1.0	1.04	V
$D_{\text{RETRY}}$	Fault retry duty cycle	TPS2491 only	0.5%	0.75%	1.0%	
<b>GATE DRIVE OUTPUT (GATE)</b>						
$I_{\text{GATE}}$	GATE sourcing current	$V_{\text{SENSE}} = V_{\text{VCC}}$ , $V_{(\text{GATE-OUT})} = 7 \text{ V}$ , $V_{\text{EN}} = \text{Hi}$	15	22	35	$\mu\text{A}$
GATE sinking current		$V_{\text{EN}} = \text{Lo}$ , $V_{\text{GATE}} = V_{\text{VCC}}$	1.8	2.4	2.8	mA
		$V_{\text{EN}} = \text{Hi}$ , $V_{\text{GATE}} = V_{\text{VCC}}$ , $V_{(\text{VCC-SENSE})} \geq 200 \text{ mV}$	75	125	250	mA
GATE output voltage, $V_{(\text{GATE-OUT})}$			12		16	V
$t_{\text{D\_ON}}$	Propagation delay: EN going true to GATE output high <sup>(1)</sup>	$V_{\text{EN}} = 0 \rightarrow 2.5 \text{ V}$ , 50% of $V_{\text{EN}}$ to 50% of $V_{\text{GATE}}$ , $V_{\text{OUT}} = V_{\text{VCC}}$ , $R_{(\text{GATE-OUT})} = 1 \text{ M}\Omega$		25	40	$\mu\text{S}$
$t_{\text{D\_OFF}}$	Propagation delay: EN going false (0 V) to GATE output low <sup>(1)</sup>	$V_{\text{EN}} = 2.5 \text{ V} \rightarrow 0$ , 50% of $V_{\text{EN}}$ to 50% of $V_{\text{GATE}}$ , $V_{\text{OUT}} = V_{\text{VCC}}$ , $R_{(\text{GATE-OUT})} = 1 \text{ M}\Omega$ , $t_{\text{FALL}} < 0.1 \mu\text{S}$		0.5	1	$\mu\text{S}$
Propagation delay: TIMER expires to GATE output low <sup>(1)</sup>		$V_{\text{TIMER}}: 0 \rightarrow 5 \text{ V}$ , $t_{\text{RISE}} < 0.1 \mu\text{S}$ , 50% of $V_{\text{TIMER}}$ to 50% of $V_{\text{GATE}}$ , $V_{\text{OUT}} = V_{\text{VCC}}$ , $R_{(\text{GATE-OUT})} = 1 \text{ M}\Omega$		0.8	1	$\mu\text{S}$
<b>POWER GOOD OUTPUT (PG)</b>						
$V_{\text{PG\_L}}$ Low voltage (sinking)		$I_{\text{PG}} = 2 \text{ mA}$		0.1	0.25	V
		$I_{\text{PG}} = 4 \text{ mA}$		0.25	0.5	V
$V_{\text{PGTL}}$	PG threshold voltage, $V_{\text{OUT}}$ rising, PG goes open drain	$V_{\text{SENSE}} = V_{\text{VCC}}$ , measure $V_{(\text{VCC-OUT})}$	0.8	1.25	1.7	V

(1) Not tested in production.

**ELECTRICAL CHARACTERISTICS (continued)**

unless otherwise noted, minimum and maximum limits apply across the recommended operating junction temperature and voltage range,  $V_{\text{TIMER}} = 0 \text{ V}$ , and all outputs unloaded; typical specifications are at  $T_J = 25^\circ\text{C}$ ,  $V_{\text{VCC}} = 48 \text{ V}$ ,  $V_{\text{TIMER}} = 0 \text{ V}$ , and all outputs unloaded; positive currents are into pins.

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
VPGTH	PG threshold voltage, $V_{\text{OUT}}$ falling, PG goes low	$V_{\text{SENSE}} = V_{\text{VCC}}$ , measure $V_{(\text{VCC-OUT})}$	2.2	2.7	3.2	V
$\Delta V_{\text{PGT}}$	PG threshold hysteresis voltage, $V_{(\text{SENSE-OUT})}$	$V_{\text{SENSE}} = V_{\text{VCC}}$		1.4		V
$t_{\text{DPG}}$	PG deglitch delay, detection to output, rising and falling edges <sup>(2)</sup>	$V_{\text{SENSE}} = V_{\text{VCC}}$	5	9	15	ms
	Leakage current, PG false, open drain				10	$\mu\text{A}$
<b>OUTPUT VOLTAGE FEEDBACK INPUT (OUT)</b>						
$I_{\text{OUT}}$	Bias current	$V_{\text{OUT}} = V_{\text{VCC}}$ , $V_{\text{EN}} = \text{Hi}$ , sinking		8	20	$\mu\text{A}$
		$V_{\text{OUT}} = \text{GND}$ , $V_{\text{EN}} = \text{Lo}$ , sourcing		18	40	$\mu\text{A}$
<b>ENABLE INPUT (EN)</b>						
$V_{\text{EN\_H}}$	Threshold, $V_{\text{EN}}$ going high		1.32	1.35	1.38	V
$V_{\text{EN\_L}}$	Threshold, $V_{\text{EN}}$ going low		1.22	1.25	1.28	V
	$V_{\text{EN}}$ hysteresis <sup>(2)</sup>			100		mV
	Leakage current	$V_{\text{EN}} = 48 \text{ V}$			1	$\mu\text{A}$
<b>INPUT SUPPLY UVLO (VCC)</b>						
	$V_{\text{VCC}}$ turn on	Rising		8.4	8.8	V
	$V_{\text{VCC}}$ turn off	Falling	7.5	8.3		V
	Hysteresis <sup>(2)</sup>			75		mV

(2) Not tested in production.

**TYPICAL CHARACTERISTICS**

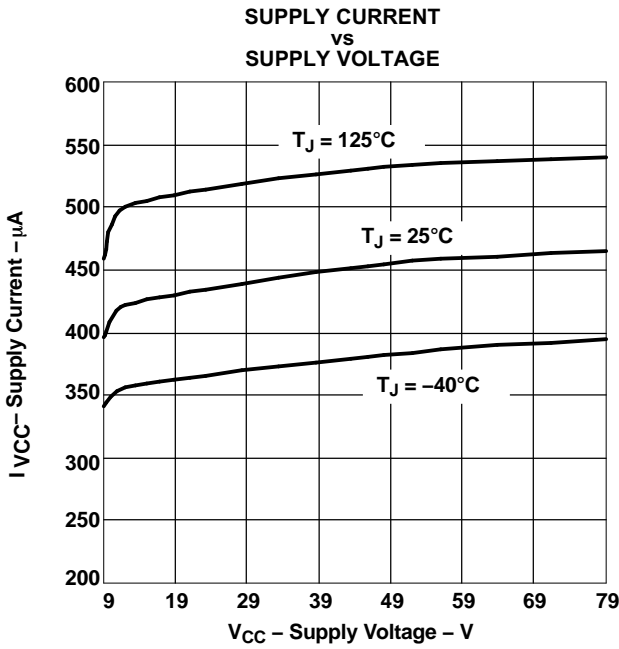


Figure 1.

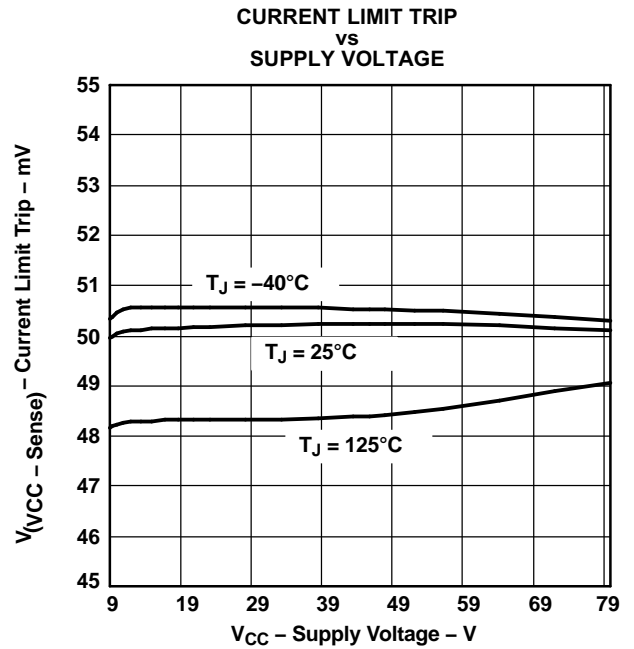


Figure 2.

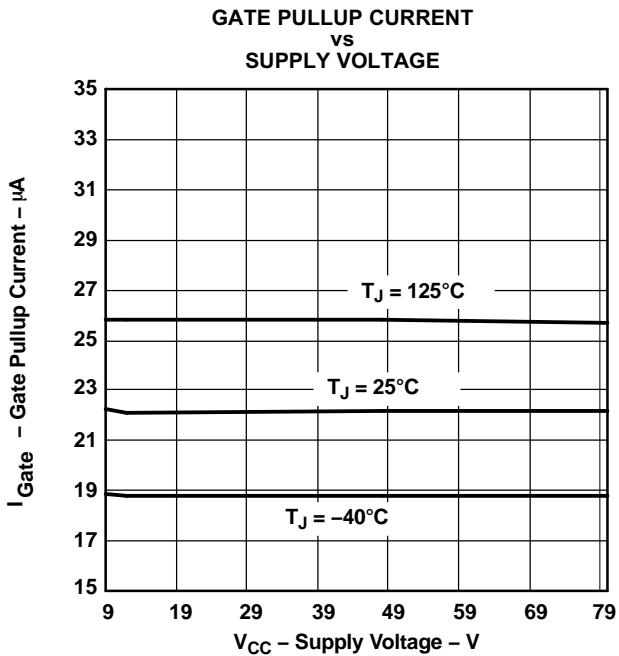


Figure 3.

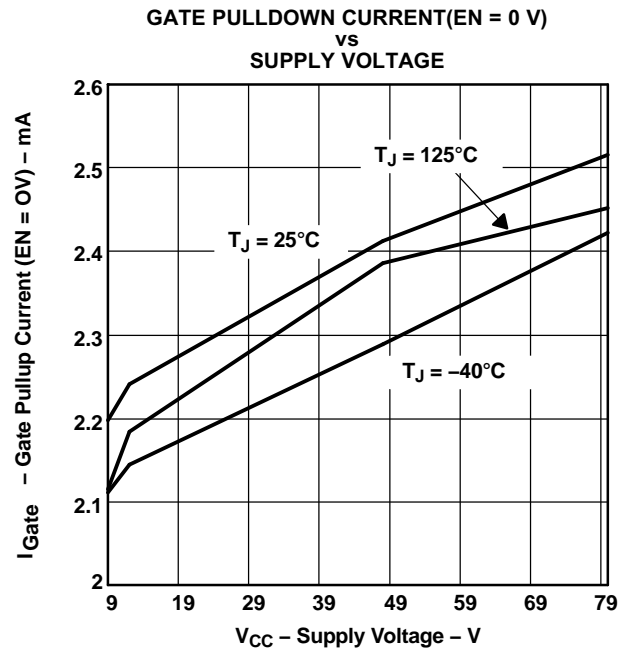
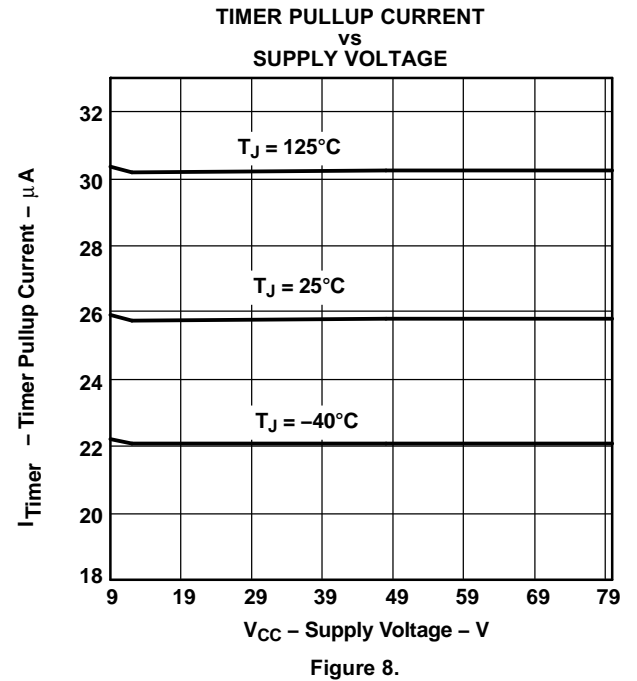
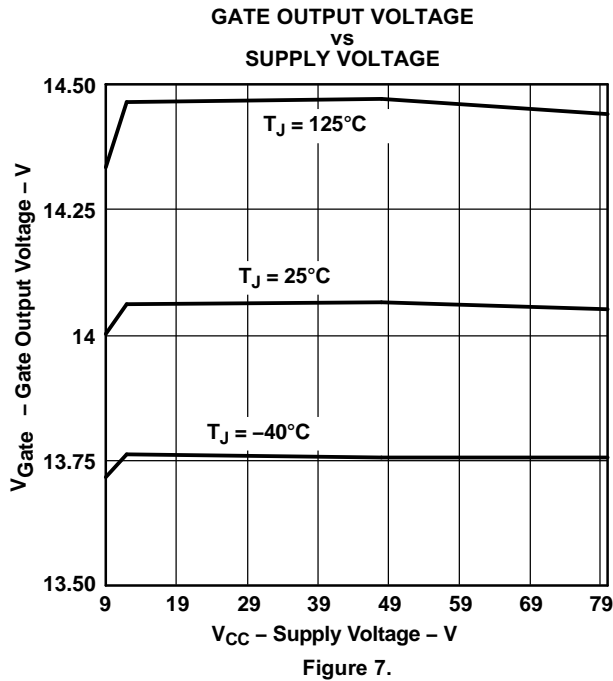
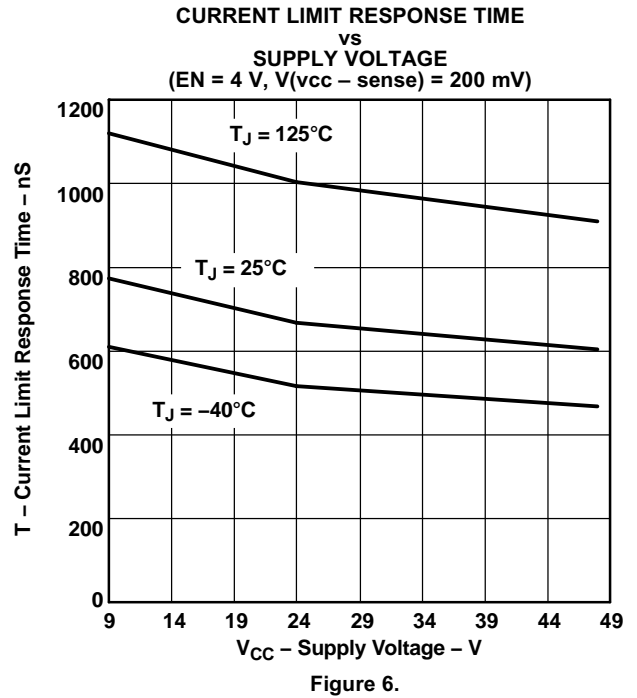
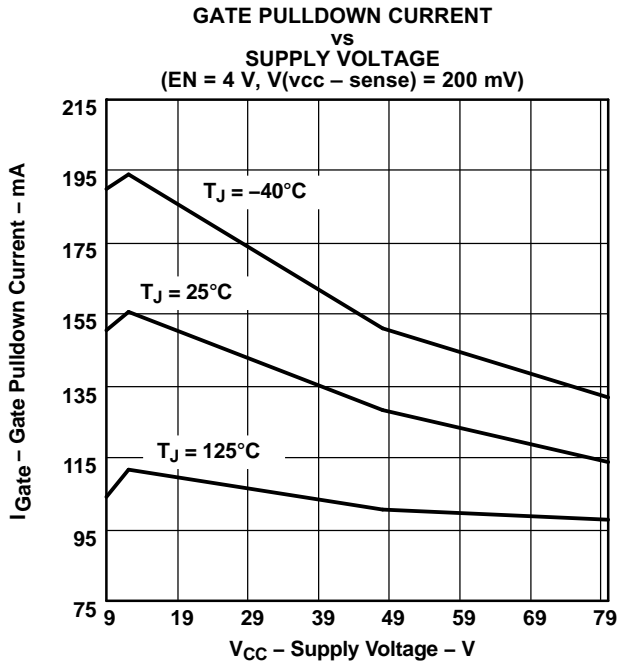


Figure 4.

TYPICAL CHARACTERISTICS (continued)



**TYPICAL CHARACTERISTICS (continued)**

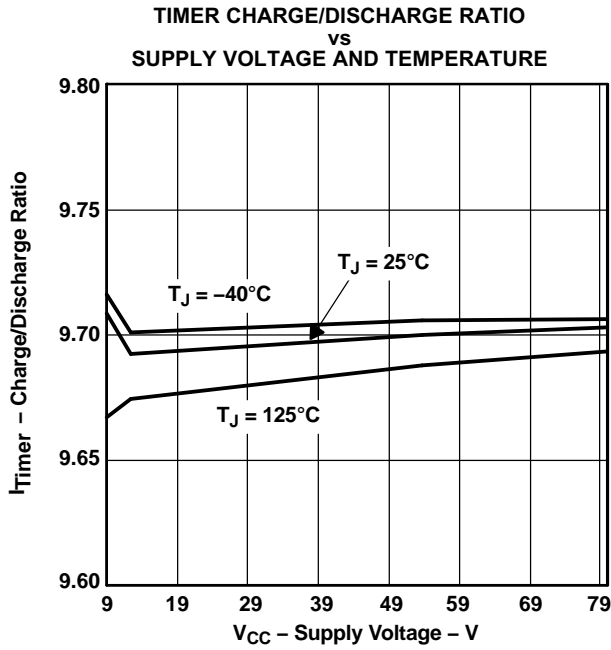


Figure 9.

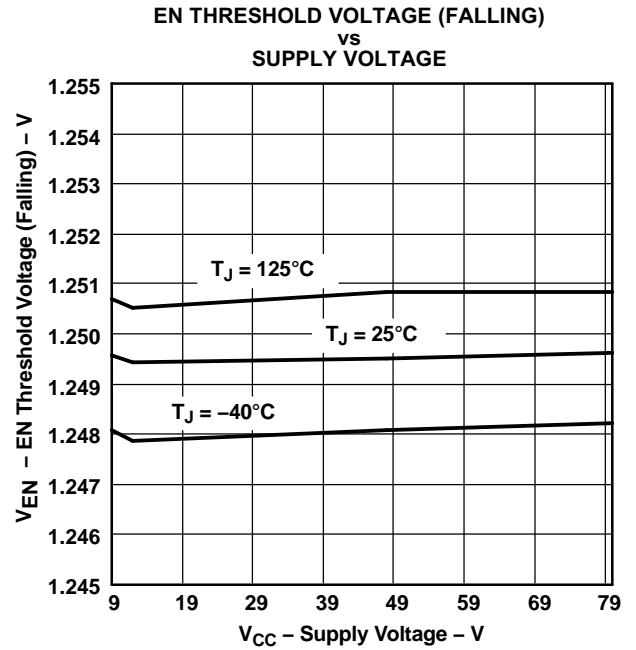


Figure 10.

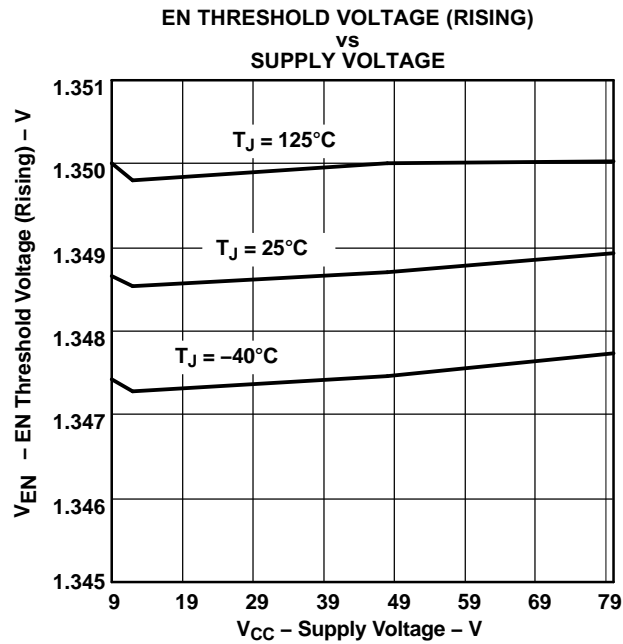
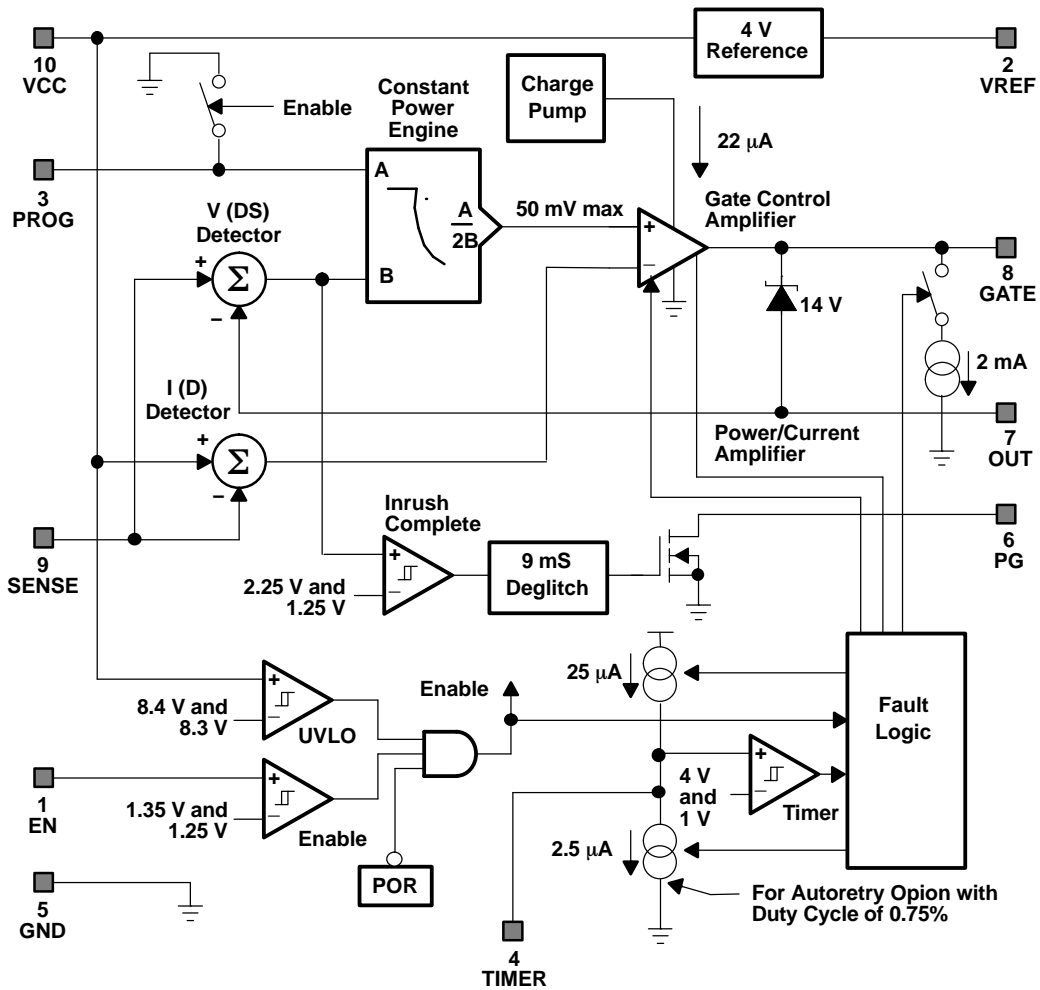


Figure 11.

FUNCTIONAL BLOCK DIAGRAM



TERMINAL FUNCTIONS

TERMINAL		I/O	DESCRIPTION
NAME	NO.		
EN	1	I	Device enable
VREF	2	O	Reference voltage output, used to set power threshold on PROG pin
PROG	3	I	Power-limit setting input
TIMER	4	I/O	Fault timing capacitor
GND	5		Ground
PG	6	O	Power good reporting output, open-drain
OUT	7	I	Output voltage feedback
GATE	8	O	Gate output
SENSE	9	I	Current-limit sense input
VCC	10	I	Supply input



## DETAILED PIN DESCRIPTION

The following description relies on the typical application diagram shown on page 1, and the functional block diagram.

**VCC:** This pin is associated with three functions: 1) biasing power to the integrated circuit, 2) input to power on reset (POR) and under voltage lockout (UVLO) functions, and 3) voltage sense at one terminal of  $R_S$  for M1 current measurement. The voltage must exceed the POR (about 6 V for roughly 400 $\mu$ S) and the internal UVLO (about 8 V) before normal operation (driving the GATE) may begin. Connections to VCC should be designed to minimize  $R_S$  voltage sensing errors and to maximize the effect of C1 and D1; place C1 at  $R_S$  rather than at the IC pin to eliminate transient sensing errors. GATE, PROG, PG, and TIMER are held low when either UVLO or POR are active.

**SENSE:** Monitors the voltage at the drain of M1, and the downstream side of  $R_S$  providing the constant power limit engine with feedback of both M1 current ( $I_D$ ) and voltage ( $V_{DS}$ ). Voltage is determined by the difference between SENSE and OUT, while the current analog is the difference between VCC and SENSE. The constant power engine uses  $V_{DS}$  to compute the allowed  $I_D$  and is clamped to 50 mV, acting like a traditional current limit at low  $V_{DS}$ . The current limit is set by the following equation:

$$I_{LIM} = \frac{50 \text{ mV}}{R_S}$$

Design the connections to SENSE to minimize  $R_S$  voltage sensing errors. Don't drive SENSE to a large voltage difference from VCC because it is internally clamped to VCC. The current limit function can be disabled by connecting SENSE to VCC.

**GATE:** Provides the high side (above VCC) gate drive for M1. It is controlled by the internal gate drive amplifier, which provides a pull-up of 22  $\mu$ A from an internal charge pump and a strong pull-down to ground of 75 mA (min). The pull-down current is a non-linear function of the amplifier overdrive; it provides small drive for small overloads, but large overdrive for fast reaction to an output short. There is a separate pull-down of 2 mA to shut M1 off when EN or the UVLO cause this to happen. An internal clamp protects the gate of M1 (to OUT) and generally eliminates the need for an external clamp in almost all cases for devices with 20 V  $V_{GS(MAX)}$  ratings; an external Zener may be required to protect the gate of devices with  $V_{GS(MAX)} < 16$  V. A small series resistance ( $R_5$ ) of 10  $\Omega$  should be inserted in the gate lead if the  $C_{ISS}$  of M1  $> 200$  pF, otherwise use 33  $\Omega$  for small MOSFETs.

A capacitor can be connected from GATE to ground to create a slower inrush with a constant current profile without affecting the amplifier stability. Add a series resistor of about 1 k $\Omega$  to the gate capacitor to maintain the gate clamping and current limit response time.

**OUT:** This input pin is used by the constant power engine and the PG comparator to measure  $V_{DS}$  of M1 as  $V_{(VCC-SENSE)}$ . Internal protection circuits leak a small current from this pin when it is low. If the load circuit can drive OUT below ground, connect a clamp (or freewheel) diode such as an S1B from OUT (cathode) to GND (anode).

**EN:** The GATE driver is enabled if the positive threshold is exceeded and the internal POR and UVLO thresholds have been satisfied. EN can be used as a logic control input, an analog input voltage monitor as illustrated by R1/R2 in the typical application circuit on page 1, or it can be tied to VCC to always enable the TPS2490/91. The hysteresis associated with the internal comparator makes this a stable method of detecting a low input condition and shutting the downstream circuits off. A TPS2490 that has latched off can be reset by cycling EN below its negative threshold and back high.

**VREF:** Provides a 4.0-V reference voltage for use in conjunction with R3/R4 of the typical application circuit to set the voltage on the PROG pin. The reference voltage is available once the internal POR and UVLO thresholds have been met. It is not designed as a supply voltage for other circuitry, therefore ensure that no more than 1 mA is drawn. Bypass capacitance is not required, but if a special application requires one, less than 1000 pF can be placed on this pin.

**PROG:** The voltage applied to this pin (0–4 V) programs the power limit used by the constant power engine. Normally, a resistor divider R3/R4 is connected from VREF to PROG to set the power limit according to the following equation:

$$V_{\text{PROG}} = \frac{P_{\text{LIM}}}{10 \times I_{\text{LIM}}}$$

where  $P_{\text{LIM}}$  is the desired power limit of M1 and  $I_{\text{LIM}}$  is the current limit setpoint (see SENSE).  $P_{\text{LIM}}$  is determined by the desired thermal stress on M1:

$$P_{\text{LIM}} < \frac{T_{\text{J(MAX)}} - T_{\text{S(MAX)}}}{R_{\theta\text{JC(MAX)}}}$$

where  $T_{\text{J(MAX)}}$  is the maximum desired transient junction temperature of M1 and  $T_{\text{S(MAX)}}$  is the maximum case temperature prior to a start or restart.

$V_{\text{PROG}}$  is used in conjunction with  $V_{\text{DS}}$  to compute the (scaled) current,  $I_{\text{D\_ALLOWED}}$ , by the constant power engine.  $I_{\text{D\_ALLOWED}}$  is compared by the gate amplifier to the actual  $I_{\text{D}}$ , and used to generate a gate drive. If  $I_{\text{D}} < I_{\text{D\_ALLOWED}}$ , the amplifier turns the gate of M1 full on because there is no overload condition; otherwise GATE is regulated to maintain the  $I_{\text{D}} = I_{\text{D\_ALLOWED}}$  relationship.

A capacitor may be tied from PROG to ground to alter the natural constant power inrush current shape. If properly designed, the effect is to cause the leading step of current in Figure 12 to look like a ramp.

PROG is internally pulled to ground whenever EN, POR, or UVLO are not satisfied or the TPS2490 is latched off. This feature serves to discharge any capacitance connected to the pin. Do not apply voltages greater than 4 V to PROG. If the constant power limit is not used, PROG should be tied to VREF through a 47-kΩ resistor.

**TIMER:** An integrating capacitor,  $C_{\text{T}}$ , connected to the TIMER pin provides a timing function that controls the fault-time for both versions and the restart interval for the TPS2491. The timer charges at 25 μA whenever the TPS2490/91 is in power limit or current limit and discharges at 2.5 μA otherwise. The charge-to-discharge current ratio is constant with temperature even though there is a positive temperature coefficient to both. If TIMER reaches 4 V, the TPS2490 pulls GATE to ground, latch off, and discharge  $C_{\text{T}}$ . The TPS2491 pulls GATE to ground and attempt a restart (re-enable GATE) after a timing sequence consisting of discharging  $C_{\text{T}}$  down to 1 V followed by 15 more charge and discharge cycles. The TPS2490 can be reset by either cycling the EN pin or the UVLO (e.g. power cycling). TIMER discharges when EN is low or UVLO or POR are active. The TIMER pin should be tied to ground if this feature is not used.

**PG:** This open-drain output is intended to interface to downstream dc/dc converters or monitoring circuits. PG goes open-drain (high voltage with a pull-up) after  $V_{\text{DS}}$  of M1 has fallen to about 1.25 V and a 9 ms deglitch time period has elapsed. PG is false (low or low resistance to ground) whenever EN is false,  $V_{\text{DS}}$  of M1 is above 2.5 V, or UVLO is active. PG can also be viewed as having an input and output voltage monitor function. The 9-ms deglitch circuit operates to filter short events that could cause PG to go inactive (low) such as a momentary overload or input voltage step.  $V_{\text{PG}}$  voltage can be greater than  $V_{\text{VCC}}$  because it's ESD protection is only with respect to ground.

**GND:** This pin is connected to system ground.

## APPLICATION INFORMATION

### BASIC OPERATION

The TPS2490/91 provides all the features needed for a positive hotswap controller. These features include: 1) under-voltage lockout; 2) adjustable (system-level) enable; 3) turn-on inrush limit; 4) high-side gate drive for an external N-channel MOSFET; 5) MOSFET protection (power limit and current limit); 6) adjustable overload timeout—also called an electronic circuit breaker; 7) charge-complete indicator for downstream converter coordination; and 8) an optional automatic restart mode. The TPS2490/91 features superior power-limiting MOSFET protection that allows independent control of current limit (to set maximum full-load current), power limit (to control junction temperature rise), and overload time (to control case temperature rise).

The typical application circuit, and oscilloscope plots of Figures 12–16 demonstrate many of the functions described above.

#### Board Plug-In (Figure 12)

Only the bypass capacitor charge current and small bias currents are evident when a board is first plugged in. The TPS2490/91 is held inactive, and GATE, PROG, TIMER, and PG are held low for less than 1 ms while internal voltages stabilize. A startup cycle is ready to take place after the stabilization.

GATE, PROG, TIMER, and PG are released after stabilization in this example because both the internal UVLO threshold and the external EN (enable) thresholds have been exceeded. The part begins sourcing current from the GATE pin and M1 begins to turn on while the voltage across it,  $V_{(SENSE-OUT)}$ , and current through it,  $V_{(VCC-SENSE)}$ , are monitored. Current initially rises to the value which satisfies the power limit engine ( $P_{LIM} \div V_{VCC}$ ) since the output capacitor was discharged.

#### TIMER and PG Operation (Figure 12)

The TIMER pin charges  $C_T$  as long as limiting action continues, and discharges at a 1/10 charge rate when limiting stops. If the voltage on  $C_T$  reaches 4 V before the output is charged, M1 is turned off and either a latch-off or restart cycle commences, depending on the part type. The open-drain PG output provides a deglitched end-of-charge indication which is based on the voltage across M1. PG is useful for preventing a downstream dc/dc converter from starting while  $C_O$  is still charging. PG goes active (open drain) about 9 ms after  $C_O$  is charged. This delay allows M1 to fully turn on and any transients in the power circuits to end before the converter starts up. The resistor pull-up shown on pin PG in the typical application diagram only demonstrates operation; the actual connection to the converter depends on the application. Timing can appear to terminate early in some designs if operation transitions out of the power limit mode into a gate charge limited mode at low  $V_{DS}$  values.

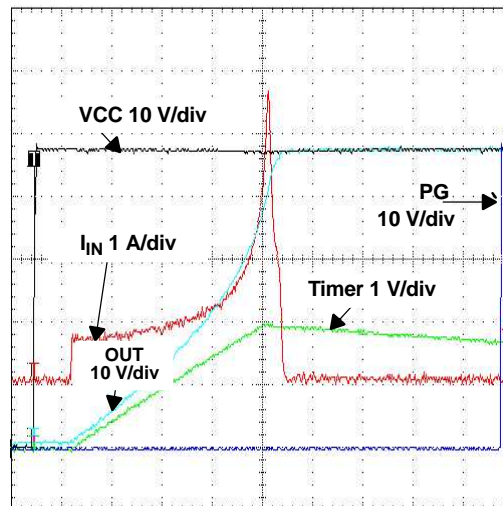


Figure 12. Basic Board Insertion

## APPLICATION INFORMATION (continued)

### Action of the Constant Power Engine (Figure 13)

The calculated power dissipated in M1,  $V_{DS} \times I_D$ , is computed under the same startup conditions as Figure 12. The current of M1, labeled  $I_{IN}$ , initially rises to the value that satisfies the constant power engine; in this case it is  $34\text{ W} \div 48\text{ V} = 0.7\text{ A}$ . The 34 W value is programmed into the engine by setting the PROG voltage using the equation given in the PROG pin description.  $V_{DS}$  of M1, which is calculated as  $V_{(VCC-OUT)}$ , falls as  $C_O$  charges, thus allowing the M1 drain current to increase. This is the result of the internal constant power engine adjusting the current limit reference to the GATE amplifier as  $C_O$  charges and  $V_{DS}$  falls. The calculated device power in Figure 13, labeled FET PWR, is seen to be flat-topped and constant within the limitations of circuit tolerance and acquisition noise. A fixed current limit is implemented by clamping the constant power engine's output to 50 mA when  $V_{DS}$  is low. This protection technique can be viewed as a specialized form of foldback limiting; the benefit over linear foldback is that it yields the maximum output current from a device over the full range of  $V_{DS}$  and still protects the device.

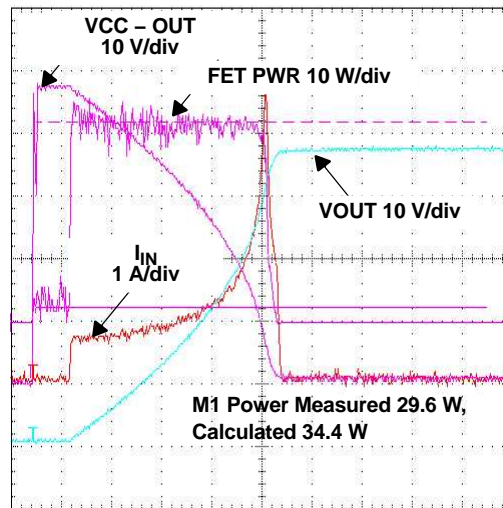
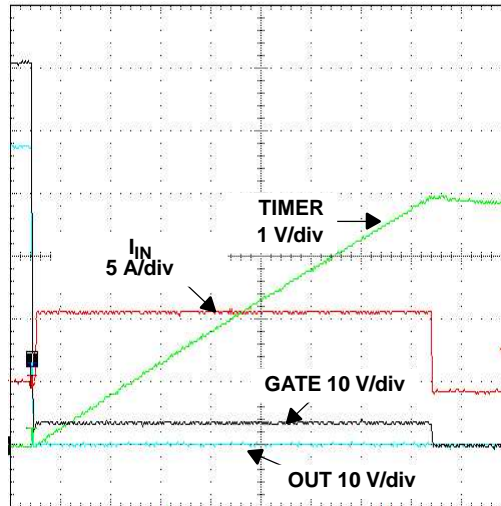


Figure 13. Computation of M1 Stress During Startup

### Response to a Hard Output Short (Figure 14 and Figure 15)

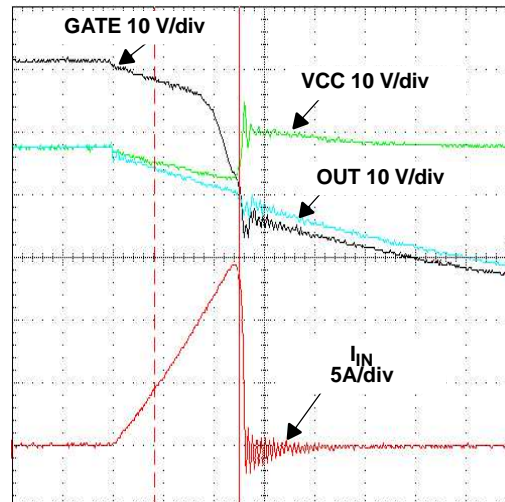
Figure 14 shows the short circuit response over the full time-out period that begins when the output voltage falls and ends when M1 is turned off. M1 current is actively controlled by the power limiting engine and gate amplifier circuit while the TIMER pin charges  $C_T$  to the 4 V threshold that causes M1 to be turned off. The TPS2490 latches off after the threshold is reached until either the input voltage drops below the UVLO threshold or EN cycles through the false (low) state. The TPS2491 goes through a timing sequence before attempting a restart.

## APPLICATION INFORMATION (continued)



**Figure 14. Current Limit Overview**

The TPS2490/91 responds rapidly to the short circuit as seen in Figure 15. The falling OUT voltage is the result of M1 and  $C_O$  currents through the short's impedance at this time scale. The internal GATE clamp causes the GATE voltage to follow the output voltage down and subsequently limits the negative  $V_{DS}$  to 1–2 V. The rapidly rising fault current overdrives the GATE amplifier causing it to overshoot and rapidly turn M1 off by sinking current to ground. M1 slowly turns back on as the GATE amplifier recovers; M1 then settles to an equilibrium operating point determined by the power limiting circuit.



**Figure 15. Current Limit Onset**

Minimal input voltage overshoot appears in Figure 15 because a local 100- $\mu$ F bypass capacitor and very short input leads were used. The input voltage would overshoot as the input current abruptly drops in a typical application due to the stored energy in the input distribution's inductance. The exact waveforms seen in an application depend upon many factors including parasitics of the voltage distribution, circuit layout, and the short itself.

## APPLICATION INFORMATION (continued)

### Automatic Restart (Figure 16)

The TPS2491 automatically initiates a restart after a fault has caused it to turn off M1. Internal control circuits use  $C_T$  to count 16 cycles before re-enabling M1. This sequence continues to repeat if the fault persists. The TIMER has a 1:10 charge-to-discharge current ratio, and uses a 1-V lower threshold. The fault-retry duty cycle specification quantifies this behavior. This small duty cycle often reduces the average short-circuit power dissipation to levels associated with normal operation and eliminates special thermal considerations for surviving a prolonged output short.

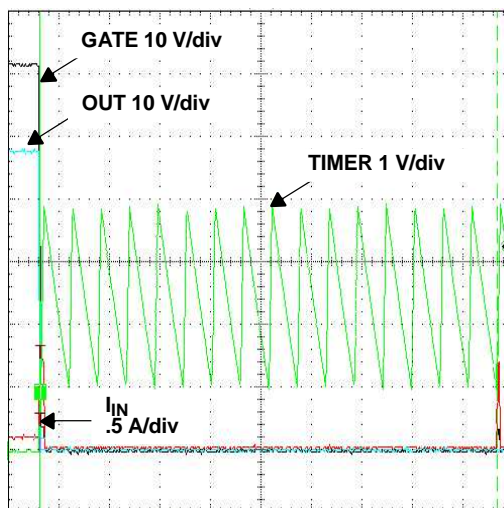


Figure 16. TPS2491 Restart Cycle Timing

## DESIGN PROCEDURE

This design procedure seeks to control the junction temperature of M1 under both static and transient conditions by selecting the device's package, cooling,  $R_{DS(on)}$ , current limit, fault timeout, and power limit. The following procedure assumes that a unit running at full load and maximum ambient temperature experiences a brief input power interruption sufficient to discharge  $C_O$ , but short enough to keep M1 from cooling. A full  $C_O$  recharge then takes place. Adjust this procedure to fit your application and design criteria.

This procedure assumes that  $C_O$  is the only load during inrush. Only simple first-order thermal models, natural convection and a large PCB pad for M1 are assumed. The assumptions build generous safety margins into the design to allow for the inherent inaccuracies of the models and variations of real-world conditions.

Other tools and applications information are available on the TI website that supplement the following procedure.

### STEP 1. Choose $R_S$

Given the maximum operating current,  $I_{MAX}$ , compute the current sense resistance,  $R_S$ .

$$R_S = \frac{0.05}{1.2 \times I_{MAX}}$$

This equation allows for minimum current limit, a sense resistor tolerance of 5%, and 5% margin. Round the result down to the nearest available standard value.

### STEP 2. Choose M1

First select a  $V_{DS}$  rating that allows for the maximum input voltage and transients. Next select an operating  $R_{DS(on)}$ , package, and cooling to control operating temperature. The following equation computes the value of  $R_{DS(on)(MAX)}$  at a junction temperature of  $T_{J(MAX)}$ . Most manufacturers list  $R_{DS(on)(MAX)}$  at 25°C and provide a derating curve from which values at other temperatures can be derived. Compute the maximum allowable on-resistance,  $R_{DS(on)(MAX)}$ , using the equation:

## APPLICATION INFORMATION (continued)

$$R_{\text{DSON(MAX)}} \leq \frac{T_{\text{J(MAX)}} - T_{\text{A(MAX)}}}{R_{\theta\text{JA}} \times I_{\text{MAX}}^2}$$

where  $T_{\text{J(MAX)}}$  is the desired maximum steady-state junction temperature (typically 125°C), and  $T_{\text{A(MAX)}}$  is the maximum ambient temperature.  $R_{\theta\text{JA}}$ , the junction-to-ambient thermal resistance, depends upon the package style chosen and the details of heat-sinking and cooling. Note the  $R_{\theta\text{JC}}$  and  $R_{\theta\text{JA}}$  for use below.

### STEP 3. Choose $P_{\text{LIM}}$ , R3, R4

M1 dissipates large amounts of power during power-up or output short circuit. The power limit  $P_{\text{LIM}}$  of the TPS2940/91 should be set to prevent the die temperature from exceeding a short term maximum temperature,  $T_{\text{J(MAX)2}}$ . The short-term  $T_{\text{J(MAX)2}}$  could be set as high as 150°C while still leaving ample margin to the usual manufacturer's rating of 175°C. An expression for calculating  $P_{\text{LIM}}$  is:

$$P_{\text{LIM}} \leq 0.7 \times \frac{T_{\text{J(MAX)2}} - \left[ \left( I_{\text{MAX}}^2 \times R_{\text{DSON}} \times R_{\theta\text{CA}} \right) + T_{\text{A(MAX)}} \right]}{R_{\theta\text{JC}}}$$

where  $R_{\theta\text{JC}}$  is M1 junction-to-case thermal resistance,  $R_{\text{DSON}}$  is the channel resistance at the maximum operating temperature, and the factor of 0.7 represents the tolerance of the constant power engine. Next calculate  $V_{\text{PROG}}$  and the divider resistors R3 and R4. R3 must be greater than 4 kΩ, but it is recommended that 10 kΩ or greater be used.

$$V_{\text{PROG}} = \frac{P_{\text{LIM}}}{10 \times I_{\text{LIM}}} \quad \text{where} \quad I_{\text{LIM}} = \frac{0.05}{R_{\text{S}}}$$

$$\frac{R4}{R3 + R4} = \frac{V_{\text{PROG}}}{V_{\text{REF}}}$$

### STEP 4. Choose $t_{\text{ON}}$ , $C_{\text{T}}$

The on-time,  $t_{\text{ON}}$ , set by capacitor  $C_{\text{T}}$  must suffice to fully charge the load capacitance  $C_{\text{O}}$  without triggering the fault circuitry. Assuming that only the load capacitance draws current during startup:

$$t_{\text{ON}} = \begin{cases} \frac{C_{\text{O}} \times P_{\text{LIM}}}{2 \times I_{\text{LIM}}^2} + \frac{C_{\text{O}} \times V_{\text{VCC(MAX)}}^2}{2 \times P_{\text{LIM}}} & \text{if } P_{\text{LIM}} < I_{\text{LIM}} V_{\text{VCC(MAX)}} \\ \frac{C_{\text{O}} \times V_{\text{VCC(MAX)}}}{I_{\text{LIM}}} & \text{if } P_{\text{LIM}} \geq I_{\text{LIM}} V_{\text{VCC(MAX)}} \end{cases}$$

Using this value of  $t_{\text{ON}}$ ,  $C_{\text{T}}$  is computed as:

$$C_{\text{T}} = 8.5 \times 10^{-6} \times t_{\text{ON}} \times \left( 1 + C_{\text{OUT\_TOL}} + C_{\text{T\_TOL}} \right)$$

where  $C_{\text{T\_TOL}}$  and  $C_{\text{OUT\_TOL}}$  are the tolerances associated with each capacitor. Assuming  $C_{\text{O}}$  is a 20% tolerance part,  $C_{\text{OUT\_TOL}}$  has a value of 0.2. This expression assures the worst case set of parts will always start.

### STEP 5. Choose The Turn On Voltage, R1 & R2

Assuming that EN is used as an analog input, the turn-on voltage,  $V_{\text{ON}}$  and turn-off voltage,  $V_{\text{OFF}}$  are defined as:

$$V_{\text{ON}} = \frac{1.35 \text{ V}}{\left( \frac{R2}{R1 + R2} \right)} \quad V_{\text{OFF}} = \frac{1.25 \text{ V}}{\left( \frac{R2}{R1 + R2} \right)}$$

Use caution in selecting very large values of R1 and R2 because the leakage current causes errors in the threshold voltages.

## APPLICATION INFORMATION (continued)

### STEP 6. Choose R5, R6, & C1

R5 is intended to suppress high-frequency oscillations; a resistor of 10Ω will serve for most applications but if M1 has a C<sub>ISS</sub> below 200 pF, then use 33 Ω. Applications with larger MOSFETs and very short wiring may not require R5. R6 is required only if the PG output drives a circuit that requires it. It is recommended that the sink current be less than 2 mA. C1 is a bypass capacitor to help with control of transient voltages, unit emissions, and local supply noise while in the disabled state. Where acceptable, a value in the range of 0.001 μF to 0.1 μF is recommended.

### STEP 7. Choose D1

Transient voltage suppressor D1 is required in applications where there will be enough energy in the distribution inductance to cause a voltage surge above the TPS2490/91 rated maximum. Such transients can be caused by card insertions or shorts on the input or output of the TPS2490/91.

## ALTERNATIVE INRUSH DESIGNS

### Gate Capacitor (dV/dt) Control

The TPS2490/91 can be used with applications that require constant turn-on currents. The current is controlled by a single capacitor from the GATE terminal to ground with a series resistor. M1 appears to operate as a source follower (following the gate voltage) in this implementation. Choose a time to charge, Δt, based on the output capacitor, input voltage V<sub>I</sub>, and desired charge current, I<sub>CHARGE</sub>. Select I<sub>CHARGE</sub> to be less than P<sub>LIM</sub> ÷ V<sub>VCC</sub> if the power limit feature is kept.

$$\Delta t = \frac{C_O \times V_{VCC}}{I_{CHARGE}}$$

To select the gate capacitance:

$$C_G = \left( I_{GATE} \times \frac{\Delta t}{V_{VCC}} \right) - C_{ISS}$$

where C<sub>ISS</sub> is the gate capacitance of M1, and I<sub>GATE</sub> is the nominal gate charge current. The TIMER capacitor can then be selected to be much smaller as the current and power limit is not active during initial power on. A series resistor of about 1 kΩ should be used in conjunction with C<sub>G</sub>.

### PROG Inrush Control

A capacitor can be connected from the PROG pin to ground to reduce the initial current step seen in Figure 12 based on the typical application circuit on page 1. This method maintains a relatively fast turn-on time without the drawbacks of a gate-to-ground capacitor that include increased short circuit response time and less predictable gate clamping.

## ADDITIONAL DESIGN CONSIDERATIONS

### Use of PG

Use the PG pin to control and coordinate a downstream dc/dc converter. A long time delay is needed to allow C<sub>O</sub> to fully charge before the converter starts if this is not done. An undesirable latchup condition can be created between the TPS2490 output characteristic and the dc/dc converter input characteristic if the converter starts while C<sub>O</sub> is still charging; the PG pin is one way to avoid this.

### Faults and Backplane Voltage Droop

A hard short at the output of the TPS2490/91 during normal operation could result in activation of the enable or UVLO circuit instead of the current limit if the input voltage droops sufficiently. The lower GATE drive in this condition will cause a prolonged, larger over-current spike. This can be eliminated by filtering EN, or distributing capacitance on the bus itself. Capacitance from adjacent plugged-in units may help with this as well.



## **APPLICATION INFORMATION (continued)**

### **Output Clamp Diode**

Inductive loads on the output may drive the OUT pin below GND when the circuit is unplugged or during a current limit. The OUT pin ratings can be maintained with a small diode, such as an S1B, across TPS2490/91 OUT to GND.

### **Gate Clamp Diode**

The TPS2490/91 has a relatively well-regulated gate voltage of 12–16 V, even with low supply voltages. A small clamp Zener from gate to source of M1, such as a BZX84C7V5, is recommended if  $V_{GS}$  of M1 is rated below this.

### **High Gate Capacitance Applications**

Gate voltage overstress and abnormally large fault current spikes can be caused by large gate capacitance. An external gate clamp Zener diode is recommended if the total gate capacitance of M1 exceeds about 4000 pF. When gate capacitor inrush control is used, a 1-k $\Omega$  resistor in series with  $C_G$  is recommended. If the series R-C combination is used for MOSFETs with  $C_{ISS}$  less than 3000 pF, then a Zener is not necessary.

### **Output Short Circuit Measurements**

Repeatable short-circuit testing results are difficult to obtain. The many details of source bypassing, input leads, circuit layout and component selection, output shorting method, relative location of the short, and instrumentation all contribute to obtaining different results. The actual short itself exhibits a certain degree of randomness as it microscopically bounces and arcs. Care in configuration and methods must be used to obtain realistic results. Do not expect to see waveforms exactly like those in the data sheet—every setup differs.

### **Layout Considerations**

Good layout practice places the power devices D1,  $R_S$ , M1, and  $C_O$  so power flows in a sequential fashion, and preferably in a straight line. A ground plane under the power and the TPS2490/91 is desirable. The TPS2490/91 should be placed close to the sense resistor and the MOSFET; a Kelvin connection is recommended to achieve accurate current sensing across  $R_S$ . A low-impedance GND connection is required because the TPS2490/91 can momentarily sink upwards of 100 mA from the gate of M1. The GATE amplifier has high bandwidth while active, so keep the gate trace length short. The PROG, TIMER, and EN pins have high input impedances, therefore keep their input leads short. Oversize power traces and power device connections to assure low voltage drop and good thermal performance.

**PACKAGING INFORMATION**

Orderable Device	Status <sup>(1)</sup>	Package Type	Package Drawing	Pins	Package Qty	Eco Plan <sup>(2)</sup>	Lead/Ball Finish	MSL Peak Temp <sup>(3)</sup>
TPS2490DGS	ACTIVE	MSOP	DGS	10	80	TBD	Call TI	Call TI
TPS2490DGSG4	ACTIVE	MSOP	DGS	10	80	TBD	Call TI	Call TI
TPS2490DGSR	ACTIVE	MSOP	DGS	10	2500	TBD	Call TI	Call TI
TPS2490DGSRG4	ACTIVE	MSOP	DGS	10	2500	TBD	Call TI	Call TI
TPS2491DGS	ACTIVE	MSOP	DGS	10	80	TBD	Call TI	Call TI
TPS2491DGSG4	ACTIVE	MSOP	DGS	10	80	TBD	Call TI	Call TI
TPS2491DGSR	ACTIVE	MSOP	DGS	10	2500	TBD	Call TI	Call TI
TPS2491DGSRG4	ACTIVE	MSOP	DGS	10	2500	TBD	Call TI	Call TI

<sup>(1)</sup> The marketing status values are defined as follows:

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**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

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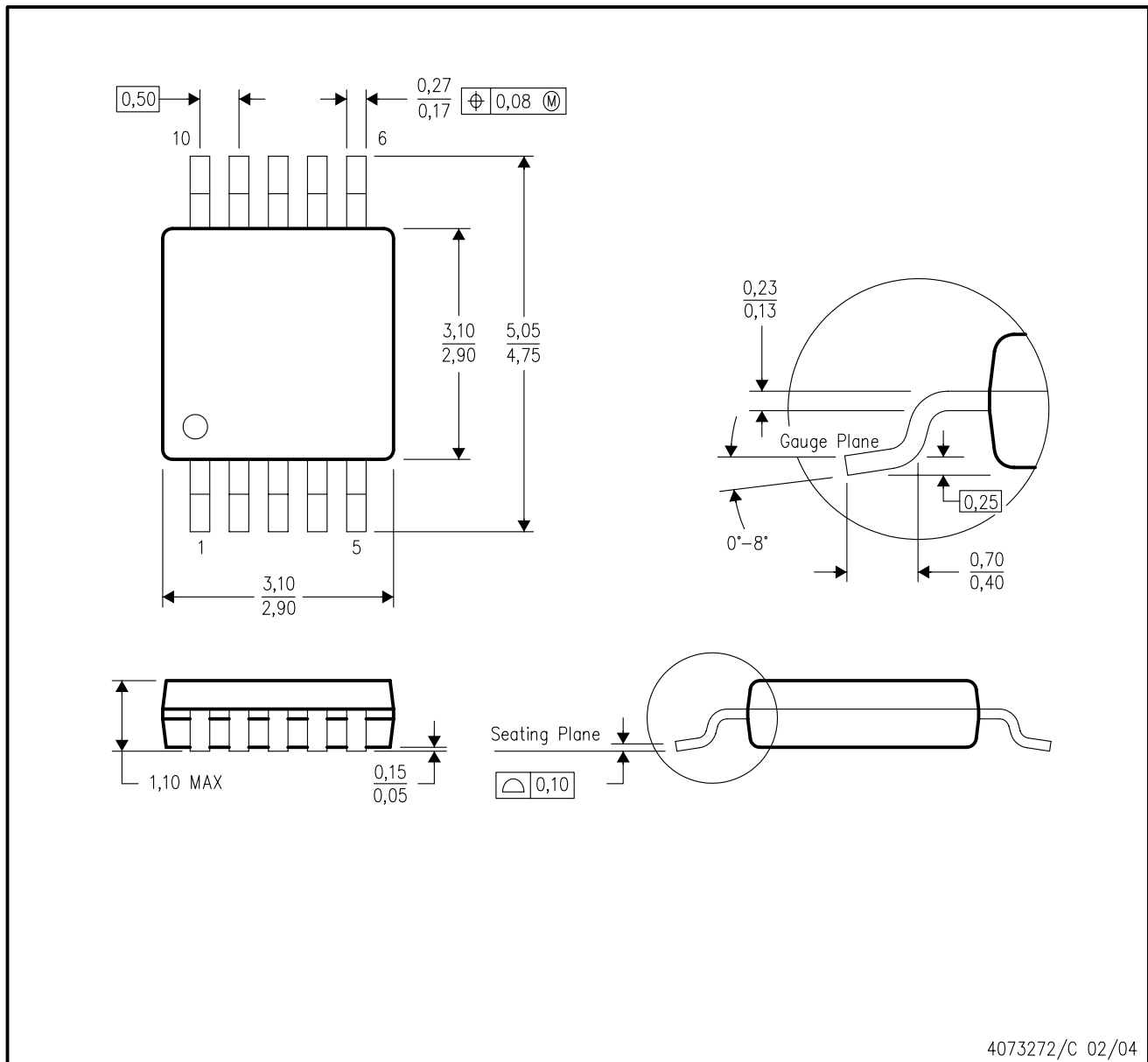
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DGS (S-PDSO-G10)

PLASTIC SMALL-OUTLINE PACKAGE



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  - D. Falls within JEDEC MO-187 variation BA.

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