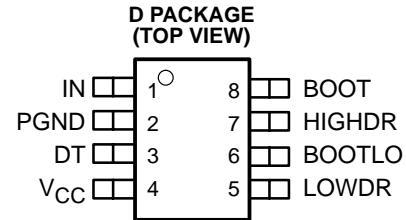


# TPS2836, TPS2837 SYNCHRONOUS-BUCK MOSFET DRIVER WITH DEAD-TIME CONTROL

SLVS224B – NOVEMBER 1999 – REVISED AUGUST 2002

- Floating Bootstrap or Ground-Reference High-Side Driver
- Adaptive Dead-Time Control
- 50-ns Max Rise/Fall Times With 3.3-nF Load
- 2.4-A Typical Output Current
- 4.5-V to 15-V Supply Voltage Range
- TTL-Compatible Inputs
- Internal Schottky Bootstrap Diode
- Low Supply Current...3 mA Typical
- Ideal for High-Current Single or Multiphase Power Supplies
- – 40°C to 125°C Operating Virtual Junction-Temperature Range



## description

The TPS2836 and TPS2837 are MOSFET drivers for synchronous-buck power stages. These devices are ideal for designing a high-performance power supply using switching controllers that do not have MOSFET drivers. The drivers are designed to deliver minimum 2-A peak currents into large capacitive loads. The high-side driver can be configured as ground-reference or as floating-bootstrap. An adaptive dead-time control circuit eliminates shoot-through currents through the main power FETs during switching transitions and provides high efficiency for the buck regulator.

The TPS2836 has a noninverting input, while the TPS2837 has an inverting input. These drivers, available in 8-terminal SOIC packages, operate over a junction temperature range of – 40°C to 125°C.

### AVAILABLE OPTIONS

T <sub>J</sub>	PACKAGED DEVICES
	SOIC (D)
– 40°C to 125°C	TPS2836D TPS2837D

The D package is available taped and reeled. Add R suffix to device type (e.g., TPS2836DR)

### Related Synchronous MOS FET Drivers

DEVICE NAME	ADDITIONAL FEATURES	INPUTS	
TPS2830	ENABLE, SYNC and CROWBAR	CMOS	Noninverted
TPS2831			Inverted
TPS2832	W/O ENABLE, SYNC and CROWBAR	CMOS	Noninverted
TPS2833			Inverted
TPS2834	ENABLE, SYNC and CROWBAR	TTL	Noninverted
TPS2835			Inverted



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PRODUCTION DATA information is current as of publication date. Products conform to specifications per the terms of Texas Instruments standard warranty. Production processing does not necessarily include testing of all parameters.

 **TEXAS  
INSTRUMENTS**

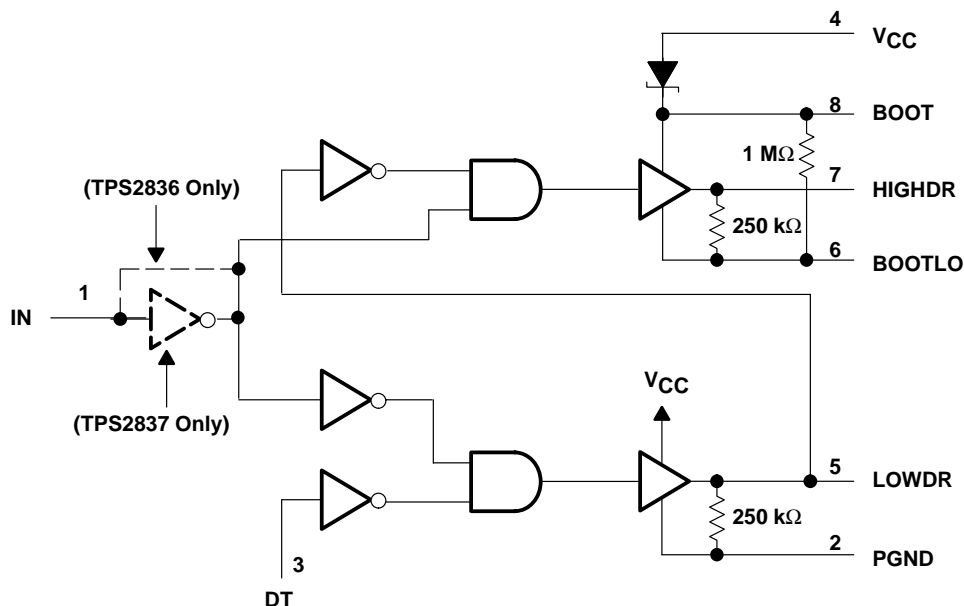
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# TPS2836, TPS2837 SYNCHRONOUS-BUCK MOSFET DRIVER WITH DEAD-TIME CONTROL

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## functional block diagram



## Terminal Functions

TERMINAL NAME	NO.	I/O	DESCRIPTION
BOOT	8	I	Bootstrap terminal. A ceramic capacitor is connected between BOOT and BOOTLO to develop the floating bootstrap voltage for the high-side MOSFET. The capacitor value is typically between 0.1 $\mu$ F and 1 $\mu$ F.
BOOTLO	6	O	This terminal connects to the junction of the high-side and low-side MOSFETs.
DT	3	I	Dead-time control terminal. Connect DT to the junction of the high-side and low-side MOSFETs
HIGHDR	7	O	Output drive for the high-side power MOSFET
IN	1	I	Input signal to the MOSFET drivers (noninverting input for the TPS2836; inverting input for the TPS2837).
LOWDR	5	O	Output drive for the low-side power MOSFET
PGND	2		Power ground. Connect to the FET power ground.
VCC	4	I	Input supply. Recommended that a 1 $\mu$ F capacitor be connected from VCC to PGND.

**detailed description**

**low-side driver**

The low-side driver is designed to drive low  $r_{DS(on)}$  N-channel MOSFETs. The current rating of the driver is 2 A, source and sink.

**high-side driver**

The high-side driver is designed to drive low  $r_{DS(on)}$  N-channel MOSFETs. The current rating of the driver is 2 A, source and sink. The high-side driver can be configured as a ground-reference driver or a floating bootstrap driver. The internal bootstrap diode is a Schottky for improved drive efficiency. The maximum voltage that can be applied between the BOOT terminal and ground is 30 V.

**dead-time (DT) control**

Dead-time control prevents shoot-through current from flowing through the main power FETs during switching transitions by controlling the turnon times of the MOSFET drivers. The high-side driver is not allowed to turn on until the gate drive voltage to the low-side FET is low, and the low-side driver is not allowed to turn on until the voltage at the junction of the power FETs ( $V_{drain}$ ) is low; the TTL-compatible DT terminal connects to the junction of the power FETs.

**IN**

The IN terminal is a TTL-compatible digital terminal that is the input control signal for the drivers. The TPS2836 has a noninverting input; the TPS2837 has an inverting input.

**absolute maximum ratings over operating free-air temperature (unless otherwise noted)†**

Supply voltage range, $V_{CC}$ (see Note 1)	–0.3 V to 16 V
Input voltage range: BOOT to PGND (high-side driver ON)	–0.3 V to 30 V
BOOTLO to PGND	–0.3 V to 16 V
BOOT to BOOTLO	–0.3 V to 16 V
IN	–0.3 V to 16 V
DT	–0.3 V to 30 V
Continuous total power dissipation	See Dissipation Rating Table
Operating virtual junction temperature range, $T_J$	–40°C to 125°C
Storage temperature range, $T_{stg}$	–65°C to 150°C
Lead temperature soldering 1,6 mm (1/16 inch) from case for 10 seconds	260°C

† Stresses beyond those listed under “absolute maximum ratings” may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under “recommended operating conditions” is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

NOTE 1: Unless otherwise specified, all voltages are with respect to PGND.

**DISSIPATION RATING TABLE**

PACKAGE	$T_A \leq 25^\circ\text{C}$ POWER RATING	DERATING FACTOR ABOVE $T_A = 25^\circ\text{C}$	$T_A = 70^\circ\text{C}$ POWER RATING	$T_A = 85^\circ\text{C}$ POWER RATING
D	600 mW	6.0 mW/°C	330 mW	240 mW

**recommended operating conditions**

	MIN	NOM	MAX	UNIT
Supply voltage, $V_{CC}$	4.5		15	V
Input voltage   BOOT to PGND	4.5		28	V

# TPS2836, TPS2837 SYNCHRONOUS-BUCK MOSFET DRIVER WITH DEAD-TIME CONTROL

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electrical characteristics over recommended operating virtual junction temperature range,  
 $V_{CC} = 6.5\text{ V}$ ,  $C_L = 3.3\text{ nF}$  (unless otherwise noted)

## supply current

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
V <sub>CC</sub>	Supply voltage range		4.5		15	V
	Quiescent current	V <sub>CC</sub> = 15 V, V <sub>(ENABLE)</sub> = LOW			100	μA
	Quiescent current	V <sub>CC</sub> = 15 V, V <sub>(ENABLE)</sub> = HIGH		300	400	
	Quiescent current	V <sub>CC</sub> = 12 V, BOOTLO grounded, f <sub>SWX</sub> = 200 kHz, C <sub>LOWDR</sub> = 50 pF, C <sub>HIGHDR</sub> = 50 pF, See Note 2		3		mA

NOTE 2: Ensured by design, not production tested.

## output drivers

PARAMETER			TEST CONDITIONS	MIN	TYP	MAX	UNIT	
Peak output-current	High-side sink (see Note 4)	Duty cycle < 2%, t <sub>pw</sub> < 100 μs (see Note 3)	V <sub>BOOT</sub> - V <sub>BOOTLO</sub> = 4.5 V, V <sub>HIGHDR</sub> = 4 V	0.7	1.1		A	
			V <sub>BOOT</sub> - V <sub>BOOTLO</sub> = 6.5 V, V <sub>HIGHDR</sub> = 5 V	1.1	1.5			
			V <sub>BOOT</sub> - V <sub>BOOTLO</sub> = 12 V, V <sub>HIGHDR</sub> = 10.5 V	2	2.4			
	High-side source (see Note 4)	Duty cycle < 2%, t <sub>pw</sub> < 100 μs (see Note 3)	V <sub>BOOT</sub> - V <sub>BOOTLO</sub> = 4.5 V, V <sub>HIGHDR</sub> = 0.5 V	1.2	1.4		A	
			V <sub>BOOT</sub> - V <sub>BOOTLO</sub> = 6.5 V, V <sub>HIGHDR</sub> = 1.5 V	1.3	1.6			
			V <sub>BOOT</sub> - V <sub>BOOTLO</sub> = 12 V, V <sub>HIGHDR</sub> = 1.5 V	2.3	2.7			
	Low-side sink (see Note 4)	Duty cycle < 2%, t <sub>pw</sub> < 100 μs (see Note 3)	V <sub>CC</sub> = 4.5 V, V <sub>LOWDR</sub> = 4 V	1.3	1.8		A	
			V <sub>CC</sub> = 6.5 V, V <sub>LOWDR</sub> = 5 V	2	2.5			
			V <sub>CC</sub> = 12 V, V <sub>LOWDR</sub> = 10.5 V	3	3.5			
	Low-side source (see Note 4)	Duty cycle < 2%, t <sub>pw</sub> < 100 μs (see Note 3)	V <sub>CC</sub> = 4.5 V, V <sub>LOWDR</sub> = 0.5 V	1.4	1.7		A	
			V <sub>CC</sub> = 6.5 V, V <sub>LOWDR</sub> = 1.5 V	2	2.4			
			V <sub>CC</sub> = 12 V, V <sub>LOWDR</sub> = 1.5 V	2.5	3			
Output resistance	High-side sink (see Note 4)		V <sub>BOOT</sub> - V <sub>BOOTLO</sub> = 4.5 V, V <sub>HIGHDR</sub> = 0.5 V			5	Ω	
			V <sub>BOOT</sub> - V <sub>BOOTLO</sub> = 6.5 V, V <sub>HIGHDR</sub> = 0.5 V			5		
			V <sub>BOOT</sub> - V <sub>BOOTLO</sub> = 12 V, V <sub>HIGHDR</sub> = 0.5 V			5		
	High-side source (see Note 4)			V <sub>BOOT</sub> - V <sub>BOOTLO</sub> = 4.5 V, V <sub>HIGHDR</sub> = 4 V			75	Ω
				V <sub>BOOT</sub> - V <sub>BOOTLO</sub> = 6.5 V, V <sub>HIGHDR</sub> = 6 V			75	
				V <sub>BOOT</sub> - V <sub>BOOTLO</sub> = 12 V, V <sub>HIGHDR</sub> = 11.5 V			75	
	Low-side sink (see Note 4)			V <sub>DRV</sub> = 4.5 V, V <sub>LOWDR</sub> = 0.5 V			9	Ω
				V <sub>DRV</sub> = 6.5 V, V <sub>LOWDR</sub> = 0.5 V			7.5	
				V <sub>DRV</sub> = 12 V, V <sub>LOWDR</sub> = 0.5 V			6	
	Low-side source (see Note 4)			V <sub>DRV</sub> = 4.5 V, V <sub>LOWDR</sub> = 4 V			75	Ω
				V <sub>DRV</sub> = 6.5 V, V <sub>LOWDR</sub> = 6 V			75	
				V <sub>DRV</sub> = 12 V, V <sub>LOWDR</sub> = 11.5 V			75	

NOTES: 3. Ensured by design, not production tested.

4. The pullup/pulldown circuits of the drivers are bipolar and MOSFET transistors in parallel. The peak output current rating is the combined current from the bipolar and MOSFET transistors. The output resistance is the r<sub>DS(on)</sub> of the MOSFET transistor when the voltage on the driver output is less than the saturation voltage of the bipolar transistor.



**TPS2836, TPS2837**  
**SYNCHRONOUS-BUCK MOSFET DRIVER**  
**WITH DEAD-TIME CONTROL**

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**electrical characteristics over recommended operating virtual junction temperature range,  $V_{CC} = 6.5\text{ V}$ ,  $C_L = 3.3\text{ nF}$  (unless otherwise noted) (continued)**

**dead-time**

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{IH}$	High-level input voltage		LOWDR Over the $V_{CC}$ range (see Note 3)	0.7 $V_{CC}$		
$V_{IL}$	Low-level input voltage				1 V	
$V_{IH}$	High-level input voltage	DT Over the $V_{CC}$ range	2			V
$V_{IL}$	Low-level input voltage					1 V

NOTE 3: Ensured by design, not production tested.

**digital control terminals (IN)**

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{IH}$	High-level input voltage		Over the $V_{CC}$ range	2		
$V_{IL}$	Low-level input voltage				1 V	

**switching characteristics over recommended operating virtual junction temperature range,  $C_L = 3.3\text{ nF}$  (unless otherwise noted)**

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
Rise time	HIGHDR output (see Note 3)		$V_{BOOT} = 4.5\text{ V}$ , $V_{BOOTLO} = 0\text{ V}$	60		
		$V_{BOOT} = 6.5\text{ V}$ , $V_{BOOTLO} = 0\text{ V}$	50			
		$V_{BOOT} = 12\text{ V}$ , $V_{BOOTLO} = 0\text{ V}$	50			
	LOWDR output (see Note 3)	$V_{CC} = 4.5\text{ V}$	40			ns
		$V_{CC} = 6.5\text{ V}$	30			
		$V_{CC} = 12\text{ V}$	30			
Fall time	HIGHDR output (see Note 3)	$V_{BOOT} = 4.5\text{ V}$ , $V_{BOOTLO} = 0\text{ V}$	50			ns
		$V_{BOOT} = 6.5\text{ V}$ , $V_{BOOTLO} = 0\text{ V}$	40			
		$V_{BOOT} = 12\text{ V}$ , $V_{BOOTLO} = 0\text{ V}$	40			
	LOWDR output (see Note 3)	$V_{CC} = 4.5\text{ V}$	40			ns
		$V_{CC} = 6.5\text{ V}$	30			
		$V_{CC} = 12\text{ V}$	30			
Propagation delay time	HIGHDR going low (excluding dead-time) (see Note 3)	$V_{BOOT} = 4.5\text{ V}$ , $V_{BOOTLO} = 0\text{ V}$	95			ns
		$V_{BOOT} = 6.5\text{ V}$ , $V_{BOOTLO} = 0\text{ V}$	80			
		$V_{BOOT} = 12\text{ V}$ , $V_{BOOTLO} = 0\text{ V}$	65			
	LOWDR going high (excluding dead-time) (see Note 3)	$V_{BOOT} = 4.5\text{ V}$ , $V_{BOOTLO} = 0\text{ V}$	80			ns
		$V_{BOOT} = 6.5\text{ V}$ , $V_{BOOTLO} = 0\text{ V}$	70			
		$V_{BOOT} = 12\text{ V}$ , $V_{BOOTLO} = 0\text{ V}$	60			
Propagation delay time	LOWDR going low (excluding dead-time) (see Note 3)	$V_{CC} = 4.5\text{ V}$	80			ns
		$V_{CC} = 6.5\text{ V}$	70			
		$V_{CC} = 12\text{ V}$	60			
Driver nonoverlap time	DT to LOWDR and LOWDR to HIGHDR (see Note 3)	$V_{CC} = 4.5\text{ V}$	40		170	ns
		$V_{CC} = 6.5\text{ V}$	25		135	
		$V_{CC} = 12\text{ V}$	15		85	

NOTE 3: Ensured by design, not production tested.

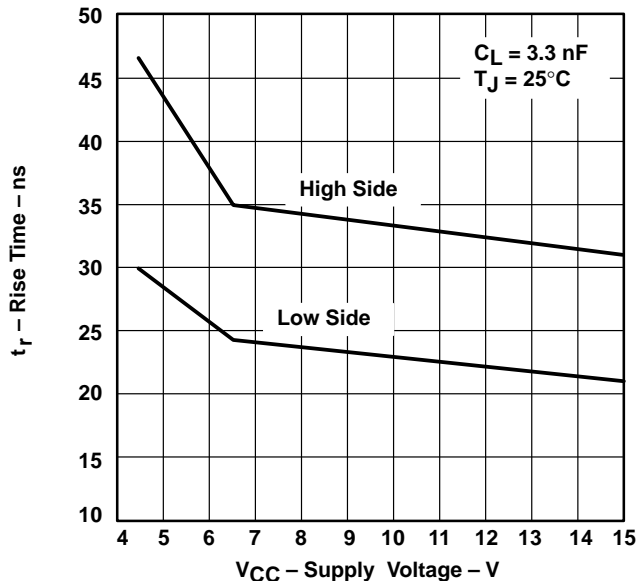


**TPS2836, TPS2837**  
**SYNCHRONOUS-BUCK MOSFET DRIVER**  
**WITH DEAD-TIME CONTROL**

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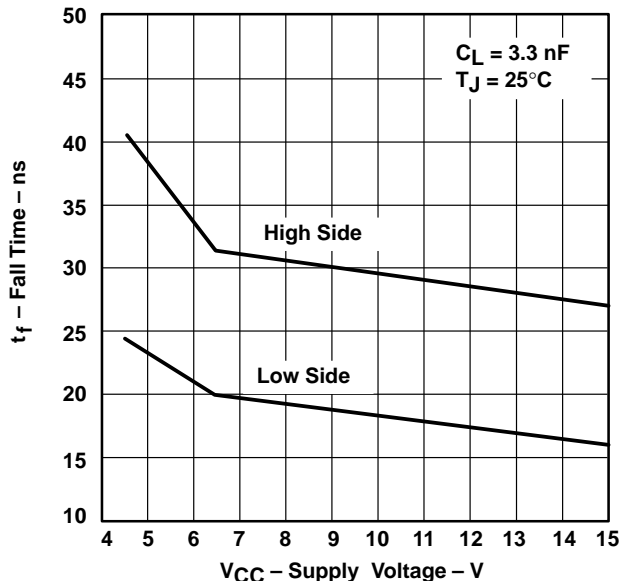
**TYPICAL CHARACTERISTICS**

**RISE TIME**  
**vs**  
**SUPPLY VOLTAGE**



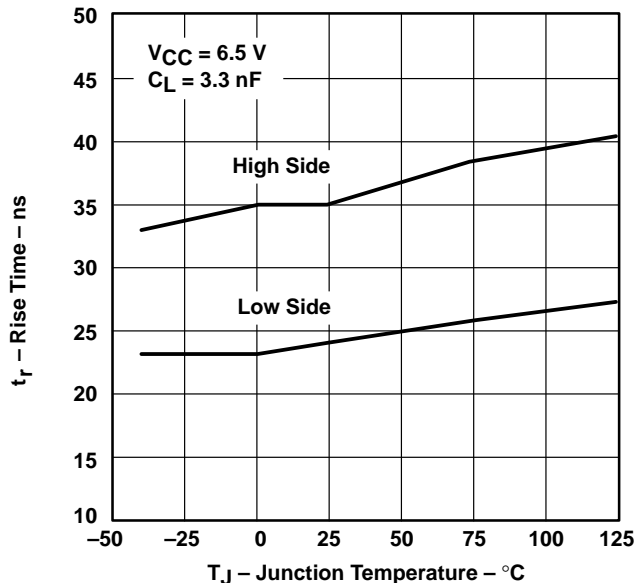
**Figure 1**

**FALL TIME**  
**vs**  
**SUPPLY VOLTAGE**



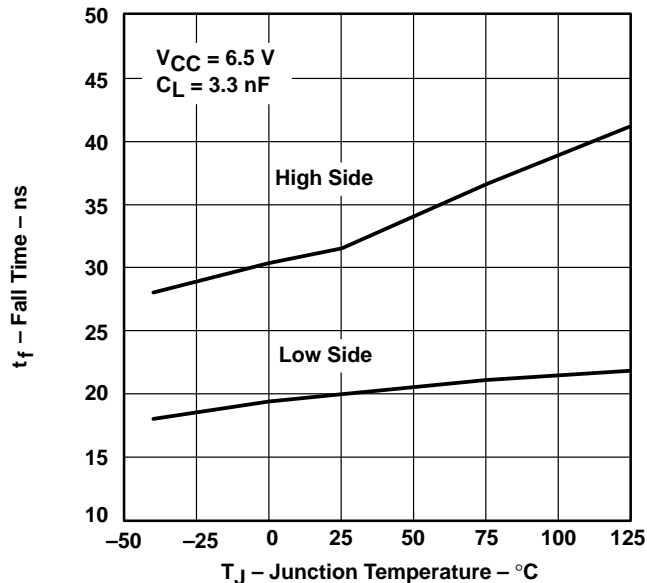
**Figure 2**

**RISE TIME**  
**vs**  
**JUNCTION TEMPERATURE**



**Figure 3**

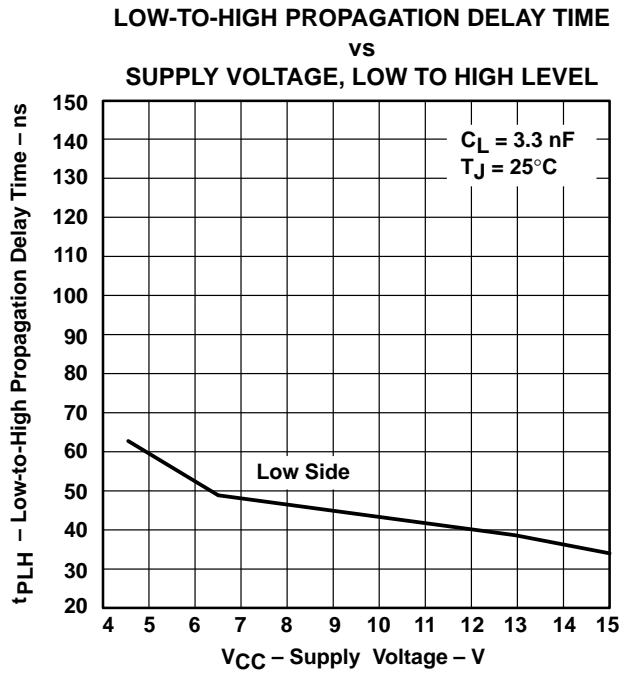
**FALL TIME**  
**vs**  
**JUNCTION TEMPERATURE**



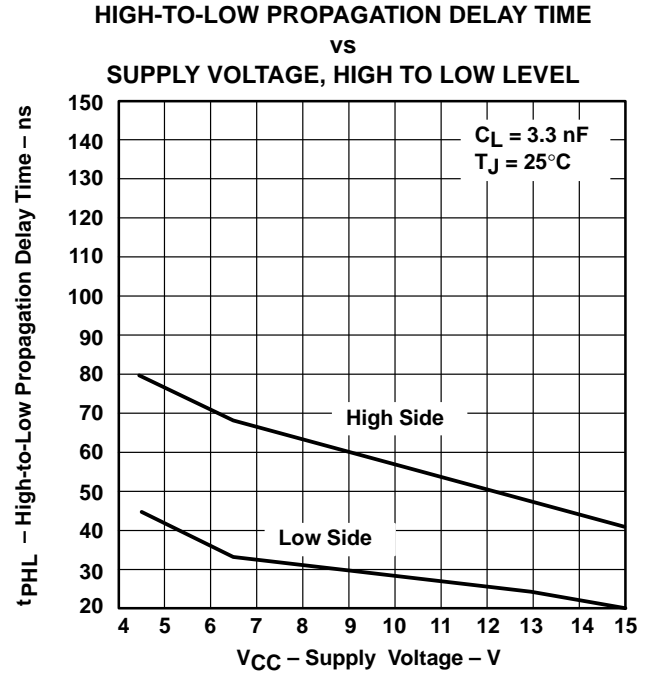
**Figure 4**



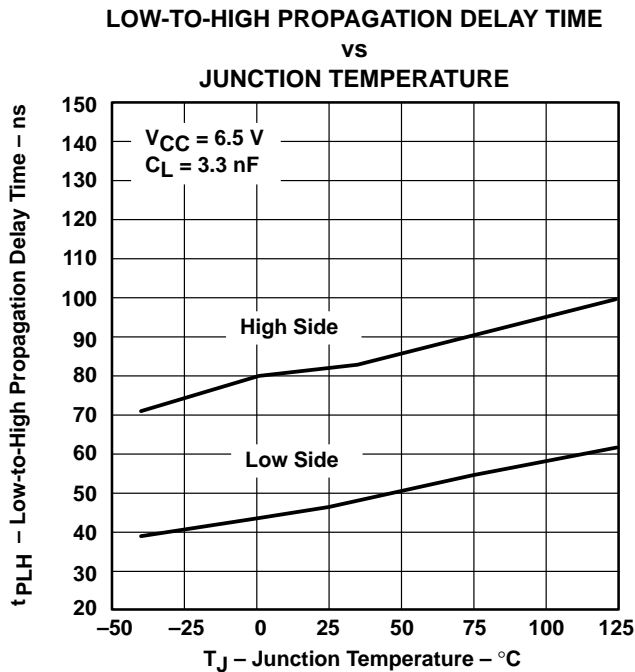
**TYPICAL CHARACTERISTICS**



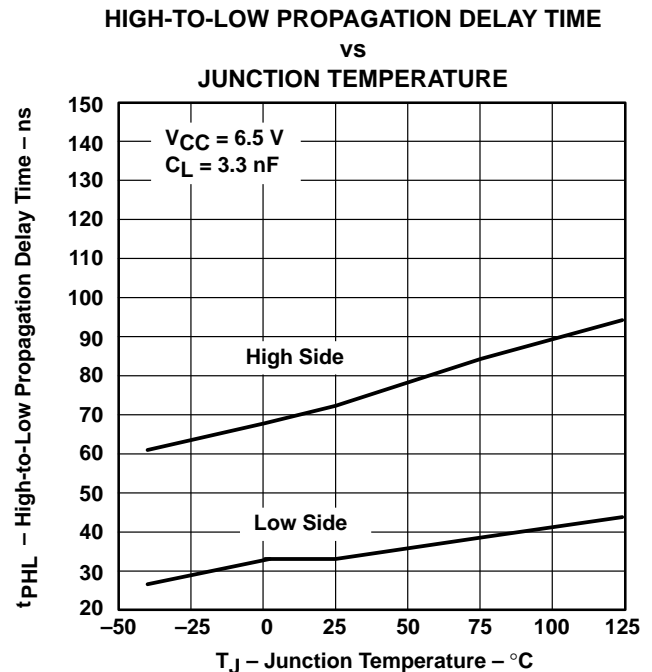
**Figure 5**



**Figure 6**



**Figure 7**



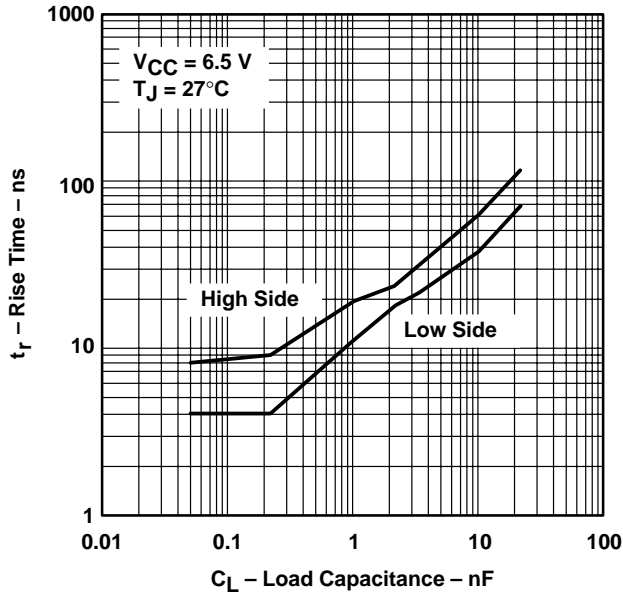
**Figure 8**

**TPS2836, TPS2837**  
**SYNCHRONOUS-BUCK MOSFET DRIVER**  
**WITH DEAD-TIME CONTROL**

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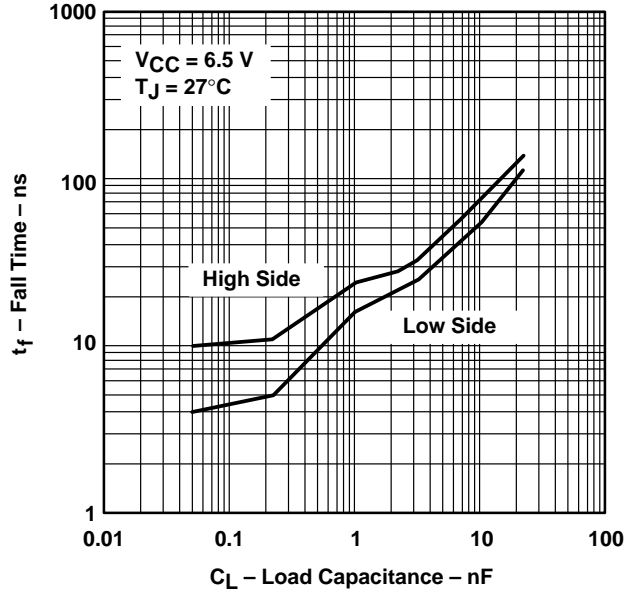
**TYPICAL CHARACTERISTICS**

**DRIVER-OUTPUT RISE TIME**  
**vs**  
**LOAD CAPACITANCE**



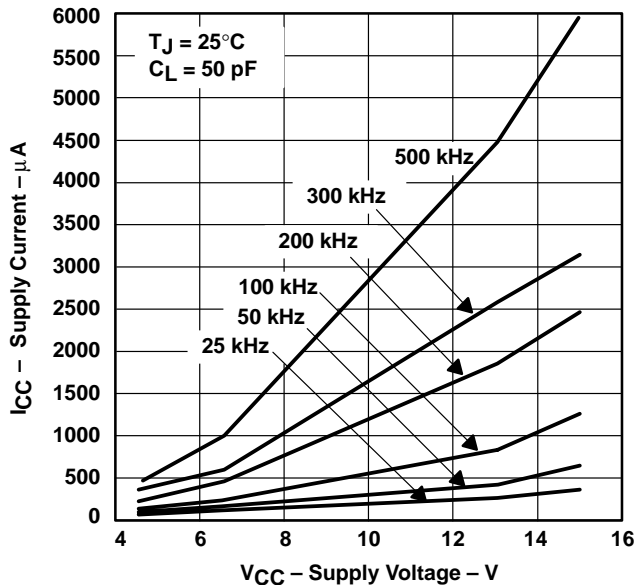
**Figure 9**

**DRIVER-OUTPUT FALL TIME**  
**vs**  
**LOAD CAPACITANCE**



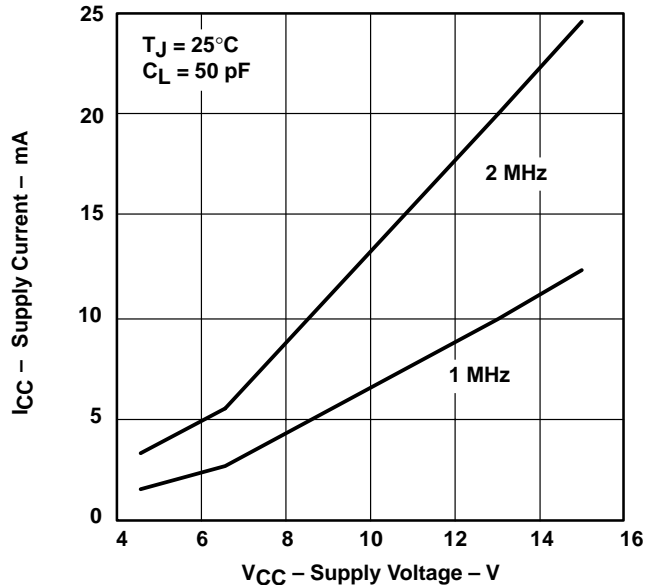
**Figure 10**

**SUPPLY CURRENT**  
**vs**  
**SUPPLY VOLTAGE**



**Figure 11**

**SUPPLY CURRENT**  
**vs**  
**SUPPLY VOLTAGE**



**Figure 12**





TYPICAL CHARACTERISTICS

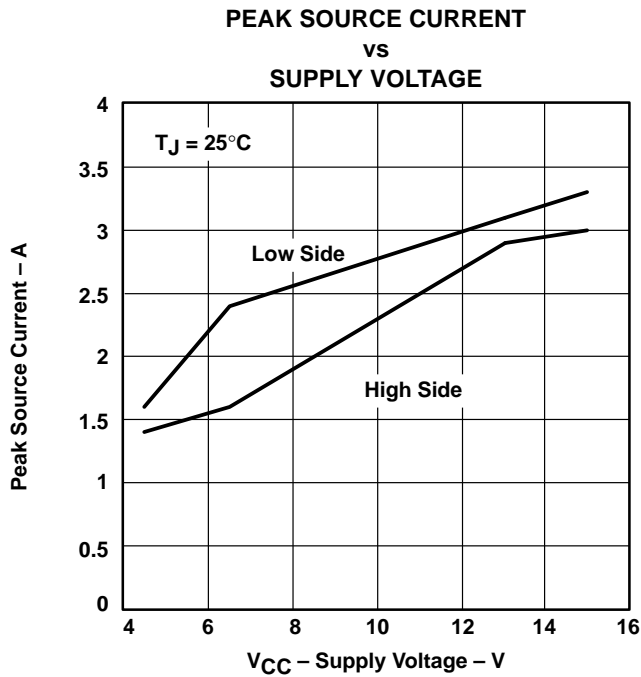


Figure 13

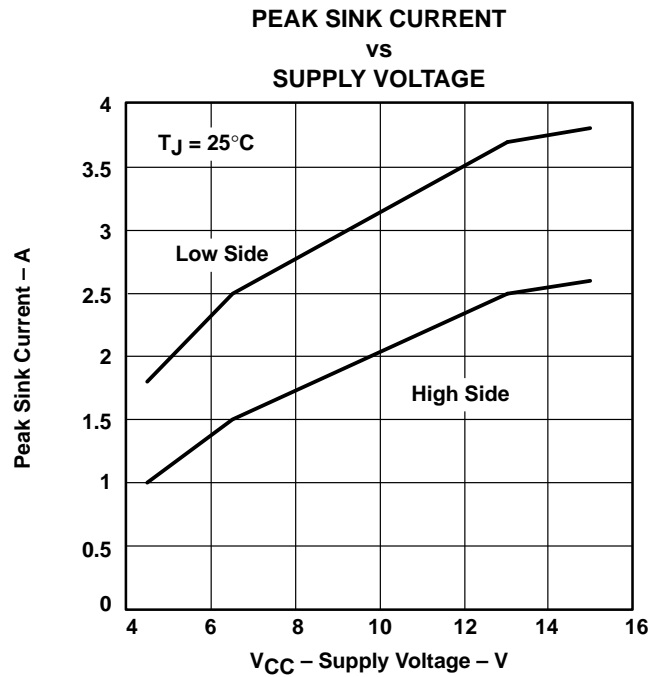


Figure 14

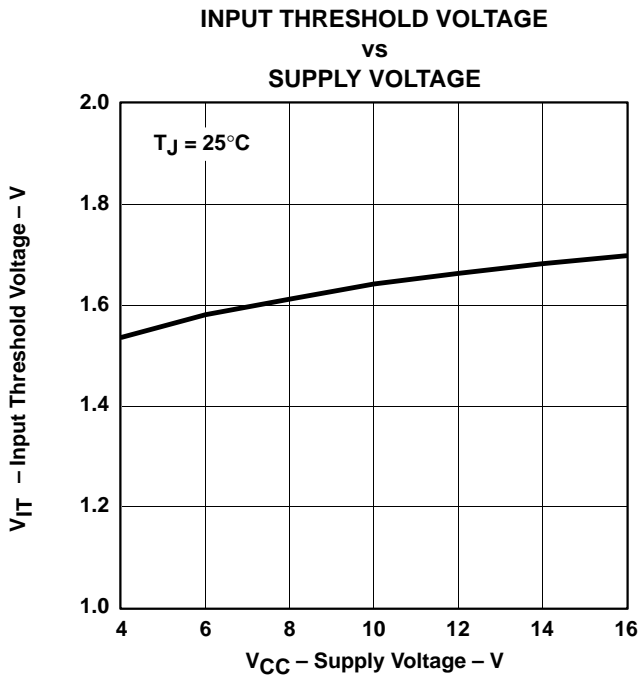


Figure 15

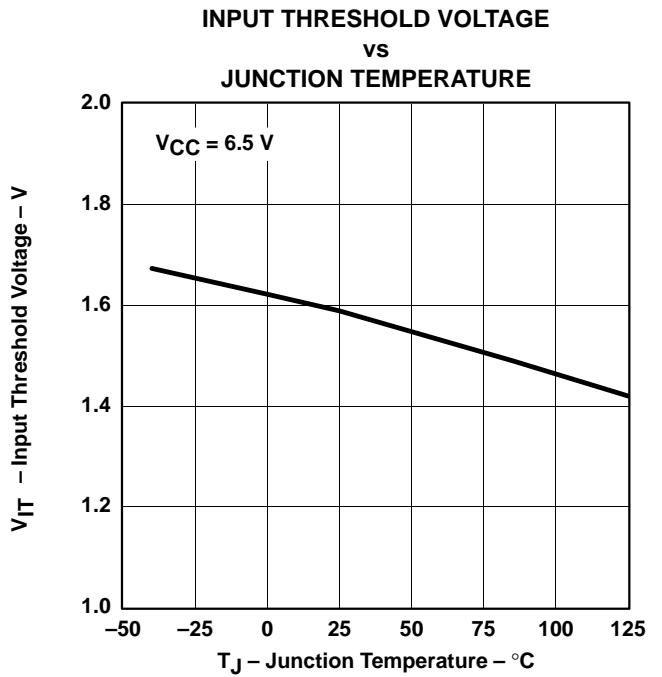


Figure 16

# TPS2836, TPS2837 SYNCHRONOUS-BUCK MOSFET DRIVER WITH DEAD-TIME CONTROL

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## APPLICATION INFORMATION

Figure 17 shows the circuit schematic of a 100-kHz synchronous-buck converter implemented with a TL5001A pulse-width-modulation (PWM) controller and a TPS2837 driver. The converter operates over an input range from 4.5 V to 12 V and has a 3.3-V output. The circuit can supply 3 A continuous load and the transient load is 5 A. The converter achieves an efficiency of 94% for  $V_{IN} = 5\text{ V}$ ,  $I_{load} = 1\text{ A}$ , and 93% for  $V_{IN} = 5\text{ V}$ ,  $I_{load} = 3\text{ A}$ .

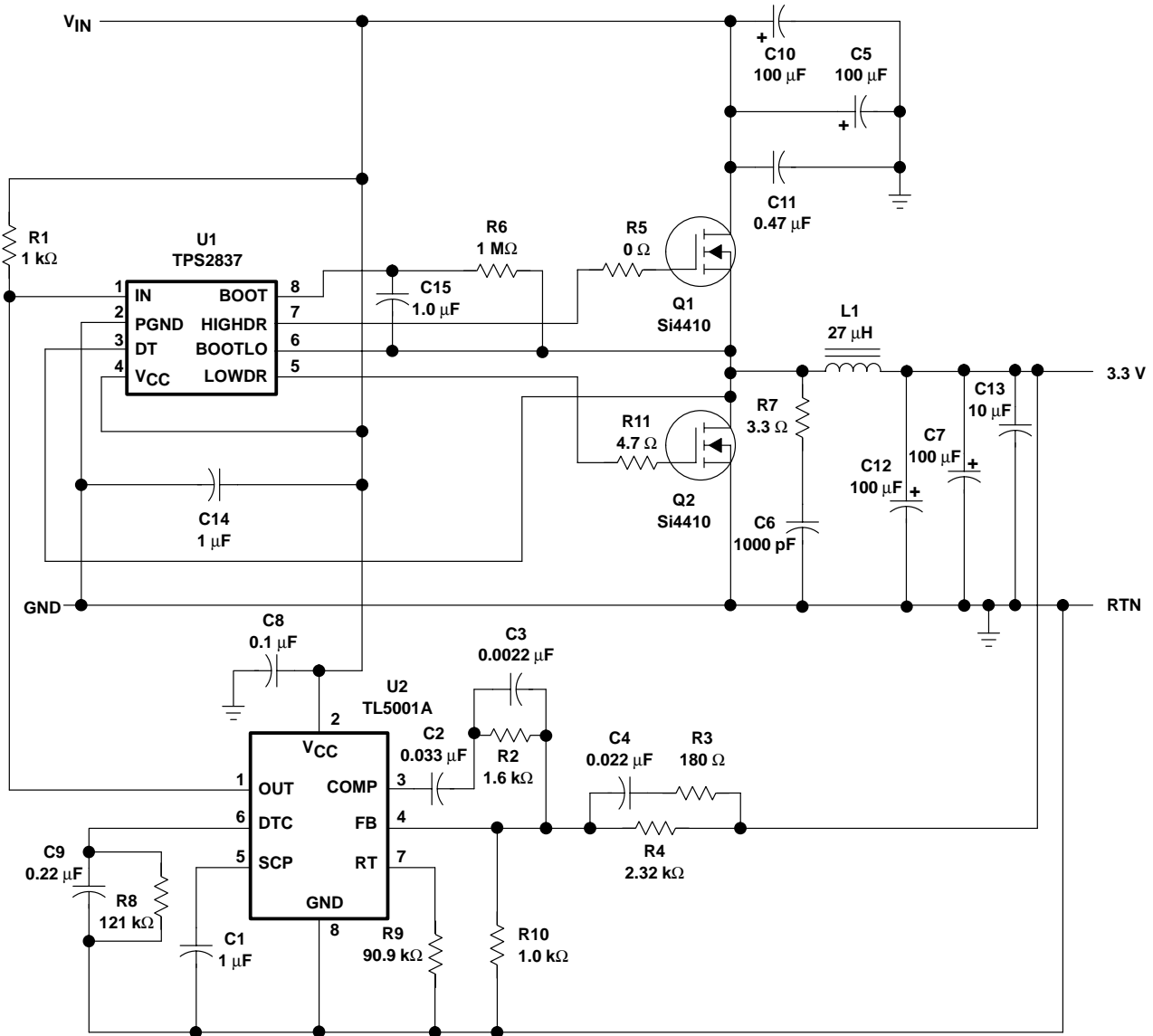


Figure 17. 3.3 V 3 A Synchronous-Buck Converter Circuit

### APPLICATION INFORMATION

Great care should be taken when laying out the PC board. The power-processing section is the most critical and will generate large amounts of EMI if not properly configured. The junction of Q1, Q2, and L1 should be very tight. The connection from Q1 drain to the positive sides of C5, C10, and C11 and the connection from Q2 source to the negative sides of C5, C10, and C11 should be as short as possible. The negative terminals of C7 and C12 should also be connected to Q2 source.

Next, the traces from the MOSFET driver to the power switches should be considered. The BOOTLO signal from the junction of Q1 and Q2 carries the large gate drive current pulses and should be as heavy as the gate drive traces. The bypass capacitor (C14) should be tied directly across  $V_{CC}$  and PGND.

The next most sensitive node is the FB node on the controller (terminal 4 on the TL5001A). This node is very sensitive to noise pickup and should be isolated from the high-current power stage and be as short as possible. The ground around the controller and low-level circuitry should be tied to the power ground as the output. If these three areas are properly laid out, the rest of the circuit should not have other EMI problems and the power supply will be relatively free of noise.

**TPS2836, TPS2837**  
**SYNCHRONOUS-BUCK MOSFET DRIVER**  
**WITH DEAD-TIME CONTROL**

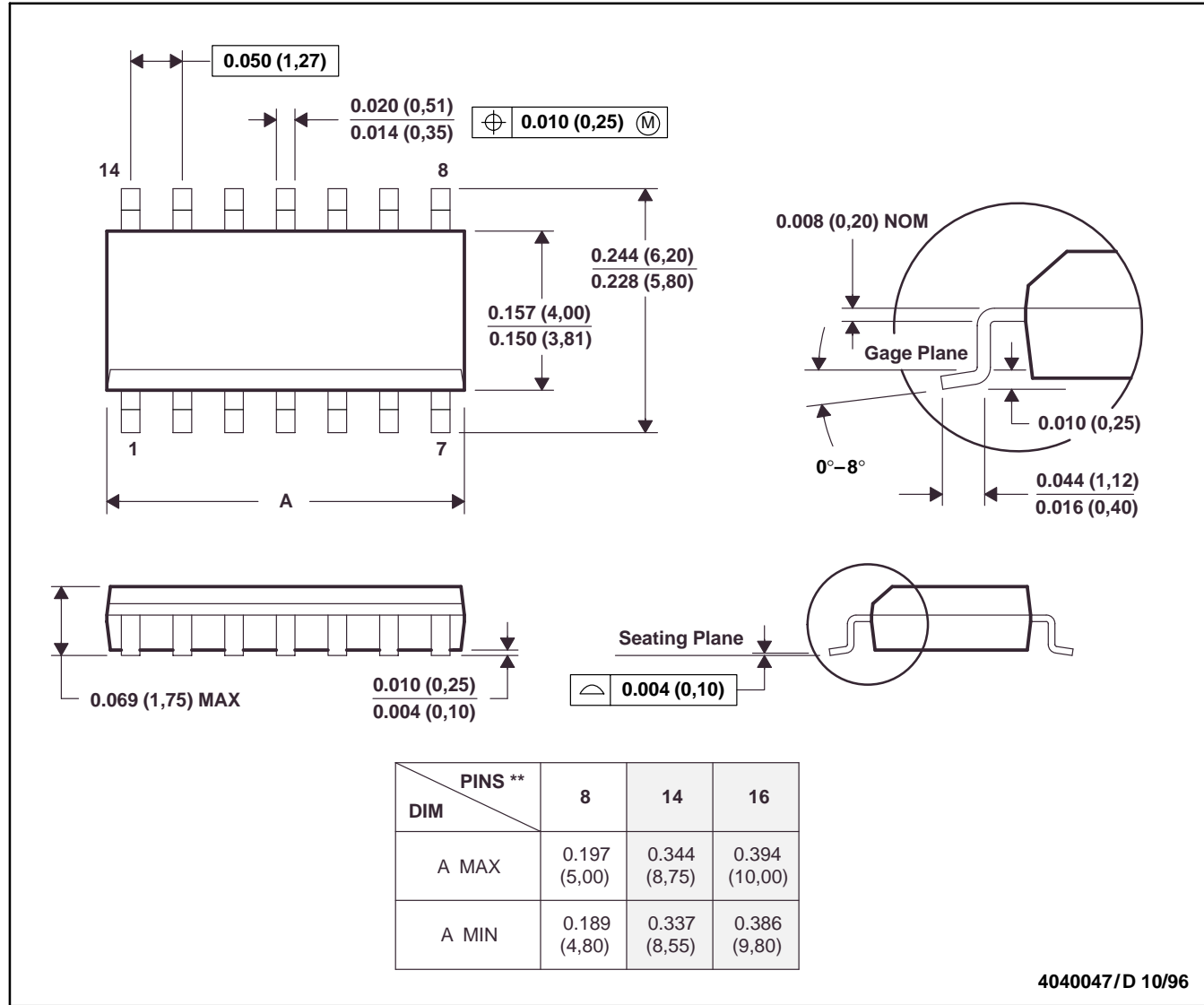
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**MECHANICAL DATA**

**D (R-PDSO-G\*\*)**

**PLASTIC SMALL-OUTLINE PACKAGE**

14 PIN SHOWN



4040047/D 10/96

- NOTES: A. All linear dimensions are in inches (millimeters).  
 B. This drawing is subject to change without notice.  
 C. Body dimensions do not include mold flash or protrusion, not to exceed 0.006 (0,15).  
 D. Falls within JEDEC MS-012

**PACKAGING INFORMATION**

Orderable Device	Status <sup>(1)</sup>	Package Type	Package Drawing	Pins	Package Qty	Eco Plan <sup>(2)</sup>	Lead/Ball Finish	MSL Peak Temp <sup>(3)</sup>
TPS2836D	ACTIVE	SOIC	D	8	75	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
TPS2836DG4	ACTIVE	SOIC	D	8	75	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
TPS2836DR	ACTIVE	SOIC	D	8	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
TPS2836DRG4	ACTIVE	SOIC	D	8	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
TPS2837D	ACTIVE	SOIC	D	8	75	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
TPS2837DG4	ACTIVE	SOIC	D	8	75	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
TPS2837DR	ACTIVE	SOIC	D	8	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
TPS2837DRG4	ACTIVE	SOIC	D	8	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM

<sup>(1)</sup> The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

<sup>(2)</sup> Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check <http://www.ti.com/productcontent> for the latest availability information and additional product content details.

**TBD:** The Pb-Free/Green conversion plan has not been defined.

**Pb-Free (RoHS):** TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

**Pb-Free (RoHS Exempt):** This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

**Green (RoHS & no Sb/Br):** TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

<sup>(3)</sup> MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

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**TAPE AND REEL INFORMATION**



**QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE**



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TPS2836DR	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1
TPS2837DR	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1

**TAPE AND REEL BOX DIMENSIONS**



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TPS2836DR	SOIC	D	8	2500	346.0	346.0	29.0
TPS2837DR	SOIC	D	8	2500	346.0	346.0	29.0

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