

### 16-BIT 250-KSPS SAMPLING CMOS ANALOG-TO-DIGITAL CONVERTER

#### **FEATURES**

- 105dB SFDR at 250-kHz Sample Rate
- Standard ±10-V Input Range
- ±1.5 LSB Max INL
- ±1 LSB Max DNL, 16-Bits No Missing Codes
- ±2 mV Max Bipolar Zero Error With ±0.4 PPM/°C Drift
- ±0.1% FSR Max Full-Scale Error With ±2 PPM/°C Drift
- Single 5-V Supply Operation
- Pin-Compatible With ADS7805 (Low Speed) and 12-Bit ADS8504/7804
- Uses Internal or External Reference
- Full Parallel Data Output
- 70-mW Typ Power Dissipation at 250 KSPS
- 28-Pin SSOP and SOIC Packages

#### **APPLICATIONS**

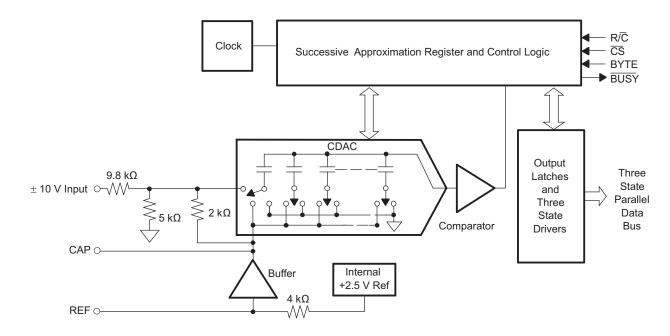
- Industrial Process Control
- Data Acquisition Systems
- Digital Signal Processing
- Medical Equipment
- Instrumentation

#### DESCRIPTION

The ADS8505 is a complete 16-bit sampling A/D converter using state-of-the-art CMOS structures. It contains a complete 16-bit, capacitor-based, SAR A/D with S/H, reference, clock, interface for microprocessor use, and 3-state output drivers.

The ADS8505 is specified at a 250-kHz sampling rate over the full temperature range. Precision resistors provide an industry standard  $\pm 10$ -V input range, while the innovative design allows operation from a single +5-V supply, with power dissipation under 100 mW.

The ADS8505 is available in 28-pin SOIC and 28-pin SSOP packages, both fully specified for operation over the industrial –40°C to 85°C temperature range.





Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.





These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

#### PACKAGE/ORDERING INFORMATION(1)

PRODUCT	MINIMUM RELATIVE ACCURACY (LSB)	NO MISSING CODE	MINIMUM SINAD (dB)	SPECIFICATION TEMPERATURE RANGE	PACKAGE LEAD	PACKAGE DESIGNATOR	ORDERING NUMBER	TRANSPORT MEDIA, QTY
					SO-28	DW	ADS8505IBDW	Tube, 20
ADCOFOEID	14.5	16	86	–40°C to 85°C	30-26	DVV	ADS8505IBDWR	Tape and Reel, 1000
ADS8505IB	±1.5	10			SSOP-28	DB	ADS8505IBDB	Tube, 50
							ADS8505IBDBR	Tape and Reel, 2000
					SO-28	DW	ADS8505IDW	Tube, 20
ADS8505I	+4	15	83	40°C to 85°C	50-28	DVV	ADS8505IDWR	Tape and Reel, 1000
ADS6505I	±4	15	83	-40°C to 85°C	SSOP-28	DB	ADS8505IDB	Tube, 50
					33UP-28	DB	ADS8505IDBR	Tape and Reel, 2000

<sup>(1)</sup> For the most current package and ordering information, see the Package Option Addendum at the end of this document, or see the TI website at www.ti.com.

### **ABSOLUTE MAXIMUM RATINGS**(1)

over operating free-air temperature range (unless otherwise noted)(2)

		UNIT			
	V <sub>IN</sub>	±25V			
Analog inputs	REF	+V <sub>ANA</sub> + 0.3 V to AGND2 – 0.3 V			
	CAP	Indefinite short to AGND2, momentary short to V <sub>ANA</sub>			
	DGND, AGND1, AGND2	±0.3 V			
Ground voltage differences	V <sub>ANA</sub>	6 V			
Ground voltage differences	$V_{DIG}$ to $V_{ANA}$	0.3 V			
	$V_{DIG}$	6 V			
Digital inputs		$-0.3 \text{ V to +V}_{DIG} + 0.3 \text{ V}$			
Maximum junction temperatu	re	165°C			
Internal power dissipation		825 mW			
Lead temperature (soldering,	10s)	300°C			

<sup>(1)</sup> Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

#### **ELECTRICAL CHARACTERISTICS**

 $T_A = -40$ °C to 85°C,  $f_s = 250$  kHz,  $V_{DIG} = V_{ANA} = 5$  V, using internal reference (unless otherwise noted)

PARAMETER	TEST CONDITIONS	ADS8505I			ADS8505IB			UNIT
PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	MIN	TYP	MAX	UNII
Resolution				16			16	Bits
ANALOG INPUT		•						
Voltage range			±10			±10		V
Impedance			11.5			11.5		kΩ
Capacitance			50			50		pF
THROUGHPUT SPEED		•						
Conversion cycle	Acquire and convert			4			4	μs
Throughput rate		250			250			kHz

<sup>(2)</sup> All voltage values are with respect to network ground terminal.

### **ELECTRICAL CHARACTERISTICS (continued)**

 $T_A = -40^{\circ}C$  to  $85^{\circ}C$ ,  $f_S = 250$  kHz,  $V_{DIG} = V_{ANA} = 5$  V, using internal reference (unless otherwise noted)

	PARAMETER	PARAMETER TEST CONDITIONS ADS8505I		051			ADS8505IB		
	TANAMETEN	TEOT CONDITIONS	MIN	TYP	MAX	MIN	TYP	MAX	UNIT
DC ACCL	JRACY								
INL	Integral linearity error		-4		4	-1.5		1.5	LSB(1)
DNL	Differentiall linearity error		-2		2	-1		1	LSB(1)
	No missing codes		15			16			Bits
	Transition noise(2)			0.77			0.77		LSB
	Full-scale error(3)(4)	Int. ref.	-0.5		0.5	-0.25		0.25	%FSR
	Full-scale error drift	Int. ref.		±7			±7		ppm/°C
	Full-scale error(3)(4)	Ext. 2.5-V ref.	-0.25		0.25	-0.1	±0.01	0.1	%FSR
	Full-scale error drift	Ext. 2.5-V ref.		±2			±2		ppm/°C
	Bipolar zero error <sup>(3)</sup>		-5		5	-2		2	mV
	Bipolar zero error drift			±0.4			±0.4		ppm/°C
	Power supply sensitivity $(V_{DIG} = V_{ANA} = V_D)$	+4.75 V < V <sub>D</sub> < +5.25 V	-8		8	-8		8	LSB
AC ACCU	JRACY	<u> </u>			<u>.</u>			<u>.</u>	
SFDR	Spurious free dynamic range	f <sub>I</sub> = 20 kHz	92	98		96	105		dB <sup>(5)</sup>
THD	Total harmonic distortion	f <sub>I</sub> = 20 kHz		-98	-92		-103	-96	dB
01114.0	0: 1: ( :	f <sub>I</sub> = 20 kHz	83	88		86	88		dB
SINAD	Signal-to-(noise + distortion)	-60-dB Input		30			32		dB
SNR	Signal-to-noise ratio	f <sub>I</sub> = 20 kHz	83	88		86	88		dB
	Full-power bandwidth <sup>(6)</sup>			500			500		kHz
SAMPLIN	IG DYNAMICS	I.	1.		'			'	
	Aperture delay			5			5		ns
	Transient response	FS Step			2			2	μs
	Overvoltage recovery <sup>(7)</sup>			150			150		ns
REFERE	NCE	I	1		'			'	
	Internal reference voltage		2.48	2.5	2.52	2.48	2.5	2.52	V
	Internal reference source current (must use external buffer)			1			1		μΑ
	Internal reference drift			8			8		ppm/°C
	External reference voltage range for specified linearity		2.3	2.5	2.7	2.3	2.5	2.7	V
	External reference current drain	Ext. 2.5-V ref.			100			100	μΑ
DIGITAL	INPUTS	I							
	Logic levels								
V <sub>IL</sub>	Low-level input voltage		-0.3		0.8	-0.3		0.8	V
V <sub>IH</sub>	High-level input voltage		2.0		V <sub>DIG</sub> +0.3 V	2.0		V <sub>DIG</sub> +0.3 V	V
I <sub>IL</sub>	Low-level input current				±10			±10	μΑ
I <sub>IH</sub>	High-level input current				±10			±10	μΑ
DIGITAL	OUTPUTS	I							
	Data format (parallel 16-bits)								
	Data coding (binary 2's complement)								
V <sub>OL</sub>	Low-level output voltage	I <sub>SINK</sub> = 1.6 mA			0.4			0.4	V
V <sub>OH</sub>	High-level output voltage	I <sub>SOURCE</sub> = 500 mA	4			4			V
	Leakage current	Hi-Z state, V <sub>OUT</sub> = 0 V to V <sub>DIG</sub>			±5			±5	μА
	Output capacitance	Hi-Z state			15			15	pF

- (1) LSB means least significant bit. For the 16-bit,  $\pm 10$ -V input ADS8505, one LSB is 305  $\mu$ V.
- (2) Typical rms noise at worst case transitions and temperatures.
- (3) As measured with fixed resistors shown in Figure 27. Adjustable to zero with external potentiometer.
- (4) Full-scale error is the worst case of -full-scale or +full-scale deviation from ideal first and last code transitions, divided by the transition voltage (not divided by the full-scale range) and includes the effect of offset error.
- (5) All specifications in dB are referred to a full-scale ±10-V input.
- (6) Full-power bandwidth is defined as the full-scale input frequency at which signal-to-(noise + distortion) degrades to 60 dB, or 10 bits of accuracy.
- (7) Recovers to specified performance after 2 x FS input overvoltage.



### **ELECTRICAL CHARACTERISTICS (continued)**

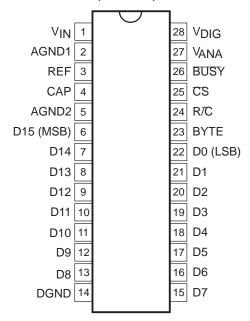
 $T_A = -40$ °C to 85°C,  $f_S = 250$  kHz,  $V_{DIG} = V_{ANA} = 5$  V, using internal reference (unless otherwise noted)

	PARAMETER	TEST CONDITIONS		ADS8505I			ADS8505IB		UNIT
	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	MIN	TYP	MAX	UNII
DIGITAL	L TIMING								
	Bus access timing				83			83	ns
	Bus relinquish timing				83			83	ns
POWER	SUPPLIES								
$V_{\text{DIG}}$	Digital input voltage		4.75	5	5.25	4.75	5	5.25	V
V <sub>ANA</sub>	Analog input voltage	Must be < \/	4.75	5	5.25	4.75	5	5.25	V
I <sub>DIG</sub>	Digital input current	Must be ≤ V <sub>ANA</sub>		2	5		2	5	mA
I <sub>ANA</sub>	Analog input current			12	15		12	15	mA
	Power dissipation	f <sub>S</sub> = 250 kHz		70	100		70	100	mW
TEMPE	RATURE RANGE								
	Specified performance		-40		85	-40		85	°C
	Derated performance <sup>(8)</sup>		-55		125	-55		125	°C
	Storage		-65		150	-65		150	°C
THERM	AL RESISTANCE (⊖ <sub>JA</sub> )								
	SSOP			62			62		°C/W
	SO			46			46		°C/W

<sup>(8)</sup> The internal reference may not be started correctly beyond the industrial temperature range (-40°C to 85°C), therefore use of an external reference is recommended.

#### **DEVICE INFORMATION**

# DB OR DW PACKAGE (TOP VIEW)



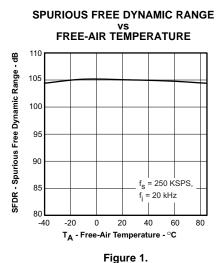
## **DEVICE INFORMATION (continued)**

### **Terminal Functions**

TERMINAL		DIGITAL	DECODIDETON			
NAME	DB/DW NO.	1/0	DESCRIPTION			
AGND1	2		Analog ground. Used internally as ground reference point.			
AGND2	5		Analog ground.			
BUSY	26	0	At the start of a conversion, $\overline{\text{BUSY}}$ goes low and stays low until the conversion is completed and the digital outputs have been updated.			
BYTE	23	I	Selects 8 most significant bits (low) or 8 least significant bits (high).			
CAP	4		Reference buffer capacitor. 2.2-μF Tantalum capacitor to ground.			
<u>cs</u>	25	I	Internally ORed with R/C. If R/C is low, a falling edge on CS initiates a new conversion.			
DGND	14		Digital ground.			
D15 (MSB)	6	0	Data bit 15. Most significant bit (MSB) of conversion results. Hi-Z state when $\overline{\text{CS}}$ is high, or when $R/\overline{\text{C}}$ is low.			
D14	7	0	Data bit 14. Hi-Z state when $\overline{CS}$ is high, or when R/ $\overline{C}$ is low.			
D13	8	0	Data bit 13. Hi-Z state when $\overline{CS}$ is high, or when R/ $\overline{C}$ is low.			
D12	9	0	Data bit 12. Hi-Z state when $\overline{CS}$ is high, or when R/ $\overline{C}$ is low.			
D11	10	0	Data bit 11. Hi-Z state when $\overline{CS}$ is high, or when R/ $\overline{C}$ is low.			
D10	11	0	Data bit 10. Hi-Z state when $\overline{CS}$ is high, or when $R/\overline{C}$ is low.			
D9	12	0	Data bit 9. Hi-Z state when $\overline{CS}$ is high, or when R/ $\overline{C}$ is low.			
D8	13	0	Data bit 8. Hi-Z state when $\overline{CS}$ is high, or when R/ $\overline{C}$ is low.			
D7	15	0	Data bit 7. Hi-Z state when $\overline{CS}$ is high, or when R/ $\overline{C}$ is low.			
D6	16	0	Data bit 6. Hi-Z state when $\overline{CS}$ is high, or when R/ $\overline{C}$ is low.			
D5	17	0	Data bit 5. Hi-Z state when $\overline{CS}$ is high, or when R/ $\overline{C}$ is low.			
D4	18	0	Data bit 4. Hi-Z state when $\overline{CS}$ is high, or when R/ $\overline{C}$ is low.			
D3	19	0	Data bit 3. Hi-Z state when $\overline{CS}$ is high, or when R/ $\overline{C}$ is low.			
D2	20	0	Data bit 2. Hi-Z state when $\overline{CS}$ is high, or when R/ $\overline{C}$ is low.			
D1	21	0	Data bit 1. Hi-Z state when $\overline{CS}$ is high, or when R/ $\overline{C}$ is low.			
D0 (LSB)	22	0	Data bit 0. Least significant bit (LSB) of conversion results. Hi-Z state when $\overline{CS}$ is high, or when $R/\overline{C}$ is low.			
R/C	24	I	With $\overline{\text{CS}}$ low and $\overline{\text{BUSY}}$ high, a falling edge on R/ $\overline{\text{C}}$ initiates a new conversion. With $\overline{\text{CS}}$ low, a rising edge on R/ $\overline{\text{C}}$ enables the parallel output.			
REF	3		Reference input/output. 2.2-μF Tantalum capacitor to ground.			
V <sub>ANA</sub>	27		Analog supply input. Nominally +5 V. Decouple to ground with 0.1-μF ceramic and 10-μF tantalum capacitors.			
$V_{DIG}$	28		Digital supply input. Nominally +5 V. Connect directly to pin 27. Must be $\leq$ V <sub>ANA</sub> .			
V <sub>IN</sub>	1		Analog input. See Figure 28.			



#### **TYPICAL CHARACTERISTICS**



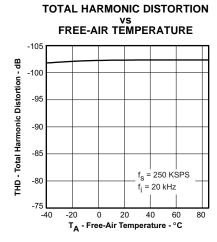
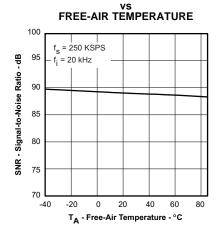


Figure 2.

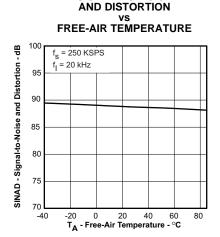
**SIGNAL-TO-NOISE RATIO** 



SIGNAL-TO-NOISE RATIO

Figure 3.

SIGNAL-TO-NOISE AND DISTORTION



SIGNAL-TO-NOISE

Figure 4.

SPURIOUS FREE DYNAMIC RANGE

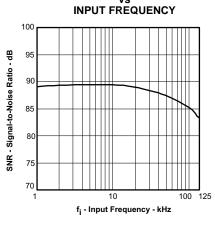


Figure 5.

TOTAL HARMONIC DISTORTION

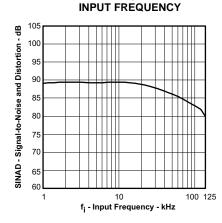


Figure 6.

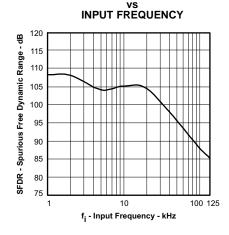


Figure 7.

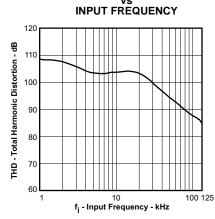


Figure 8.

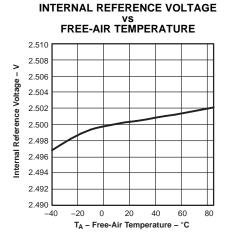
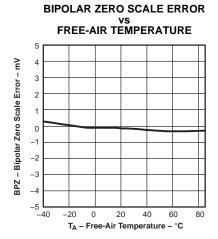


Figure 9.

### **TYPICAL CHARACTERISTICS (continued)**



**NEGATIVE FULL-SCALE ERROR** vs FREE-AIR TEMPERATURE 0.25 Internal Reference 0.2 Negative Full-Scale Error - %FSR 0.15 0.1 0.05 -0.05 -0.1 -0.15 -0.2 -0.25

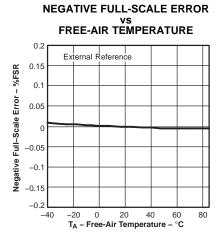
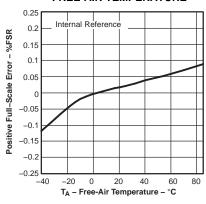


Figure 10.

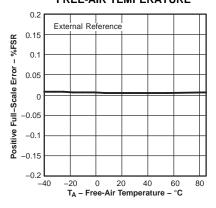
 $T_A$  – Free-Air Temperature –  $^{\circ}C$ Figure 11.

Figure 12.

### **POSITIVE FULL-SCALE ERROR** vs FREE-AIR TEMPERATURE



**POSITIVE FULL-SCALE ERROR** vs FREE-AIR TEMPERATURE



**SUPPLY CURRENT** 

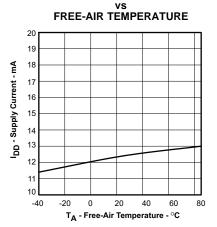
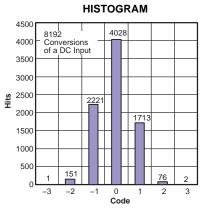


Figure 13.

Figure 14.

Figure 15.





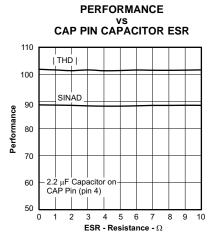
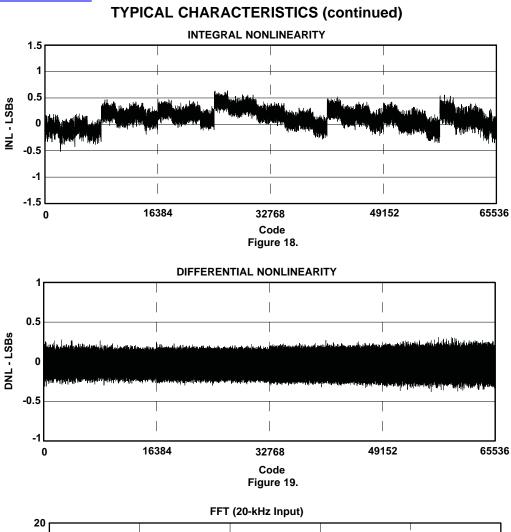
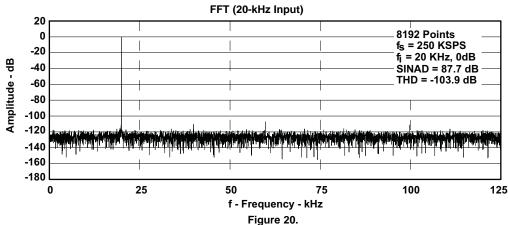


Figure 17.







#### **BASIC OPERATION**

Figure 21 shows a basic circuit to operate the ADS8505 with a full parallel data output. Taking R/ $\overline{C}$  (pin 24) low for a minimum of 40 ns (1.75  $\mu$ s max) initiates a conversion.  $\overline{BUSY}$  (pin 26) goes low and stays low until the conversion is completed and the output registers are updated. Data is output in binary 2's complement format with the MSB on pin 6.  $\overline{BUSY}$  going high can be used to latch the data.

## **BASIC OPERATION (continued)**

The ADS8505 begins tracking the input signal at the end of the conversion. Allowing 4  $\mu$ s between convert commands assures accurate acquisition of a new signal.

The offset and gain are adjusted internally to allow external trimming with a single supply. The external resistors compensate for this adjustment and can be left out if the offset and gain are corrected in software (refer to the CALIBRATION section).

#### STARTING A CONVERSION

The combination of  $\overline{CS}$  (pin 25) and  $R/\overline{C}$  (pin 24) low for a minimum of 40 ns immediately puts the sample/hold of the ADS8505 in the hold state and starts conversion n.  $\overline{BUSY}$  (pin 26) goes low and stays low until conversion n is completed and the internal output register has been updated. All new convert commands during  $\overline{BUSY}$  low will abort the conversion in progress and reset the ADC (see Figure 26).

The ADS8505 begins tracking the input signal at the end of the conversion. Allowing 4  $\mu$ s between convert commands assures accurate acquisition of a new signal. Refer to Table 1 for a summary of  $\overline{CS}$ , R/ $\overline{C}$ , and  $\overline{BUSY}$  states and Figure 23 through Figure 25 for the timing diagrams.

 $\overline{\text{CS}}$  and R/ $\overline{\text{C}}$  are internally ORed and level triggered. There is not a requirement which input goes low first when initiating a conversion. If, however, it is critical that  $\overline{\text{CS}}$  or R/ $\overline{\text{C}}$  initiates conversion n, be sure the less critical input is low at least 10 ns prior to the initiating input.

To reduce the number of control pins,  $\overline{CS}$  can be tied low using R/ $\overline{C}$  to control the read and convert modes. The parallel output becomes active whenever R/ $\overline{C}$  goes high. Refer to the READING DATA section.

CS	R/C	BUSY	OPERATION
1	Х	Х	None. Databus is in Hi-Z state.
$\rightarrow$	0	1	Initiates conversion <i>n</i> . Databus remains in Hi-Z state.
0	<b>\</b>	1	Initiates conversion <i>n</i> . Databus enters Hi-Z state.
0	1	1	Conversion <i>n</i> completed. Valid data from conversion <i>n</i> on the databus.
$\downarrow$	1	1	Enables databus with valid data from conversion <i>n</i> .
$\downarrow$	1	0	Enables databus with valid data from conversion $n-1$ <sup>(1)</sup> . Conversion $n$ in progress.
0	1	0	Enables databus with valid data from conversion $n-1$ <sup>(1)</sup> . Conversion $n$ in progress.
0	0	1	Data is invalid. $\overline{\text{CS}}$ and/or R/ $\overline{\text{C}}$ must be high when $\overline{\text{BUSY}}$ goes high.
Х	<b>\</b>	0	Conversion <i>n</i> is halted. Causes ADC to reset. (2)

Table 1. Control Line Functions for Read and Convert

<sup>(1)</sup> See Figure 23 and Figure 24 for constraints on data valid from conversion *n-1*.

<sup>(2)</sup> See Figure 26 for details on ADC reset.



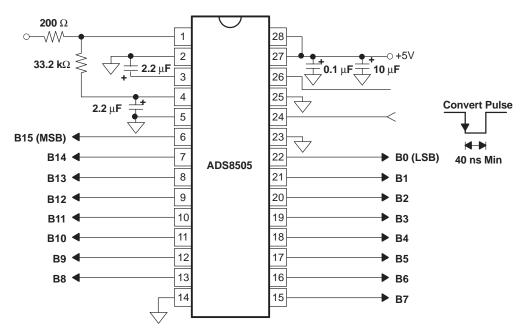


Figure 21. Basic Operation

#### **READING DATA**

The ADS8505 outputs full or byte-reading parallel data in binary 2's complement data output format. The parallel output is active when  $R/\overline{C}$  (pin 24) is high and  $\overline{CS}$  (pin 25) is low. Any other combination of  $\overline{CS}$  and  $R/\overline{C}$  3-states the parallel output. Valid conversion data can be read in a full parallel, 16-bit word or two 8-bit bytes on pins 6-13 and pins 15-22. BYTE (pin 23) can be toggled to read both bytes within one conversion cycle. Refer to Table 2 for ideal output codes and Figure 22 for bit locations relative to the state of BYTE.

DESCRIPTION	ANALOG INPUT	DIGITAL OUTPUT BINAR	Y 2'S COMPLEMENT
DESCRIPTION	ANALOG INPUT	BINARY CODE	HEX CODE
Full-scale range	±10 V		
Least significant bit (LSB)	305 μV		
Full scale (10 V-1 LSB)	9.999695 V	0111 1111 1111 1111	7FFF
Midscale	0 V	0000 0000 0000 0000	0000
One LSB below midscale	-305 μV	1111 1111 1111 1111	FFFF
-Full scale	-10 V	1000 0000 0000 0000	8000

**Table 2. Ideal Input Voltages and Output Codes** 

### PARALLEL OUTPUT (After a Conversion)

After conversion n is completed and the output registers have been updated,  $\overline{\text{BUSY}}$  (pin 26) goes high. Valid data from conversion n is available on D15-D0 (pins 6-13 and 15-22).  $\overline{\text{BUSY}}$  going high can be used to latch the data. Refer to Table 3, Figure 24, and Figure 25 for timing specifications.

### PARALLEL OUTPUT (During a Conversion)

After conversion n has been initiated, valid data from conversion n-1 can be read and is valid up to  $t_2$  (2.2  $\mu$ s typ) after the start of conversion n. Do not attempt to read data from  $t_2$  (2.2  $\mu$ s typ) after the start of conversion n until  $\overline{\text{BUSY}}$  (pin 26) goes high; this may result in reading invalid data. Refer to Table 3, Figure 23, Figure 24, and Figure 25 for timing specifications.

**Note:** For the best possible performance, data should not be read during a conversion. The switching noise of the asynchronous data transfer can cause digital feedthrough degrading converter performance.

The number of control lines can be reduced by tying  $\overline{CS}$  low while using the falling edge of  $R/\overline{C}$  to initiate conversions and the rising edge of  $R/\overline{C}$  to activate the output mode of the converter. See Figure 23.

Table	3.	Conversion	<b>Timing</b>
-------	----	------------	---------------

SYMBOL	DESCRIPTION	MIN	TYP	MAX	UNITS
t <sub>w1</sub>	Pulse duration, convert	40		1750	ns
t <sub>a</sub>	Access time, data valid after R/C low		2.2	3.2	μs
t <sub>pd</sub>	Propagation delay time, BUSY from R/C low		15	25	ns
t <sub>w2</sub>	Pulse duration, BUSY low			2.2	μs
t <sub>d1</sub>	Delay time, BUSY after end of conversion		5		ns
t <sub>d2</sub>	Delay time, aperture		5		ns
t <sub>conv</sub>	Conversion time			2.2	μs
t <sub>acq</sub>	Acquisition time	1.8			μs
t <sub>dis</sub>	Disable time, bus	10	30	83	ns
t <sub>d3</sub>	Delay time, BUSY after data valid	35	50		ns
t <sub>v</sub>	Valid time, previous data remains valid after R/C low	1.5	2		μs
t <sub>conv</sub> + t <sub>acq</sub>	Throughput time			4	μs
t <sub>su</sub>	Setup time, R/C to CS	10			ns
t <sub>c</sub>	Cycle time between conversions	4			μs
t <sub>en</sub>	Enable time, bus	10	30	83	ns
t <sub>d4</sub>	Delay time, BYTE	5	10	30	ns

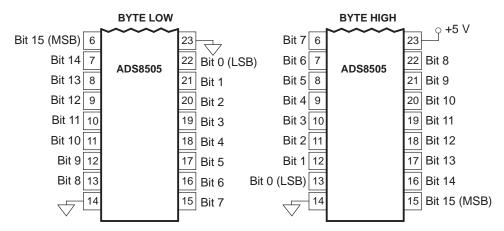


Figure 22. Bit Locations Relative to State of BYTE (Pin 23)



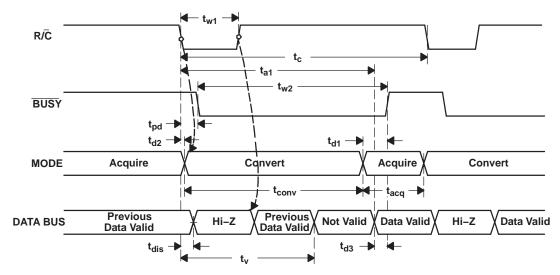


Figure 23. Conversion Timing with Outputs Enabled after Conversion (CS Tied Low)

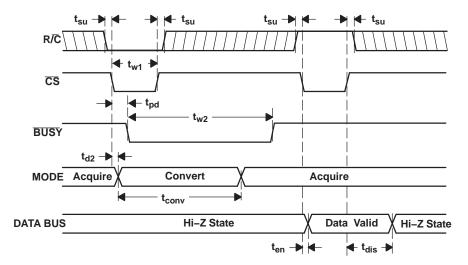


Figure 24. Using CS to Control Conversion and Read Timing

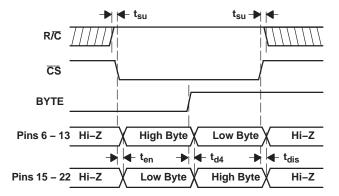


Figure 25. Using CS and BYTE to Control Data Bus

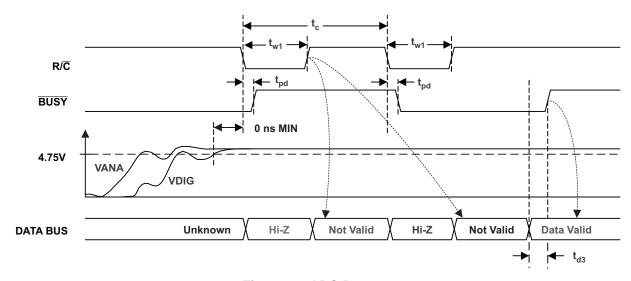


Figure 26. ADC Reset

#### **ADC RESET**

The ADC reset function of the ADS8505 can be used to terminate the current conversion cycle. Bringing  $R/\overline{C}$  low for at least 40 ns while BUSY is low will initiate the ADC reset. To initiate a new conversion,  $R/\overline{C}$  must return to the high state and remain high long enough to acquire a new sample (see Table 3,  $t_c$ ) before going low to initiate the next conversion sequence. In applications that do not monitor the BUSY signal, it is recommended that the ADC reset function be implemented as part of a system initialization sequence.

#### **INPUT RANGES**

The ADS8505 offers a standard  $\pm 10$ -V input range. Figure 28 shows the necessary circuit connections for the ADS8505 with and without hardware trim. Offset and full-scale error specifications are tested and specified with the fixed resistors shown in Figure 28(b). Full-scale error includes offset and gain errors measured at both +FS and -FS. Adjustments for offset and gain are described in the CALIBRATION section of this data sheet.

Offset and gain are adjusted internally to allow external trimming with a single supply. The external resistors compensate for this adjustment and can be left out if the offset and gain are corrected in software (refer to the CALIBRATION section).

The nominal input impedance of 11.5 k $\Omega$  results from the combination of the internal resistor network shown on the front page of the product data sheet and the external resistors. The input resistor divider network provides inherent overvoltage protection assured to at least  $\pm 25$  V. The 1% resistors used for the external circuitry do not compromise the accuracy or drift of the converter. They have little influence relative to the internal resistors, and tighter tolerances are not required.

The input signal must be referenced to AGND1. This minimizes the ground loop problem typical to analog designs. The analog signal should be driven by a low impedance source. A typical driving circuit using an OPA627 or OPA132 is shown in Figure 27.



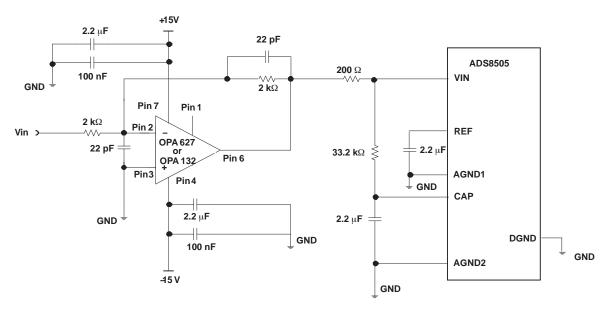


Figure 27. Typical Driving Circuit (±10 V, No Trim)

#### **APPLICATION INFORMATION**

#### **CALIBRATION**

The ADS8505 can be trimmed in hardware or software. The offset should be trimmed before the gain since the offset directly affects the gain. To achieve optimum performance, several iterations may be required.

#### **Hardware Calibration**

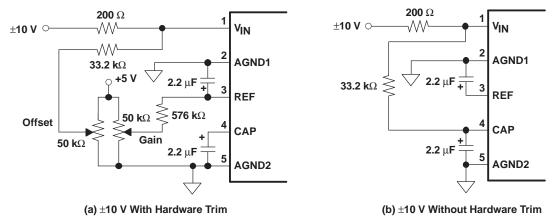
To calibrate the offset and gain of the ADS8505, install the proper resistors and potentiometers as shown in Figure 28(a).

#### **Software Calibration**

To calibrate the offset and gain of the ADS8505 in software, no external resistors are required. See the No Calibration section for details on the effects of the external resistors.

#### No Calibration

See Figure 28(b) for circuit connections. The external resistors shown in Figure 28(b) may not be necessary in some applications. These resistors provide compensation for an internal adjustment of the offset and gain which allows calibration with a single supply.



Note: Use 1% metal film resistors.

Figure 28. Circuit Diagram With and Without External Resistors

#### **REFERENCE**

The ADS8505 can operate with its internal 2.5-V reference or an external reference. By applying an external reference to pin 5, the internal reference can be bypassed. The reference voltage at REF is buffered internally with the output on CAP (pin 4).

The internal reference has an 8 ppm/°C drift (typical) and accounts for approximately 20% of the full-scale error (FSE =  $\pm 0.5$ %).

#### **REF**

REF (pin 3) is an input for an external reference or the output for the internal 2.5-V reference. A 2.2-µF capacitor should be connected as close to the REF pin as possible. The capacitor and the output resistance of REF create a low-pass filter to bandlimit noise on the reference. Using a smaller value capacitor introduces more noise to the reference degrading the SNR and SINAD. The REF pin should not be used to drive external ac or dc loads.

The range for the external reference is 2.3 V to 2.7 V and determines the actual LSB size. Increasing the reference voltage increases the full-scale range and the LSB size of the converter which can improve the SNR.



#### **APPLICATION INFORMATION (continued)**

#### **CAP**

CAP (pin 4) is the output of the internal reference buffer. A  $2.2 - \mu F$  capacitor can be placed between the CAP pin and ground. Because the internal reference buffer is internally compensated, the external capacitor is not necessary for compensation of the reference buffer. This relaxes the performance requirements of the capacitor and makes the performance of the ADC less sensitive to the capacitor.

The output of the buffer is capable of driving up to 2 mA of current to a dc load. A dc load requiring more than 2 mA of current from the CAP pin begins to degrade the linearity of the ADS8505. Using an external buffer allows the internal reference to be used for larger dc loads and ac loads. Do not attempt to directly drive an ac load with the output voltage on CAP. This causes performance degradation of the converter.

#### **LAYOUT**

#### **POWER**

For optimum performance, tie the analog and digital power pins to the same +5-V power supply and tie the analog and digital grounds together. As noted in the electrical specifications, the ADS8505 uses 90% of its power for the analog circuitry. The ADS8505 should be considered as an analog component.

The +5-V power for the A/D should be separate from the +5 V used for the system's digital logic. Connecting  $V_{DIG}$  (pin 28) directly to a digital supply can reduce converter performance due to switching noise from the digital logic. For best performance, the +5-V supply can be produced from whatever analog supply is used for the rest of the analog signal conditioning. If +12-V or +15-V supplies are present, a simple +5-V regulator can be used. Although it is not suggested, if the digital supply must be used to power the converter, be sure to properly filter the supply. Either using a filtered digital supply or a regulated analog supply, both  $V_{DIG}$  and  $V_{ANA}$  should be tied to the same +5-V source.

#### **GROUNDING**

Three ground pins are present on the ADS8505. DGND is the digital supply ground. AGND2 is the analog supply ground. AGND1 is the ground which all analog signals internal to the A/D are referenced. AGND1 is more susceptible to current induced voltage drops and must have the path of least resistance back to the power supply.

All the ground pins of the A/D should be tied to the analog ground plane, separated from the system's digital logic ground, to achieve optimum performance. Both analog and digital ground planes should be tied to the *system* ground as near to the power supplies as possible. This helps to prevent dynamic digital ground currents from modulating the analog ground through a common impedance to power ground.

#### SIGNAL CONDITIONING

The FET switches used for the sample/hold on many CMOS A/D converters release a significant amount of charge injection which can cause the driving op-amp to oscillate. The FET switch on the ADS8505, compared to the FET switches on other CMOS A/D converters, releases 5% to 10% of the charge. There is also a resistive front end which attenuates any charge which is released. The end result is a minimal requirement for the anti-alias filter on the front end. Any op-amp sufficient for the signal in an application is sufficient to drive the ADS8505.

The resistive front end of the ADS8505 also provides an assured  $\pm 25$ -V overvoltage protection. In most cases, this eliminates the need for external input protection circuitry.

#### **INTERMEDIATE LATCHES**

The ADS8505 does have 3-state outputs for the parallel port, but intermediate latches should be used if the bus is to be active during conversions. If the bus is not active during conversion, the 3-state outputs can be used to isolate the A/D from other peripherals on the same bus. The 3-state outputs can also be used when the A/D is the only peripheral on the data bus.

Intermediate latches are beneficial on any monolithic A/D converter. The ADS8505 has an internal LSB size of 38  $\mu$ V. Transients from fast switching signals on the parallel port, even when the A/D is 3-stated, can be coupled through the substrate to the analog circuitry causing degradation of converter performance.



### **Revision History**

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

С	hanges from Original (September, 2005) to A Revision	Page
•	Added SFDR value	1
•	Added SFDR value	1
•	Changed 3.0 to 1.5 Minimum Relative Accuracy	
•	Changed REF and CAP - reversed	2
•	Changed INL, SFDR, THD, SNR values	2
•	Changed SFDR-TA, THD-TA, SINAD-TA, SNR-fi, SINAD-fi SFDR-fi, THD-fi, IDD-TA, CAP ESR, INL, DNL, and FFT curves	
•	Changed CAP description	16
С	hanges from A Revision (October, 2006) to B Revision	Page
•	Deleted text from basic operation description	8
•	Changed text in starting a conversion description	
•	Changed operation descriptions and R/C in table	9
•	Added SAR Reset timing	13
•	Added ADC RESET section	



26-May-2007

#### PACKAGING INFORMATION

Orderabl	e Device	Status <sup>(1)</sup>	Package Type	Package Drawing	Pins	Package Qty	e Eco Plan <sup>(2)</sup>	Lead/Ball Finish	MSL Peak Temp <sup>(3)</sup>
ADS85	05IBDB	ACTIVE	SSOP	DB	28	50	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR
ADS8505	SIBDBG4	ACTIVE	SSOP	DB	28	50	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR
ADS850	5IBDBR	ACTIVE	SSOP	DB	28	2000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR
ADS8505	IBDBRG4	ACTIVE	SSOP	DB	28	2000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR
ADS850	05IBDW	ACTIVE	SOIC	DW	28	20	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR
ADS8505	SIBDWG4	ACTIVE	SOIC	DW	28	20	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR
ADS850	5IBDWR	ACTIVE	SOIC	DW	28	1000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR
ADS8505I	BDWRG4	ACTIVE	SOIC	DW	28	1000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR
ADS85	05IDB	ACTIVE	SSOP	DB	28	50	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR
ADS850	5IDBG4	ACTIVE	SSOP	DB	28	50	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR
ADS850	05IDBR	ACTIVE	SSOP	DB	28	2000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR
ADS8505	SIDBRG4	ACTIVE	SSOP	DB	28	2000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR
ADS85	05IDW	ACTIVE	SOIC	DW	28	20	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR
ADS850	5IDWG4	ACTIVE	SOIC	DW	28	20	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR
ADS850	)5IDWR	ACTIVE	SOIC	DW	28	1000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR
ADS8505	SIDWRG4	ACTIVE	SOIC	DW	28	1000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR

<sup>&</sup>lt;sup>(1)</sup> The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

**TBD:** The Pb-Free/Green conversion plan has not been defined.

**Pb-Free** (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

**Pb-Free (RoHS Exempt):** This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

<sup>(2)</sup> Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check <a href="http://www.ti.com/productcontent">http://www.ti.com/productcontent</a> for the latest availability information and additional product content details.



#### PACKAGE OPTION ADDENDUM

26-May-2007

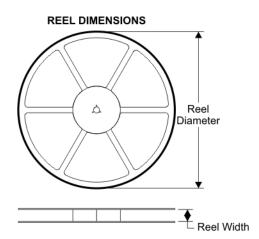
(3) MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

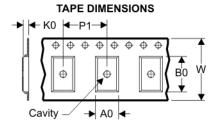
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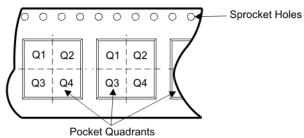
#### TAPE AND REEL BOX INFORMATION





	Dimension designed to accommodate the component width
B0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

#### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



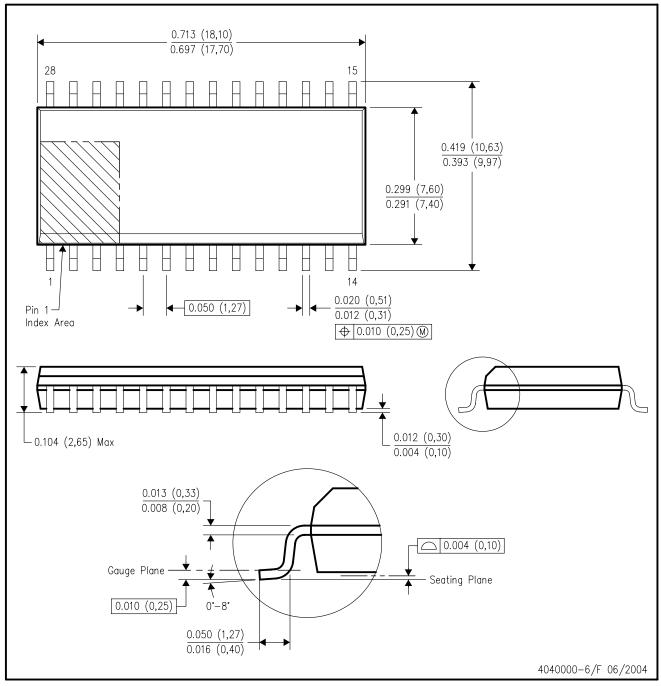
Device	Package	Pins	Site	Reel Diameter (mm)	Reel Width (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
ADS8505IBDBR	DB	28	SITE 60	330	16	8.1	10.4	2.5	12	16	Q1
ADS8505IBDWR	DW	28	SITE 60	330	32	11.35	18.67	3.1	16	32	Q1
ADS8505IDBR	DB	28	SITE 60	330	16	8.1	10.4	2.5	12	16	Q1
ADS8505IDWR	DW	28	SITE 60	330	32	11.35	18.67	3.1	16	32	Q1



Device	Package	Pins	Site	Length (mm)	Width (mm)	Height (mm)
ADS8505IBDBR	DB	28	SITE 60	535.4	167.7	48.3
ADS8505IBDWR	DW	28	SITE 60	346.0	346.0	49.0
ADS8505IDBR	DB	28	SITE 60	346.0	346.0	33.0
ADS8505IDWR	DW	28	SITE 60	346.0	346.0	49.0

# DW (R-PDSO-G28)

### PLASTIC SMALL-OUTLINE PACKAGE



NOTES:

- A. All linear dimensions are in inches (millimeters).
- B. This drawing is subject to change without notice.
- C. Body dimensions do not include mold flash or protrusion not to exceed 0.006 (0,15).
- D. Falls within JEDEC MS-013 variation AE.



### DB (R-PDSO-G\*\*)

#### **PLASTIC SMALL-OUTLINE**

#### **28 PINS SHOWN**



NOTES: A. All linear dimensions are in millimeters.

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