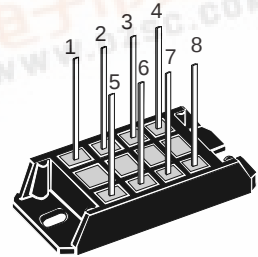
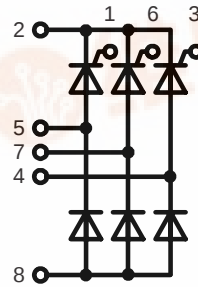


Three Phase Half Controlled Rectifier Bridge

$$I_{dAVM} = 43 \text{ A}$$

$$V_{RRM} = 1200\text{-}1600 \text{ V}$$

V_{RSM} V_{DSM} V	V_{RRM} V_{DRM} V	Type
1300	1200	VVZ 40-12io1
1500	1400	VVZ 40-14io1
1700	1600	VVZ 40-16io1



Symbol	Test Conditions		Maximum Ratings	
I_{dAV} I_{dAVM} I_{FRMS}, I_{TRMS}	$T_K = 100^{\circ}\text{C}$; module		34	A
	module		43	A
	per leg		25	A
I_{FSM}, I_{TSM}	$T_{VJ} = 45^{\circ}\text{C};$	$t = 10\text{ ms}$ (50 Hz), sine	320	A
	$V_R = 0$	$t = 8.3\text{ ms}$ (60 Hz), sine	340	A
	$T_{VJ} = T_{VJM}$	$t = 10\text{ ms}$ (50 Hz), sine	290	A
	$V_R = 0$	$t = 8.3\text{ ms}$ (60 Hz), sine	310	A
I^2t	$T_{VJ} = 45^{\circ}\text{C}$	$t = 10\text{ ms}$ (50 Hz), sine	510	A^2s
	$V_R = 0$	$t = 8.3\text{ ms}$ (60 Hz), sine	485	A^2s
	$T_{VJ} = T_{VJM}$	$t = 10\text{ ms}$ (50 Hz), sine	420	A^2s
	$V_R = 0$	$t = 8.3\text{ ms}$ (60 Hz), sine	400	A^2s
$(di/dt)_{cr}$	$T_{VJ} = T_{VJM}$ $f = 400\text{ Hz}, t_p = 200\text{ }\mu\text{s}$ $V_D = 2/3 V_{DRM}$	repetitive, $I_T = 50\text{ A}$	150	$\text{A}/\mu\text{s}$
	$I_G = 0.3\text{ A},$ $di_G/dt = 0.3\text{ A}/\mu\text{s}$	non repetitive, $I_T = 1/3 \cdot I_{dAV}$	500	$\text{A}/\mu\text{s}$
$(dv/dt)_{cr}$	$T_{VJ} = T_{VJM}; V_{DR} = 2/3 V_{DRM}$ $R_{GK} = \infty$; method 1 (linear voltage rise)		1000	$\text{V}/\mu\text{s}$
V_{RGM}			10	V
P_{GM}	$T_{VJ} = T_{VJM}$ $I_T = I_{TAVM}$	$t_p = 30\text{ }\mu\text{s}$	≤ 10	W
		$t_p = 500\text{ }\mu\text{s}$	≤ 5	W
		$t_p = 10\text{ ms}$	≤ 1	W
P_{GAVM}			0.5	W
T_{VJ}			-40...+125	$^{\circ}\text{C}$
T_{VJM}			125	$^{\circ}\text{C}$
T_{stg}			-40...+125	$^{\circ}\text{C}$
V_{ISOL}	50/60 Hz, RMS	$t = 1\text{ min}$	3000	V~
	$I_{ISOL} \leq 1\text{ mA}$	$t = 1\text{ s}$	3600	V~
M_d	Mounting torque	(M5)	2-2.5	Nm
		(10-32 UNF)	18-22	lb.in.
Weight	typ.		28	g

Features

- Package with DCB ceramic base plate
- Isolation voltage 3600 V~
- Planar passivated chips
- Soldering terminals
- UL registered E 72873

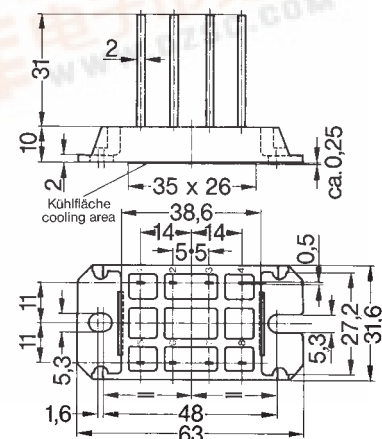
Applications

- Input rectifier for switch mode power supplies (SMPS)
- Softstart capacitor charging
- Electric drives and auxiliaries

Advantages

- Easy to mount with two screws
- Space and weight savings
- Improved temperature and power cycling

Dimensions in mm (1 mm = 0.0394")



Symbol	Test Conditions	Characteristic Values
I_R, I_D	$V_R = V_{RRM}; V_D = V_{DRM}$ $T_{VJ} = T_{VJM}$ $T_{VJ} = 25^\circ\text{C}$	$\leq 5 \text{ mA}$ $\leq 0.3 \text{ mA}$
V_F, V_T	$I_F, I_T = 30 \text{ A}, T_{VJ} = 25^\circ\text{C}$	$\leq 1.33 \text{ V}$
V_{T0} r_T	For power-loss calculations only ($T_{VJ} = 125^\circ\text{C}$)	0.85 V $15 \text{ m}\Omega$
V_{GT}	$V_D = 6 \text{ V};$ $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = -40^\circ\text{C}$	$\leq 1.0 \text{ V}$ $\leq 1.2 \text{ V}$
I_{GT}	$V_D = 6 \text{ V};$ $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = -40^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$	$\leq 65 \text{ mA}$ $\leq 80 \text{ mA}$ $\leq 50 \text{ mA}$
V_{GD} I_{GD}	$T_{VJ} = T_{VJM};$ $T_{VJ} = T_{VJM};$ $V_D = 2/3 V_{DRM}$ $V_D = 2/3 V_{DRM}$	$\leq 0.2 \text{ V}$ $\leq 5 \text{ mA}$
I_L	$I_G = 0.3 \text{ A}; t_G = 30 \mu\text{s}$ $di_G/dt = 0.3 \text{ A}/\mu\text{s}$ $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = -40^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$	$\leq 150 \text{ mA}$ $\leq 200 \text{ mA}$ $\leq 100 \text{ mA}$
I_H	$T_{VJ} = 25^\circ\text{C}; V_D = 6 \text{ V}; R_{GK} = \infty$	$\leq 100 \text{ mA}$
t_{gd}	$T_{VJ} = 25^\circ\text{C}; V_D = 1/2 V_{DRM}$ $I_G = 0.3 \text{ A}; di_G/dt = 0.3 \text{ A}/\mu\text{s}$	$\leq 2 \mu\text{s}$
t_q Q_r	$T_{VJ} = 125^\circ\text{C}; I_T = 15 \text{ A}, t_p = 300 \mu\text{s}, -di/dt = 10 \text{ A}/\mu\text{s}$ $V_R = 100 \text{ V}, dv/dt = 20 \text{ V}/\mu\text{s}, V_D = 2/3 V_{DRM}$	typ. $150 \mu\text{s}$ $75 \mu\text{C}$
R_{thJC}	per thyristor (diode); DC current per module	1.0 K/W 0.17 K/W
R_{thJH}	per thyristor (diode); DC current per module	1.6 K/W 0.27 K/W
d_s	Creeping distance on surface	7 mm
d_A	Creepage distance in air	7 mm
a	Max. allowable acceleration	50 m/s^2