



## 8-Channel VARIABLE GAIN AMPLIFIER

### FEATURES

- 3V OPERATION
- LOW INPUT NOISE:  $1.2\text{nV}\sqrt{\text{Hz}}$  at  $f_{\text{IN}} = 5\text{MHz}$
- EXTREMELY LOW POWER OPERATION:  
75mW/CHANNEL
- INTEGRATED LOW-PASS, 2-POLE FILTER  
14MHz BANDWIDTH

- INTEGRATED INPUT CLAMP DIODES
- DIFFERENTIAL OUTPUT
- INTEGRATED INPUT LNA
- READABLE CONTROL REGISTERS
- INTEGRATED CONTINUOUS WAVE (CW)  
PROCESSOR

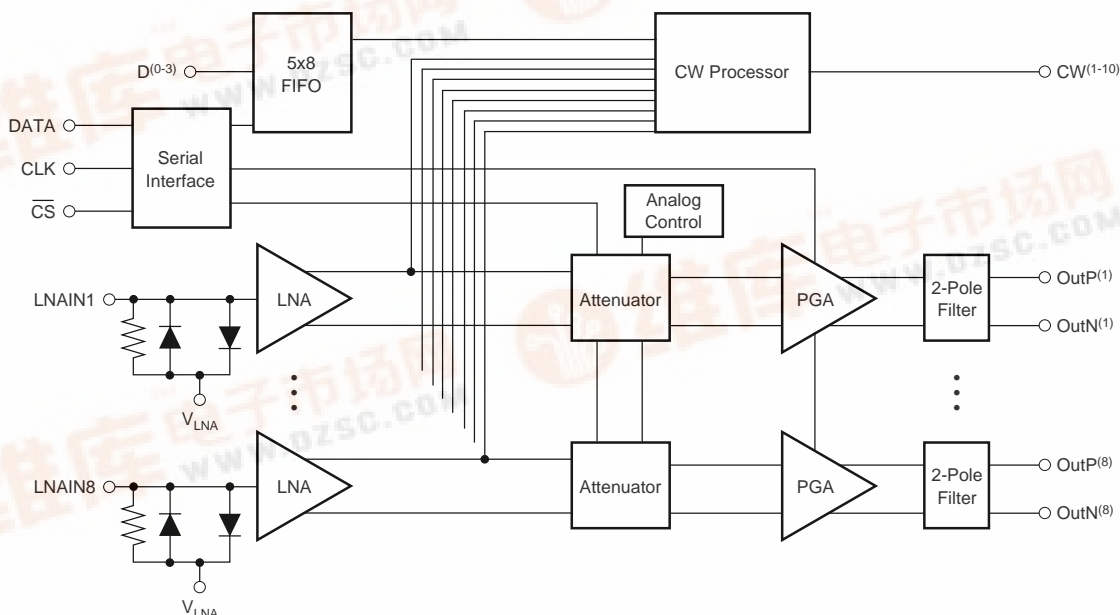
### DESCRIPTION

The VCA8613 is an 8-channel variable gain amplifier ideally suited to portable ultrasound applications. Excellent dynamic performance enables use in low-power, high-performance portable applications. Each channel consists of a Low-Noise pre-Amplifier (LNA) and a Variable Gain Amplifier (VGA). The differential outputs of the LNA can be switched through the 8x10 cross-point switch, which is programmable through the serial interface input port.

The output of the LNA is fed directly into the VGA stage. The VGA consists of two parts, a Voltage Controlled Attenuator (VCA) and a Programmable Gain Amplifier (PGA). The gain and

gain range of the PGA can be digitally configured separately. The gain of the PGA can be varied between two discrete settings of 21dB and 26dB. The VCA has four programmable maximum attenuation settings: 29dB, 33dB, 36.5dB, and 40dB. Also, the VCA can be continuously varied by a control voltage from 0dB to a maximum of 29dB, 33dB, 36.5dB, and 40dB.

The output of the PGA feeds directly into an integrated 2-pole, low-pass filter, allowing for direct connection to a differential input Analog-to-Digital Converter (ADC), such as the ADS5121 or ADS5122 from Texas Instruments. The VCA8613 is available in a TQFP-64 package.



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

## ABSOLUTE MAXIMUM RATINGS<sup>(1)</sup>

+AV <sub>DD</sub> .....	+3.6V
Analog Input .....	-0.3V to +AV <sub>DD</sub> + 0.3V
Logic Input .....	-0.3V to +AV <sub>DD</sub> + 0.3V
Case Temperature .....	+100°C
Junction Temperature .....	+150°C
Storage Temperature .....	+150°C
Thermal Resistance, Junction-to-Ambient ( $\theta_{JA}$ ) .....	66.6°C/W
Thermal Resistance, Junction-to-Case ( $\theta_{JC}$ ) .....	4.3°C/W

NOTE: (1) Stresses above those listed under absolute maximum ratings may cause permanent damage to the device. Exposure to absolute maximum conditions for extended periods may affect device reliability.



## ELECTROSTATIC DISCHARGE SENSITIVITY

This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

## PACKAGE/ORDERING INFORMATION<sup>(1)</sup>

PRODUCT	PACKAGE-LEAD	PACKAGE DESIGNATOR	SPECIFIED TEMPERATURE RANGE	PACKAGE MARKING	ORDERING NUMBER	TRANSPORT MEDIA, QUANTITY
VCA8613	TQFP-64	PAG	-40°C to +85°C	VCA8613Y	VCA8613YT	Tape and Reel, 250
"	"	"	"	"	VCA8613YR	Tape and Reel, 1500

NOTE: (1) For the most current package and ordering information, see the Package Option Addendum located at the end of this data sheet.

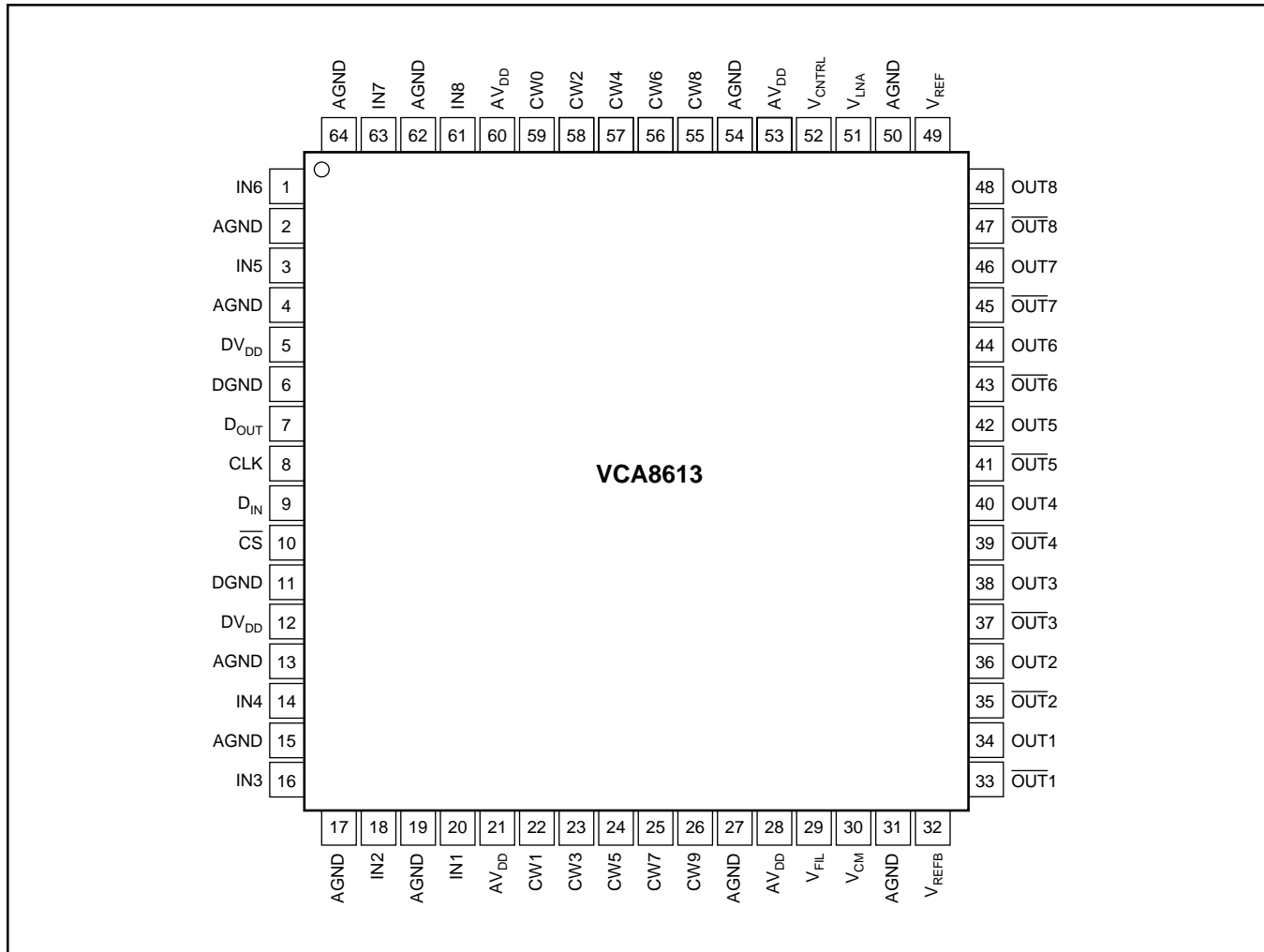
# ELECTRICAL CHARACTERISTICS: $V_{DD} = 3V$

At  $T_A = +25^\circ\text{C}$ , load resistance =  $500\Omega$  on each output to ground, unless otherwise noted. The input to the preamp (LNA) is single-ended, pre-amp gain is fixed at  $+24.5\text{dB}$ ,  $f_{IN} = 2\text{MHz}$ ,  $\text{PG} = 01$ , and the output from the VCA is differential unless otherwise noted.

PARAMETER	CONDITIONS	VCA8613			UNITS
		MIN	TYP	MAX	
<b>PREAMPLIFIER</b>					
Input Resistance			4.5		$k\Omega$
Input Capacitance			80		$pF$
Input Bias Current			1		$nA$
Maximum Input Voltage <sup>(1)</sup>			110		$mV_{PP}$
Input Voltage Noise (TGC)	$f_{IN} = 5\text{MHz}$		1.2		$nV/\sqrt{Hz}$
Input Voltage Noise (CW)	$f_{IN} = 5\text{MHz}$		1.6		$nV/\sqrt{Hz}$
Output Swing (Differential)			2		$V$
Bandwidth			70		$MHz$
Gain			25		$dB$
<b>ACCURACY</b>					
Gain Slope	$0.2V - 1.7V, VCA_{CTRL}$		20		$dB/V$
Gain Error	$0.2V - 1.7V, VCA_{CTRL}$			2	$dB$
Output Offset Voltage	Differential		20		$mV$
<b>GAIN CONTROL INTERFACE</b>					
Input Voltage ( $VCA_{CTRL}$ ) Range			0 to 2.0		$V$
Input Resistance			1		$M\Omega$
Response Time	40dB Gain Change, $\text{PG} = 11$		0.2		$\mu s$
<b>POWER SUPPLY</b>					
Specified Operating Range		2.85	3.0	3.15	$V$
Power-Down Delay			5		$\mu s$
Power-Up Delay			20		$\mu s$
Power Dissipation (TGC Mode)	Operating All Channels		600	700	$mW$
<b>PROGRAMMABLE VGA AND LOW-PASS FILTER</b>					
-3dB Cutoff (low-pass)			12		$MHz$
-3dB Cutoff (high-pass)			800		$kHz$
Slew Rate			300		$V/\mu s$
Output Impedance			10		$\Omega$
Crosstalk			49		$dB$
Output Common-Mode			1		$V$
Output Swing (Differential) <sup>(2)</sup>				2	$V_{PP}$
3rd-Harmonic Distortion			-65	-50	$dB$
2nd-Harmonic Distortion			-65	-50	$dB$
Group Delay Variation			$\pm 3$		$ns$
<b>CONTINUOUS WAVE PROCESSOR</b>					
CW Output Compliance Voltage		3		3.3	$V$
V/I Converter Transconductance		10.35	11.5	12.65	$mA/V$
Maximum CW Output Current			2.0		$mA$
<b>LOGIC INPUTS</b>					
$V_{IN}$ LOW (input low voltage)		0		0.6	$V$
$V_{IN}$ HIGH (input high voltage)		2.1		$V_{DD}$	$V$
Input Current				$\pm 1$	$\mu A$
Input Pin Capacitance			5		$pF$
Clock Input Frequency		10k		25M	$Hz$

NOTES: (1) Under conditions that input signal is within linear range of LNA. (2) Under conditions that signal is within linear range of output amplifier.

## PIN CONFIGURATION



## PIN DESCRIPTIONS

PIN	DESIGNATOR	DESCRIPTION
5, 12	DV <sub>DD</sub>	Digital Supplies
2, 4, 13, 15, 17, 19, 27, 31, 50, 54, 62, 64	AGND	Analog Ground
1, 3, 14, 16, 18, 20, 61, 63	IN <sup>(1-8)</sup>	Single-Ended LNA Inputs
22-26, 55-59	CW <sup>(0-9)</sup>	Continuous Wave Outputs
51	V <sub>LNA</sub>	Reference Voltage For LNA—Internally Generated; Requires External Bypass Cap
29	V <sub>FIL</sub>	Reference Voltage for Output Filter—Internally Generated; Requires External Bypass Cap
30	V <sub>CM</sub>	Common-Mode Voltage—Internally Generated; Requires External Bypass Cap
34, 36, 38, 40, 42, 44, 46, 48	OUT <sup>(1-8)</sup>	Positive Polarity PGA Outputs
33, 35, 37, 39, 41, 43, 45, 47	$\overline{\text{OUT}}^{\text{(1-8)}}$	Negative Polarity PGA Outputs
52	V <sub>CNTRL</sub>	Attenuator Control Input
9	D <sub>IN</sub>	Serial Data Input Pin
10	$\overline{\text{CS}}$	Serial Data Chip Select
8	CLK	Serial Data Input Clock
7	D <sub>OUT</sub>	Serial Data Output Pin
21, 28, 53, 60	AV <sub>DD</sub>	Analog Supplies
6, 11	DGND	Digital Ground
49	V <sub>REF</sub>	Reference Voltage for Attenuator—Internally Generated; Requires External Bypass
32	V <sub>REFB</sub>	Bandgap Reference Voltage—Internally Generated; Requires External Bypass Cap

## INPUT REGISTER BIT MAPS

### Byte 1—Control Byte Register Map

BIT #	NAME	DESCRIPTION
LSB	1	Start Bit Always a “1”—40-bit count-down starts upon first “1” after chip select.
1	$\overline{W/R}$	1 = Write, 0 = Read—Read prevents latching of DATA only—Control register still latched.
2	$P_{WR}$	Entire Chip. Power Control—1 = Off—Otherwise chip is on.
3	A0	Attenuator Control Bit
4	A1	Attenuator Control Bit
5	Mode	1 = TGC Mode (CW Powered Down), 0 = CW Doppler Mode (TGC Powered Down)
6	PG0	LSB of PGA Gain Control
MSB	PG1	MSB of PGA Gain Control

### Byte 2—First Data Byte

BIT #	NAME	DESCRIPTION
LSB	Data 1:0	Channel 1, LSB of Matrix Control
1	Data 1:1	Channel 1, Matrix Control
2	Data 1:2	Channel 1, Matrix Control
3	Data 1:3	Channel 1, MSB of Matrix Control
4	Data 2:0	Channel 2, LSB of Matrix Control
5	Data 2:1	Channel 2, Matrix Control
6	Data 2:2	Channel 2, Matrix Control
MSB	Data 2:3	Channel 2, MSB of Matrix Control

### Byte 3—Second Data Byte

BIT #	NAME	DESCRIPTION
LSB	Data 3:0	Channel 3, LSB of Matrix Control
1	Data 3:1	Channel 3, Matrix Control
2	Data 3:2	Channel 3, Matrix Control
3	Data 3:3	Channel 3, MSB of Matrix Control
4	Data 4:0	Channel 4, Matrix Control
5	Data 4:1	Channel 4, Matrix Control
6	Data 4:2	Channel 4, Matrix Control
MSB	Data 4:3	Channel 4, MSB of Matrix Control

### Byte 4—Third Data Byte

BIT #	NAME	DESCRIPTION
LSB	Data 5:0	Channel 5, LSB of Matrix Control
1	Data 5:1	Channel 5, Matrix Control
2	Data 5:2	Channel 5, Matrix Control
3	Data 5:3	Channel 5, MSB of Matrix Control
4	Data 6:0	Channel 6, Matrix Control
5	Data 6:1	Channel 6, Matrix Control
6	Data 6:2	Channel 6, Matrix Control
MSB	Data 6:3	Channel 6, MSB of Matrix Control

### Byte 5—Fourth Data Byte

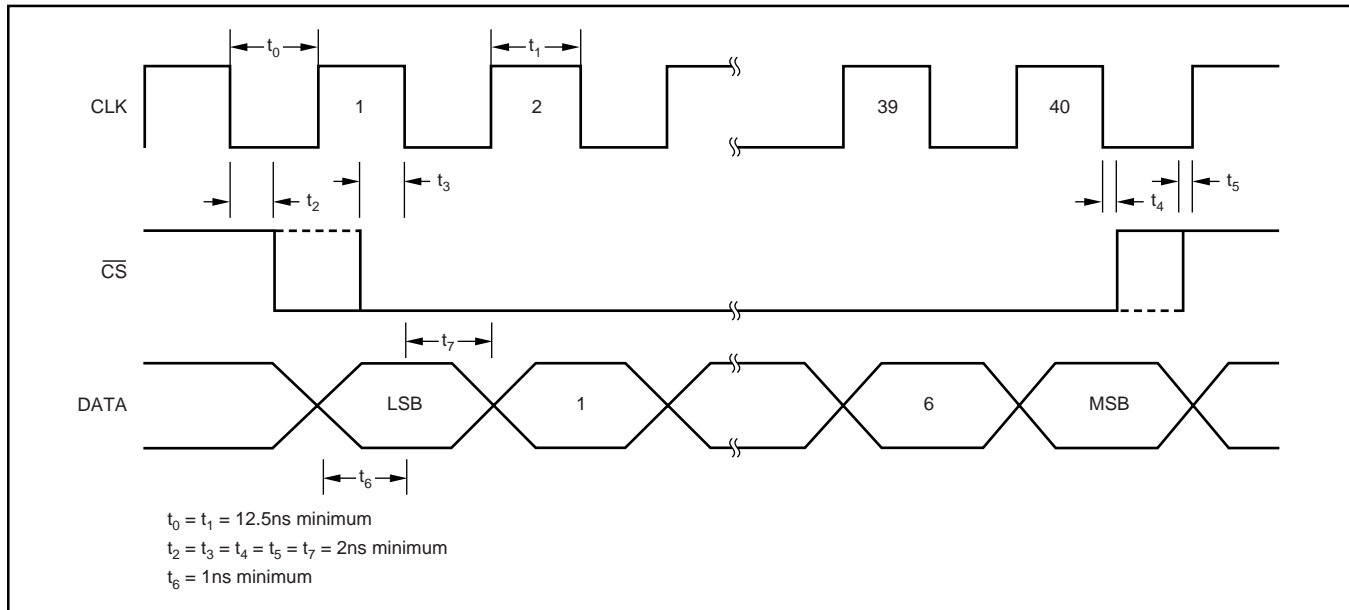
BIT #	NAME	DESCRIPTION
LSB	Data 7:0	Channel 7, LSB of Matrix Control
1	Data 7:1	Channel 7, Matrix Control
2	Data 7:2	Channel 7, Matrix Control
3	Data 7:3	Channel 7, MSB of Matrix Control
4	Data 8:0	Channel 8, Matrix Control
5	Data 8:1	Channel 8, Matrix Control
6	Data 8:2	Channel 8, Matrix Control
MSB	Data 8:3	Channel 8, MSB of Matrix Control

## WRITE/READ TIMING

Generally follows SPI Timing Specification:

- All writes and reads will be 8 bytes at a time;
- Separate write and read data lines;
- Reads will follow the same bit stream pattern seen in the write cycle;
- Reads will extract data from the FIFO, not the latched register;
- D<sub>OUT</sub> data is continuously available and need not be enabled with a read cycle. Selecting a read cycle in the control register *only* prevents latching of data. The control register is still latched.

## WRITE CYCLE TIMING



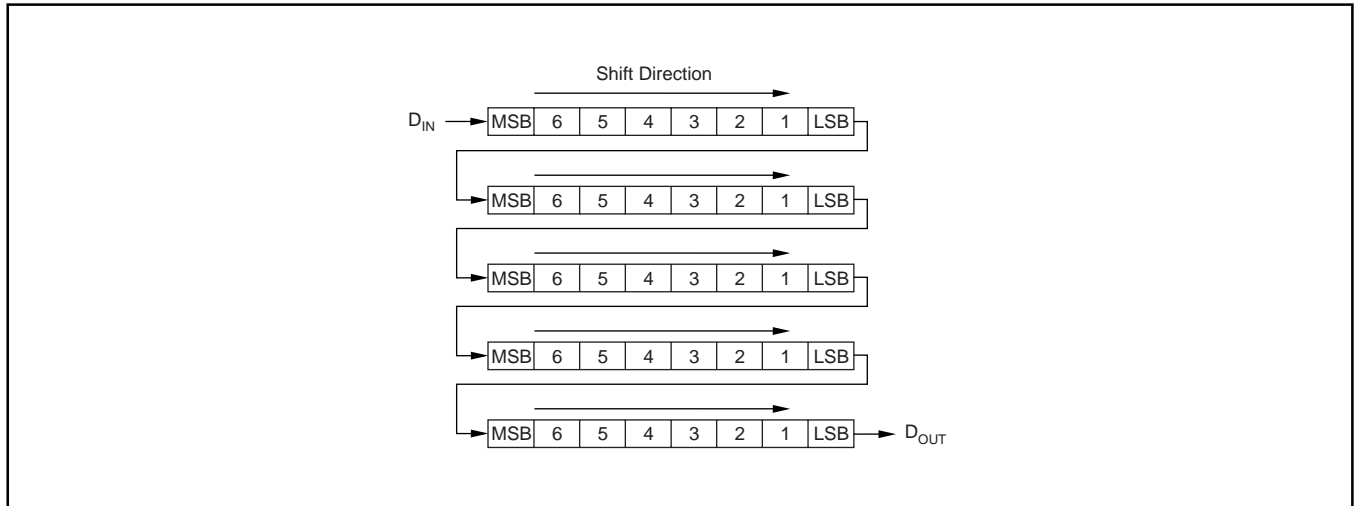
NOTE: It is highly recommended that the clock be turned off after the required data has been programmed into the VCA8613.

## SERIAL PORT TIMING TABLE

Chip Select ( $\overline{\text{CS}}$ ) must be held low (active LOW) during transfer.  $\overline{\text{CS}}$  can be held permanently low.

PARAMETER	DESCRIPTION	MIN	TYP	MAX	UNITS
$t_1$	Serial CLK Period	40			ns
$t_2$	Serial CLK HIGH Time	13			ns
$t_3$	Serial CLK LOW Time	13			ns
$t_4$	$\overline{\text{CS}}$ Falling Edge to Serial CLK Falling Edge	10			ns
$t_5$	Data Setup Time	5			ns
$t_6$	Data Hold Time	5			ns
$t_7$	Serial CLK Falling Edge to $\overline{\text{CS}}$ Rising Edge	10			ns

## DATA SHIFT SEQUENCE



A1, A0	MAXIMUM ATTENUATION
0, 0	29dB
0, 1	33dB
1, 0	36.5dB
1, 1	40dB

TABLE I. Maximum Attenuation.

PG1, PG0	PGA GAIN
0, 0	21dB
0, 1	26dB

TABLE II. PGA Gain Settings.

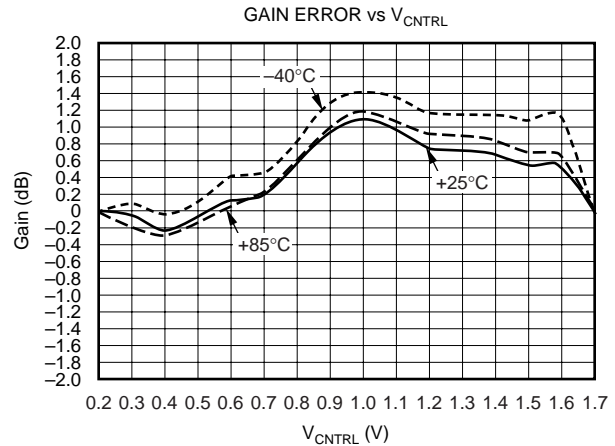
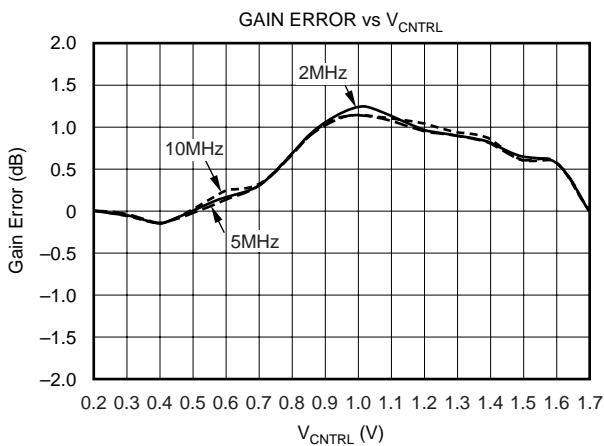
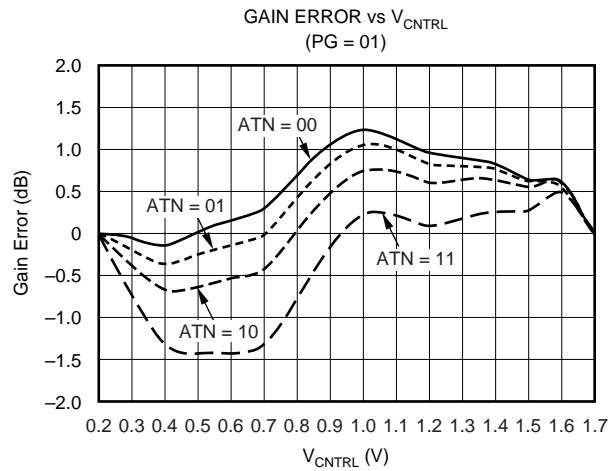
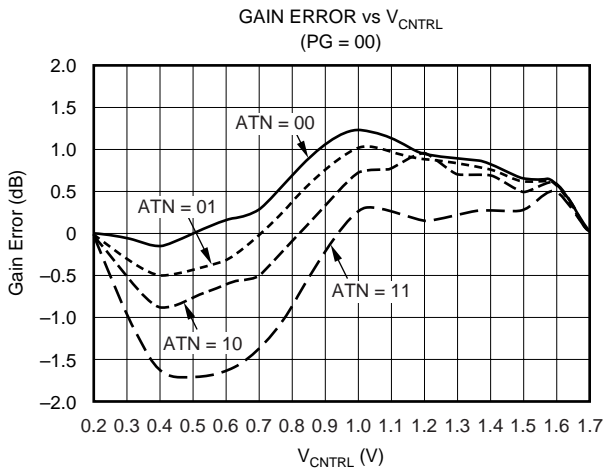
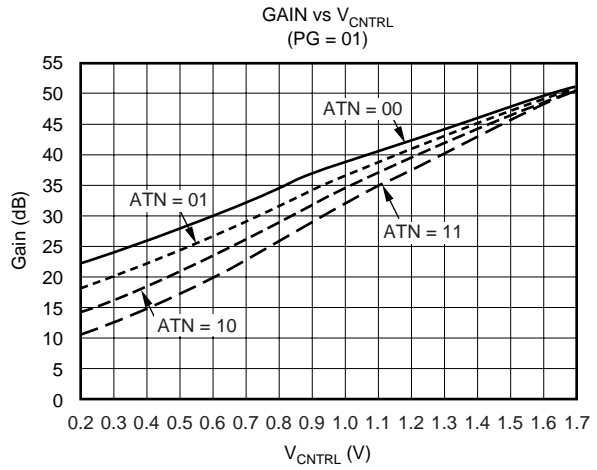
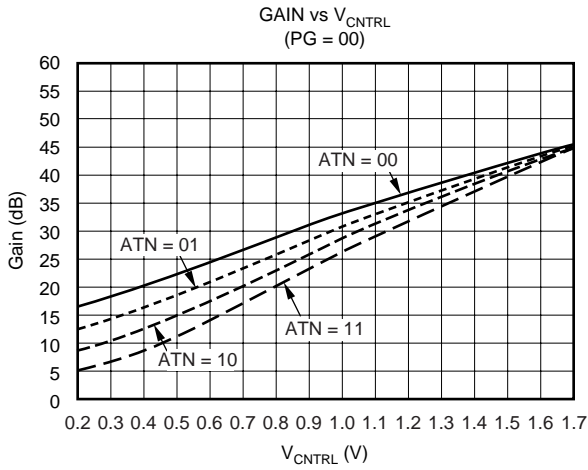
CHANNEL	CW CODING (MSB, LSB)	CHANNEL DIRECTED TO:
0	0000	Output 0
1	0001	Output 1
2	0010	Output 2
3	0011	Output 3
4	0100	Output 4
5	0101	Output 5
6	0110	Output 6
7	0111	Output 7
8	1000	Output 8
9	1001	Output 9
10	1010	Channel Tied to +V (internal)
11	1011	Channel Tied to +V (internal)
12	1100	Channel Tied to +V (internal)
13	1101	Channel Tied to +V (internal)
14	1110	Channel Tied to +V (internal)
15	1111	Channel Tied to +V (internal)

Applies to bytes 2 through 5.

TABLE III. CW Coding for Each Channel.

# TYPICAL CHARACTERISTICS

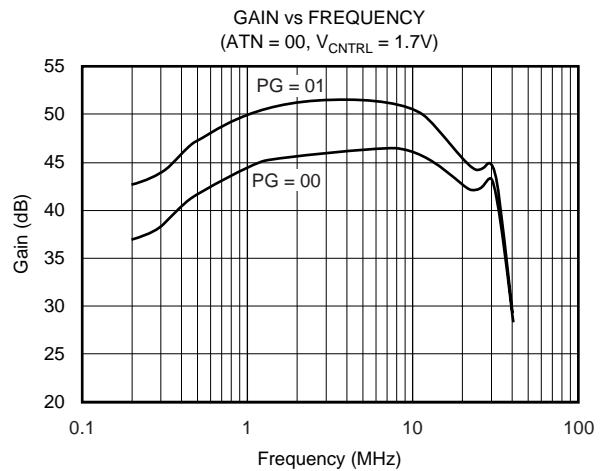
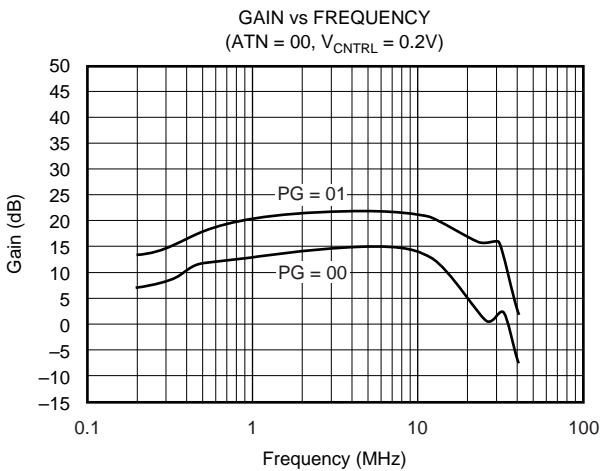
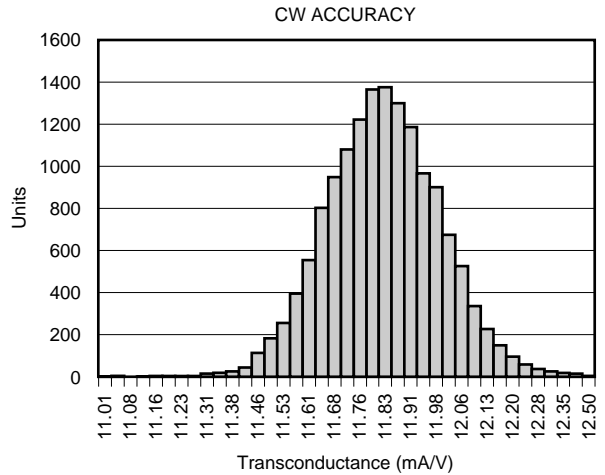
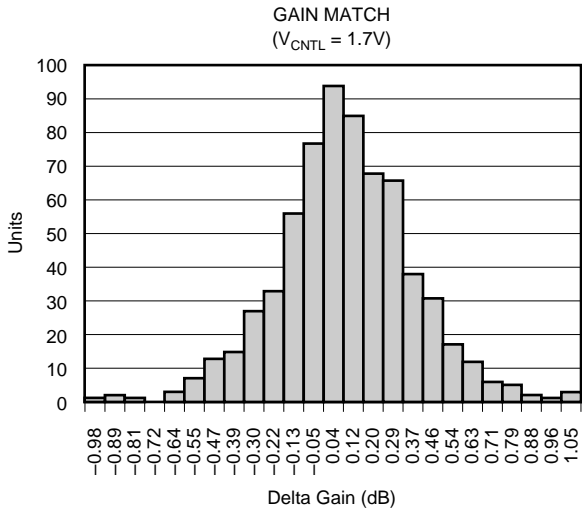
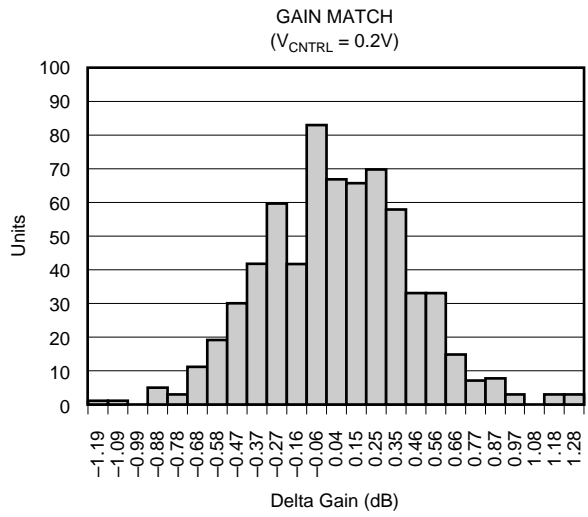
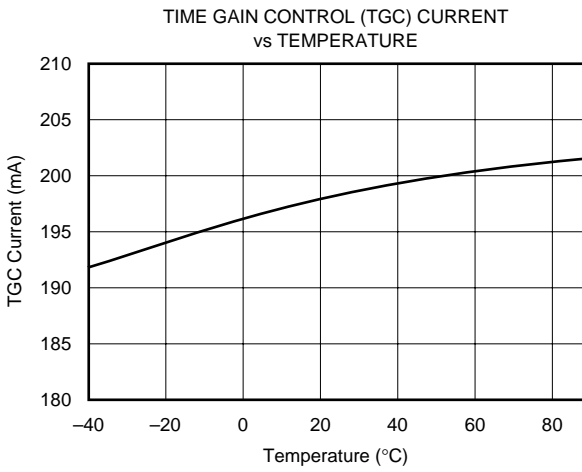
At  $T_A = +25^\circ\text{C}$ ,  $f_{IN} = 2\text{MHz}$ ,  $AT_N = 00$ ,  $PG = 01$ ,  $V_{CNTRL} = 1.7\text{V}$ , unless otherwise noted. Differential output,  $750\text{mV}_{PP}$ , and  $AV_{DD} = DV_{DD} = 3.0\text{V}$ .





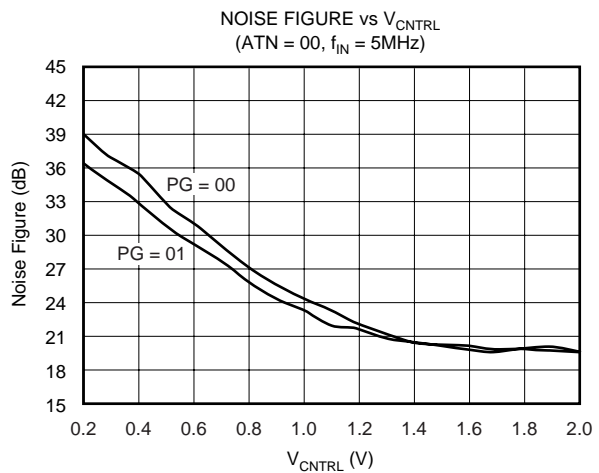
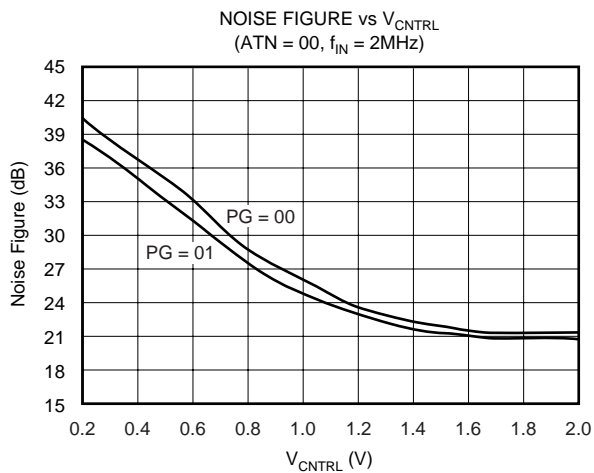
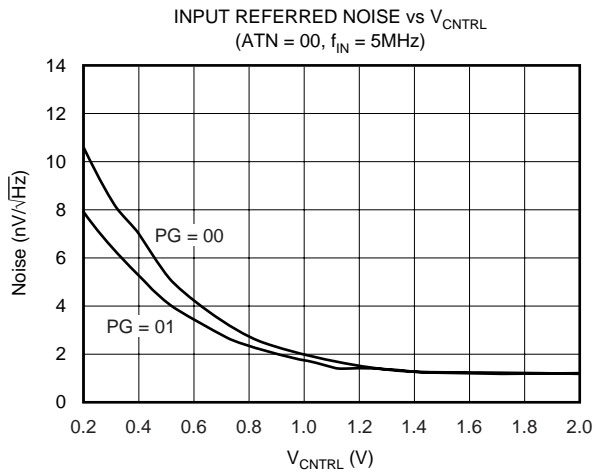
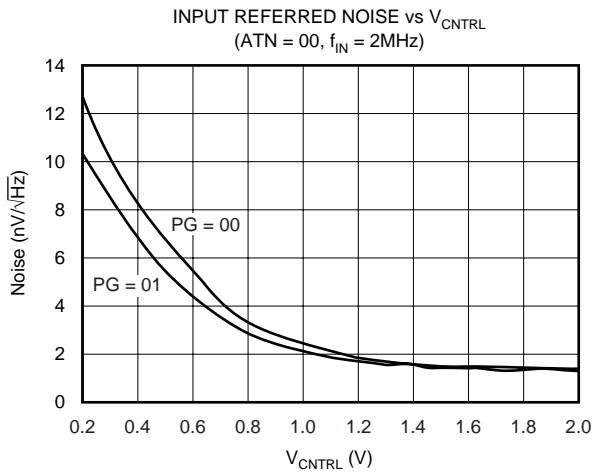
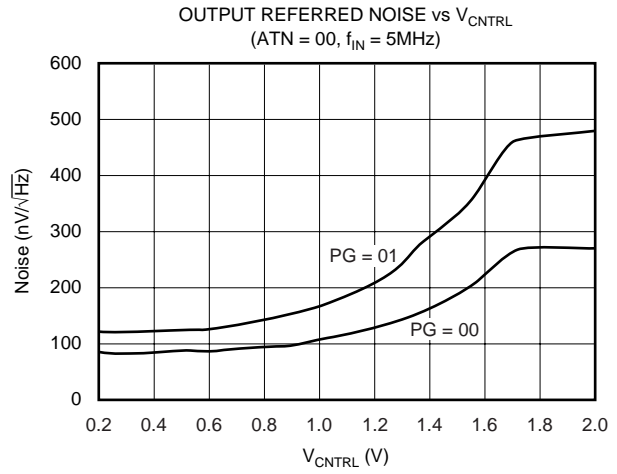
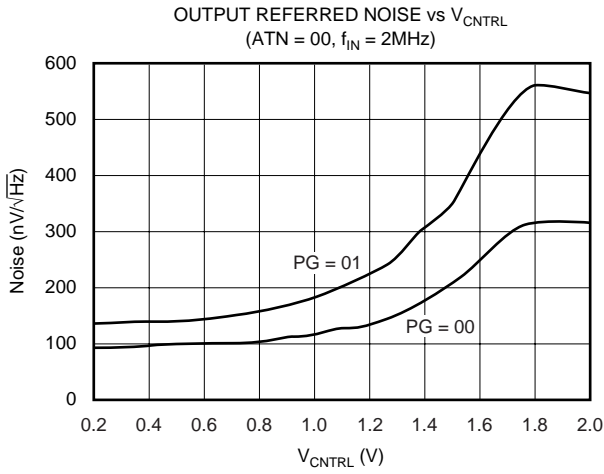
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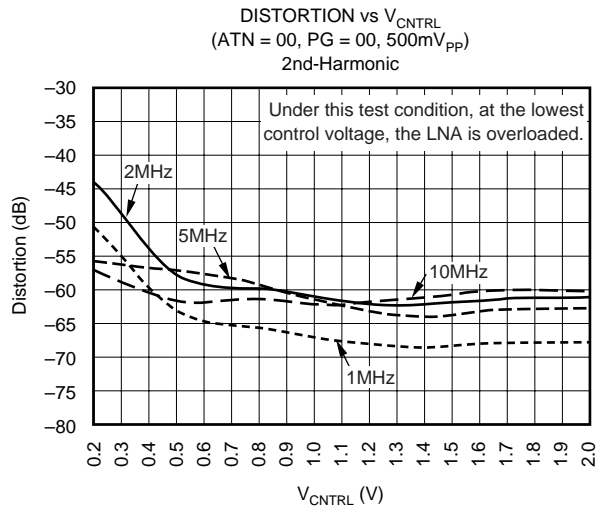
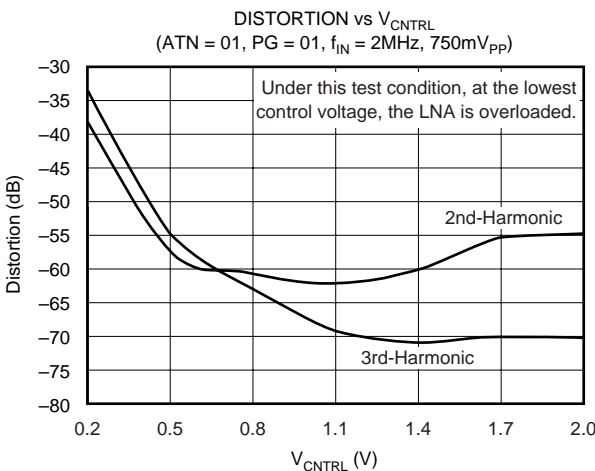
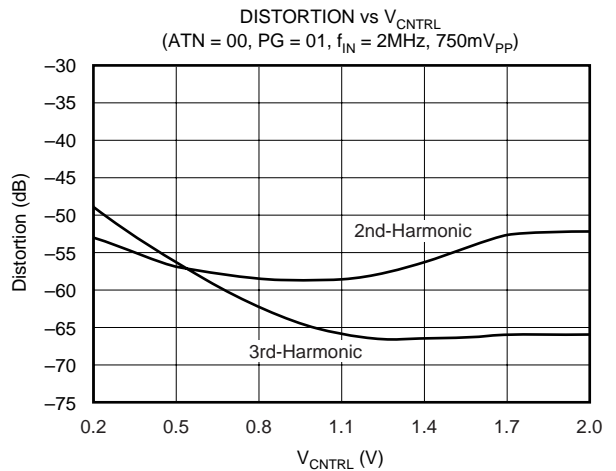
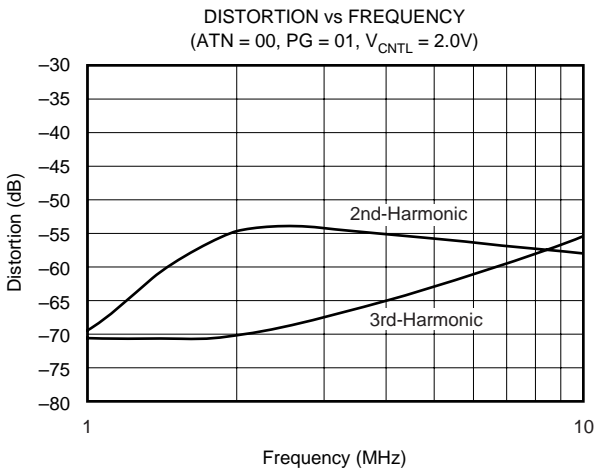
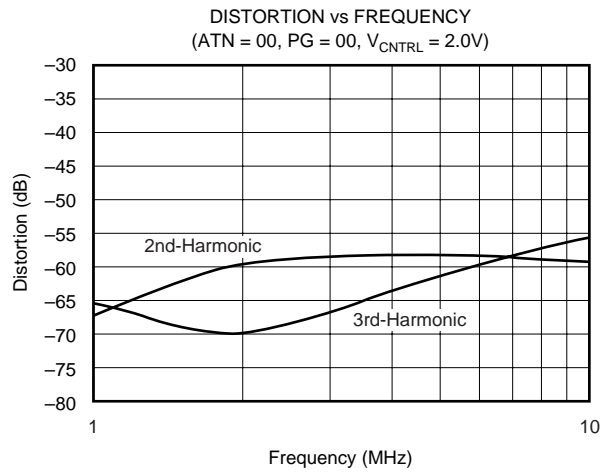
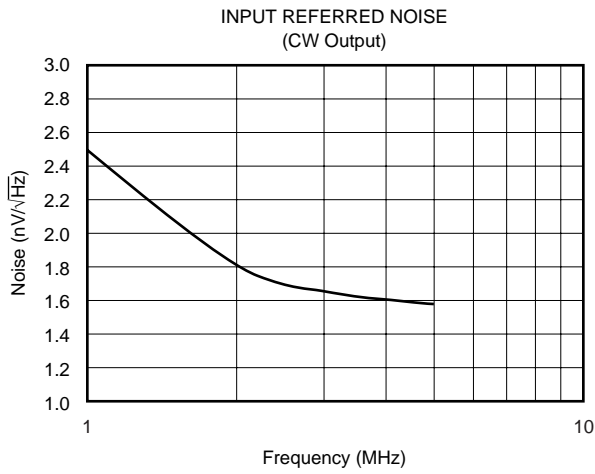
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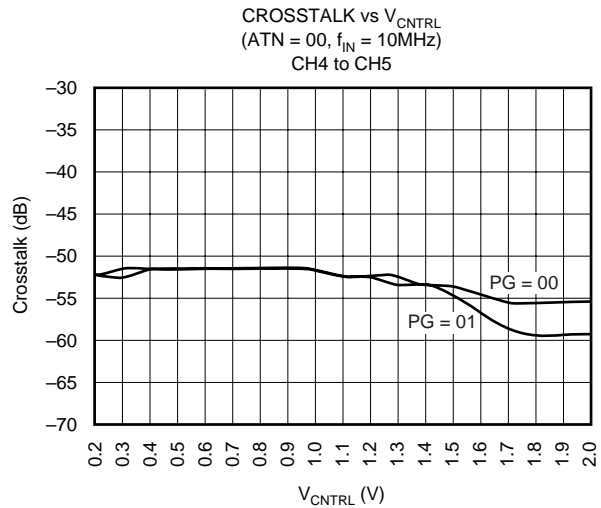
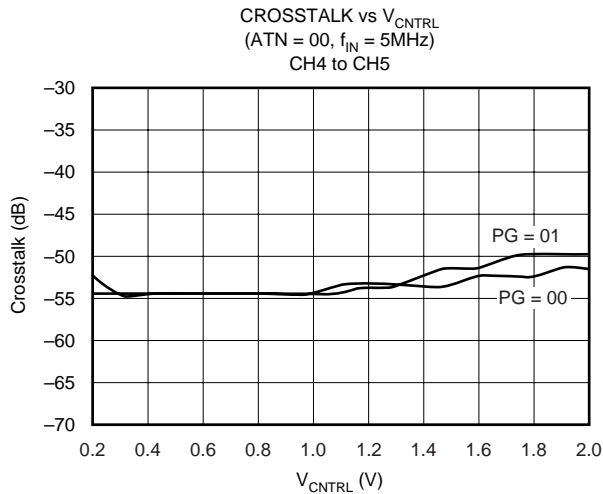
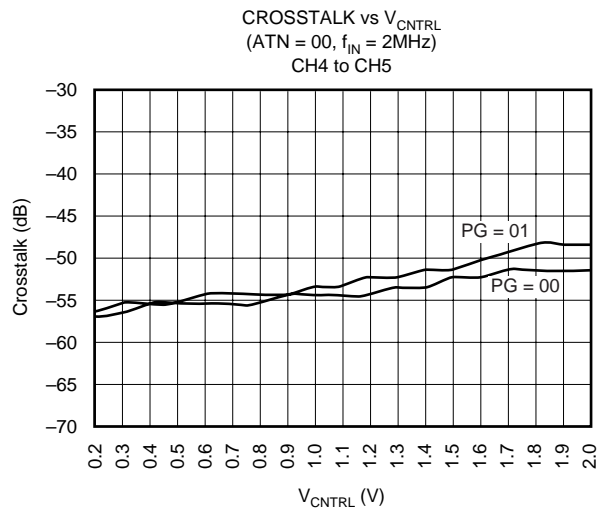
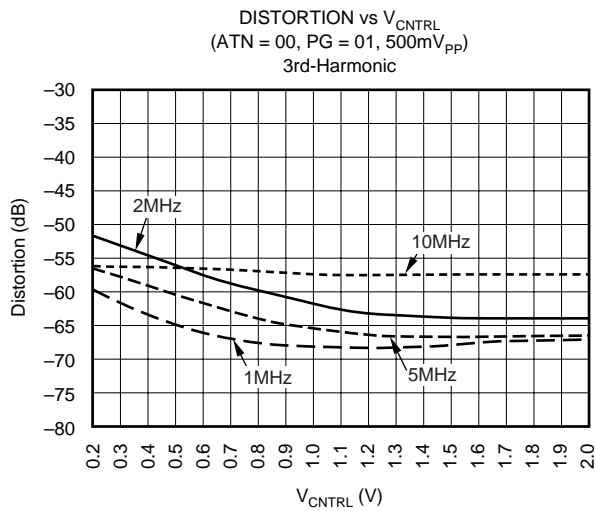
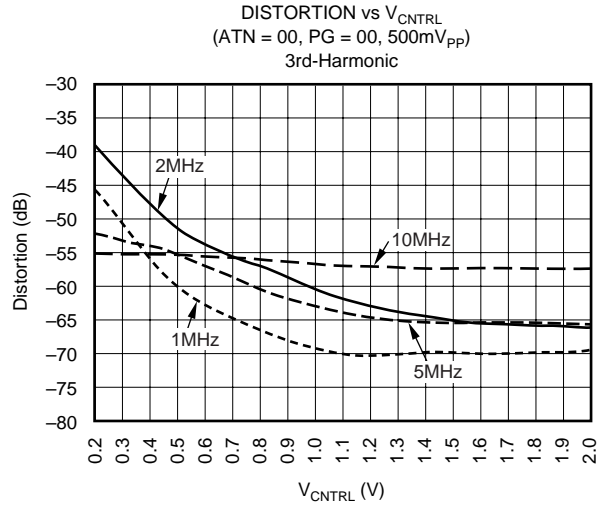
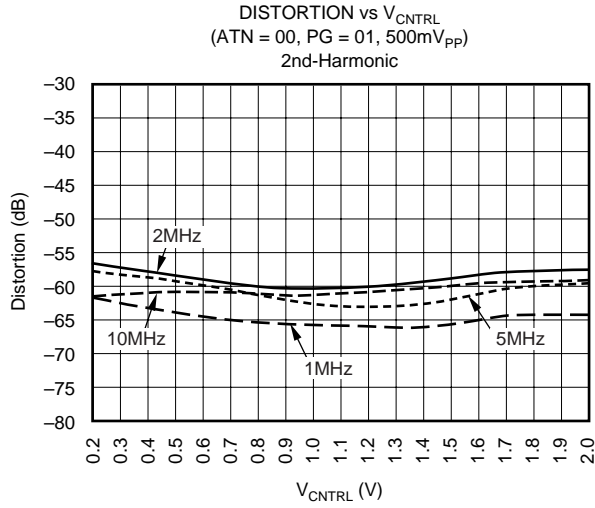
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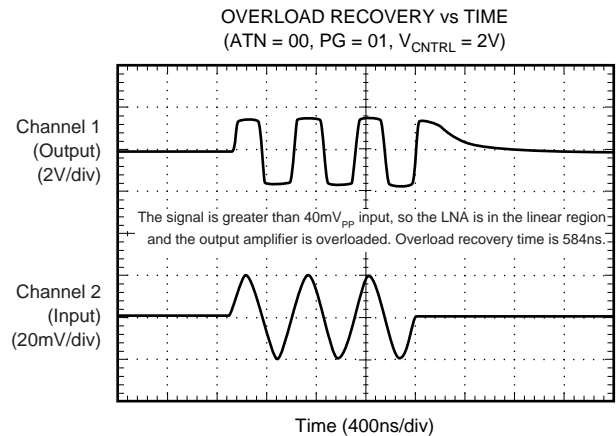
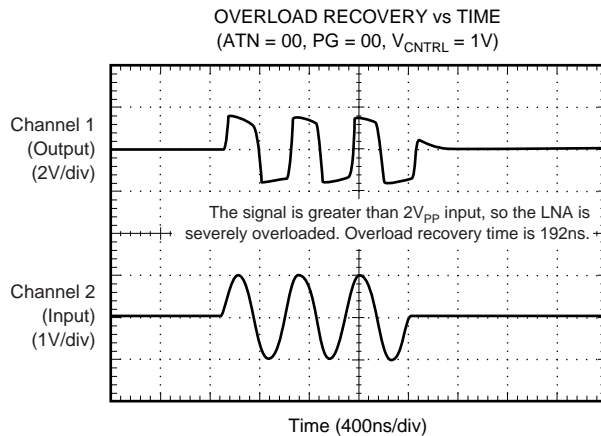
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## APPLICATION INFORMATION

### INPUT CIRCUIT

The input of the VCA8613 integrates several commonly used elements. Prior to reaching the input of the VCA, the receive signal should be coupled with a capacitor of at least 1nF, preferably more. When this AC coupling element is inserted, the LNA input bias point is held to a common-mode value of 2.4V by an integrated 4.5k $\Omega$  resistor. This common-mode value will change with temperature and may also vary from chip to chip, but for each chip, it will be held constant. In parallel with this resistor are two back-to-back clipping diodes. These diodes prevent excessive input voltages from passing through to the LNA input, preventing deep saturation effects in the LNA itself.

### LOW-NOISE PRE-AMPLIFIER (LNA)

The VCA8613 integrates a low-noise pre-amplifier. Because of the high level of integration in the system, noise performance was traded for power consumption, resulting in an extremely low-power pre-amplifier, with  $1.2\text{nV}/\sqrt{\text{Hz}}$  noise performance at 5MHz. The LNA is configured as a fixed-gain 25dB amplifier. Of this total gain, 6dB results from the single-ended to differential conversion accomplished within the LNA itself. The output of the LNA is limited to a little over 2V differential swing. This implies a maximum input voltage swing of approximately 110mV to be operating in the linear range at 5MHz. Larger input signals can be accepted by the LNA, but distortion performance will degrade with high-level input signals.

### CW DOPPLER PROCESSOR

The VCA8613 integrates many of the elements necessary to allow for the implementation of a simple CW Doppler processing circuit. One circuit that was integrated was a V/I converter following the LNA (see Figure 1). The V/I converter converts the LNA voltage output to a current which is then passed through an 8x10 switch matrix (see Figure 2). Within this switch matrix, any of the eight LNA outputs can be connected to any of ten CW output pins. This is a simple current-summing circuit such that each CW output can represent the sum of any or all the channel currents. The output current for each LNA is equal to the single-ended LNA output voltage swing divided by an internally integrated 700 $\Omega$  resistor. This resistor value may change  $\pm 5\%$  from chip to chip.

The CW output pins need a compliance voltage between 3V to 3.3V. The 3V to 3.3V can be applied through either an inductor (see Figure 3) tied to the 3V to 3.3V source or from the inverting input of an op amp circuit (see Figure 4). The architecture of the V/I converter requires a 2mA to 2.5mA current that is generated by the compliance voltage.

The CW outputs are typically routed to a passive delay line, allowing coherent summing of the signals. After summing, IQ separation and down conversion to base-band precedes a pair of high-resolution, low sample rate ADCs.

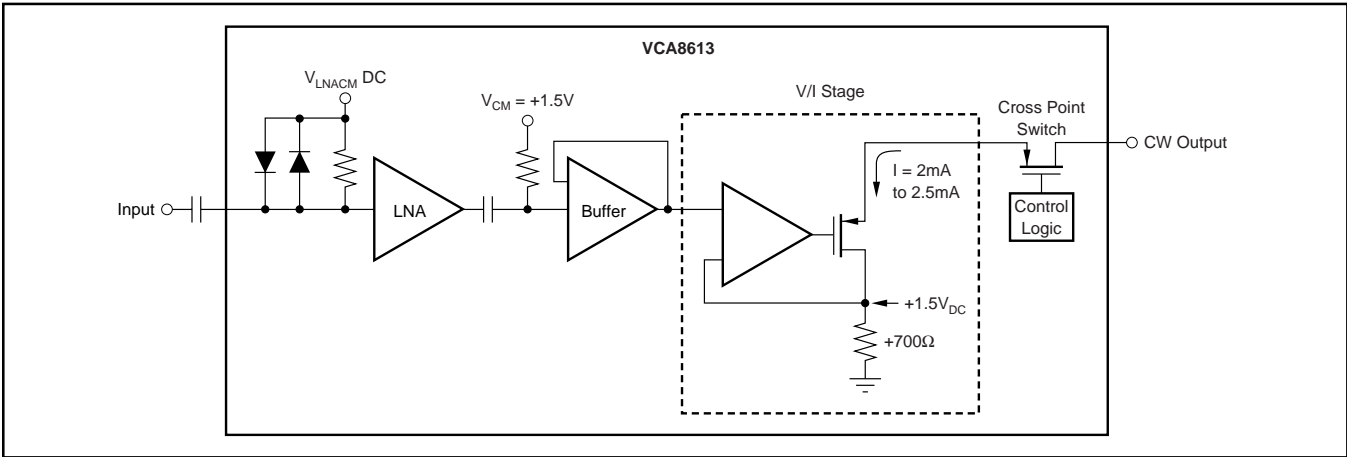


FIGURE 1. Basic CW Processing Block Diagram.

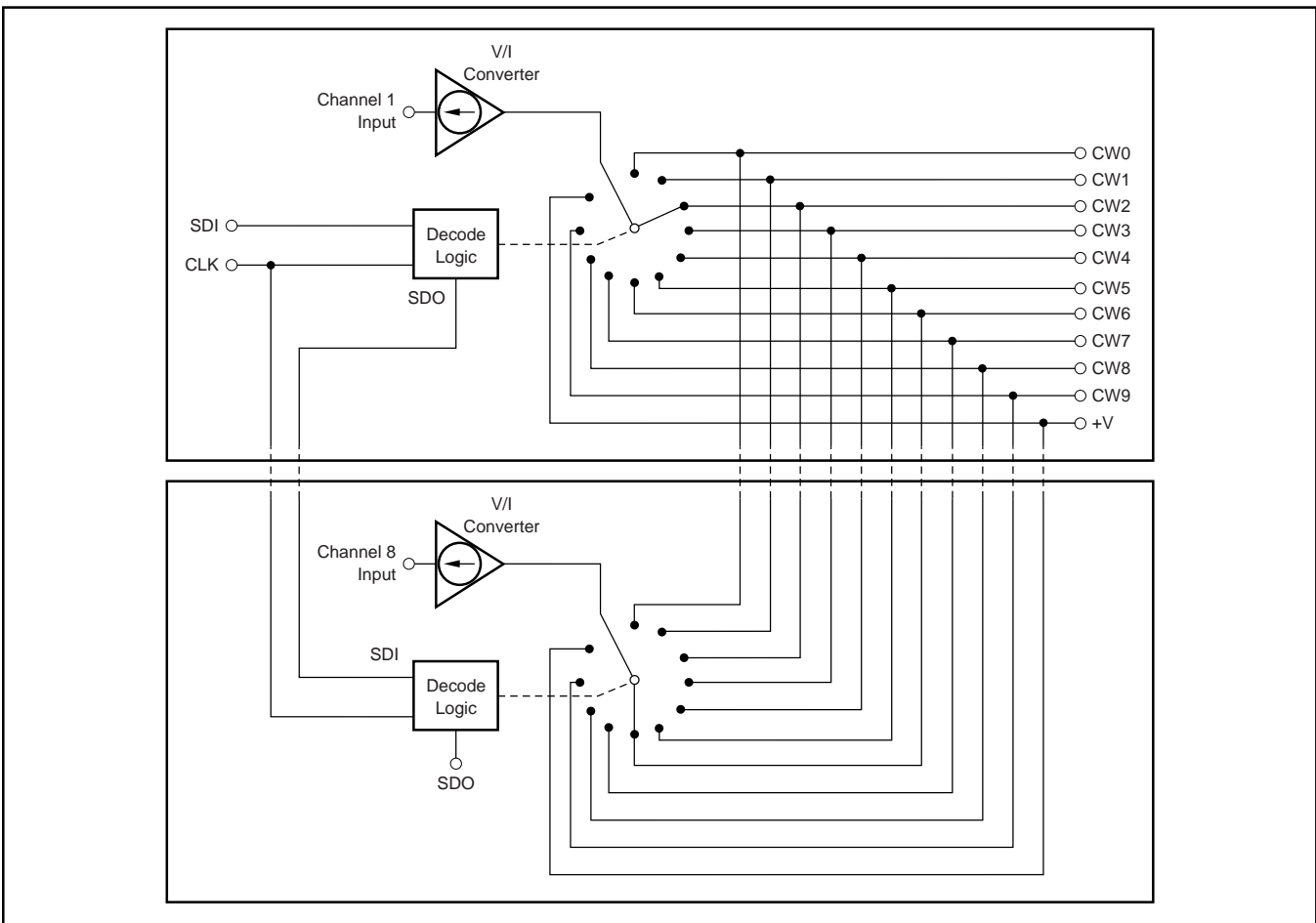


FIGURE 2. Basic CW Cross Point Switch Matrix for All Eight Channels.

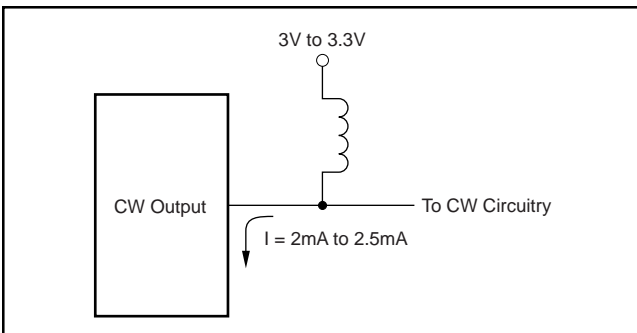


FIGURE 3. Inductor.

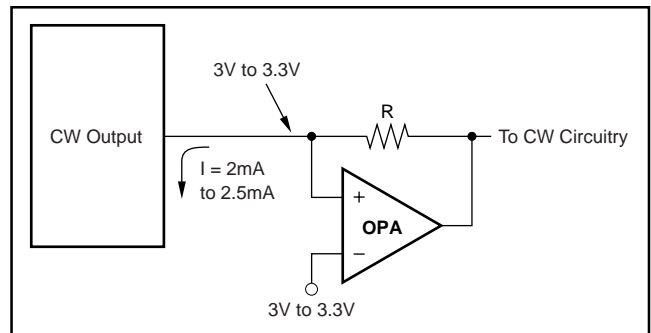


FIGURE 4. Op Amp.

## VOLTAGE-CONTROLLED ATTENUATOR (VCA)—DETAIL

The VCA is designed to have a dB-linear attenuation characteristic; that is, the gain loss in dB is constant for each equal increment of the  $VCA_{CNTRL}$  control voltage. Figure 5 shows a block diagram of the VCA. The attenuator is essentially a variable voltage divider consisting of one series input resistor,  $R_S$ , and ten identical shunt FETs, placed in parallel and controlled by sequentially-activated clipping amplifiers. Each clipping amplifier can be thought of as a specialized voltage comparator with a soft transfer characteristic and well-controlled output limit voltages. The reference voltages V1 through V10 are equally spaced over the 0V to 1.8V control voltage range. As the control voltage rises through the input range of each clipping amplifier, the amplifier output will rise from 0V (FET completely ON) to  $V_{CM} - V_T$  (FET nearly OFF), where  $V_{CM}$  is the common source voltage and  $V_T$  is the threshold voltage of the FET. As each FET approaches its OFF state and the control voltage continues to rise, the next clipping amplifier/FET combination takes over for the next portion of the piecewise-linear attenuation characteristic. Thus, low control voltages have most of the FETs turned ON, while high control voltages have most turned OFF. Each FET acts to decrease the shunt resistance of the voltage divider formed by  $R_S$  and the parallel FET network.

The attenuator is comprised of two sections, with five parallel clipping amplifier/FET combinations in each. Special reference circuitry is provided so that the  $(V_{CM} - V_T)$  limit voltage will track temperature and IC process variations, minimizing the effects on the attenuator control characteristic.

In addition to the analog  $VCA_{CNTRL}$  gain setting input, the attenuator architecture provides digitally-programmable adjustment in eight steps, via the two attenuation bits. These adjust the maximum achievable gain (corresponding to minimum attenuation in the VCA, with  $VCA_{CNTRL} = 1.8V$ ) in 5dB increments. This function is accomplished by providing multiple FET sub-elements for each of the  $Q_1$  to  $Q_{10}$  FET shunt elements (see Figure 6). In the simplified diagram of

Figure 5, each shunt FET is shown as two sub-elements,  $Q_{NA}$  and  $Q_{NB}$ . Selector switches, driven by the MGS bits, activate either or both of the sub-element FETs to adjust the maximum  $R_{ON}$  and thus achieve the stepped attenuation options.

The VCA can be used to process either differential or single-ended signals. Fully differential operation will reduce 2nd-harmonic distortion by about 10dB for full-scale signals.

Input impedance of the VCA will vary with gain setting, due to the changing resistances of the programmable voltage divider structure. At large attenuation factors (that is, low gain settings), the impedance will approach the series resistor value of approximately 120Ω.

As with the LNA stage, the VCA output is AC-coupled into the PGA. This means that the attenuation-dependent DC common-mode voltage will not propagate into the PGA, and so the PGA's DC output level will remain constant.

Finally, note that the  $VCA_{CNTRL}$  input consists of FET gate inputs. This provides very high impedance and ensures that multiple VCA8613 devices may be connected in parallel with no significant loading effects. The nominal voltage range for the  $VCA_{CNTRL}$  input spans from 0V to 1.8V. Overdriving this input ( $> 3V$ ) does not affect the performance.

## PGA POST-AMPLIFIER

Figure 7 shows a simplified circuit diagram of the PGA block. PGA gain is programmed through the serial port, and can be configured to 2 different gain settings of 21dB and 26dB, as shown in Table III. A patented circuit has been implemented in the PGA that allows for exceptional overload signal recovery.

PGA	GAIN
00	21
01	26

TABLE III. PGA Gain Settings.

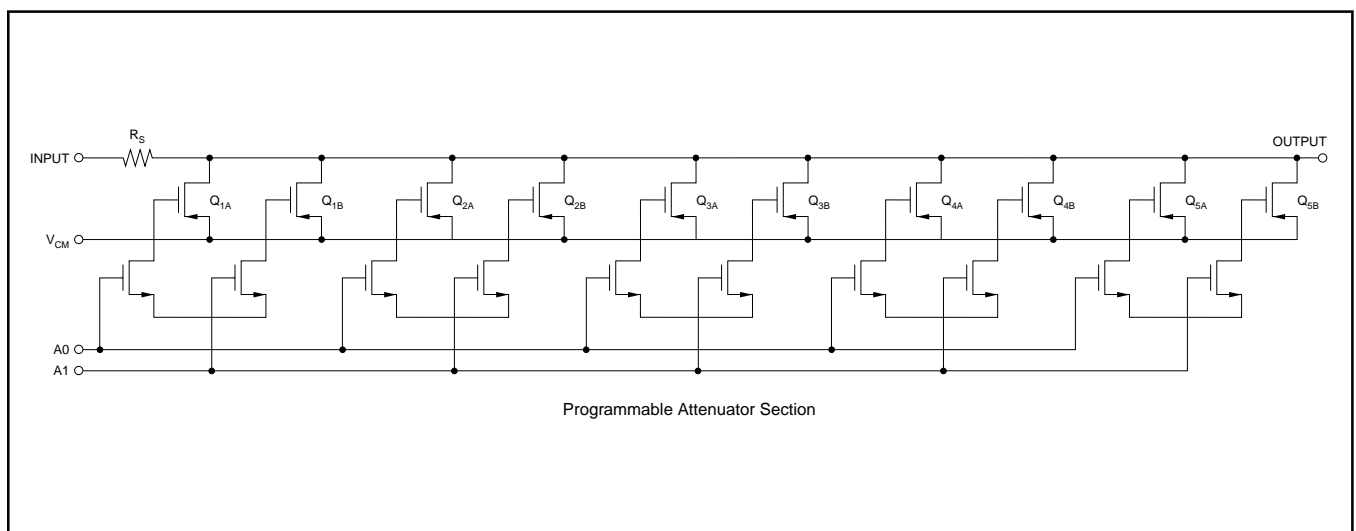


FIGURE 5. Programmable Attenuator Section.

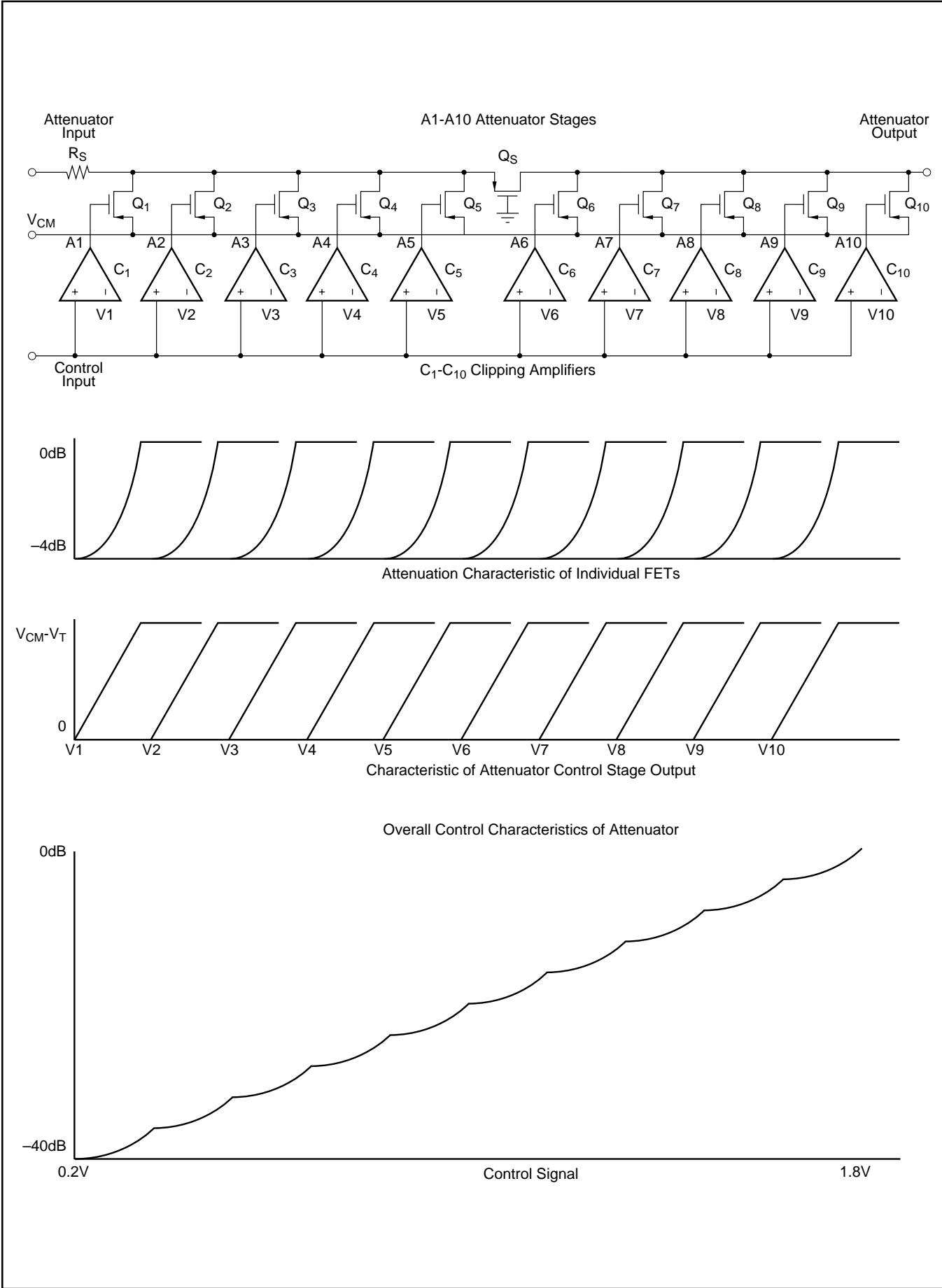


FIGURE 6. Piecewise Approximation to Logarithmic Control Characteristics.



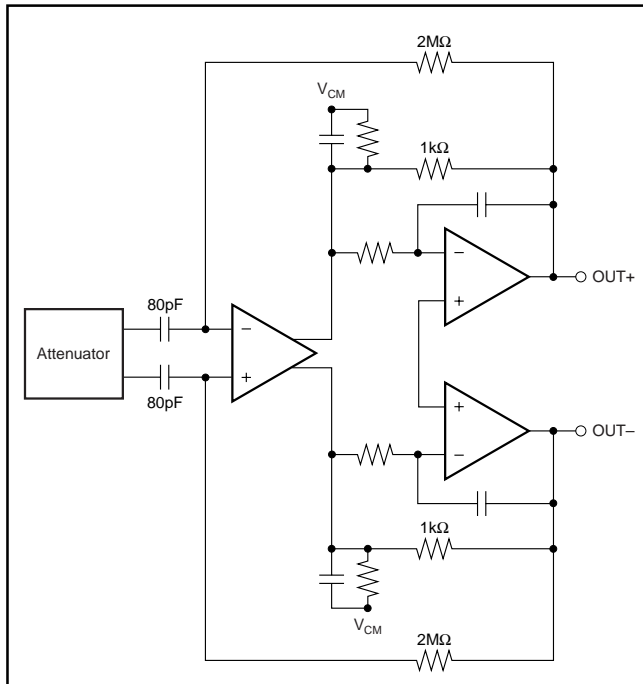


FIGURE 7. Simplified PGA and Output Filter Circuit.

### OUTPUT FILTER

The VCA8613 integrates a 2-pole low-pass Butterworth filter in the output stage, as shown in Figure 7. The cutoff frequency is implemented with passive semiconductor elements and as such, the cutoff frequency will not be precise. Table IV shows the cutoff frequency for the different PGA settings.

The variation shown in Table IV reflects deviations as measured from chip to chip and over the specified temperature range.

PGA	BANDWIDTH
00	13MHz to 14MHz
01	11MHz to 12MHz

TABLE IV. Cutoff Frequency for PGA Settings.

### SERIAL INTERFACE

The serial interface of the VCA8613 allows the user flexibility in the use of the part. The following are set from the serial control registers:

- Mode
  - TGC Mode
  - CW Mode
- Attenuation Range
- PGA Gain
- Power-Down (this is the default state in which the VCA8613 powers up)
- CW Output Selection For Each Input Channel

The serial interface uses an SPI style of interface format. The Input Register Bit Maps (see page 5) show the functionality of each control register.

### LAYOUT CONSIDERATIONS

The VCA8613 is a multi-channel amplifier capable of high gains that has integrated digital controls. Layout of the VCA8613 is fairly straightforward. By connecting all of the grounds (including the digital grounds) to the analog ground, noise performance will help to be maintained. The analog ground should be a solid plane.

Power-supply decoupling and decoupling of the control voltage ( $V_{CA\_CTRL}$ ) pin are essential in order to ensure that the noise performance be maintained. For further help in determining basic values, please refer to Figure 8.

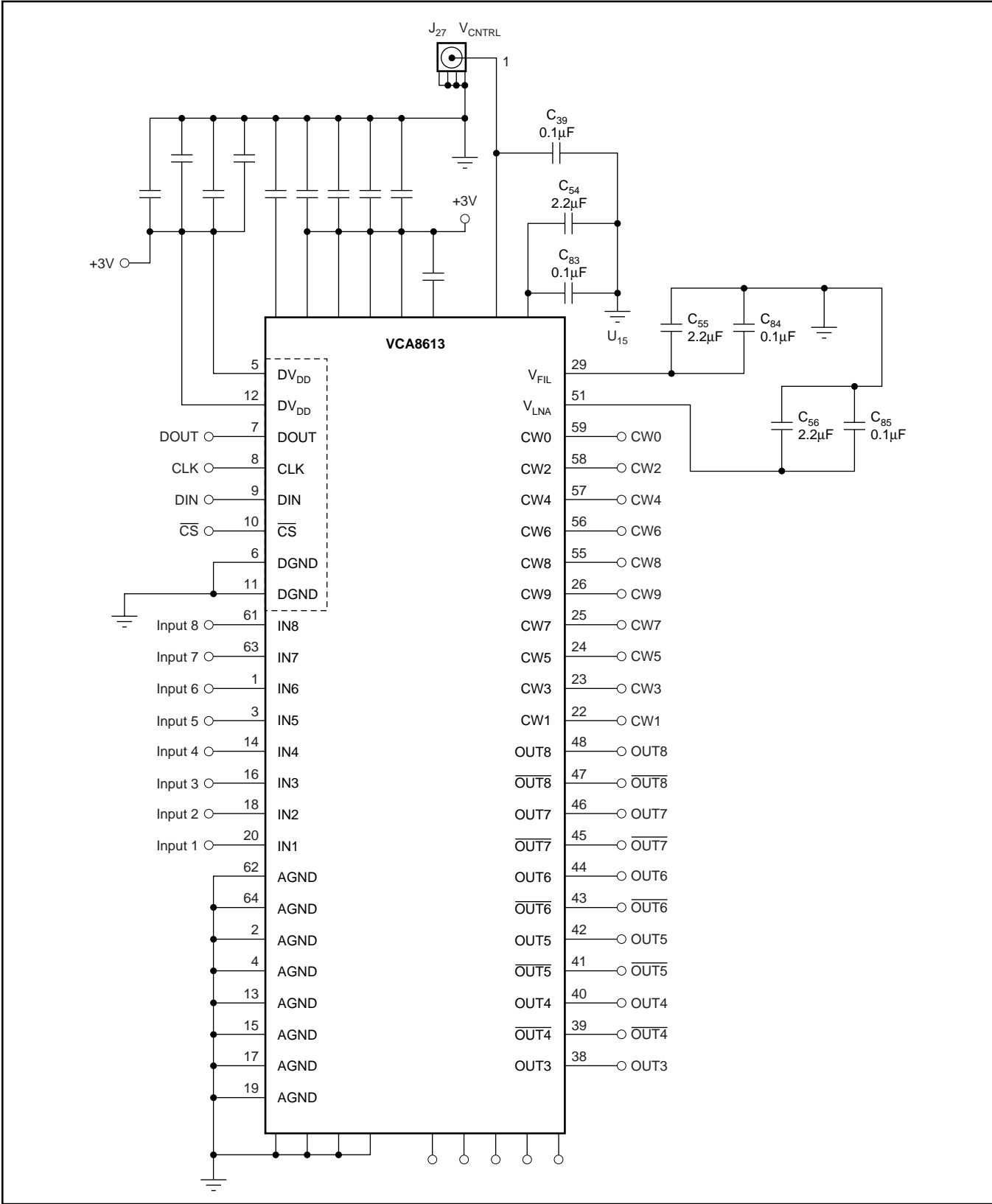


FIGURE 8. Basic Connection Diagram.

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## PACKAGING INFORMATION

ORDERABLE DEVICE	STATUS(1)	PACKAGE TYPE	PACKAGE DRAWING	PINS	PACKAGE QTY
VCA8613YR	ACTIVE	TQFP	PAG	64	1500
VCA8613YT	ACTIVE	TQFP	PAG	64	250

(1) The marketing status values are defined as follows:

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**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

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**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

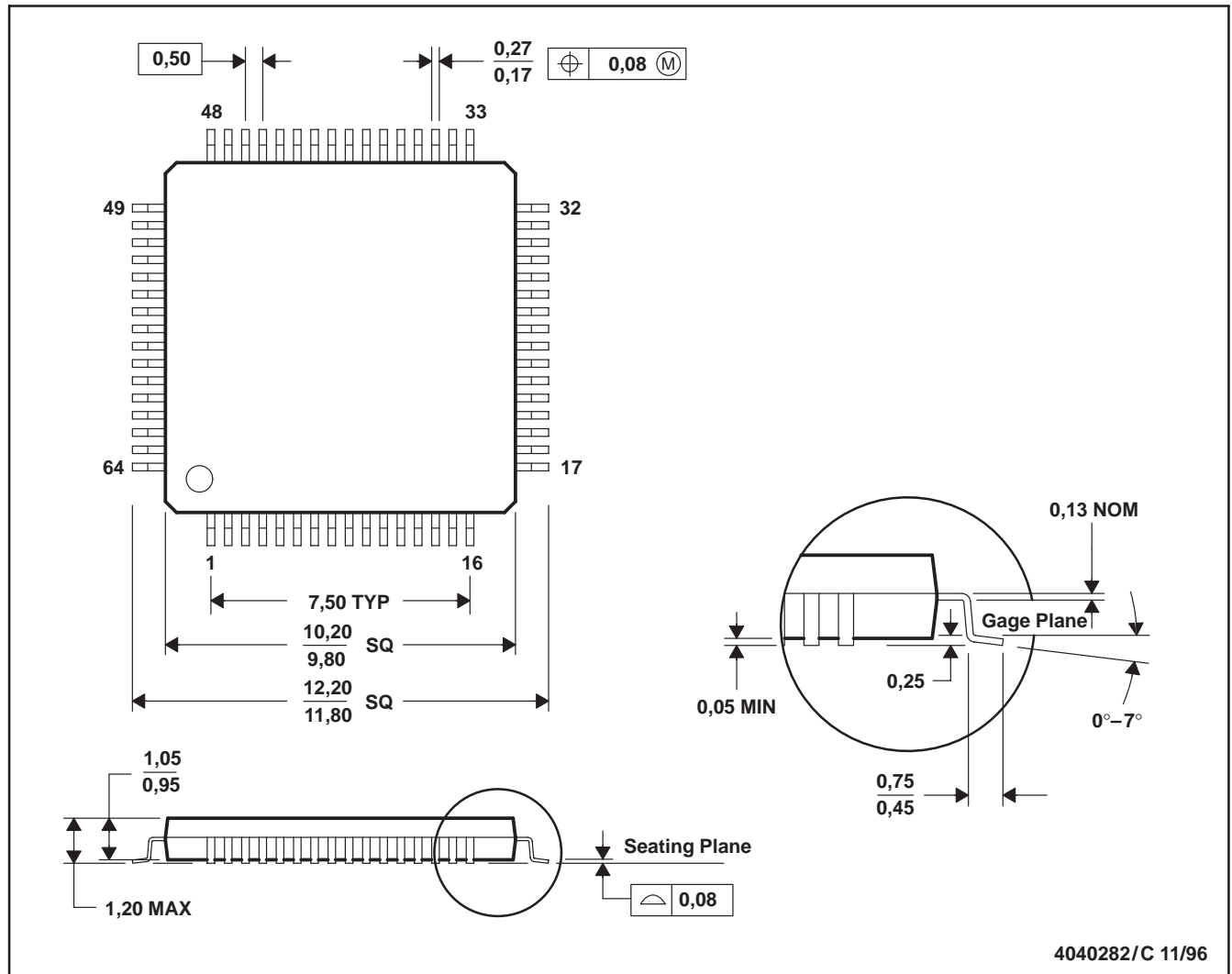
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# MECHANICAL DATA

MTQF006A – JANUARY 1995 – REVISED DECEMBER 1996

## PAG (S-PQFP-G64)

## PLASTIC QUAD FLATPACK



- NOTES: A. All linear dimensions are in millimeters.  
 B. This drawing is subject to change without notice.  
 C. Falls within JEDEC MS-026

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DSP	<a href="http://dsp.ti.com">dsp.ti.com</a>	Broadband	<a href="http://www.ti.com/broadband">www.ti.com/broadband</a>
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