

Low-Current Superhet Remote Control Receiver

Description

The U4311B-FS is a monolithic integrated circuit in bipolar technology for low-current UHF remote control super-heterodyne receivers in amplitude- or frequency-modulated mode. Typical applications are keyless car

lock-, alarm- or tele-control remote indication systems. Especially for automotive applications, it supports a superhet design with about 1 mA total current consumption as required by the car manufacturers.

Features

- Usable for amplitude- and frequency-modulated transmission systems
- Extremely low quiescent current (approximately 1 mA in standby mode due to wake-up concept)
- Wide power supply voltage range 3 to 13 V
- Sensitive IF amplifier for 10.7-MHz operating frequency
- Logarithmic AM demodulator
- FM demodulator
- Monoflop output to wake up a microcontroller
- High-performance operational amplifier to realize a data recovering filter
- Non-inverting clamping comparator with amplitude-depending hysteresis for data regeneration

Block Diagram

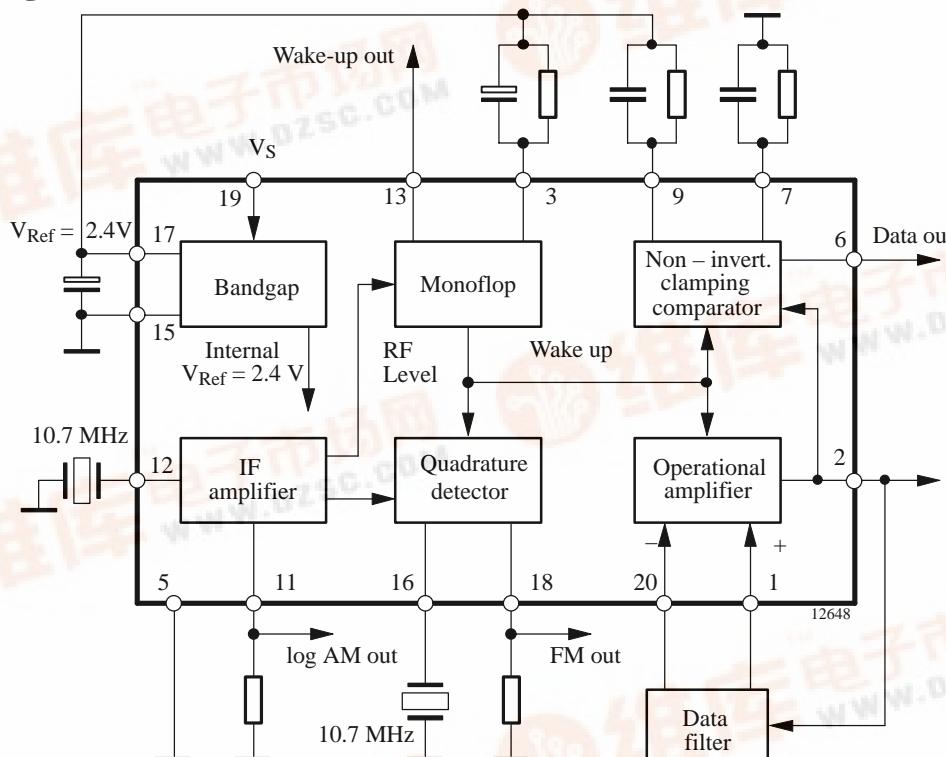


Figure 1. Block diagram

Ordering Information

Extended Type Number	Package	Remarks
U4311B-MFSG3	SSO20	Ambient temperature up to +105°C

U4311B-FS



Pin Description

Pin	Symbol	Function
1	OP _{in+}	OP amplifier non-inverted input
2	OP _{out}	OP amplifier output
3	RC _{wake}	RC wake-up reset time
4	n.c.	Not connected
5	GND2	Ground of the logical circuits
6	Comp _{out}	Comparator output
7	RC-	Comparator time constant
8	n.c.	Not connected
9	RC+	Comparator time constant
10	n.c.	Not connected
11	AM _{out}	AM current output
12	IF _{in}	IF input
13	SW _{out}	Wake-up output
14	n.c.	Not connected
15	GND1	Ground of the analog circuits
16	Discr	FM discriminator tank
17	V _{Ref}	Reference voltage
18	FM _{out}	FM discriminator output
19	V _S	Supply voltage
20	OP _{in-}	OP amplifier inverted input

Figure 2. Pinning

Internal connections see figures 4 to 19

Absolute Maximum Ratings

Parameters	Symbol	Value	Unit
Supply voltage	V _S	13	V
Power dissipation T _{amb} = 85°C	P _{tot}	400	mW
Junction temperature	T _j	125	°C
Storage temperature	T _{stg}	-55 to +125	°C
Ambient temperature for SSO20	T _{amb}	-40 to +105	°C

Thermal Resistance

Parameters	Symbol	Value	Unit
Junction ambient SSO20	R _{thJA}	140	K/W

Electrical Characteristics

$V_S = 5$ V, $T_{amb} = 25^\circ\text{C}$, $f_{in} = 10.7$ MHz; FM part: $f_{mod} = 1$ kHz, $f_{dev} = 22.5$ kHz; AM part: $f_{mod} = 1$ kHz, $m = 100\%$ unless otherwise specified

Parameters	Test Conditions / Pins	Symbol	Min.	Typ.	Max.	Unit
Characteristics						
Supply-voltage range	Pin 19	V_S	3		12	V
Quiescent supply current	Pin 19	I_q		1	1.3	mA
Active supply current	Pin 19	I_{act}		2.8	3.6	mA
Bandgap						
Regulated voltage	Pin 17	V_{Ref}	2.3	2.4	2.5	V
Output current	Pin 17	I_{Ref}			5	mA
Source resistance	Pin 17	R_{Ref}		2.3	5	Ω
External capacitor	Pin 17	C_{Ref}	10			μF
Power-supply rejection ratio	$f = 50$ Hz	Pin 17	psrr	60		dB
IF amplifier						
Input resistance	Pin 12	R_{in}	180	330	520	Ω
Input capacitance	Pin 12	C_{in}		5		pF
Typical internal 3 dB frequency	IF level 70 dB μ V Pins 12 and 18	$f_{3\text{dB}}$	8		12	MHz
-3 dB limiting point	Pin 12	$V_{FM3\text{dB}}$		30		$\text{dB}\mu\text{V}$
Recovered data voltage	Pin 18	V_{FMout}	50	130	230	mV
FM detector output resistance	Pin 18	R_{FMout}		50		k Ω
AM rejection ratio	$m = 30\%$	Pins 12 and 18	AM_{rr}	25		dB
Maximum AM input voltage	Pin 12	V_{AMmax}		90		$\text{dB}\mu\text{V}$
AM quiescent current	Pin 11	I_{AMout}	10	22	37	μA
Maximum AM current	Pin 11	$I_{AMoutmax}$		100		μA
Operational amplifier						
Gain-bandwidth product	Pins 1, 2 and 20	f_t	3	4	6.5	MHz
Excess phase	Pins 1, 2 and 20	δ		80		degree
Open loop gain	Pins 1, 2 and 20	g_0	50	70	95	dB
Output voltage range	Pin 2	ΔV_{out}		1.55		V
Common mode input voltage	Pins 1 and 20	V_{in}	0.7		1.7	V
Input offset voltage	Pins 1 and 20	V_{os}	-2.5	0	+2.5	mV
Maximum output current	Pin 2	I_{out}			5	mA
Common-mode rejection ratio	Pin 1 and 20	$cmrr$	65	85		dB
Total harmonic distortion	$V_{in} < 300$ mV, $f = 33$ kHz, unity gain circuit Pin 2	thd		1	3	%

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Electrical Characteristics (continued)

$V_S = 5 \text{ V}$, $T_{\text{amb}} = 25^\circ\text{C}$, $f_{\text{in}} = 10.7 \text{ MHz}$; FM part: $f_{\text{mod}} = 1 \text{ kHz}$, $f_{\text{dev}} = 22.5 \text{ kHz}$; AM part: $f_{\text{mod}} = 1 \text{ kHz}$, $m = 100\%$ unless otherwise specified

Parameters	Test Conditions / Pins	Symbol	Min.	Typ.	Max.	Unit
Power-supply rejection ratio	$f = 50 \text{ Hz}$ Pin 2	psrr	65	85		dB
Clamping comparator						
Typical common-mode input voltage range	Pin 2	V_{cmvr}	0.8		1.6	V
Maximum distortion voltage	$V_{\text{signal}} = 100 \text{ mV}$, $R_+ = R_- = 50 \text{ k}\Omega$, $C_+ = C_- = 200 \text{ nF}$, $f_{\text{disto}} = 50 \text{ Hz}$, $f_{\text{signal}} = 1 \text{ kHz}$ Pin 2	V_{dmax}			200	mV
Output voltage	$V_2 > (V_7 + V_9) / 2$ (10-kΩ load to V_{Ref}) Pin 6	V_{cout}		V_{Ref}		V
Output voltage	$V_2 < (V_7 + V_9) / 2$ (10-kΩ load to V_{Ref}) Pin 6	V_{cout}	0	150	250	mV
Wake-up circuit						
Minimum wake-up level	Pin 12	V_{in}		40		$\text{dB}\mu\text{V}^1)$
Internal charging resistor	Pin 3	R_{int}		1.5		kΩ
Threshold voltage	Pin 3	V_{th}		1.6		V
Output switch current	Pin 13	I_{SW}	180	250	550	μA
Output switch voltage	Pin 13	V_{SW}			5.5	V ²⁾
External wake-up resistor	Pins 3 and 17	R_{WU}	22			kΩ
External wake-up capacitor	Pins 3 and 17	C_{WU}			10	μF
Hold time (± 30%)		t_h	$\approx 1.5 \times R_{\text{WU}} \times C_{\text{WU}}$			s ³⁾
Delay time (± 30%)		t_d	$\approx C_{\text{WU}} \times 0.75 \text{ k}\Omega$			s ³⁾

1) Measured at Pin 9, (12) referred to $330 \text{ }\Omega$

2) Protected by a Z-diode, see figure 13

3) Valid for $0.1 \mu\text{F} \leq C_{\text{WU}} \leq 10 \mu\text{F}$ and $22 \text{ k}\Omega \leq R_{\text{WU}} \leq 680 \text{ k}\Omega$

Circuit Description

General Functions

The integrated circuit U4311B-FS includes the following functions: IF amplifier, FM demodulator, wake-up circuit with monoflop, operational amplifier, non-inverting data comparator and voltage regulator.

The 10.7-MHz IF signal from the front end passes the integrated IF amplifier which operates for amplitude- or frequency-modulated signals to either a logarithmic AM demodulator which was implemented to avoid settling-time problems effected by use of an automatic gain control system or a quadrature detector for FM. A data-shaping filter – advantageously realized with the internal high-performance operational amplifier – reduces system bandwidth to an optimized compromise regarding transmission distance and data recognition. Thus, an optimal bit-error rate can be achieved without any further active component.

The comparator connected to the output of the filter has a level-dependent hysteresis and clamps its reference voltage to the signal's minimum and maximum peaks as described later.

Without IF-input signal – in normal mode – only the IF amplifier and the AM demodulator which operates as a level-strength indicator are activated. If the level of the IF

signal increases, the entire circuitry is turned on by the wake-up circuit. This signal is externally available at Pin 13 and can be used to wake up a microcontroller. After an adjustable reset time, determined by the monoflop time constant, the integrated circuit returns to sleep mode. In this case, typically 1-mA supply current is required. An external resistor matched at Pin 3 to ground blocks the wake-up circuit and enables the complete functionality at lower IF level as can be seen in figures 24 and 27, but supply current increases up to typically 2.8 mA.

Function of the Clamping Comparator

The output signal of the operational amplifier is fed to the input of the non-inverting comparator and two peak detectors (Q1 and Q2, figure 3). Their time constants are distinguished by RC_+ and RC_- . The component's value must be adapted to the transmission code. The time constant should be large compared to the bit rate for optimized noise and hum suppression. To compensate the input transistor's base-emitter-voltage differences, these two signals are buffered by Q3 and Q4. The mean value is used as comparator threshold, the difference of the peak values controls the hysteresis. This clamping comparator operates as a data regenerator.

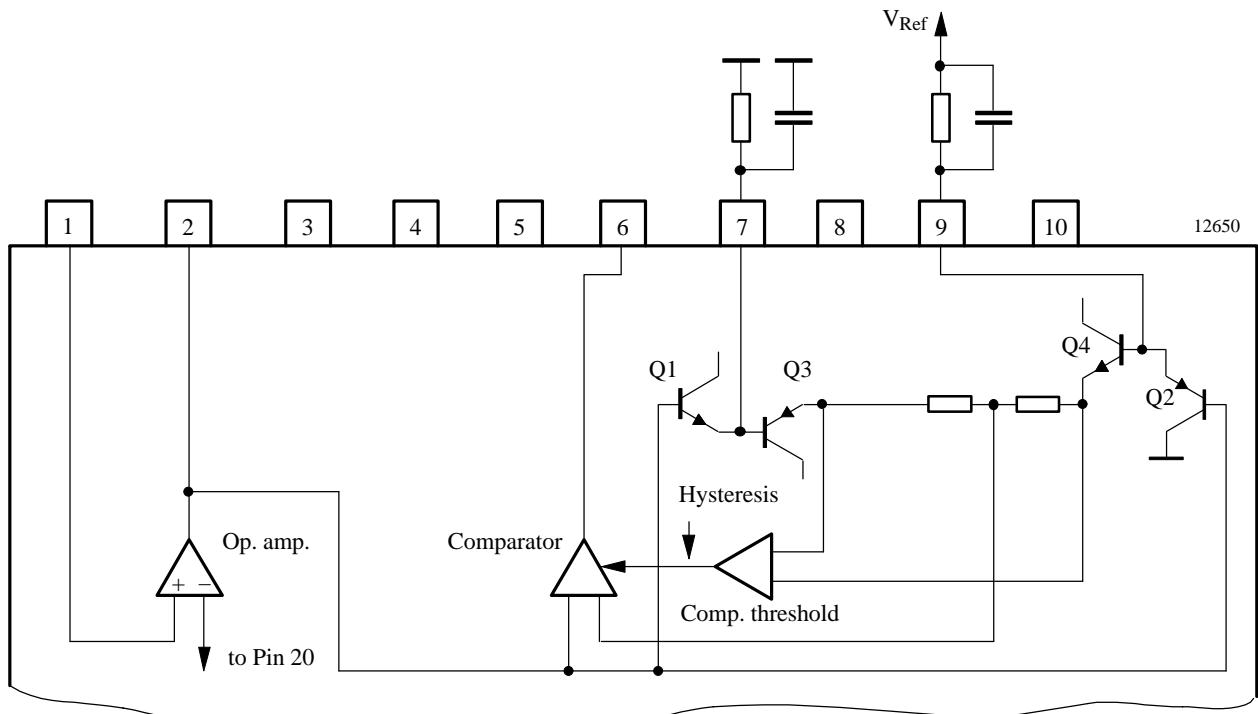


Figure 3. Principle function of the clamping comparator

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Internal Pin Circuitry

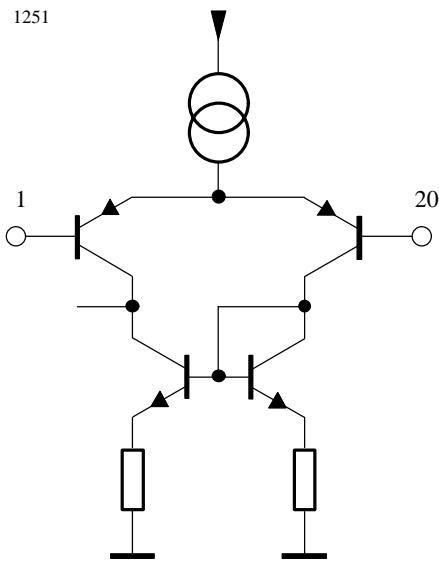


Figure 7. Pin 5 GND2

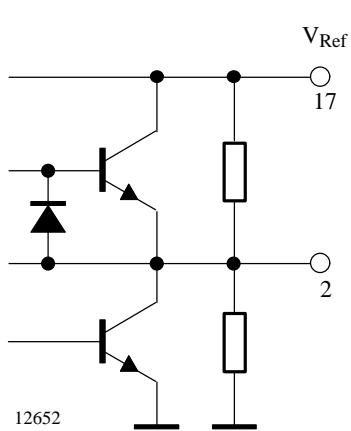


Figure 5. Pin 2 OP_{out}

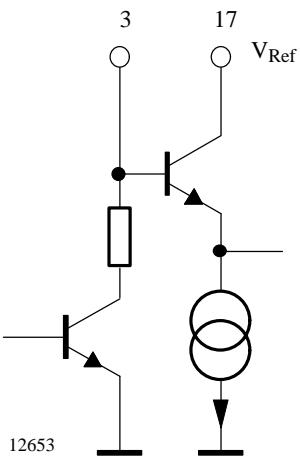


Figure 6. Pin 3 RC_{wake}

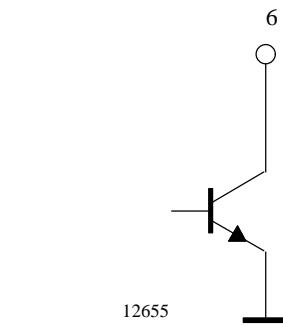


Figure 8. Pin 6 Comp_{out}

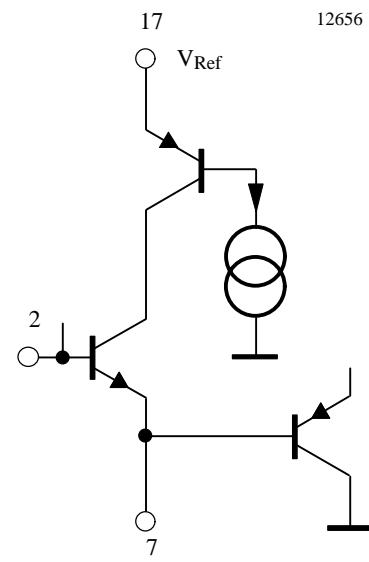


Figure 9. Pin 7 RC-

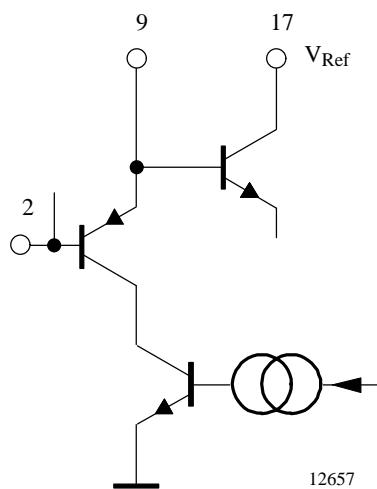


Figure 10. Pin 9 RC+

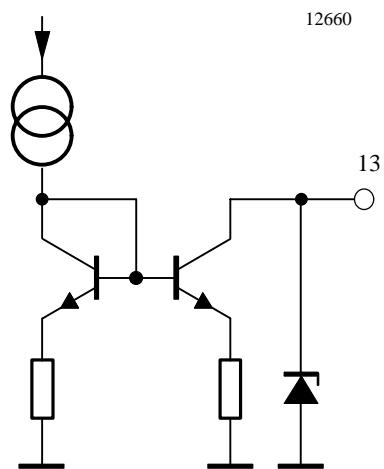


Figure 13. Pin 13 SW_{out}

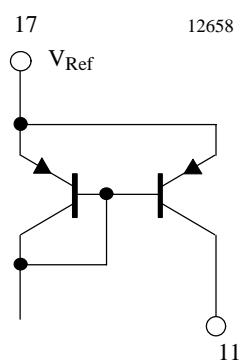


Figure 11. Pin 11 AM_{out}



Figure 14. Pin 15 GND1

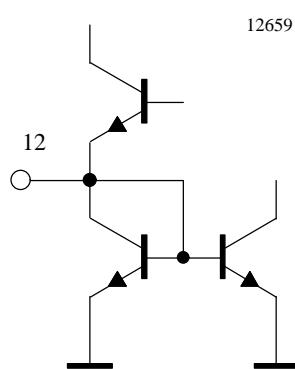


Figure 12. Pin 12 IF_{in}

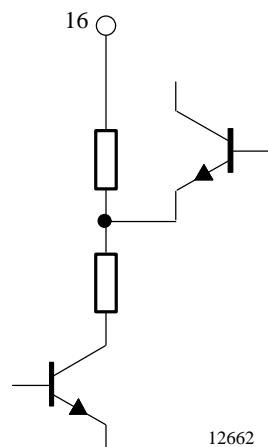


Figure 15. Pin 16 Discr

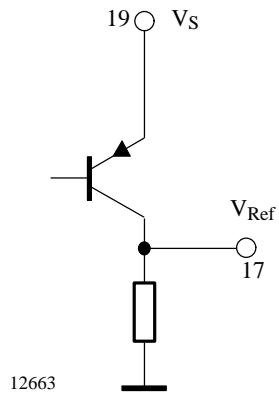


Figure 16. Pin 17 V_{Ref}

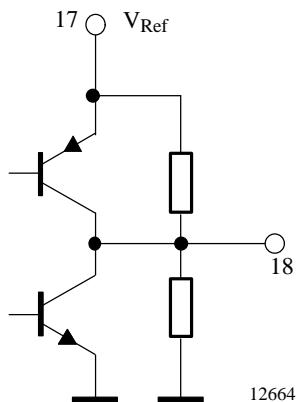


Figure 17. Pin 18 FM_{out}

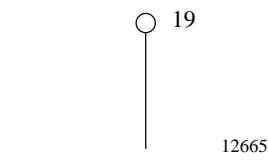


Figure 18. Pin 19 V_S

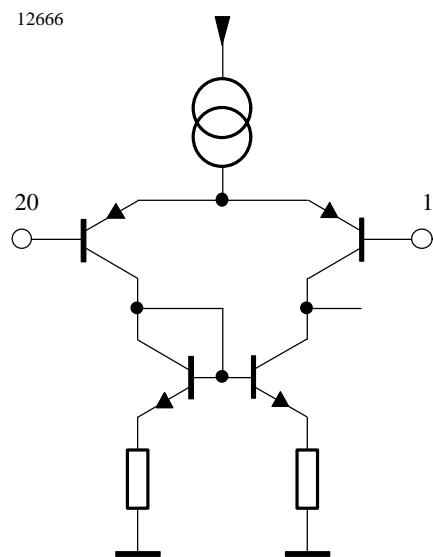


Figure 19. Pin 20 OP_{in-}

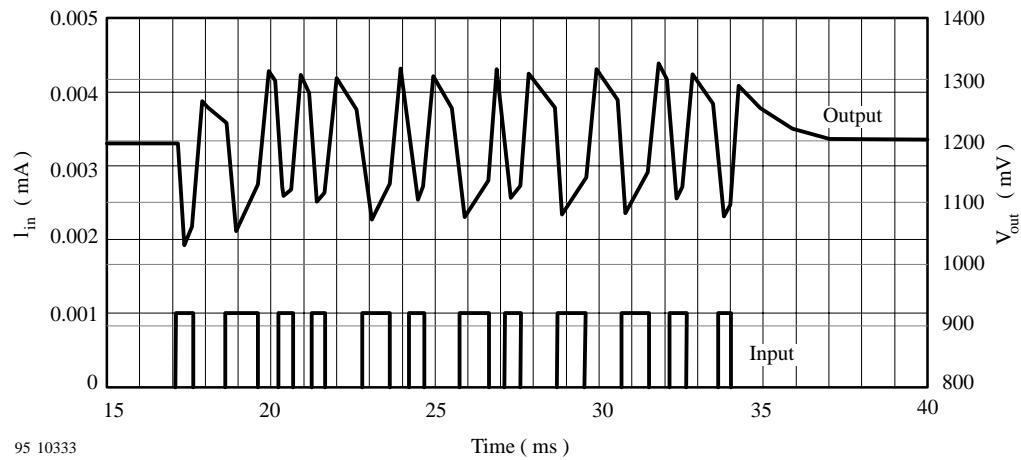


Figure 20. Time domain response of 2-kHz Bessel lowpass data filter

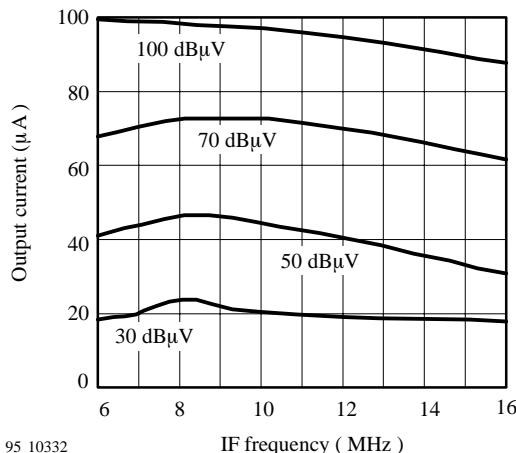


Figure 21. IF-frequency response

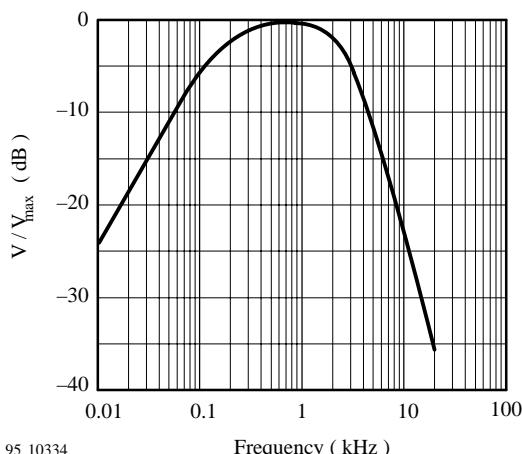


Figure 22. Frequency response of 2-kHz Bessel lowpass data filter

Data-Recovering Filter

The test circuit in figures 23 and 26 includes an example of a data-recovering filter realized with the components R_1 , R_2 , C_1 , C_2 , C_3 . It is of a second-order Bessel type with lowpass characteristic, a 3-dB cut-off frequency of 2 kHz and an additional highpass characteristic for suppressing dc and low-frequency ac components. Simulation of time domain and frequency response can be seen in figures 20 and 22. This filter gives a typical application of a 1-kBaud Manchester-code amplitude-modulated transmission.

The capacitor C_2 is responsible for the highpass cut-off frequency. In order to a correct pulse response, this highpass cut-off frequency should be as low as possible. Figure 20 shows the transient response and the influence of the dc component. The first pulses might be wrong if the highpass cut-off frequency is too low. For this reason, some burst bits must be transmitted before the real data transmission starts. On the other hand, if the cut-off frequency is too high, roof shaping of the rectangle pulses at the operational amplifier output might cause problems.

The lowpass cut-off frequency and the maximum transmission impedance V_{out}/I_{in} are distinguished by the further external elements. Careful design of the data filter enables optimized transmission range. For designing other filter parameters, please refer to filter design handbooks/ programs or request Atmel Wireless & Microcontrollers for support.

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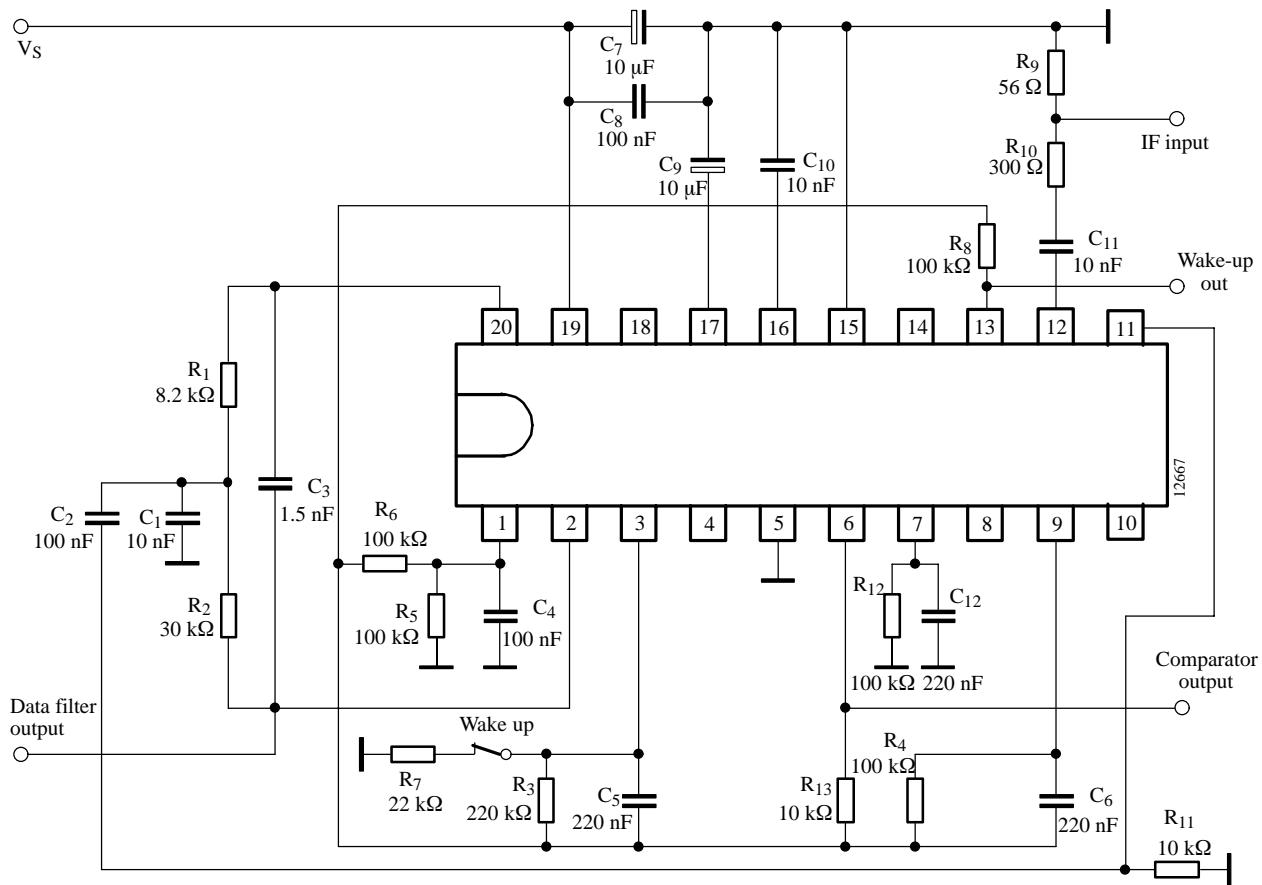


Figure 23. AM test circuit with 2-kHz Bessel lowpass data filter

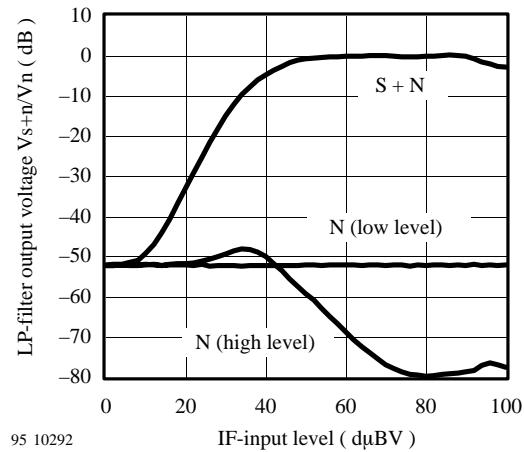


Figure 24. Signal-to-noise ratio AM

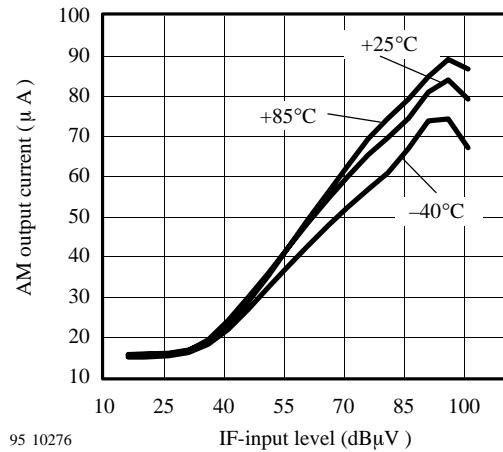


Figure 25. AM-demodulator characteristic vs. temperature

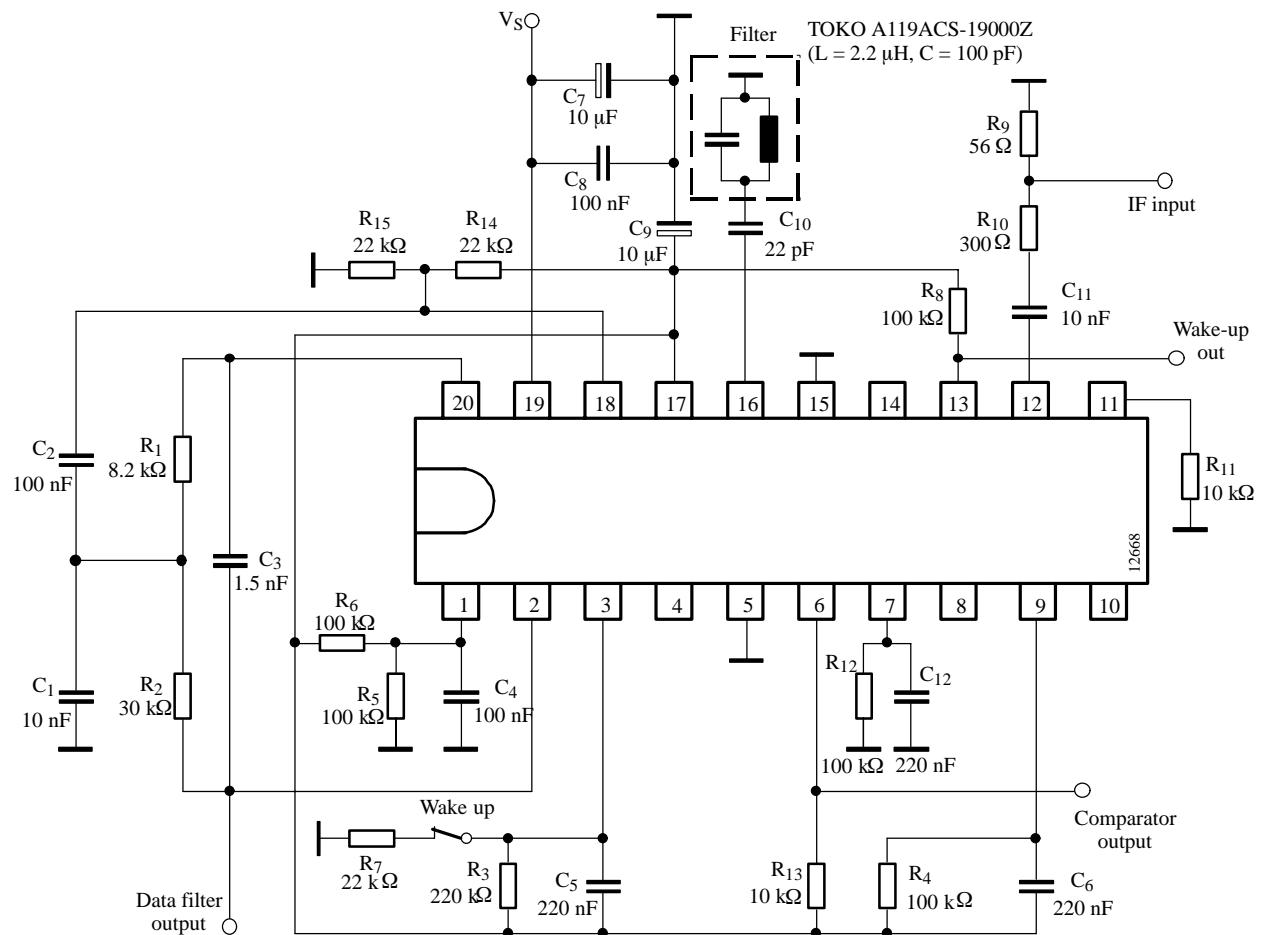


Figure 26. FM test circuit with 2-kHz Bessel lowpass data filter

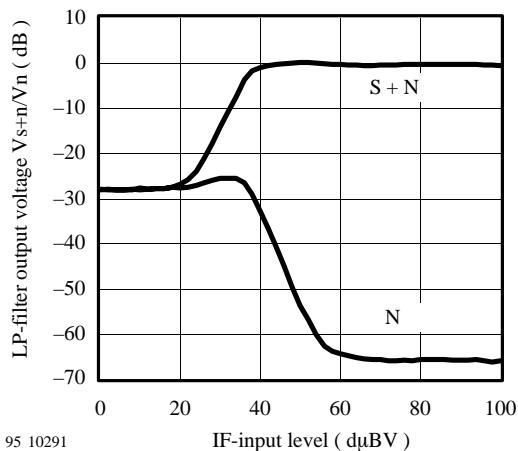


Figure 27. Signal-to-noise ratio FM; deviation 22.5 kHz

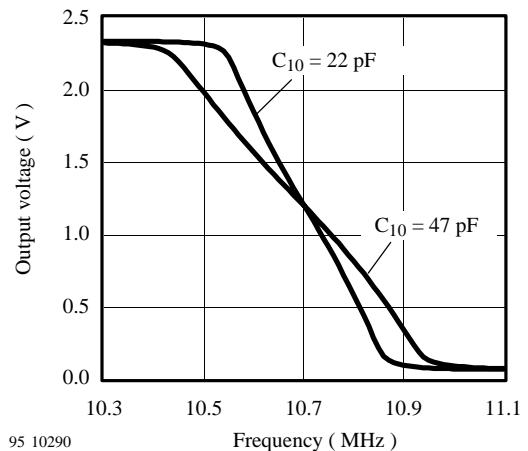


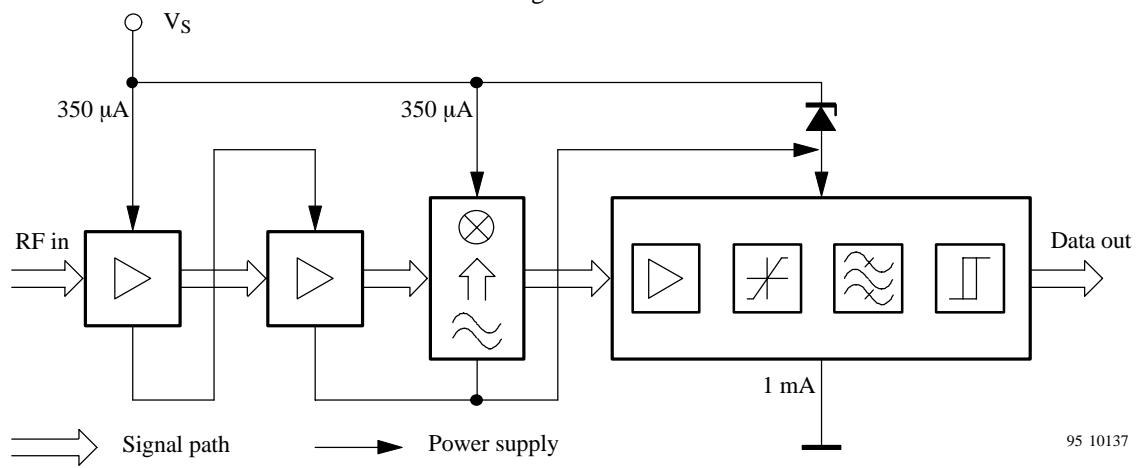
Figure 28. FM-discriminator characteristic

U4311B-FS

Application

The U4311B-FS is well-suited to implement UHF remote control or data transmission systems, based on a low-current superheterodyne receiver concept. SAW-devices may be used in the transmitter's as well as in the receiver local oscillator. The front end should be a discrete circuit application with low-current UHF transistors such as S822T or S852T (Vishay Telefunken). The frequency of the local oscillator can be determined either by coaxial resonators or SAW devices. Due to the large

SAW-resonator, tolerance an IF bandwidth – and in a FM system additionally the discriminator amplitude characteristic (see figure 28) – of 300 kHz or higher is proposed. As the circuit needs only 3.0 V supply voltage for operation, the front end may be a stacked design in order to achieve a total receiver current consumption of approximately 1 mA. Figure 29 shows a principle receiver concept diagram.



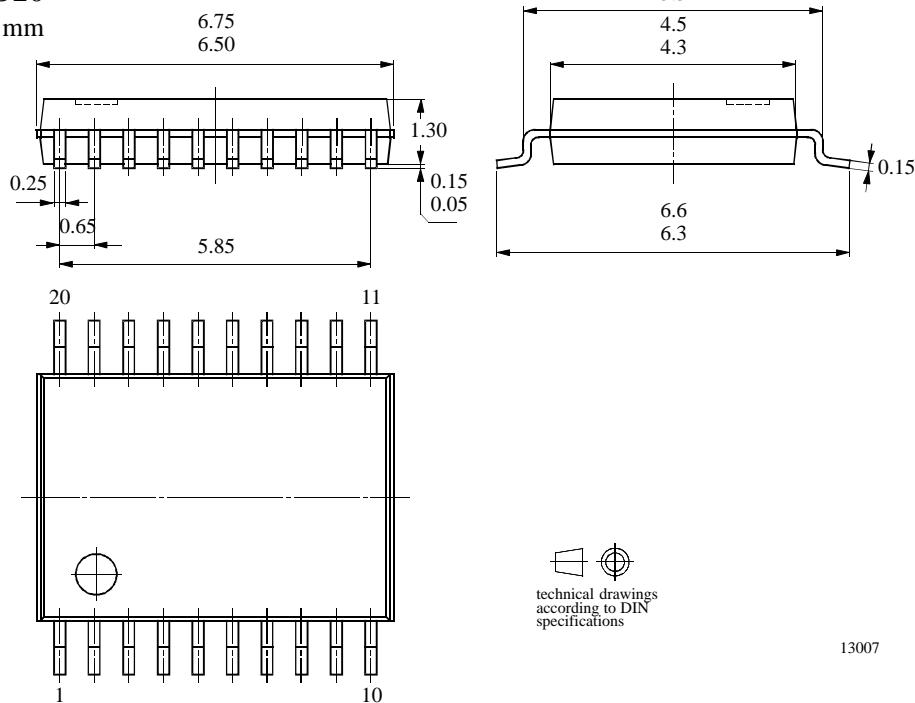
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Figure 29. Principle diagram of a UHF remote control receiver

Package Information

Package SSO20

Dimensions in mm



Ozone Depleting Substances Policy Statement

It is the policy of **Atmel Germany GmbH** to

1. Meet all present and future national and international statutory requirements.
2. Regularly and continuously improve the performance of our products, processes, distribution and operating systems with respect to their impact on the health and safety of our employees and the public, as well as their impact on the environment.

It is particular concern to control or eliminate releases of those substances into the atmosphere which are known as ozone depleting substances (ODSs).

The Montreal Protocol (1987) and its London Amendments (1990) intend to severely restrict the use of ODSs and forbid their use within the next ten years. Various national and international initiatives are pressing for an earlier ban on these substances.

Atmel Germany GmbH has been able to use its policy of continuous improvements to eliminate the use of ODSs listed in the following documents.

1. Annex A, B and list of transitional substances of the Montreal Protocol and the London Amendments respectively
2. Class I and II ozone depleting substances in the Clean Air Act Amendments of 1990 by the Environmental Protection Agency (EPA) in the USA
3. Council Decision 88/540/EEC and 91/690/EEC Annex A, B and C (transitional substances) respectively.

Atmel Germany GmbH can certify that our semiconductors are not manufactured with ozone depleting substances and do not contain such substances.

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Data sheets can also be retrieved from the Internet: <http://www.atmel-wm.com>

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