## MOTOROLA99供应商 SEMICONDUCTOR TECHNICAL DATA

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# 0 to 1000 kPa (0 to 150 PSI) On-Chip Signal Conditioned, 0.2 V to 4.7 V Output, Temperature Compensated and Calibrated, Silicon Pressure Sensor

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The MPX5999D piezoresistive transducer is a state-of-the-art pressure sensor designed for a wide range of applications, but particularly for those employing a microcontroller or microprocessor with A/D inputs. This patented, single element X-ducer combines advanced micromachining techniques, thin-film metallization and bipolar semiconductor processing to provide an accurate, high level analog output signal that is proportional to applied pressure.

Figure 1 shows a block diagram of the internal circuitry integrated on the stand-alone sensing chip.

### Features

- Temperature Compensated Over 0 to 85°C
- Ideally Suited for Microprocessor or Microcontroller–Based Systems
- Patented Silicon Shear Stress Strain Gauge
- Durable Epoxy Unibody Element

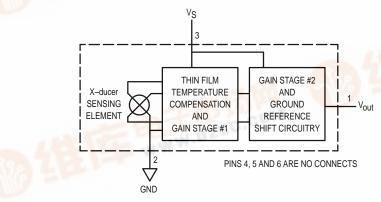


Figure 1. Fully Integrated Pressure Sensor Schematic

## MAXIMUM RATINGS(1)

Parametrics	Symbol	Value	Unit
Overpressure <sup>(2)</sup> (P1 > P2)	P <sub>max</sub>	4000	kPa
Burst Pressure <sup>(2)</sup> (P1 > P2)	Pburst	6000	kPa
Storage Temperature	T <sub>stg</sub>	-40° to +150	°C
Operating Temperature	ТА	-40° to +125	°C

1.  $T_C = 25^{\circ}C$  unless otherwise noted. Maximum Ratings apply to Case 867–08 only.

2. Extended exposure at the specified limits may cause permanent damage or degradation to the device.

3. This sensor is designed for applications where P1 is always greater than, or equal to P2.

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(Replaces MPX5999) odf.dzsc.com



X–ducer™ SILICON PRESSURE SENSORS



BASIC CHIP CARRIER ELEMENT CASE 867–08, STYLE 1

PIN NUMBER					
1	Vout	4	N/C		
2	Gnd	5	N/C		
3	VS	6	N/C		

NOTE: Pins 4, 5, and 6 are internal device connections. Do not connect to external circuitry or ground. Pin 1 is noted by the notch in the Lead.



#### **OPERATING CHARACTERISTICS** (V<sub>S</sub> = 5.0 Vdc, T<sub>A</sub> = 25°C unless otherwise noted, P1 > P2)

Characteristic	Symbol	Min	Тур	Max	Unit
Pressure Range <sup>(1)</sup>	POP	0	_	1000	kPa
Supply Voltage <sup>(2)</sup>	VS	4.75	5.0	5.25	Vdc
Supply Current	۱ <sub>0</sub>	_	7.0	10	mAdc
Zero Pressure Offset <sup>(3)</sup> (0 to $85^{\circ}$ C)	Voff	0.088	0.2	0.313	Vdc
Full Scale Output <sup>(4)</sup> (0 to 85°C)	V <sub>FSO</sub>	4.587	4.7	4.813	Vdc
Full Scale Span <sup>(5)</sup> (0 to 85°C)	V <sub>FSS</sub>	_	4.5	_	Vdc
Sensitivity	V/P	_	4.5	_	mV/kPa
Accuracy <sup>(6)</sup> (0 to 85°C)	—	_	_	± 2.5	<sup>%V</sup> FSS
Response Time(7)	t <sub>R</sub>	_	1.0	_	ms
Output Source Current at Full Scale Output	I <sub>O+</sub>	_	0.1	-	mA
Warm–Up <sup>(8)</sup>	—	_	20	—	Sec

### **MECHANICAL CHARACTERISTICS**

Characteristic	Symbol	Min	Тур	Max	Unit
Weight, Basic Element (Case 867)	-	_	4.0	—	Grams
Cavity Volume	—	—	—	0.01	IN <sup>3</sup>
Volumetric Displacement	—	—	—	0.001	IN <sup>3</sup>

NOTES:

- 1. 1.0 kPa (kiloPascal) equals 0.145 psi.
- 2. Device is ratiometric within this specified excitation range.
- 3. Offset (Voff) is defined as the output voltage at the minimum rated pressure.
- 4. Full Scale Output (V<sub>FSO</sub>) is defined as the output voltage at the maximum or full rated pressure.
- 5. Full Scale Span (V<sub>FSS</sub>) is defined as the algebraic difference between the output voltage at full rated pressure and the output voltage at the minimum rated pressure.
- 6. Accuracy (error budget) consists of the following:
  - Linearity: Output deviation from a straight line relationship with pressure over the specified pressure range.
  - Temperature Hysteresis: Output deviation at any temperature within the operating temperature range, after the temperature is cycled to and from the minimum or maximum operating temperature points, with zero differential pressure applied.
  - Pressure Hysteresis: Output deviation at any pressure within the specified range, when this pressure is cycled to and from the minimum or maximum rated pressure, at 25°C.
    - TcSpan: Output deviation over the temperature range of 0° to 85°C, relative to 25°C.
  - TcOffset: Output deviation with minimum rated pressure applied, over the temperature range of 0° to 85°C, relative to 25°C.
  - Variation from Nominal: The variation from nominal values, for Offset or Full Scale Span, as a percent of V<sub>FSS</sub>, at 25°C.
- 7. Response Time is defined as the time for the incremental change in the output to go from 10% to 90% of its final value when subjected to a specified step change in pressure.
- 8. Warm-up is defined as the time required for the device to meet the specified output voltage after the pressure has been stabilized.

9. P2 max is 500 kPa.

## **ON-CHIP TEMPERATURE COMPENSATION, CALIBRATION AND SIGNAL CONDITIONING**

Figure 2 shows the sensor output signal relative to pressure input. Typical, minimum and maximum output curves are shown for operation over 0°C to 85°C. (Device output may be nonlinear outside of the rated pressure range.)

The performance over temperature is achieved by integrating the shear–stress strain gauge, temperature compensation, calibration and signal conditioning circuitry onto a single monolithic chip.

Figure 3 illustrates the differential or gauge configuration in the basic chip carrier (Case 867). A fluoro silicone gel isolates the die surface and wire bonds from harsh environments, while allowing the pressure signal to be transmitted to the silicon diaphragm.

The MPX5999D pressure sensor operating characteristics, and internal reliability and qualification tests are based on use of dry air as the pressure media. Media other than dry air may have adverse effects on sensor performance and long-term reliability. Contact the factory for information regarding media compatibility in your application.

Figure 4 shows a typical decoupling circuit for interfacing the output of the MPX5999D to the A/D microprocessor. Proper decoupling of the power supply is recommended.

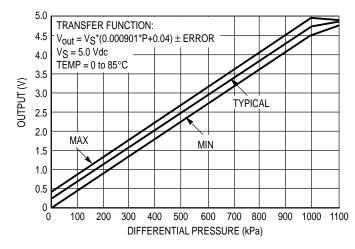
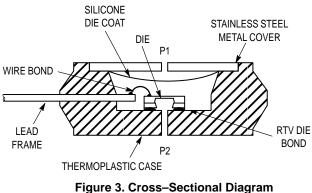
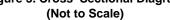
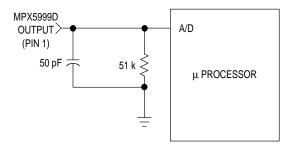
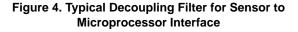


Figure 2. Output versus Pressure Differential









## PRESSURE (P1) / VACUUM (P2) SIDE IDENTIFICATION TABLE

Motorola designates the two sides of the pressure sensor as the Pressure (P1) side and the Vacuum (P2) side. The Pressure (P1) side is the side containing fluoro silicone gel which protects the die from harsh media. The Motorola MPX pressure sensor is designed to operate with positive differential pressure applied, P1 > P2.

The Pressure (P1) side may be identified by using the table below:

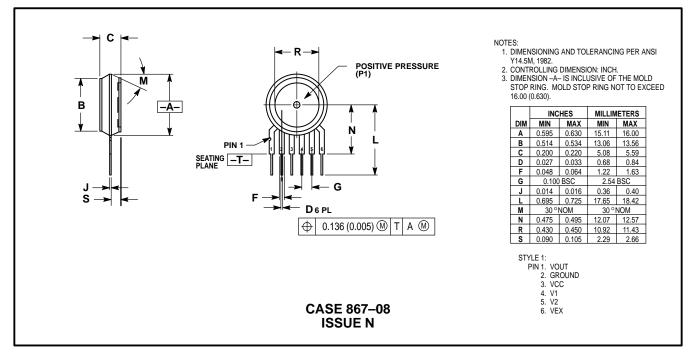
Part Number	Case Type	Pressure (P1) Side Identifier
MPX5999D	867–08	Stainless Steel Cap

#### **ORDERING INFORMATION**

The MPX5999D pressure sensor is available as an element only.

			MPX Series		
Device Type	Options	Case Type	Order Number Device Marking		
Basic Element	Differential	867–08	MPX5999D	MPX5999D	

#### PACKAGE DIMENSIONS



**BASIC ELEMENT (A, D)** 

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