SLES173-MARCH 2006

# 24-BIT, 96-kHz STEREO A/D CONVERTER WITH 6 × 2-CHANNEL MUX AND PGAE

#### **FEATURES**

- Multiplexer and Programmable-Gain Amplifier (PGA)
  - 6×2-Channel Single-Ended Inputs
  - Multiplexed Output
  - Maximum Input Level: 2.4 V rms
  - Input Resistance: 50 kΩ, Minimum
  - PGA Gain: 11-dB to -11-dB Range, 0.5
- 24-Bit Delta-Sigma Stereo A/D Converter
- Antialiasing Filter Included
- Oversampling Decimation Filter
  - Oversampling Frequency: ×64
  - Pass-Band Ripple: ±0.05 dB
  - Stop-Band Attenuation: -65 dB
  - On-Chip High-Pass Filter: 0.91 Hz (48 kHz)
- High Performance
  - THD+N: 0.0023% (Typically)
  - SNR: 101 dB (Typically)
  - Dynamic Range: 102 dB (Typically)

- PCM Audio Interface
  - Master/Slave Mode Selectable
  - Data Formats: 24-Bit Left-Justified, 24-Bit I<sup>2</sup>S, 16-, 24-Bit Right-Justified
- Mode Control by Serial Interface:
  - With SPI Control (PCM1850A)
  - With I<sup>2</sup>C Control (PCM1851A)
- Sampling Rate: 16–96 kHz
- System Clock: 256 f<sub>s</sub>, 384 f<sub>s</sub>, 512 f<sub>s</sub>, 768 f<sub>s</sub>
- Dual Power Supplies: 5 V for Analog, 3.3 V for Digital
- Package: 32-Pin TQFP

## **APPLICATIONS**

- DVD/HDD/DVD+HDD Recorder
- AV Amplifier Receiver
- CD Recorder
- MD Recorder
- Multitrack Recorder
- Electric Musical Instrument

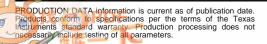
## DESCRIPTION

The PCM1850A/1851A is a high-performance, low-cost, single-chip stereo analog-to-digital converter with a single-ended analog front end that consists of a 6-stereo-input multiplexer and wide-range PGA. The PCM1850A/1851A includes a delta-sigma modulator with 64-times oversampling, a digital decimation filter and a low-cut filter that removes the dc component of the input signal. For various applications, the PCM1850A/1851A supports two modes (master and slave) and four data formats through a serial control interface, SPI for the PCM1850A and I<sup>2</sup>C for the PCM1851A. The PCM1850A/1851A is suitable for a wide variety of cost-sensitive DVD/CD/MD recorder and receiver applications where good performance and operation from a 5-V analog supply and 3.3-V digital supply is required. The PCM1850A/1851A is fabricated using a highly advanced CMOS process and is available in a small 32-pin TQFP package.



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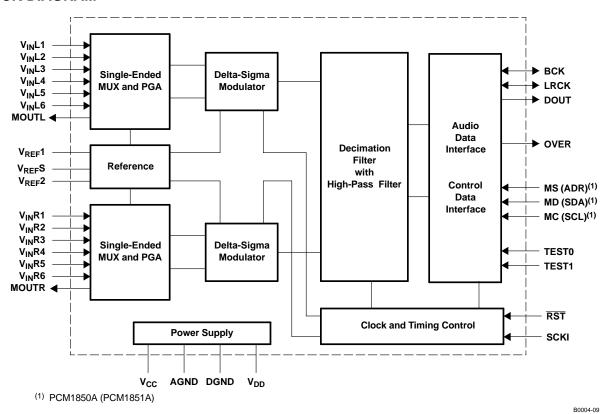




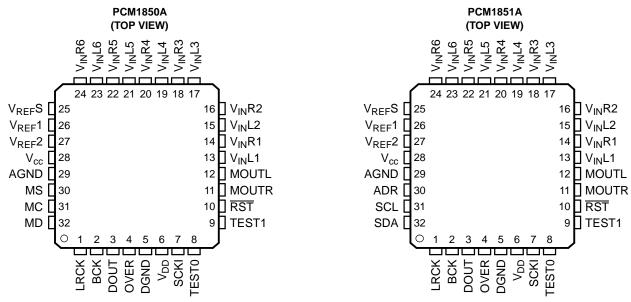
This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

#### **BLOCK DIAGRAM**



## **PIN ASSIGNMENTS**



P0040-01



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## **TERMINAL FUNCTIONS**

## **PCM1850A**

TERMINAL			DECODINE			
NAME	NO.	I/O	DESCRIPTION			
AGND	29	_	Analog GND			
BCK	2	I/O	Bit clock input/output <sup>(1)</sup>			
DGND	5	_	Digital GND			
DOUT	3	0	Audio data output			
LRCK	1	I/O	Sampling clock input/output <sup>(1)</sup>			
MC	31	I	Mode-control clock input <sup>(2)</sup>			
MD	32	I	Mode-control data input <sup>(2)</sup>			
MOUTL	12	0	Multiplexer output, L-channel			
MOUTR	11	0	Multiplexer output, R-channel			
MS	30	I	Mode-control select input <sup>(3)</sup>			
OVER	4	0	Overflow flag			
RST	10	I	Reset, active-LOW <sup>(3)</sup>			
SCKI	7	I	System clock input; 256 f <sub>S</sub> , 384 f <sub>S</sub> , 512 f <sub>S</sub> , or 768 f <sub>S</sub> <sup>(2)</sup>			
TEST0	8	I	Test 0, must be connected to GND <sup>(3)</sup>			
TEST1	9	I	Test 1, must be connected to GND <sup>(3)</sup>			
V <sub>CC</sub>	28	_	Analog power supply, 5-V			
$V_{DD}$	6	_	Digital power supply, 3.3-V			
V <sub>IN</sub> L1	13	I	Analog input 1, L-channel			
V <sub>IN</sub> L2	15	I	Analog input 2, L-channel			
V <sub>IN</sub> L3	17	I	Analog input 3, L-channel			
V <sub>IN</sub> L4	19	I	Analog input 4, L-channel			
V <sub>IN</sub> L5	21	I	Analog input 5, L-channel			
V <sub>IN</sub> L6	23	I	Analog input 6, L-channel			
V <sub>IN</sub> R1	14	I	Analog input 1, R-channel			
V <sub>IN</sub> R2	16	I	Analog input 2, R-channel			
V <sub>IN</sub> R3	18	I	Analog input 3, R-channel			
V <sub>IN</sub> R4	20	I	Analog input 4, R-channel			
V <sub>IN</sub> R5	22	I	Analog input 5, R-channel			
V <sub>IN</sub> R6	24	I	Analog input 6, R-channel			
V <sub>REF</sub> S	25	_	Reference S decoupling capacitor (= 0.5 V <sub>CC</sub> )			
V <sub>REF</sub> 1	26		Reference 1 decoupling capacitor (= 0.5 V <sub>CC</sub> )			
V <sub>REF</sub> 2	27	_	Reference 2 decoupling capacitor (= V <sub>CC</sub> )			

- Schmitt-trigger input with internal pulldown resistor (50 k $\Omega$ , typically) Schmitt-trigger input, 5-V tolerant Schmitt-trigger input with internal pulldown resistor (50 k $\Omega$ , typically), 5-V tolerant



## PCM1851A

TERMINAL			DECORPTION			
NAME	NO.	I/O	DESCRIPTION			
ADR	30	I	Mode control address select input <sup>(1)</sup>			
AGND	29	_	Analog GND			
BCK	2	I/O	Bit clock input/output <sup>(2)</sup>			
DGND	5	_	Digital GND			
DOUT	3	0	Audio data output			
LRCK	1	I/O	Sampling clock input/output <sup>(2)</sup>			
MOUTL	12	0	Multiplexer output, L-channel			
MOUTR	11	0	Multiplexer output, R-channel			
OVER	4	0	Overflow flag			
RST	10	I	Reset, active-LOW <sup>(1)</sup>			
SCKI	7	I	System clock input; 256 f <sub>S</sub> , 384 f <sub>S</sub> , 512 f <sub>S</sub> , or 768 f <sub>S</sub> <sup>(3)</sup>			
SCL	31	I	Mode-control clock input <sup>(3)</sup>			
SDA	32	I/O	Mode-control data input/output <sup>(4)</sup>			
TEST0	8	I	Test 0, must be connected to GND <sup>(1)</sup>			
TEST1	9	I	Test 1, must be connected to GND <sup>(1)</sup>			
V <sub>CC</sub>	28	_	Analog power supply, 5-V			
$V_{DD}$	6	_	Digital power supply, 3.3-V			
V <sub>IN</sub> L1	13	I	Analog input 1, L-channel			
V <sub>IN</sub> L2	15	I	Analog input 2, L-channel			
V <sub>IN</sub> L3	17	I	Analog input 3, L-channel			
V <sub>IN</sub> L4	19	I	Analog input 4, L-channel			
V <sub>IN</sub> L5	21	I	Analog input 5, L-channel			
V <sub>IN</sub> L6	23	I	Analog input 6, L-channel			
V <sub>IN</sub> R1	14	I	Analog input 1, R-channel			
V <sub>IN</sub> R2	16	I	Analog input 2, R-channel			
V <sub>IN</sub> R3	18	I	Analog input 3, R-channel			
V <sub>IN</sub> R4	20	I	Analog input 4, R-channel			
V <sub>IN</sub> R5	22	I	Analog input 5, R-channel			
V <sub>IN</sub> R6	24	I	Analog input 6, R-channel			
V <sub>REF</sub> S	25	_	Reference S decoupling capacitor (= 0.5 V <sub>CC</sub> )			
V <sub>REF</sub> 1	26	_	Reference 1 decoupling capacitor (= 0.5 V <sub>CC</sub> )			
V <sub>REF</sub> 2	27	_	Reference 2 decoupling capacitor (= V <sub>CC</sub> )			

- Schmitt-trigger input with internal pulldown resistor (50 k $\Omega$ , typically), 5-V tolerant Schmitt-trigger input with internal pulldown resistor (50 k $\Omega$ , typically) Schmitt-trigger input, 5-V tolerant Schmitt-trigger input/open-drain LOW output, 5-V tolerant

- (2) (3) (4)

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## **ABSOLUTE MAXIMUM RATINGS**(1)

over operating free-air temperature range (unless otherwise noted)

		VALUE	UNIT
V <sub>CC</sub>	Cumhuualtaga	-0.3 to 6.5	V
$V_{DD}$	Supply voltage	-0.3 to 4	V
	Ground voltage differences: AGND, DGND	±0.1	V
	Digital input voltage: LRCK, BCK, DOUT, OVER	$-0.3$ to $(V_{DD} + 0.3) < 4$	V
	Digital input voltage: RST, SCKI, MS (ADR) <sup>(2)</sup> , MC (SCL) <sup>(2)</sup> , MD (SDA) <sup>(2)</sup> , TEST0, TEST1	-0.3 to 6.5	V
	Analog input voltage: V <sub>IN</sub> L1–6, V <sub>IN</sub> R1–6	$-3$ to $(V_{CC} + 3) < 9$	V
	Analog input voltage: MOUTL, MOUTR, V <sub>REF</sub> 1, V <sub>REF</sub> 2, V <sub>REF</sub> S	$-0.3$ to $(V_{CC} + 0.3) < 6.5$	V
	Input current (any pins except supplies)	±10	mA
	Ambient temperature under bias	-40 to 125	°C
	Storage temperature	-55 to 150	°C
	Junction temperature	150	°C
	Lead temperature (soldering)	260°C, 5 s	
	Package temperature (IR reflow, peak)	260	°C

<sup>(1)</sup> Stresses beyond those listed under absolute maximum ratings may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under recommended operating conditions is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

## RECOMMENDED OPERATING CONDITIONS

over operating free-air temperature range (unless otherwise noted)

				MIN	NOM	MAX	UNIT
$V_{CC}$	Analog supply voltage			4.5	5	5.5	V
$V_{DD}$	Digital supply voltage	Digital supply voltage		2.7	3.3	3.6	V
	Analog input voltage, full scale (0 dB)	V <sub>CC</sub> = 5 V, PGA gain = 5.5 dB			2		Vrms
	Digital input logic family				TTL		
	Digital input alogar fragues as	System clock		4.096		49.152	MHz
	Digital input clock frequency	Sampling clock		16		96	kHz
	Digital output load capacitance					20	pF
$T_A$	Operating free-air temperature			40		85	°C

## **ELECTRICAL CHARACTERISTICS**

All specifications at  $T_A = 25$ °C,  $V_{CC} = 5$  V,  $V_{DD} = 3.3$  V, master mode,  $f_S = 48$  kHz, system clock = 256  $f_S$ , 24-bit data (unless otherwise noted)

	DADAMETED	DAD AMETER TEST CONDITIONS	PCM1850	PCM1850APJT, PCM1851APJT		
	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
DIGIT	AL INPUT/OUTPUT — DATA FO	RMAT	,			
	Audio data interface format		Left-justifi	ed, I <sup>2</sup> S, right-j	ustified	
	Audio data bit length			16, 24		bits
	Audio data format		MSB-fir	st, 2s compler	ment	
f <sub>S</sub>	Sampling frequency		16	48	96	kHz
		256 f <sub>S</sub>	4.096	12.288	24.576	
	System alook froquency	384 f <sub>S</sub>	6.144	18.432	36.864	MHz
	System clock frequency	512 f <sub>S</sub>	8.192	24.576	49.152	IVITZ
		768 f <sub>S</sub>	12.288	36.864	_	

<sup>(2)</sup> PCM1850A (PCM1851A)



## **ELECTRICAL CHARACTERISTICS (continued)**

All specifications at  $T_A = 25$ °C,  $V_{CC} = 5$  V,  $V_{DD} = 3.3$  V, master mode,  $f_S = 48$  kHz, system clock = 256  $f_S$ , 24-bit data (unless otherwise noted)

	D. D. A. WETED	TEGT COURTIONS	PCM1850A	APJT, PCM18	51APJT	
	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
INPUT	LOGIC					
V <sub>IH</sub> <sup>(1)</sup>			2		$V_{DD}$	
V <sub>IL</sub> <sup>(1)</sup>	Lamort In alla Inval		0		0.8	\/D0
V <sub>IH</sub> <sup>(2)(3)</sup>	Input logic level		2		5.5	VDC
V <sub>IL</sub> (2)(3	)		0		0.8	
I <sub>IH</sub> (2)		$V_{IN} = V_{DD}$			±10	
I <sub>IL</sub> (2)	Input logic current	$V_{IN} = 0$			±10	^
I <sub>IH</sub> <sup>(1)(3)</sup>	input logic current	$V_{IN} = V_{DD}$		65	100	μΑ
I <sub>IL</sub> (1)(3)		V <sub>IN</sub> = 0			±10	
OUTPU	IT LOGIC					
$V_{OH}^{(4)}$	Output logic level	$I_{OUT} = -4 \text{ mA}$	2.8			VDC
V <sub>OL</sub> <sup>(4)(5</sup>	Output logic level	I <sub>OUT</sub> = 4 mA			0.5	VDC
AFE M	ULTPLEXER					
	Input channels			6		
	Input level for full scale			2	2.4	Vrms
	Center voltage (V <sub>REF</sub> 1)	Selected channel		$0.5\ V_{CC}$		V
	Center voltage (V <sub>REF</sub> S)	Unselected channel		0.5 V <sub>CC</sub>		V
	Input impedance	Selected channel	50	169		kΩ
	input impedance	Unselected channel	50	57		N22
AFE PO	SA .					
	Gain range		-11	0	11	dB
	Gain step			0.5		dB
	Monotonicity			Specified		
	Antialiasing filter frequency response	−3 dB, PGA gain = −5.5 dB		300		kHz
MONIT	OR OUTPUT					
	Output level for full scale	AC-coupled, >10 $k\Omega$		$0.6 V_{CC}$		Vp-p
	Output load	AC-coupled	10			kΩ
	THD+N (6)(7)	AC-coupled, 10 kΩ, 3 Vp-p output		0.0016%		
S/N	Signal-to-noise ratio (6)(7)	AC-coupled, 10 kΩ		104		dB
	Gain error (6)(7)	AC-coupled, 10 kΩ		-3		% of FSR
	Center voltage			0.5 V <sub>CC</sub>		V
ADC						
	Resolution			24		bits
	Full-scale input voltage			0.6 V <sub>CC</sub>		Vp-p

- Pins 1, 2: LRCK, BCK (In slave mode, Schmitt-trigger input, with 50-kΩ typical pulldown resistor)
- Pins 7, 31, 32: SCKI, MC/SCL (PCM1850A/1851A), MD/SDA (PCM1850A/1851A) (Schmitt-trigger input, 5-V tolerant)
  Pins 8–10, 30: TEST0, TEST1, RST, MS/ADR (PCM1850A/1851A) (Schmitt-trigger input, with 50-kΩ typical pulldown resistor, 5-V tolerant)
- Pins 1-4: LRCK, BCK (in master mode), DOUT, OVER
- Pin 32: SDA (PCM1851A) (open-drain LOW output)
- Analog performance specifications are tested with the System Two™ audio measurement system by Audio Precision™, using a 400-Hz HPF and 20-kHz LPF in the RMS mode at  $f_{\rm IN}$  = 1 kHz.
- Reference level (0 dB) is specified as 2-V rms input on V<sub>IN</sub>L[1:6] and V<sub>IN</sub>R[1:6] pins with PGA gain of -5.5 dB.



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## **ELECTRICAL CHARACTERISTICS (continued)**

All specifications at  $T_A = 25$ °C,  $V_{CC} = 5$  V,  $V_{DD} = 3.3$  V, master mode,  $f_S = 48$  kHz, system clock = 256  $f_S$ , 24-bit data (unless otherwise noted)

	D.1.D.1.14ETED	ARAMETER TEST CONDITIONS		PCM1850APJT, PCM1851APJT			
	PARAMETER	TEST CONDITIONS	MIN TYP M		MAX	UNIT	
ACCURA	ACY						
	Gain mismatch, channel-to-channel			±1	±3	% of FSR	
	Gain error			±2	±5	% of FSR	
	Bipolar zero error	High-pass filter bypass		±2		% of FSR	
DYANAN	MIC PERFORMANCE (1) (2)						
		$f_S = 48 \text{ kHz}, V_{IN} = -0.5 \text{ dB (1.89 Vrms)}$		0.0023%	0.004%		
THD+N	Total harmonic distortion + noise (3)	$f_S = 96 \text{ kHz}^{(4)},$ $V_{IN} = -0.5 \text{ dB (1.89 Vrms)}$		0.0027%			
	HOISE (4)	$f_S = 48 \text{ kHz}, V_{IN} = -60 \text{ dB (2 mVrms)}$		1%			
		$f_S = 96 \text{ kHz}^{(4)}, V_{IN} = -60 \text{ dB (2 mVrms)}$		1%			
	Dynamic range (3)	f <sub>S</sub> = 48 kHz, A-weighted	96	102		dB	
	Dynamic range (9)	f <sub>S</sub> = 96 kHz <sup>(4)</sup> , A-weighted		102		uD	
S/N	Signal-to-noise ratio (3)	f <sub>S</sub> = 48 kHz, A-weighted	96	101		dB	
3/IN	Signal-to-noise ratio (9)	f <sub>S</sub> = 96 kHz <sup>(4)</sup> , A-weighted		102		uБ	
	Channel separation	$f_S = 48 \text{ kHz}$	92	98		dB	
	(between L-ch and R-ch) (3)	$f_S = 96 \text{ kHz}^{(4)}$		100		uБ	
	Channel separation (among	$f_S = 48 \text{ kHz}$	90	96		dB	
	channels) <sup>(5)</sup>	$f_S = 96 \text{ kHz}^{(4)}$		96		uБ	
DIGITAL	FILTER PERFORMANCE						
	Pass band				0.454 f <sub>S</sub>	Hz	
	Stop band		0.583 f <sub>S</sub>			Hz	
	Pass-band ripple				±0.05	dB	
	Stop-band attenuation		-65			dB	
	Delay time			17.4/f <sub>S</sub>		S	
	HPF frequency response	-3 dB		0.019 f <sub>S</sub>		mHz	

<sup>(1)</sup> Analog performance specifications are tested with the System Two™ audio measurement system by Audio Precision™, using a 400-Hz HPF and 20-kHz LPF in the RMS mode at  $f_{IN} = 1$  kHz.

<sup>(2)</sup> Reference level (0 dB) is specified as 2-V rms input on V<sub>IN</sub>L[1:6] and V<sub>IN</sub>R[1:6] pins with PGA gain of –5.5 dB.
(3) Unselected channel inputs are terminated to AGND with 0.33 μF.
(4) f<sub>S</sub> = 96 kHz, system clock = 256 f<sub>S</sub>.
(5) 2-V rms input is applied to all unselected channels, and input of selected channel is terminated to AGND with 0.33 μF.



## **ELECTRICAL CHARACTERISTICS (continued)**

All specifications at  $T_A = 25^{\circ}C$ ,  $V_{CC} = 5$  V,  $V_{DD} = 3.3$  V, master mode,  $f_S = 48$  kHz, system clock = 256  $f_S$ , 24-bit data (unless otherwise noted)

	DADAMETED	PARAMETER TEST CONDITIONS PCM1850A		PJT, PCM18			
PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT	
POWE	R-SUPPLY REQUIREMENTS				<u> </u>		
V <sub>CC</sub>	Valtage renge		4.5	5	5.5	VDC	
$V_{DD}$	Voltage range		2.7	3.3	3.6	VDC	
		Operational		28	35	mA	
I <sub>CC</sub>		Powered down (2)		190		μΑ	
	Supply current (1)	f <sub>S</sub> = 48 kHz		6	10	A	
		f <sub>S</sub> = 96 kHz <sup>(3)</sup>		12		mA	
I <sub>DD</sub>		Powered down <sup>(2)</sup> , PCM1850A		80			
		Powered down <sup>(2)</sup> , PCM1851A		280		μΑ	
		Operating, f <sub>S</sub> = 48 kHz		160	208		
	Danier diagination	Operating, f <sub>S</sub> = 96 kHz <sup>(3)</sup>		180		\^/	
	Power dissipation	Powered down <sup>(2)</sup> , PCM1850A		1.2		mW	
		Powered down <sup>(2)</sup> , PCM1851A		1.9			
TEMPE	RATURE RANGE						
	Operation temperature		-40		85	°C	
	Thermal resistance $(\theta_{JA})$			80		°C/W	

<sup>(1)</sup> Minimum load on DOUT (pin 3), BCK (pin 2), LRCK (pin 1)

<sup>(2)</sup> Halt SCKI, BCK, LRCK. (3) f<sub>S</sub> = 96 kHz, system clock = 256 f<sub>S</sub>.

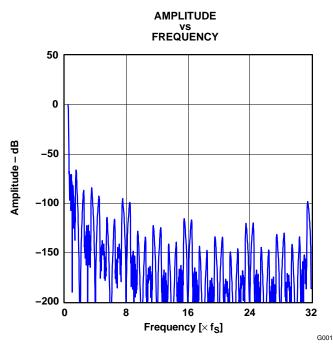


## TYPICAL PERFORMANCE CURVES OF INTERNAL FILTER

All specifications at  $T_A = 25$ °C,  $V_{CC} = 5$  V,  $V_{DD} = 3.3$  V, master mode,  $f_S = 48$  kHz, system clock = 256  $f_S$ , 24-bit data (unless otherwise noted).

## **DIGITAL FILTER**

#### **Decimation Filter Frequency Response**



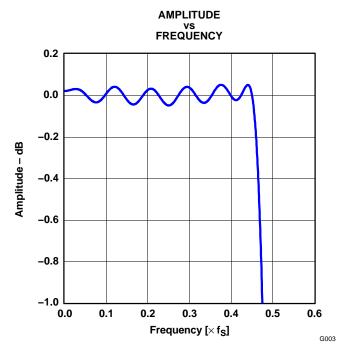
-10 -20 -30 Amplitude – dB -40 -50 -60 -70 -80 -90 -100 0.25 0.00 0.50 1.00 Frequency [ $\times f_S$ ]

**AMPLITUDE** 

vs FREQUENCY

Figure 1. Overall Characteristics

Figure 2. Stop-Band Attenuation Characteristics



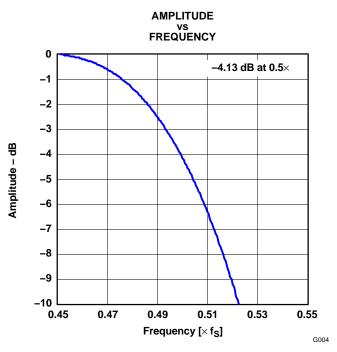


Figure 3. Pass-Band Ripple Characteristics

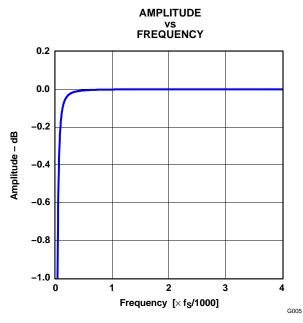
Figure 4. Transition-Band Characteristics



## TYPICAL PERFORMANCE CURVES OF INTERNAL FILTER (continued)

All specifications at  $T_A = 25$ °C,  $V_{CC} = 5$  V,  $V_{DD} = 3.3$  V, master mode,  $f_S = 48$  kHz, system clock = 256  $f_S$ , 24-bit data (unless otherwise noted).

## **High-Pass Filter Frequency Response**



**AMPLITUDE** vs FREQUENCY 0 -10 -20 -30 Amplitude - dB -40 -50 -60 -70 -80 -90 -100 0.4 0.2 0.3 0.0 Frequency [x f<sub>S</sub>/1000] G006

Figure 5. HPF Pass-Band Characteristics

Figure 6. HPF Stop-Band Characteristics

## **ANALOG FILTER**

## Antialiasing Filter Frequency Response (at PGA Gain = -5.5 dB)

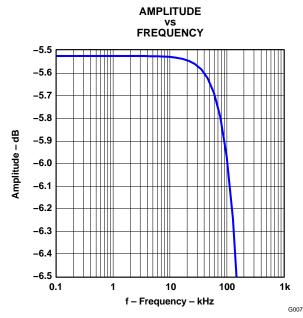


Figure 7. Antialiasing Filter Pass-Band Characteritics

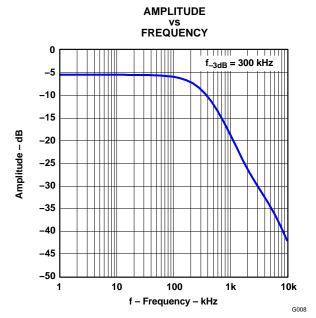
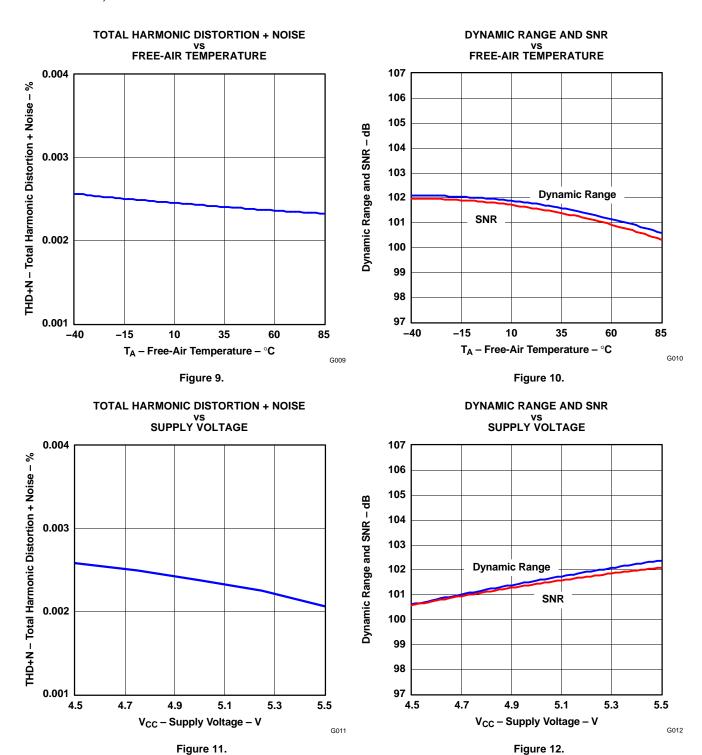


Figure 8. Antialiasing Filter Stop-Band Characteritics



## TYPICAL PERFORMANCE CURVES AT PGA GAIN = -5.5 dB

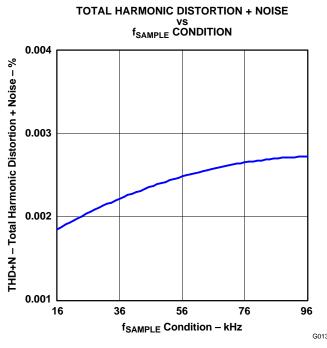
All specifications at  $T_A = 25$ °C,  $V_{CC} = 5$  V,  $V_{DD} = 3.3$  V, master mode,  $f_S = 48$  kHz, system clock = 256  $f_S$ , 24-bit data (unless otherwise noted).





## TYPICAL PERFORMANCE CURVES AT PGA GAIN = -5.5 dB (continued)

All specifications at  $T_A = 25$ °C,  $V_{CC} = 5$  V,  $V_{DD} = 3.3$  V, master mode,  $f_S = 48$  kHz, system clock = 256  $f_S$ , 24-bit data (unless otherwise noted).



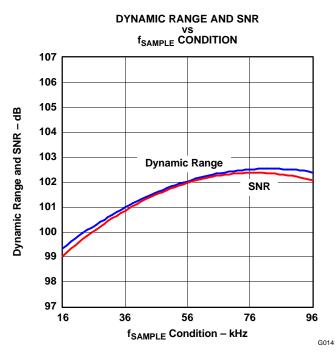
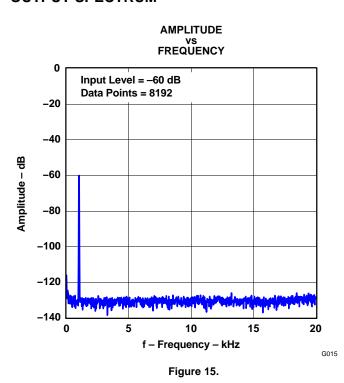


Figure 13.

Figure 14.

## **OUTPUT SPECTRUM**



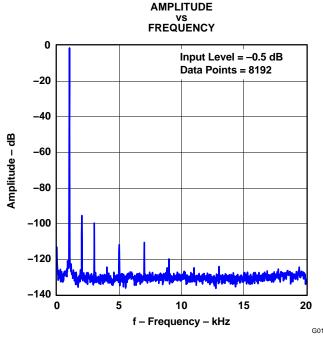


Figure 16.



## TYPICAL PERFORMANCE CURVES AT PGA GAIN = -5.5 dB (continued)

All specifications at  $T_A = 25$ °C,  $V_{CC} = 5$  V,  $V_{DD} = 3.3$  V, master mode,  $f_S = 48$  kHz, system clock = 256  $f_S$ , 24-bit data (unless otherwise noted).

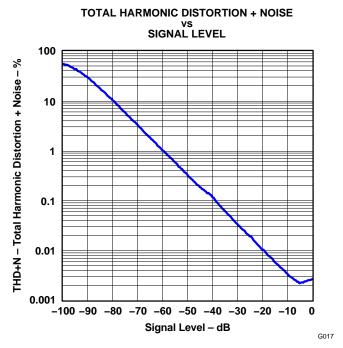
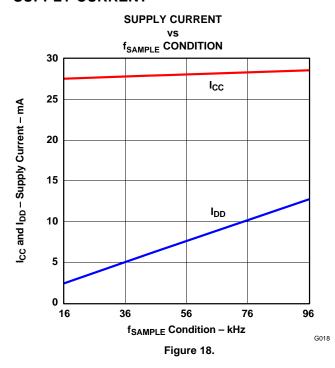
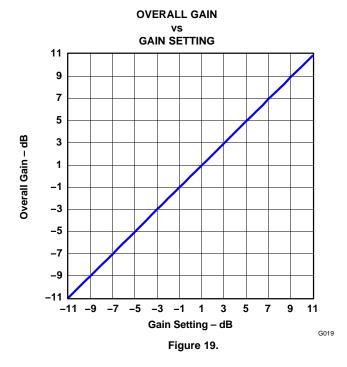


Figure 17.

## **SUPPLY CURRENT**



## **PGA GAIN LINEARITY**





#### **DETAILED DESCRIPTION**

#### SYSTEM CLOCK

The PCM1850A/1851A supports 256  $f_S$ , 384  $f_S$ , 512  $f_S$ , and 768  $f_S$  as the system clock, where  $f_S$  is the audio sampling frequency. The system clock must be supplied on SCKI (pin 7).

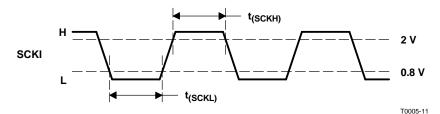
The PCM1850A/1851A has a system clock detection circuit which automatically senses if the system clock is operating at 256  $f_S$ , 384  $f_S$ , 512  $f_S$ , or 768  $f_S$  in slave mode. In master mode, the system clock frequency must be selected by mode control via the serial port. The 768- $f_S$  system clock is not available in master mode or for  $f_S$  = 88.2 kHz and 96 kHz in the slave mode. The system clock is divided into 128  $f_S$  and 64  $f_S$  automatically, and these frequencies are used to operate the digital filter and the delta-sigma modulator, respectively.

Table 1 shows the relationship of typical sampling frequency to system clock frequency, and Figure 20 shows system clock timing.

SYSTEM CLOCK FREQUENCY (MHz) SAMPLING RATE FREQUENCY (kHz) 256 f<sub>S</sub> 768 f<sub>S</sub><sup>(1)</sup> 384 f<sub>S</sub> 512 f<sub>S</sub> 16.384 24.576 32 8.192 12.288 44.1 11.2896 16.9344 22.5792 33.8688 48 12.288 18.432 24.576 36.864 16.384 24.576 32.768 49.152 64 88.2 22.5792 33.8688 45.1584 96 24.576 36.864 49.152

Table 1. Sampling Frequency and System Clock Frequency

## (1) Slave mode only



SYMBOL	PARAMETER	MIN	MAX	UNIT
t <sub>(SCKH)</sub>	System clock pulse duration, HIGH	8		ns
t <sub>(SCKL)</sub>	System clock pulse duration, LOW	8		ns

Figure 20. System Clock Timing

## **POWER-ON-RESET SEQUENCE**

The PCM1850A/1851A has an internal power-on-reset circuit, and initialization (reset) is performed automatically at the time that the power supply ( $V_{DD}$ ) exceeds 2.2 V (typical). While  $V_{DD}$  < 2.2 V (typical) and for 1024 system clocks after  $V_{DD}$  > 2.2 V (typical), the PCM1850A/1851A stays in the reset state and the digital output is forced to zero. The digital output is valid after the reset state is released and the time of  $4500/f_S$  has passed. At the moment of the power-on-reset release, the PCM1850A/1851A does not need a system clock. Figure 21 illustrates the internal power-on-reset timing and the digital output for power-on reset.

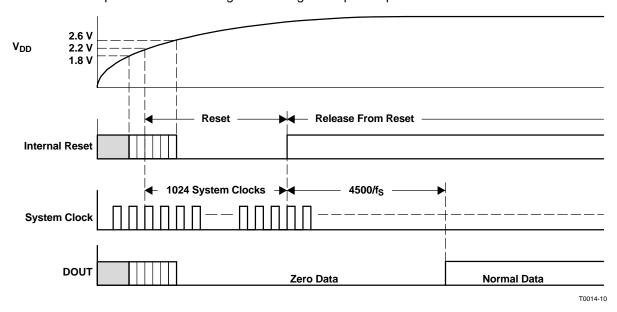


Figure 21. Internal Power-On-Reset Timing

#### **ANALOG FRONT END**

The PCM1850A/1851A has a built-in analog front-end circuit, which is shown in the block diagram of Figure 22. Selection of the multiplexer input and PGA gain is controlled by mode control via the serial port as shown in Table 2 and Table 3. The change of the input selection and the gain selection is performed immediately after the serial control packet for the change is sent. A popping noise or other unexpected transient response could be generated in the audio signal during channel and gain change. Because the PCM1850A/1851A has no zero-cross detection and no other buffering capability for channel and gain change, appropriate data handling in the digital domain is recommended to control transients.

The PCM1850A/1851A analog front end permits only ac input via an input capacitor; dc input is prohibited. A signal source resistance of less than 1 k $\Omega$  is recommended for the  $V_{IN}xx$  pins.

All unselected channel inputs are terminated  $V_{REF}S$  (= 0.5  $V_{CC}$ ) using a resistor, typically 57 k $\Omega$ .

The PCM1850A/1851A employs MOUTL/R pins (pins 12 and 11) to monitor the multiplexer output. The load on these pins must be ac-coupled and not less than 10 k $\Omega$ . The full-scale output level is typically 0.6 V<sub>CC</sub>.

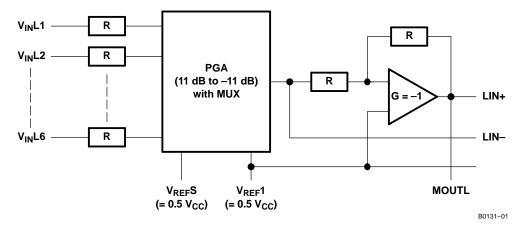


Figure 22. Analog Front-End Block Diagram (L-Channel)

Table 2. Multiplexer Input Selection

CH2	CH1	CH0	CHANNEL	
0	0	0	Mute	
0	0	1	Channel 1 (default)	
0	1	0	Channel 2	
0	1	1	Channel 3	
1	0	0	Channel 4	
1	0	1	Channel 5	
1	1	0	Channel 6	
1	1	1	Mute	



## Table 3. PGA Gain Selection

Table 3. PGA Gain Selection							
PG5	PG4	PG3	PG2	PG1	PG0	PGA GAIN [dB]	R <sub>IN</sub> [kΩ, Typical] <sup>(1)</sup>
0	0	1	0	1	0	-11 (default)	201
0	0	1	0	1	1	-10.5	199
0	0	1	1	0	0	-10	196
0	0	1	1	0	1	-9.5	193
0	0	1	1	1	0	<b>–</b> 9	190
0	0	1	1	1	1	-8.5	188
0	1	0	0	0	0	-8	185
0	1	0	0	0	1	-7.5	181
0	1	0	0	1	0	<b>-7</b>	178
0	1	0	0	1	1	-6.5	175
0	1	0	1	0	0	-6	172
0	1	0	1	0	1	-5.5	169
0	1	0	1	1	0	-5	165
0	1	0	1	1	1	-4.5	162
0	1	1	0	0	0	-4	158
0	1	1	0	0	1	-3.5	155
0	1	1	0	1	0	-3	151
0	1	1	0	1	1	-2.5	147
0	1	1	1	0	0	-2	144
0	1	1	1	0	1	-1.5	140
0	1	1	1	1	0	-1	136
0	1	1	1	1	1	-0.5	133
1	0	0	0	0	0	0	129
1	0	0	0	0	1	0.5	125
1	0	0	0	1	0	1	122
1	0	0	0	1	1	1.5	118
1	0	0	1	0	0	2	114
1	0	0	1	0	1	2.5	111
1	0	0	1	1	0	3	107
1	0	0	1	1	1	3.5	103
1	0	1	0	0	0	4	100
1	0	1	0	0	1	4.5	96
1	0	1	0	1	0	5	93
1	0	1	0	1	1	5.5	89
1	0	1	1	0	0	6	86
1	0	1	1	0	1	6.5	83
1	0	1	1	1	0	7	80
1	0	1	1	1	1	7.5	77
1	1	0	0	0	0	8	73
1	1	0	0	0	1	8.5	70
1	1	0	0	1	0	9	68
1	1	0	0	1	1	9.5	65
1	1	0	1	0	0	10	62
1	1	0	1	0	1	10.5	59
1	1	0	1	1	0	11	57

<sup>(1)</sup>  $R_{IN}(k\Omega, typical) = 258/(1 + 10^{GAIN/20})$ The PCM1850A/1851A becomes mute for PG[5:0] values other than those listed.

#### **SERIAL AUDIO DATA INTERFACE**

The PCM1850A/1851A interfaces with the audio system through BCK (pin 2), LRCK (pin 1), and DOUT (pin 3).

#### **Interface Mode**

The PCM1850A/1851A supports both master and slave modes as interface modes, and they are selected by mode control via the serial port as shown in Table 4.

In master mode, the PCM1850A/1851A provides the timing for serial audio data communications between the PCM1850A/1851A and the digital audio processor or external circuit. While in slave mode, the PCM1850A/1851A receives the timing for data transfer from an external controller.

**Table 4. Interface Mode** 

MD1	MD0	INTERFACE MODE					
0	0	ave mode (256 f <sub>S</sub> , 384 f <sub>S</sub> , 512 f <sub>S</sub> , 768 f <sub>S</sub> ) (default)					
0	1	Master mode (256 f <sub>S</sub> )					
1	0	Master mode (384 f <sub>S</sub> )					
1	1	Master mode (512 f <sub>S</sub> )					

#### Master Mode

In master mode, BCK and LRCK work as output pins, and these pins are controlled by timing which is generated in the clock and timing control circuit of the PCM1850A/1851A. The frequency of BCK is fixed at  $64 \times LRCK$ . A  $768-f_S$  system clock is not available in master mode.

#### Slave Mode

In slave mode, BCK and LRCK work as input pins. The PCM1850A/1851A accepts the 64 BCK/LRCK or 48 BCK/LRCK (only for 384  $f_S$  SCKI) format. A 768- $f_S$  system clock is not available for  $f_S$  = 88.2 kHz and 96 kHz in slave mode.

#### **Data Format**

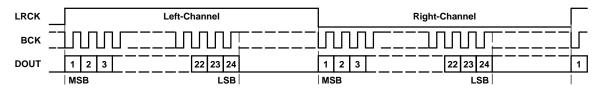
The PCM1850A/1851A supports four audio data formats in both master and slave modes, and they are selected by mode control via the serial port as shown in Table 5. Figure 23 illustrates the data formats in both slave and master modes.

**Table 5. Data Format** 

FORMAT NO.	FORMAT NO. FMT2		FORMAT	
0	1	0	1	Left-justified, 24-bit
1	1	0	0	I <sup>2</sup> S, 24-bit, (default)
2	0	0	0	Right-justified, 24-bit
3	0	1	1	Right-justified, 16-bit

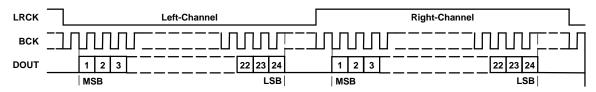
## FORMAT 0: FMT[2:0] = 101b

24-Bit, MSB-First, Left-Justified



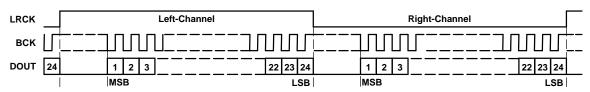
## FORMAT 1: FMT[2:0] = 100b

24-Bit, MSB-First, I2S



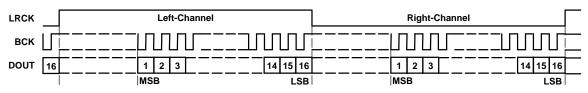
## FORMAT 2: FMT[2:0] = 000b

24-Bit, MSB-First, Right-Justified



#### FORMAT 3: FMT[2:0] = 011b

16-Bit, MSB-First, Right-Justified



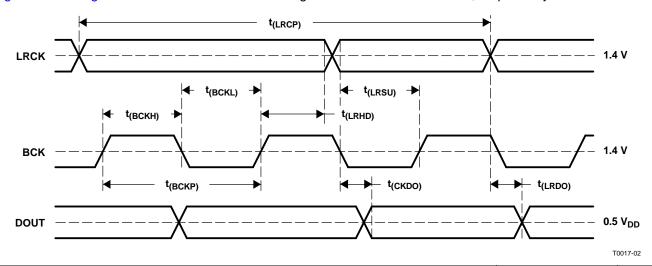
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Figure 23. Audio Data Format (LRCK, BCK Work as Inputs in Slave Mode and Outputs in Master Mode)



## **Interface Timing**

Figure 24 and Figure 25 illustrate the interface timing in slave and master modes, respectively.

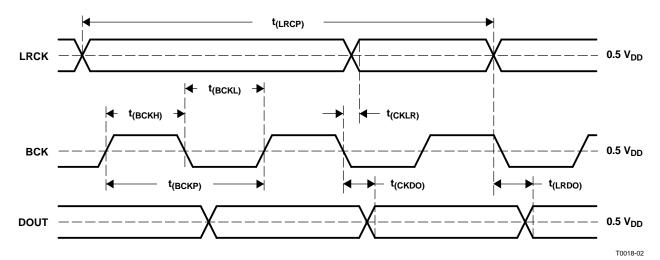


SYMBOL	PARAMETER	MIN	TYP	MAX	UNIT
t <sub>(BCKP)</sub>	BCK period	150			ns
t <sub>(BCKH)</sub>	BCK pulse duration, HIGH	60			ns
t <sub>(BCKL)</sub>	BCK pulse duration, LOW	60			ns
t <sub>(LRSU)</sub>	LRCK setup time to BCK rising edge	20			ns
t <sub>(LRHD)</sub>	LRCK hold time to BCK rising edge	20			ns
t <sub>(LRCP)</sub>	LRCK period	10			μs
t <sub>(CKDO)</sub>	Delay time, BCK falling edge to DOUT valid	-10		20	ns
t <sub>(LRDO)</sub>	Delay time, LRCK edge to DOUT valid	-10		20	ns
t <sub>r</sub>	Rise time of all signals			10	ns
t <sub>f</sub>	Fall time of all signals			10	ns

NOTE: Timing measurement reference level is 1.4 V for input and 0.5  $V_{DD}$  for output. Rise and fall times are measured from 10% to 90% of IN/OUT signal swing. Load capacitance of DOUT is 20 pF.

Figure 24. Audio Data Interface Timing (Slave Mode: LRCK, BCK Work as Inputs)

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SYMBOL	PARAMETER	MIN	TYP	MAX	UNIT
t <sub>(BCKP)</sub>	BCK period	150	1/(64 f <sub>S</sub> )	1000	ns
t <sub>(BCKH)</sub>	BCK pulse duration, HIGH	60	0.5 t <sub>(BCKP)</sub>	400	ns
t <sub>(BCKL)</sub>	BCK pulse duration, LOW	60	0.5 t <sub>(BCKP)</sub>	400	ns
t <sub>(CKLR)</sub>	Delay time, BCK falling edge to LRCK valid	-10		20	ns
t <sub>(LRCP)</sub>	LRCK period	10	1/f <sub>S</sub>	60	μs
t <sub>(CKDO)</sub>	Delay time, BCK falling edge to DOUT valid	-10		20	ns
t <sub>(LRDO)</sub>	Delay time, LRCK edge to DOUT valid	-10		20	ns
t <sub>r</sub>	Rise time of all signals			10	ns
t <sub>f</sub>	Fall time of all signals			10	ns

NOTE: Timing measurement reference level is 0.5 V<sub>DD</sub>. Rise and fall times are measured from 10% to 90% of IN/OUT signal swing. Load capacitance of all signals is 20 pF.

Figure 25. Audio Data Interface Timing (Master Mode: LRCK, BCK Work as Outputs)



#### SYNCHRONIZATION WITH DIGITAL AUDIO SYSTEM

In slave mode, the PCM1850A/1851A operates under LRCK, synchronized with system clock SCKI. The PCM1850A/1851A does not need a specific phase relationship between LRCK and SCKI, but does require the synchronization of LRCK and SCKI.

If the relationship between LRCK and SCKI changes more than ±6 BCKs for 64 BCKs/frame (±5 BCKs for 48 BCKs/frame) during one sample period due to LRCK or SCKI jitter, internal operation of the ADC halts within 1/fs and digital output is forced into the BPZ code until resynchronization between LRCK and SCKI is completed.

In the case of changes less than ±5 BCKs for 64 BCKs/frame (±4 BCKs for 48 BCKs/frame), resynchronization with simultaneous discontinuity in the digital output does not occur.

Figure 26 illustrates the digital output response for loss of synchronization and resynchronization. During undefined data, the PCM1850A/1851A might generate some noise in the audio signal. Also, the transition of normal to undefined data and undefined or zero data to normal creates a discontinuity of data in the digital output, which could generate some noise in the audio signal.

It is recommended to set RST (pin 10) to LOW to get stable analog performance when the sampling rate, interface mode, or data format is changed.

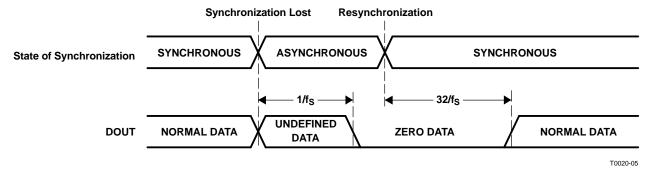


Figure 26. ADC Digital Output for Loss of Synchronization and Resynchronization

**Power-Down Control** 

RST (pin 10) controls the entire ADC operation. During reset mode, the supply current of the analog section is shut off and the digital section is initialized. DOUT (pin 3) is also disabled. Halting SCKI, BCK, and LRCK is recommended to minimize power dissipation.

RST	POWER-DOWN MODE
LOW	Reset and power-down modes
HIGH	Normal operation mode

#### **Overflow Flag Output**

The PCM1850A/1851A has an output flag (pin 4) that indicates when overflow occurs in the L-channel or R-channel, and this flag remains HIGH at least during the 8192/f<sub>s</sub> time for a momentary overflow occurrence.

#### **HPF Bypass Control**

The built-in HPF function for dc component rejection can be bypassed via the serial port. In bypass mode, the dc component of the analog input signal, the internal dc offset, etc., are converted and included in the digital output data.

BYP	HPF (HIGH-PASS FILTER) MODE
0	Normal (no dc component on DOUT) mode (default)
1	Bypass (dc component on DOUT) mode



## **System Reset Control**

The system reset control is used to resynchronize the system via the serial port when the system clock frequency, interface mode, and data format are changed. Change them while SRST = LOW. If they are changed during normal operation, analog performance can be degraded.

SRST SYSTEM RESET						
0	Resynchronization					
1	Normal operation (default)					

## **Mode Register Reset Control**

The MRST bit is used to reset the mode control register to its default settings via the serial port.

MRST	MODE REGISTER RESET
0	Set default value
1	Normal operation (default)

## SPI SERIAL CONTROL PORT FOR MODE CONTROL (PCM1850A)

The user-programmable built-in functions of the PCM1850A can be controlled through a serial control port with the SPI format. All operations for the serial control port use 16-bit data words. Figure 27 shows the control data word format. The most-significant bit must be set to 0. Seven bits, labeled IDX[6:0], set the register index (or address) for write operations. The least-significant eight bits, D[7:0], contain the data to be written to the register specified by IDX[6:0].

Figure 28 shows the functional timing diagram for writing to the serial control port. MS (pin 30) is held at a logic-1 state until a register needs to be written. To start the register write cycle, MS is set to logic-0. Sixteen clocks are then provided on MC (pin 31), corresponding to the 16 bits of the control data word on MD (pin 32). After the sixteenth clock cycle has completed, the data is latched into the indexed mode control register in the write operation. To write the next data word, MS must be set to 1 once.

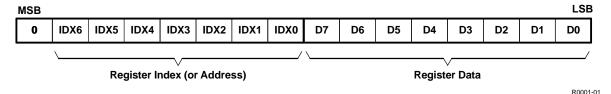
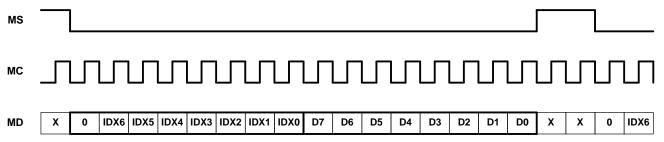


Figure 27. Control Data Word Format for MD



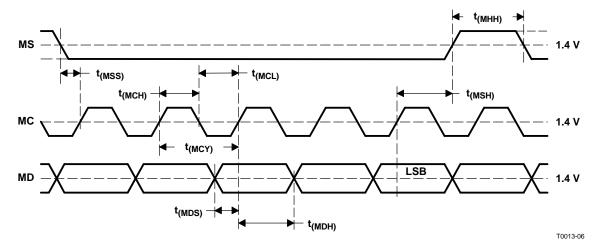
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Figure 28. Serial Control Format



## **CONTROL INTERFACE TIMING REQUIREMENTS (PCM1850A)**

Figure 29 shows a detailed timing diagram for the serial control interface of the PCM1850A. These timing parameters are critical for proper control port operation.



SYMBOL	PARAMETER	MIN	MAX	UNIT
t <sub>(MCY)</sub>	MC pulse cycle time	100		ns
t <sub>(MCL)</sub>	MC LOW-level time	40		ns
t <sub>(MCH)</sub>	MC HIGH-level time	40		ns
t <sub>(MHH)</sub>	MS HIGH-level time	80		ns
t <sub>(MSS)</sub>	MS falling edge to MC rising edge	15		ns
t <sub>(MSH)</sub>	MS hold time <sup>(1)</sup>	15		ns
t <sub>(MDH)</sub>	MD hold time	15		ns
t <sub>(MDS)</sub>	MD setup time	15		ns

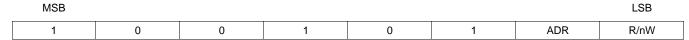
<sup>(1)</sup> MC rising edge for LSB to MS rising edge

Figure 29. PCM1850A Control Interface Timing

## I<sup>2</sup>C SERIAL CONTROL PORT FOR MODE CONTROL (PCM1851A)

The user-programmable built-in function of the PCM1851A can be controlled through the I<sup>2</sup>C-format serial control port, SDA (pin 32) and SCL (pin 31). The PCM1851A supports the I<sup>2</sup>C serial bus and the data transmission protocol for standard mode as a slave device. This protocol is explained in I<sup>2</sup>C specification 2.0.

## **Slave Address**



The PCM1851A has 7 bits for its own slave address. The first six bits (MSBs) of the slave address are factory preset to 100101. The last bit of the address byte is the device select bit, which can be user-defined by the ADR pin (pin 30). A maximum of two PCM1851As can be connected on the same bus at one time. Each PCM1851A responds when it receives its own slave address.

#### **Packet Protocol**

A master device must control packet protocol, which consists of start condition, slave address with read/write bit, data if write or acknowledgement if read, and stop condition. The PCM1851A supports only slave receivers, so the  $R/\overline{W}$  bit must be set to 0.

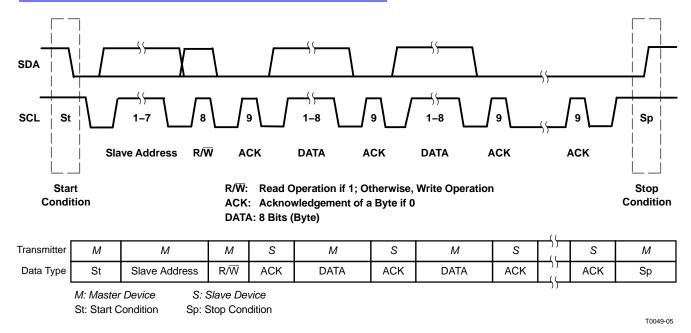


Figure 30. Basic I<sup>2</sup>C Framework

## **Write Operation**

The PCM1851A has only the write mode. A master can write to any PCM1851A registers using single or multiple accesses. The master sends a PCM1851A slave address with a write bit, a register address, and the data. If multiple access is required, the address is that of the starting register, followed by the data to be transferred. When the data are received properly, the index register is incremented by 1 automatically. When the index register reaches 33h, the next value is 31h. When undefined registers are accessed, the PCM1851A does not send an acknowledgement. Figure 31 is a diagram of the write operation. The register address and the write data are 8 bits and MSB-first format.

Data Type St Slave Address W ACK Reg Address ACK Write Data 1 ACK Write Data 2 ACK ACK Sp	Transmitter	М	М	М	S	M S		M S		М	S	~( —)}	S	М
	Data Type	St	Slave Address	W	ACK	Reg Address	ACK	Write Data 1	ACK	Write Data 2	ACK	(_	ACK	Sp

M: Master Device S: Slave Device

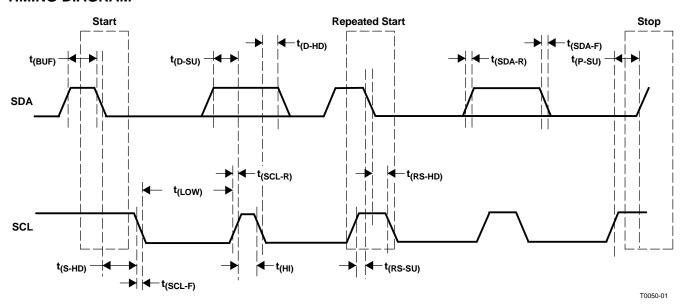
St: Start Condition ACK: Acknowledge  $\overline{W}$ : Write Sp: Stop Condition

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Figure 31. Framework for Write Operation



## **TIMING DIAGRAM**



SYMBOL	PARAMETER	MIN	MAX	UNIT
f <sub>(SCL)</sub>	SCL clock frequency		100	kHz
t <sub>(BUF)</sub>	Bus free time between STOP and START conditions	4.7		μs
$t_{(LOW)}$	Low period of the SCL clock	4.7		μs
t <sub>(HI)</sub>	High period of the SCL clock	4		μs
t <sub>(RS-SU)</sub>	Setup time for START/repeated START condition	4.7		μs
t <sub>(S-HD)</sub> , t <sub>(RS-HD)</sub>	Hold time for START/repeated START condition	4		μs
t <sub>(D-SU)</sub>	Data setup time	250		ns
t <sub>(D-HD)</sub>	Data hold time	0	900	ns
t <sub>(SCL-R)</sub>	Rise time of SCL signal	20 + 0.1 C <sub>B</sub>	1000	ns
t <sub>(SCL-F)</sub>	Fall time of SCL signal	20 + 0.1 C <sub>B</sub>	1000	ns
t <sub>(SDA-R)</sub>	Rise time of SDA signal	20 + 0.1 C <sub>B</sub>	1000	ns
t <sub>(SDA-F)</sub>	Fall time of SDA signal	20 + 0.1 C <sub>B</sub>	1000	ns
t <sub>(P-SU)</sub>	Setup time for STOP condition	4		μs
C <sub>B</sub>	Capacitive load for SDA and SCL lines		400	pF
V <sub>NH</sub>	Noise margin at HIGH level for each connected device (including hysteresis)	0.2 V <sub>DD</sub>		V

Figure 32. PCM1851A Control Interface Timing Requirements

## **MODE CONTROL REGISTERS**

#### **User-Programmable Mode Control Functions**

The PCM1850A/1851A has several user-programmable functions which are accessed via control registers. The registers are programmed using the serial control port which is discussed in the SPI Serial Control Port for Mode Control (PCM1850A) and I<sup>2</sup>C Serial Control Port for Mode Control (PCM1851A) sections of this data sheet. Table 6 lists the available mode control functions, along with their reset default conditions and associated register index.

#### **Register Map**

The mode control register map is shown in Table 7. Each register includes an index (or address) indicated by the IDX[6:0] bits B[14:8].

**Table 6. User-Programmable Mode Control Functions** 

FUNCTION	RESET DEFAULT	REGISTER	BIT(S)
Mode register reset	Normal operation	31	MRST
PGA gain control	–11 dB	31	PG[5:0]
Multiplexer input channel control	Channel 1	32	CH[2:0]
HPF bypass control	HPF enable	33	BYP
System reset	Normal operation	33	SRST
Audio interface mode control	Slave	33	MD[1:0]
Audio interface format control	I <sup>2</sup> S	33	FMT[2:0]

#### **Table 7. Mode Control Register Map**

HEX	B15	B14	B13	B12	B11	B10	В9	В8	В7	В6	B5	B4	В3	B2	B1	В0
Register 31	0	0	1	1	0	0	0	1	RSV <sup>(1)</sup>	MRST	PG5	PG4	PG3	PG2	PG1	PG0
Register 32	0	0	1	1	0	0	1	0	RSV <sup>(1)</sup>	CH2	CH1	CH0				
Register 33	0	0	1	1	0	0	1	1	BYP	SRST	RSV <sup>(1)</sup>	MD1	MD0	FMT2	FMT1	FMT0

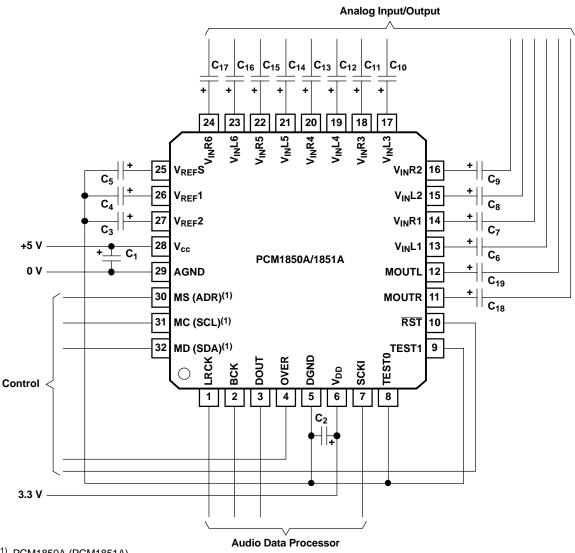
<sup>(1)</sup> RSV bits must be always written as 0. No values can be written in address 30h.



#### APPLICATION INFORMATION

#### TYPICAL CIRCUIT CONNECTION DIAGRAM

The following figure illustrates a typical circuit connection diagram for six stereo inputs and an analog monitor.



(1) PCM1850A (PCM1851A)

S0181-01

NOTE: C<sub>1</sub>, C<sub>2</sub>: 0.1-μF ceramic and 10-μF electrolytic capacitors are recommended, depending on layout and power supply.  $C_3$ ,  $C_4$ ,  $C_5$ : 0.1- $\mu$ F ceramic and 10- $\mu$ F electrolytic capacitors are recommended.  $C_6 - C_{17}$ : A 0.33- $\mu$ F capacitor gives a 2.9-Hz ( $\tau = 0.33 \,\mu$ F × 169 k $\Omega$ ) typical cutoff frequency at the HPF input in normal operation, and it requires power-on settling time with a 56-ms time constant in the power-on initialization period. Cutoff frequency and time constant depend on PGA gain. Cutoff frequency varies from 2.4 Hz to 8.5 Hz for 0.33 µF. DC-coupled input is inhibited for the analog input, V<sub>IN</sub>L[1:6] and V<sub>IN</sub>R[1:6]. C<sub>18</sub>-C<sub>19</sub>: A 2.2-μF capacitor with a 10-kΩ load gives a 7.2-Hz cutoff frequency.

## **APPLICATION INFORMATION (continued)**

#### **BOARD DESIGN AND LAYOUT CONSIDERATIONS**

## V<sub>CC</sub>, V<sub>DD</sub> Pins

The digital and analog power supply lines to the PCM1850A/1851A must be bypassed to the corresponding ground pins with 0.1- $\mu$ F ceramic and 10- $\mu$ F electrolytic capacitors as close to the pins as possible to maximize the dynamic performance of the ADC.

## **AGND, DGND Pins**

To maximize the dynamic performance of the PCM1850A/1851A, the analog and digital grounds are not connected internally. These grounds must have low impedance to avoid digital noise feeding back into the analog ground. Therefore, they should be connected directly to each other under the parts to reduce the potential of a noise problem.

## V<sub>IN</sub>L[1:6], V<sub>IN</sub>R[1:6] Pins

A 0.33- $\mu$ F capacitor is recommended as the ac-coupling capacitor, which gives a 2.4- to 8.5-Hz cutoff frequency. If higher full-scale input voltage is required, it can be adjusted by adding only one series resistor to each  $V_{IN}xx$  pin, but a signal source resistance less than 1 k $\Omega$  is recommended for these pins in order to keep accuracy of the gain control command and to maintain crosstalk performance.

#### **MOUTL, MOUTR Pins**

An ac-coupled light load is recommended; a 2.2- $\mu$ F capacitor with a 10- $k\Omega$  load gives a 7.2-Hz cutoff frequency.

#### V<sub>RFF</sub>1, V<sub>RFF</sub>2, V<sub>RFF</sub>S Pins

Between  $V_{REF}1$  and AGND,  $V_{REF}2$  and AGND, and  $V_{REF}S$  and AGND, 0.1- $\mu$ F ceramic and 10- $\mu$ F electrolytic capacitors are recommended to ensure low source impedance of the ADC references. These capacitors should be located as close as possible to the  $V_{REF}1$ ,  $V_{REF}2$ , and  $V_{REF}S$  pins to reduce dynamic errors on the ADC references. The differential voltage between  $V_{RFF}2$  and AGND sets the analog input full-scale range.

## BCK and LRCK Pins (in Master Mode), DOUT Pin

These pins have enough load-driving capability. However, if the output line is long, locating a buffer near the PCM1850A/1851A and minimizing load capacitance is recommended in order to minimize the digital-analog crosstalk and maximize the dynamic performance of the ADC.

## **System Clock**

Because the PCM1850A/1851A operates based on a system clock, the quality of the system clock can influence dynamic performance. Therefore, it is recommended to consider the system clock duty, jitter, and the time difference between the system clock transition and the BCK or LRCK transition in slave mode.





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#### **PACKAGING INFORMATION**

Orderable Device	Status <sup>(1)</sup>	Package Type	Package Drawing	Pins	Package Qty	e Eco Plan <sup>(2)</sup>	Lead/Ball Finish	MSL Peak Temp <sup>(3)</sup>
PCM1850APJT	ACTIVE	TQFP	PJT	32	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCM1850APJTG4	ACTIVE	TQFP	PJT	32	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCM1850APJTR	ACTIVE	TQFP	PJT	32	1000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCM1850APJTRG4	ACTIVE	TQFP	PJT	32	1000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCM1851APJT	ACTIVE	TQFP	PJT	32	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCM1851APJTG4	ACTIVE	TQFP	PJT	32	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCM1851APJTR	ACTIVE	TQFP	PJT	32	1000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCM1851APJTRG4	ACTIVE	TQFP	PJT	32	1000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM

<sup>&</sup>lt;sup>(1)</sup> The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined.

**Pb-Free** (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

**Pb-Free (RoHS Exempt):** This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

**Green (RoHS & no Sb/Br):** TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

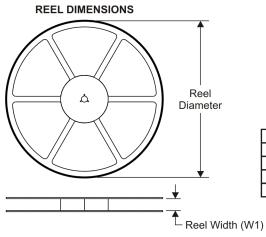
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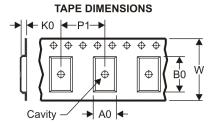
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## TAPE AND REEL INFORMATION





Α	0	Dimension designed to accommodate the component width
В	0	Dimension designed to accommodate the component length
		Dimension designed to accommodate the component thickness
٧	٧	Overall width of the carrier tape
ГР	1	Pitch between successive cavity centers

## QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE

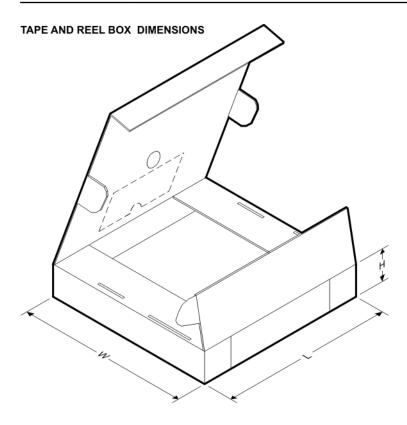


#### \*All dimensions are nominal

Device		Package Drawing			Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
PCM1851APJTR	TQFP	PJT	32	1000	330.0	16.8	9.6	9.6	1.5	12.0	16.0	Q2

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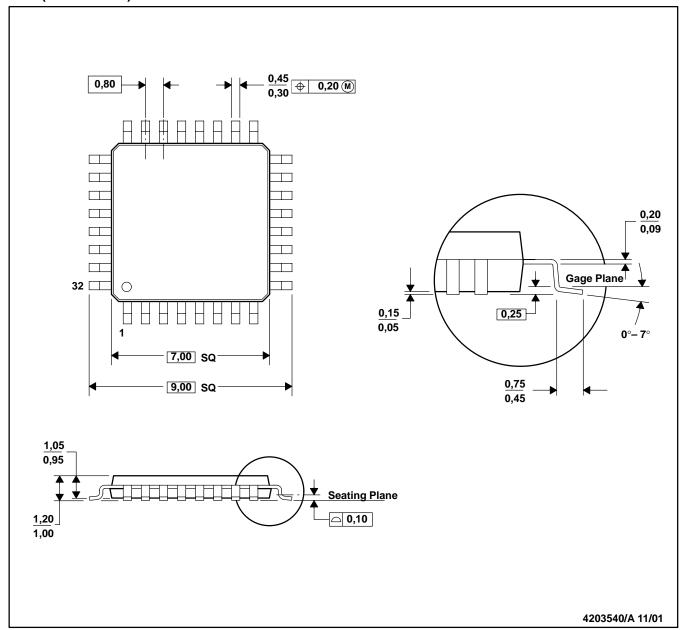


#### \*All dimensions are nominal

ĺ	Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
	PCM1851APJTR	TQFP	PJT	32	1000	346.0	346.0	33.0

## PJT (S-PQFP-N32)

## PLASTIC QUAD FLATPACK



NOTES: A. All linear dimensions are in millimeters.

B. This drawing is subject to change without notice.

C. Falls within JEDEC MS-026

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