

[查询"LM135AZ"供应商](#)

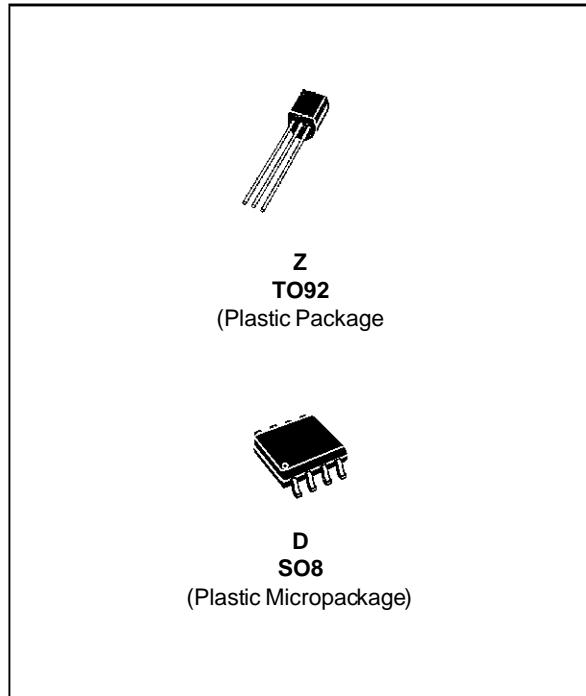


**SGS-THOMSON**  
MICROELECTRONICS

**LM135**  
**LM235-LM335,A**

## PRECISION TEMPERATURE SENSORS

- DIRECTLY CALIBRATED IN  $^{\circ}\text{K}$
- $1^{\circ}\text{C}$  INITIAL ACCURACY
- OPERATES FROM  $450\mu\text{A}$  TO  $5\text{mA}$
- LESS THAN  $1\Omega$  DYNAMIC IMPEDANCE



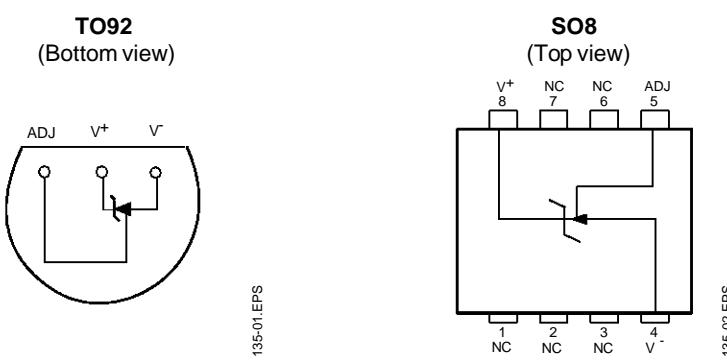
### DESCRIPTION

The LM135, LM235, LM335 are precision temperature sensors which can be easily calibrated. They operate as a 2-terminal Zener and the breakdown voltage is directly proportional to the absolute temperature at  $10\text{mV}/^{\circ}\text{K}$ . The circuit has a dynamic impedance of less than  $1\Omega$  and operates within a range of current from  $450\mu\text{A}$  to  $5\text{mA}$  without alteration of its characteristics. Calibrated at  $+25^{\circ}\text{C}$ , the LM135, LM235, LM335 have a typical error of less than  $1^{\circ}\text{C}$  over a  $100^{\circ}\text{C}$  temperature range. Unlike other sensors, the LM135, LM235, LM335 have a linear output.

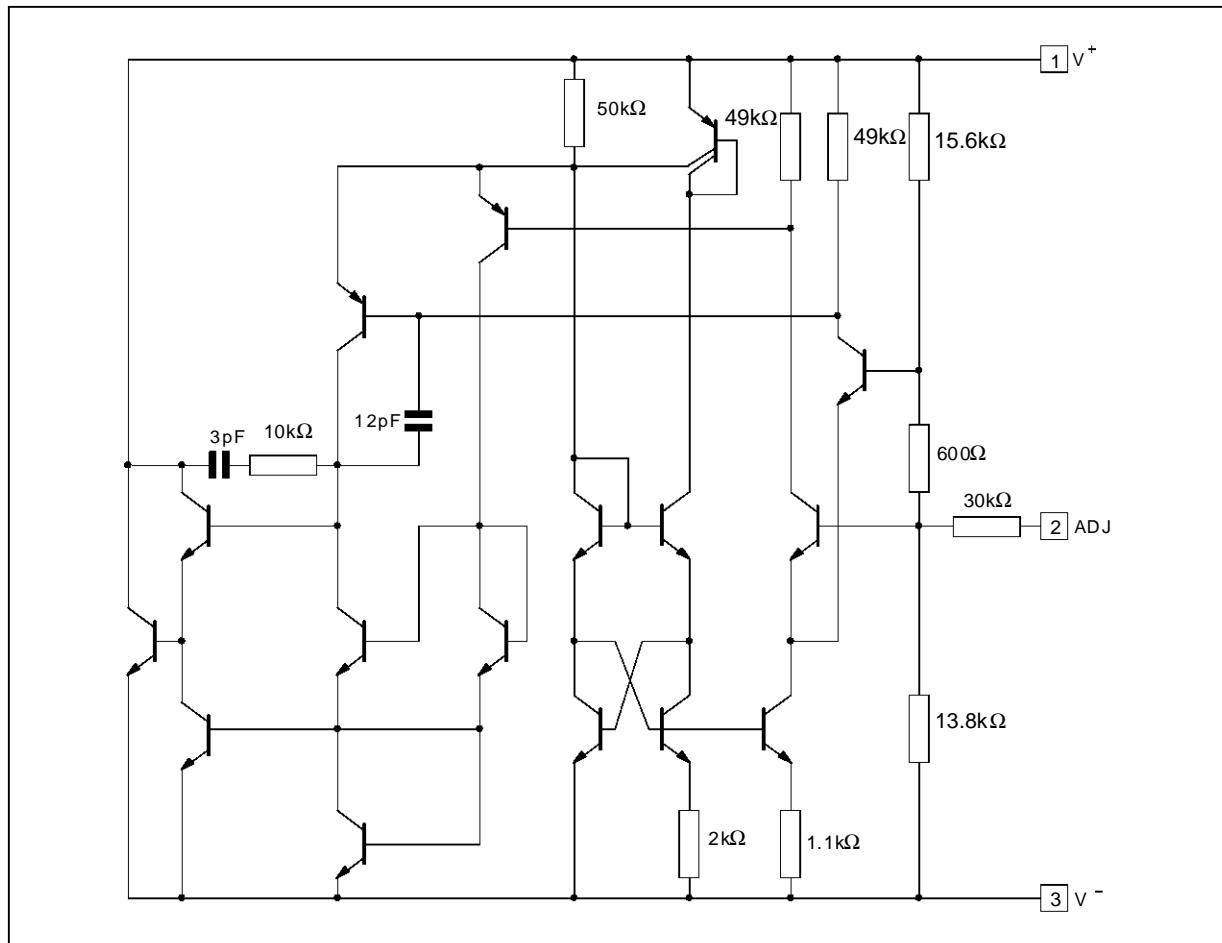
### ORDER CODES

Part num- ber	Temperature Range	Package	
		Z	D
LM135	$-55^{\circ}\text{C}, +150^{\circ}\text{C}$	•	•
LM235	$-40^{\circ}\text{C}, +125^{\circ}\text{C}$	•	•
LM335,A	$-40^{\circ}\text{C}, +100^{\circ}\text{C}$	•	•

### PIN CONNECTIONS



**SCHEMATIC DIAGRAM**



**ABSOLUTE MAXIMUM RATINGS**

Symbol	Parameter	LM135	LM235	LM335,A	Unit
$I_R$ $I_F$	Current Reverse Forward	15 10	15 10	15 10	mA
$T_{oper}$	Operating Free-air Temperature Range - (note 1) Continuous Intermittent	-55 to +150 +150 to +200	-40 to +125 +125 to +150	-40 to +100 +100 to +125	°C
$T_{stg}$	Storage Temperature Range	-65 to +150	-65 to +150	-65 to +150	°C

Note : 1.  $T_j \leq 150^\circ\text{C}$

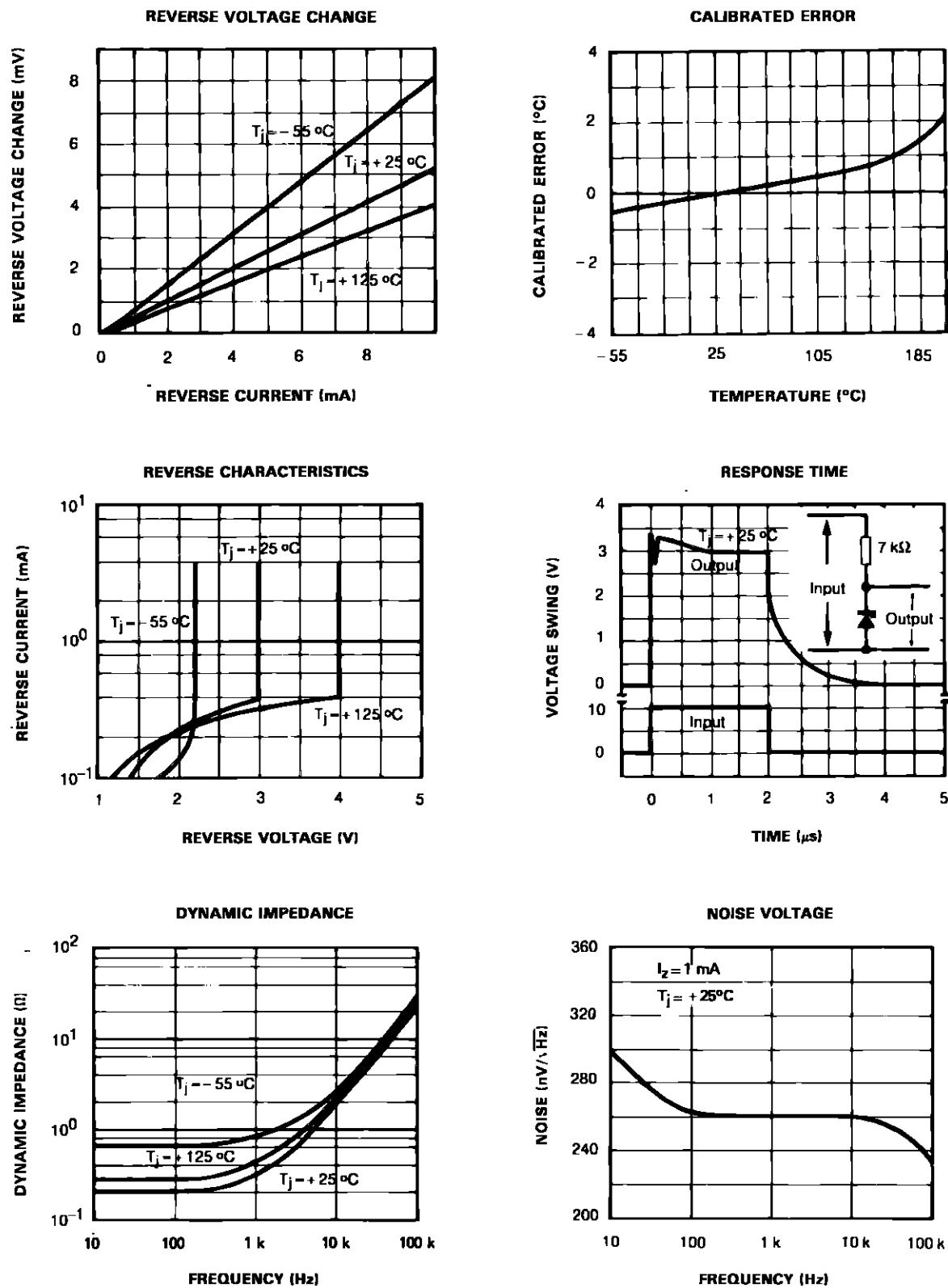
## TEMPERATURE ACCURACY

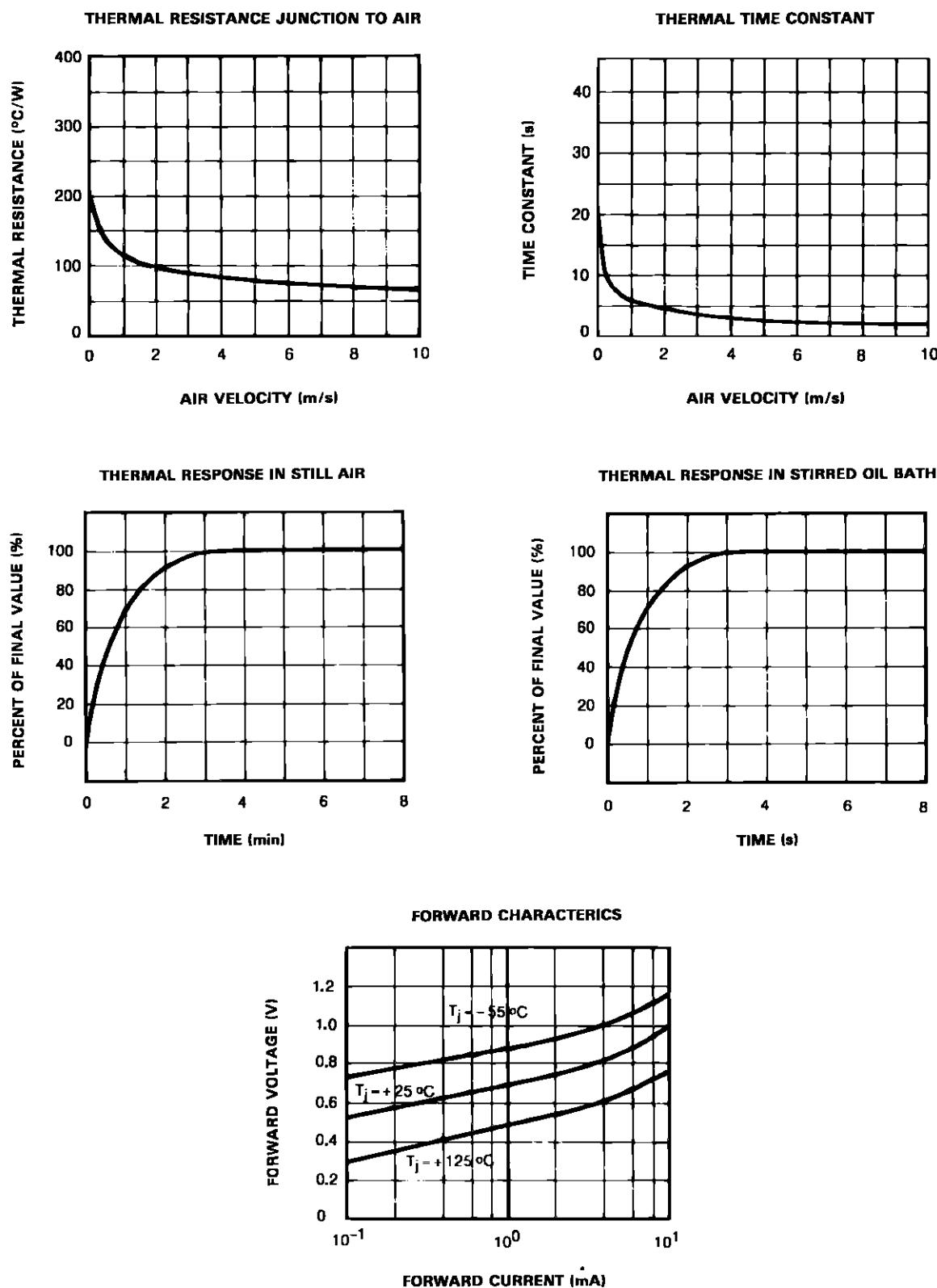
Parameter	LM135 - LM235 LM335A			LM335			Unit
	Min.	Typ.	Max.	Min.	Typ.	Max.	
Operating Output Voltage $T_{case} = +25^\circ\text{C}$ , $I_R = 1\text{mA}$	2.95	2.98	3.01	2.92	2.98	3.04	V
Uncalibrated Temperature Error ( $I_R = 1\text{mA}$ ) $T_{case} = +25^\circ\text{C}$ $T_{min.} \leq T_{case} \leq T_{max.}$		1 2	3 5		2 4	6 9	°C
Temperature Error with $25^\circ\text{C}$ Calibration $T_{min.} \leq T_{case} \leq T_{max.}$ , $I_R = 1\text{mA}$ LM135 - LM235 LM335 LM335A		0.5 0.5	1.5 1		1	2	°C
Calibrated Error at Extended Temperature $T_{case} = T_{max.}$ (intermittent)		2			2		°C
Non-linearity ( $I_R = 1\text{mA}$ ) LM135 - LM235 LM335 LM335A		0.3 0.3	1 1.5		0.3	1.5	°C

## ELECTRICAL CHARACTERISTICS - (note 1)

Parameter	LM135 - LM235			LM335,A			Unit
	Min.	Typ.	Max.	Min.	Typ.	Max.	
Operating output voltage change with current $450\mu\text{A} \leq I_R \leq 5\text{mA}$ at constant temperature		2.5	10		3	14	mV
Dynamic Impedance ( $I_R = 1\text{mA}$ )		0.5			0.6		Ω
Output Voltage Temperature Drift		+10			+10		mV/°C
Time Constant	Still Air Air 0.5m/s Stirred Oil	80 10 1			80 10 1		s
Time Stability ( $T_{case} = +125^\circ\text{C}$ )		0.2			0.2		°C/kh

Note : 1. Accuracy measurements are made in a well-stirred oil bath. For other conditions, self heating must be considered.





## APPLICATION HINTS

There is an easy method of calibrating the device for higher accuracies (see typical applications).

The single point calibration works because the output of the LM135, LM235, LM335 is proportional to the absolute temperature with the extrapolated output of sensor going to 0V at 0°K (-273.15°C). Errors in output voltage versus temperature are only slope. Thus a calibration of the slope at one temperature corrects errors at all temperatures.

The output of the circuit (calibrated or not) can be given by the equation :  $V_{OT} = V_{OT_0} \times \frac{T}{T_0}$

where T is the unknown temperature and  $T_0$  is the reference temperature (in °K).

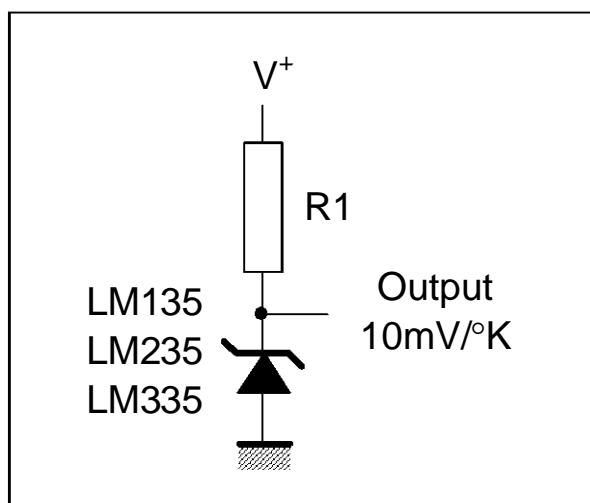
Nominally the output is calibrated at 10mV/°K.

Precautions should be taken to ensure good sensing accuracy. As in the case of all temperatures sensors, self heating can decrease accuracy. The LM135, LM235, LM335 should operate with a low current, but sufficient to drive the sensor and its calibration circuit to their maximum operating temperature.

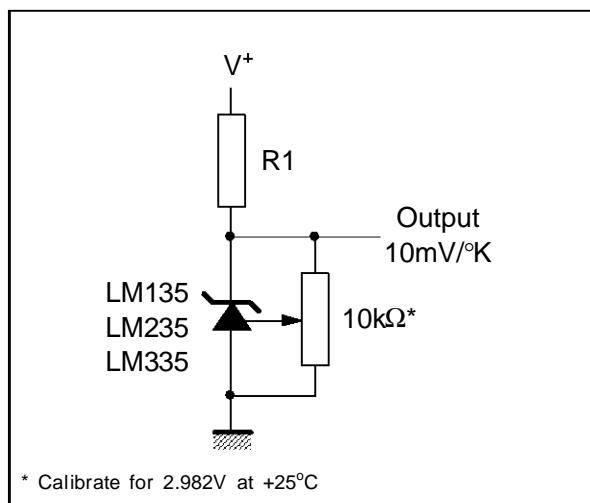
If the sensor is used in surroundings where the thermal resistance is constant, the errors due to self heating can be externally calibrated. This is possible if the circuit is biased with a temperature stable current. Heating will then be proportional to zener voltage and therefore temperature. In this way the error due to self heating is proportional to the absolute temperature as scale factor errors.

## TYPICAL APPLICATIONS

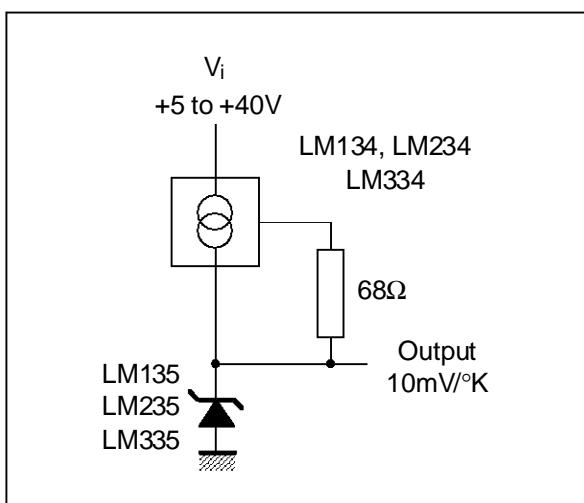
### BASIC TEMPERATURE SENSOR



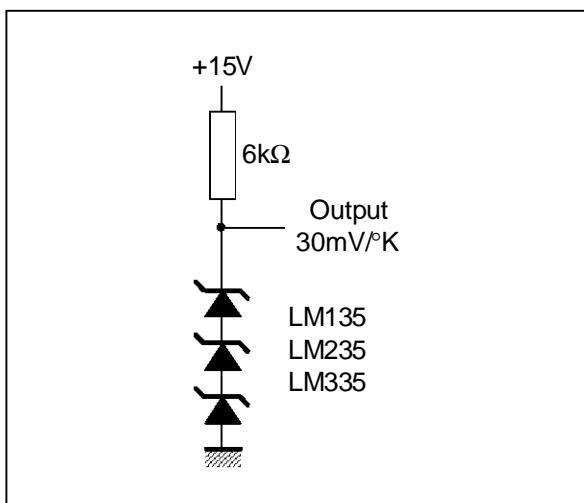
CALIBRATED SENSOR



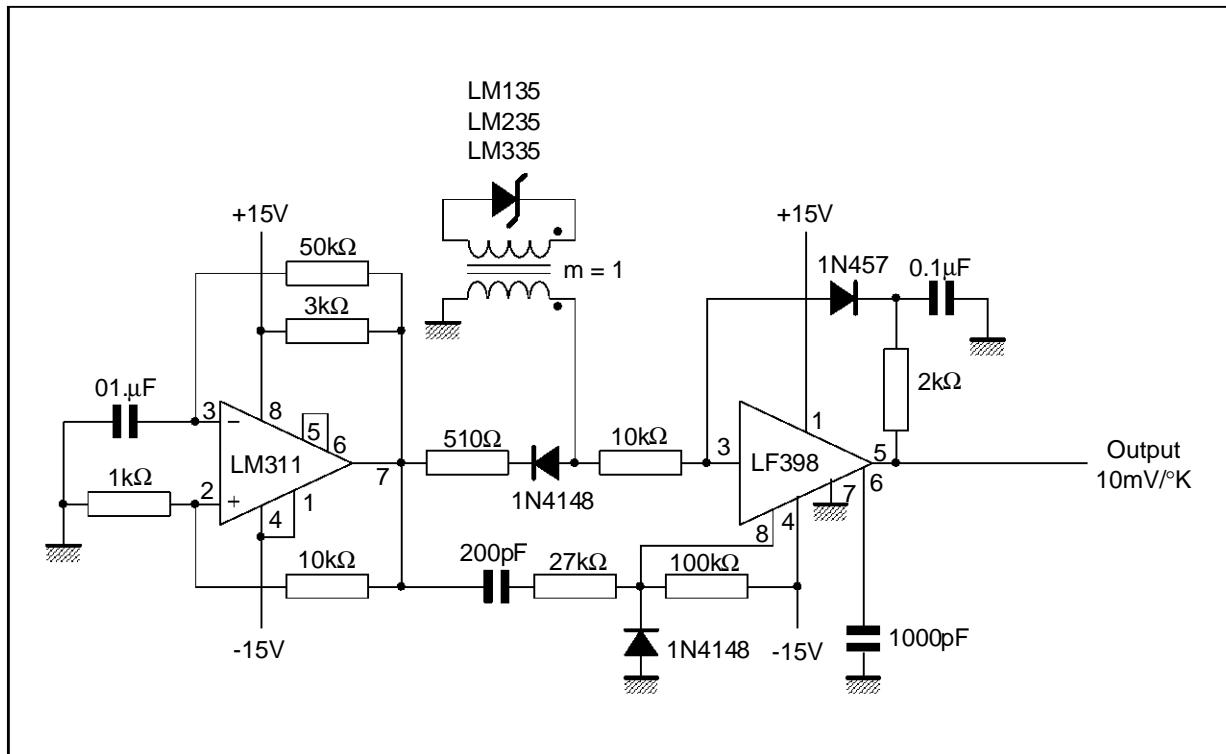
### WIDE OPERATING SUPPLY



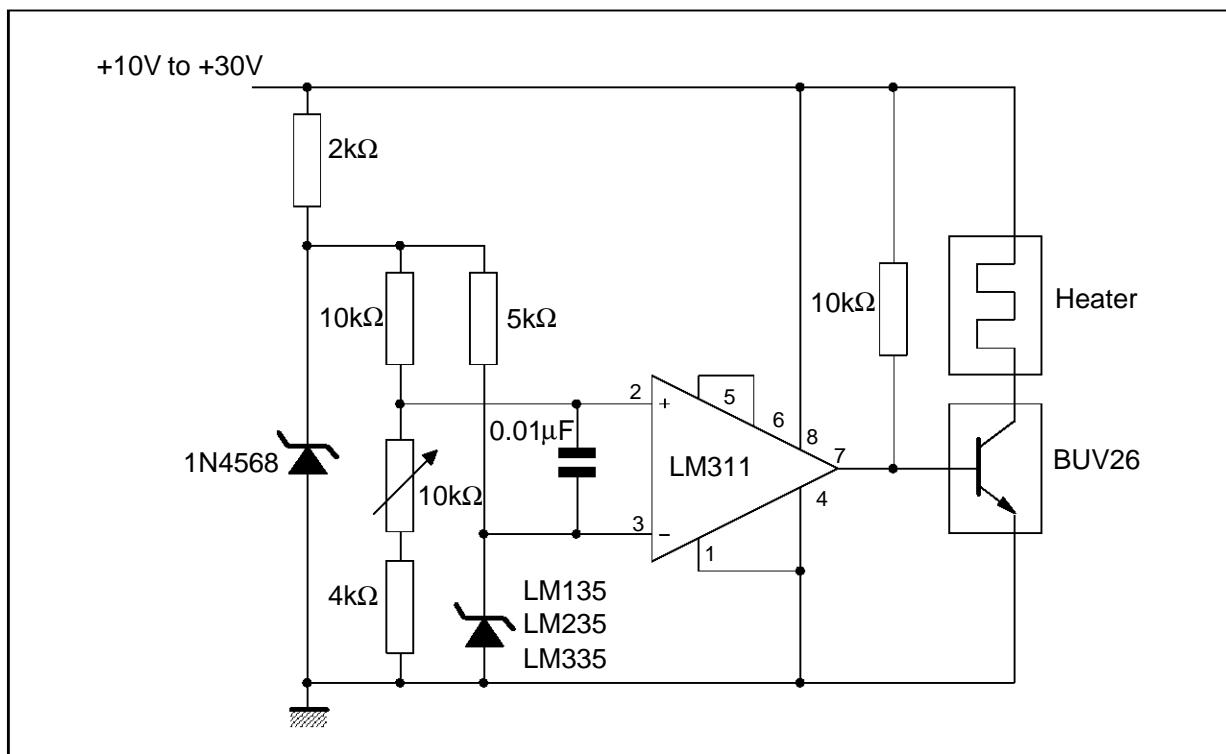
AVERAGE TEMPERATURE SENSING



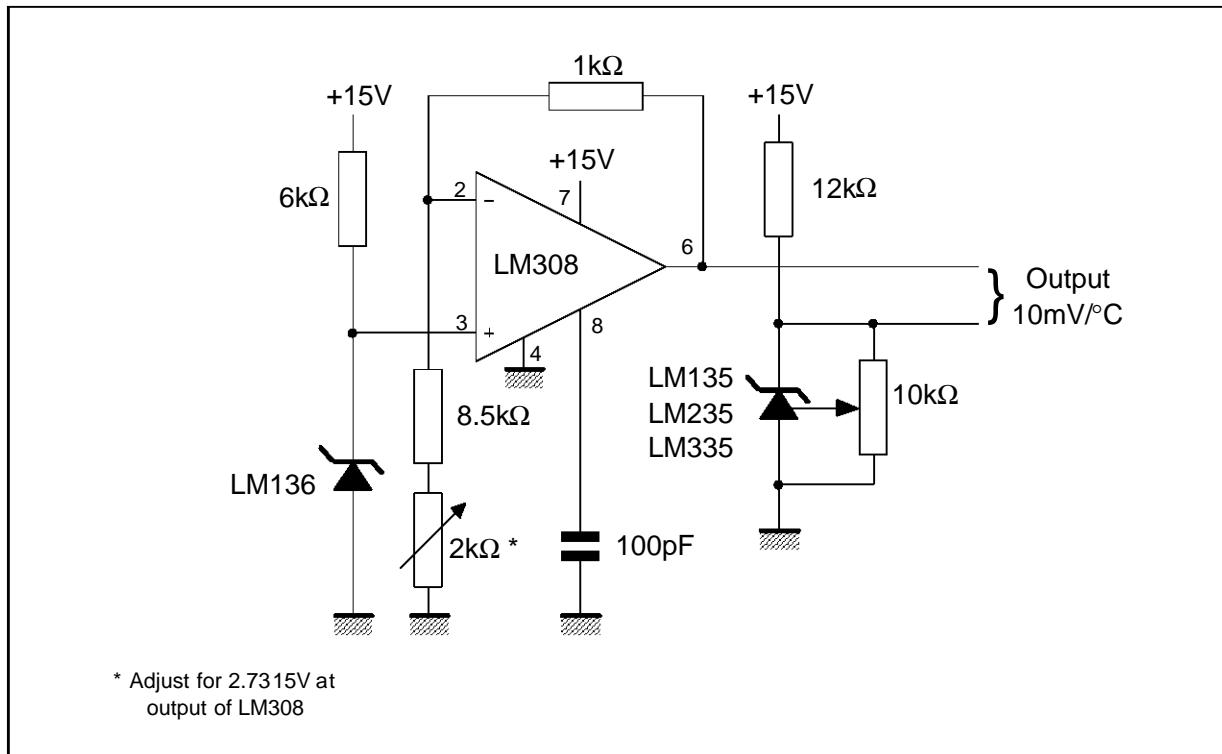
## ISOLATED TEMPERATURE SENSOR



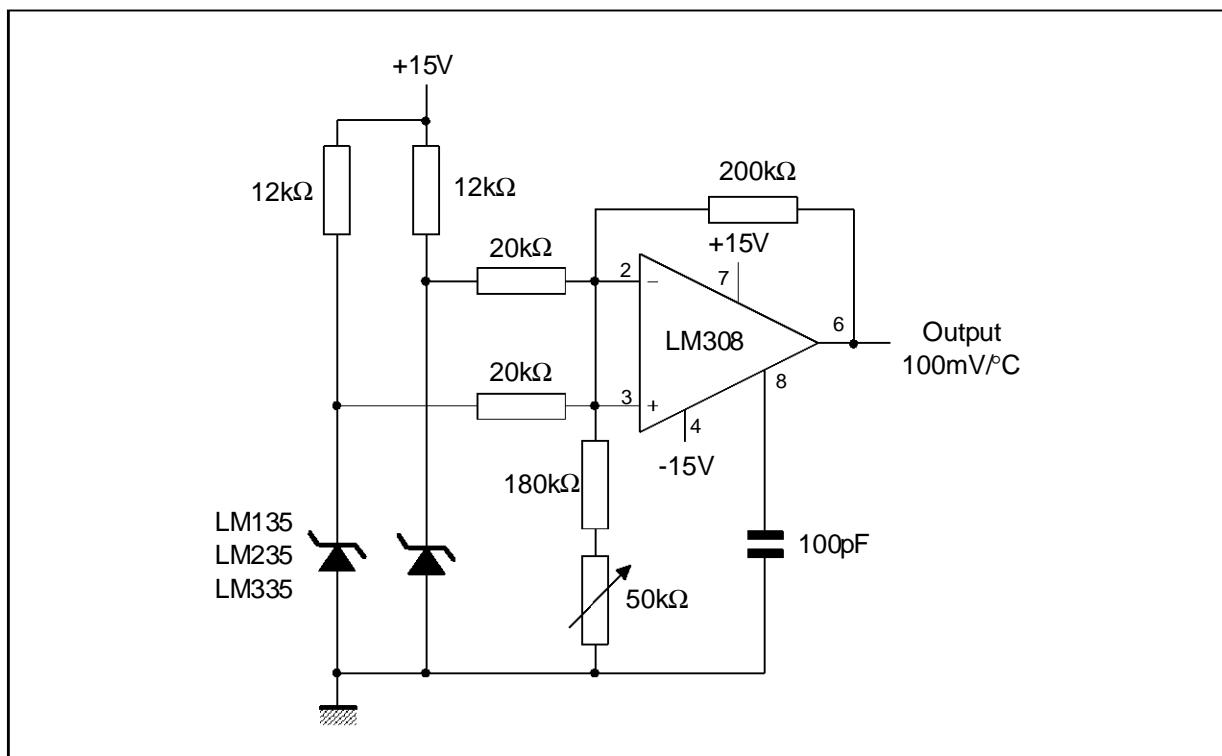
## SIMPLE TEMPERATURE CONTROLLER



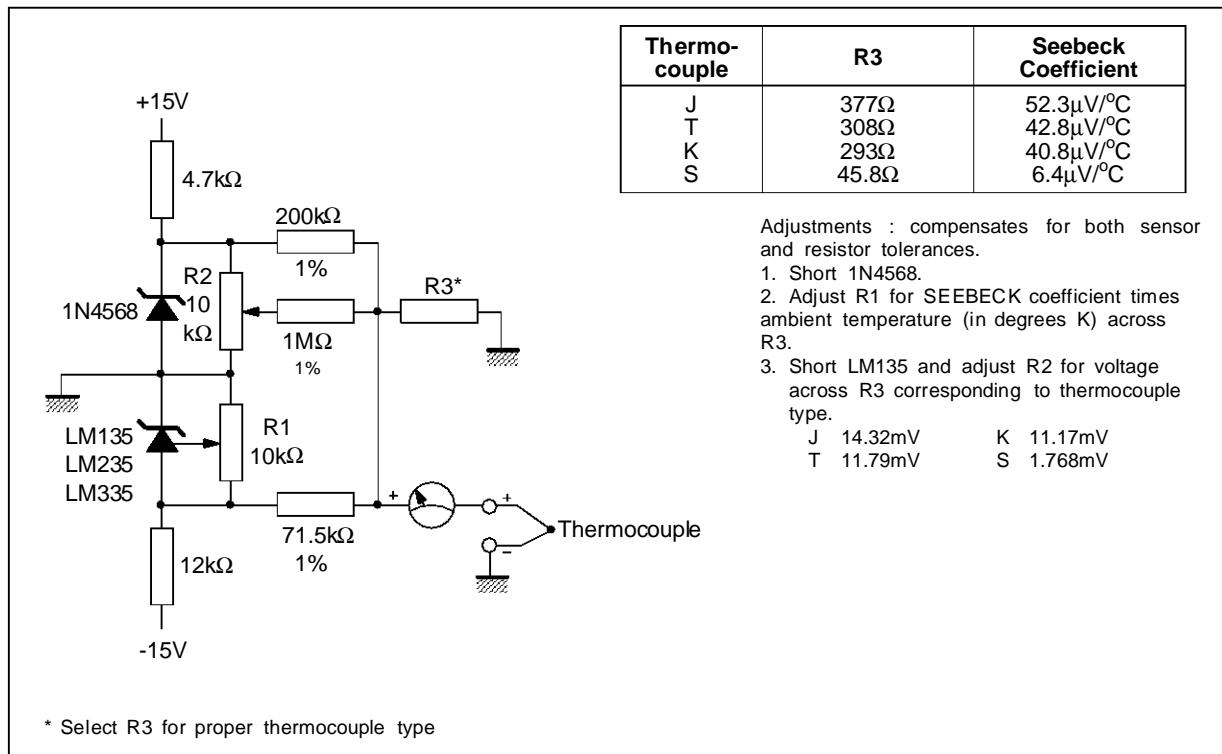
CENTIGRADE THERMOMETER



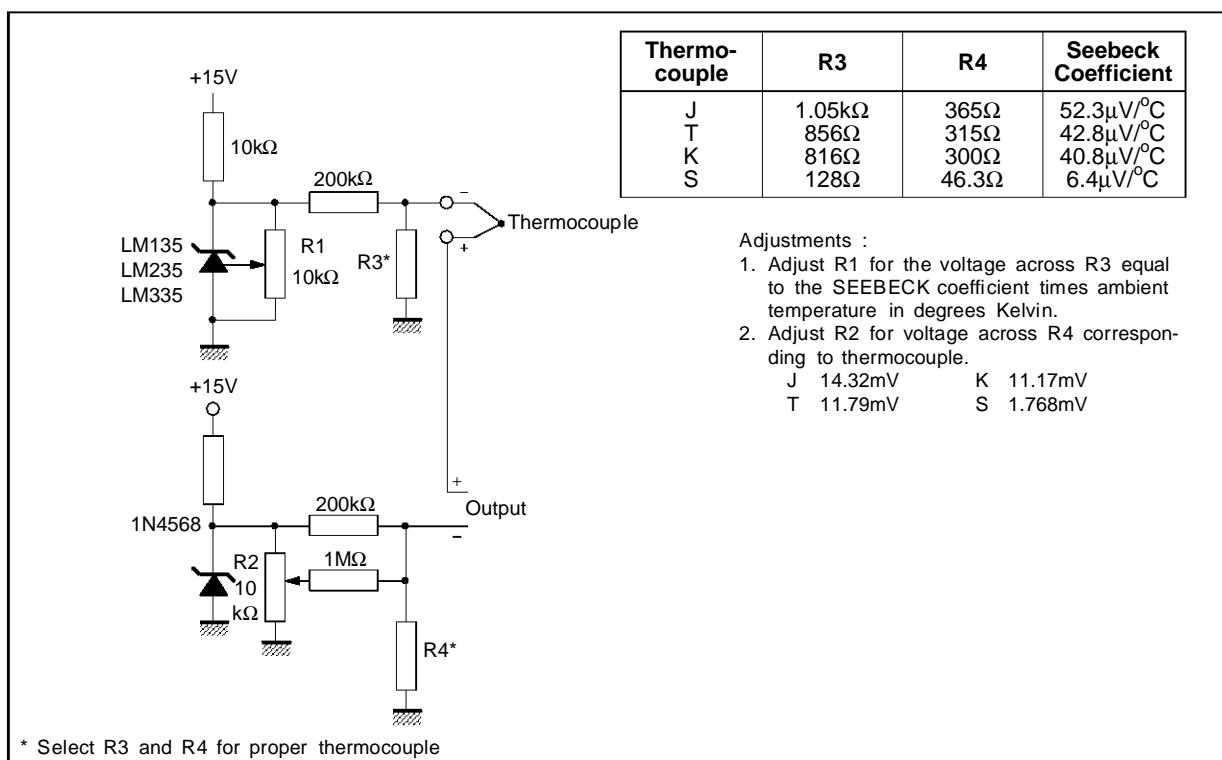
DIFFERENTIAL TEMPERATURE SENSOR



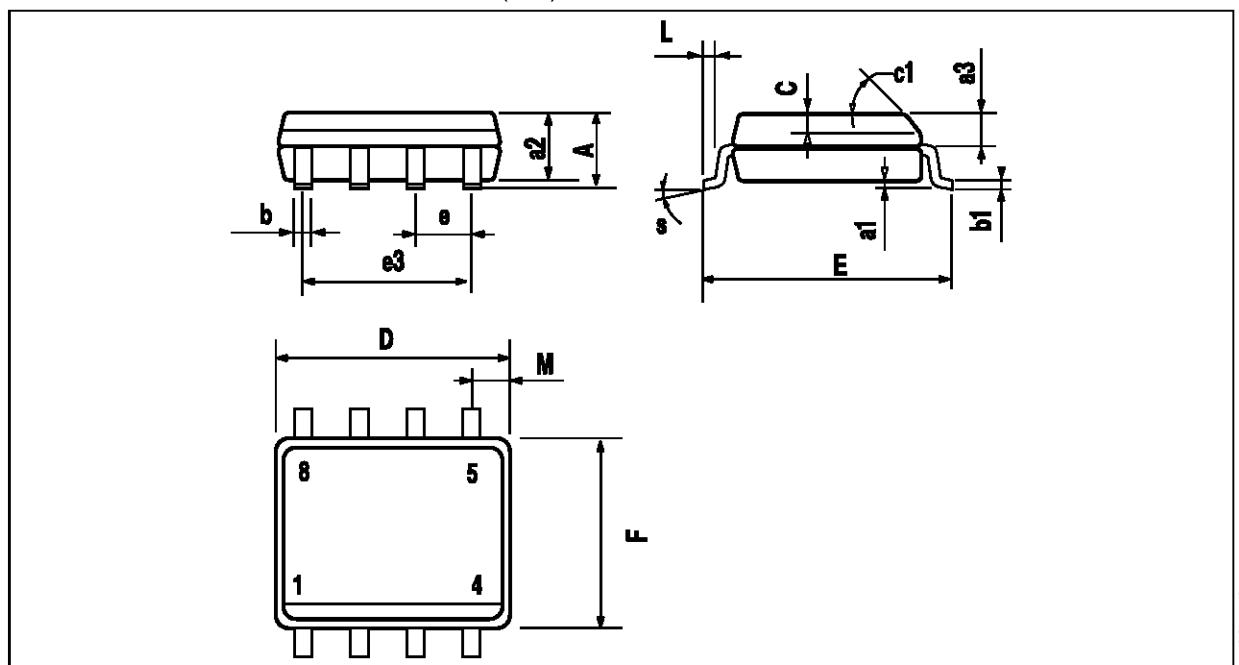
THERMOCOUPLE COLD JUNCTION COMPENSATION  
(compensation for grounded thermocouple)



## SINGLE POWER SUPPLY COLD JUNCTION COMPENSATION



**PACKAGE MECHANICAL DATA**  
8 PINS - PLASTIC MICROPACKAGE (SO)



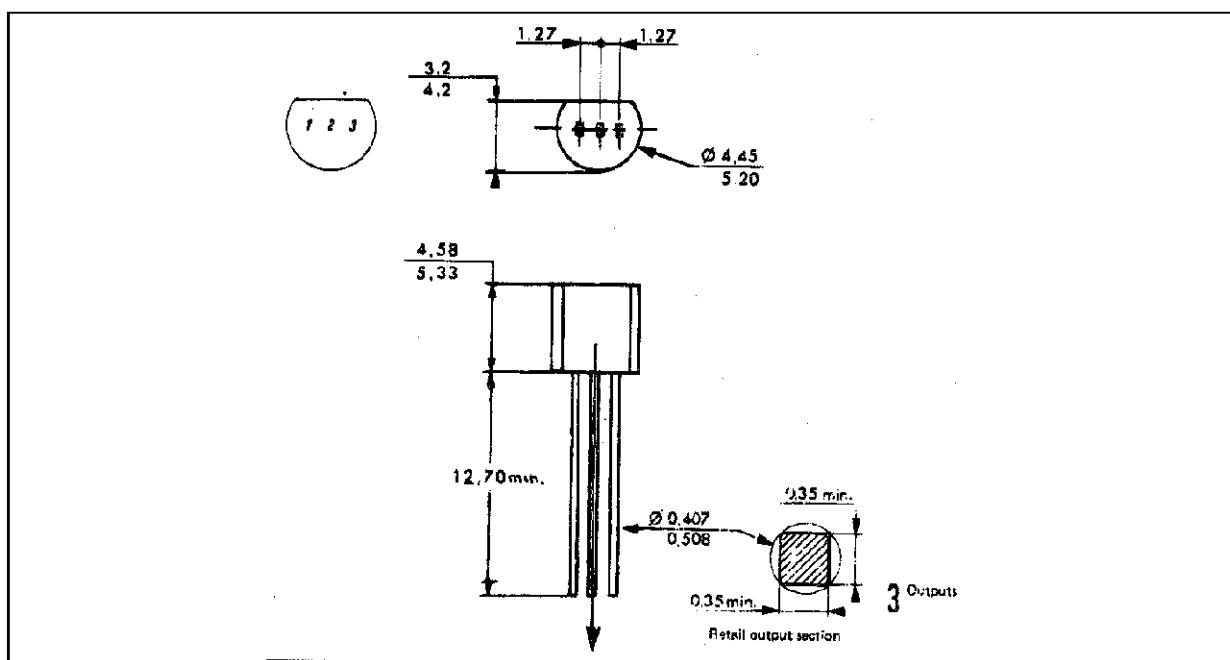
PI-SO8-EPS

Dimensions	Millimeters			Inches		
	Min.	Typ.	Max.	Min.	Typ.	Max.
A			1.75			0.069
a1	0.1		0.25	0.004		0.010
a2			1.65			0.065
a3	0.65		0.85	0.026		0.033
b	0.35		0.48	0.014		0.019
b1	0.19		0.25	0.007		0.010
C	0.25		0.5	0.010		0.020
c1	45° (typ.)					
D	4.8		5.0	0.189		0.197
E	5.8		6.2	0.228		0.244
e		1.27			0.050	
e3		3.81			0.150	
F	3.8		4.0	0.150		0.157
L	0.4		1.27	0.016		0.050
M			0.6			0.024
S	8° (max.)					

SO8-TBL

## PACKAGE MECHANICAL DATA

3 PINS - PLASTIC PACKAGE TO92

PM-T092.IMG  
TO92TBL

Dimensions	Millimeters			Inches		
	Min.	Typ.	Max.	Min.	Typ.	Max.
L		1.27			0.05	
B	3.2	3.7	4.2	0.126	0.1457	0.1654
O1	4.45	5.00	5.2	0.1752	0.1969	0.2047
C	4.58	5.03	5.33	0.1803	0.198	0.2098
K	12.7			0.5		
O2	0.407	0.5	0.508	0.016	0.0197	0.02
a	0.35			0.0138		

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