1.1 mA 200 MHz Current Feedback Op Amp with Enable Feature

NCS2501 is a 1.1 mA 200 MHz current feedback monolithic operational amplifier featuring high slew rate and low differential gain and phase error. The current feedback architecture allows for a superior bandwidth and low power consumption. This device features an enable pin.

Features

- -3.0 dB Small Signal BW (A_V = +2.0, V_O = 0.5 V_{p-p}) 200 MHz Typ
- Slew Rate 450 V/us
- Supply Current 1.1 mA
- Input Referred Voltage Noise 4.0 nV/√Hz
- THD $-55 \text{ dB } (f = 5.0 \text{ MHz}, V_O = 2.0 \text{ V}_{p-p})$
- Output Current 100 mA
- Enable Pin Available
- Pin Compatible with EL5160, MAX4180, OPA683
- Pb-Free Packages are Available

Applications

- Portable Video
- Line Drivers
- Radar/Communication Receivers
- Set Top Box
- NTSC/PAL/HDTV

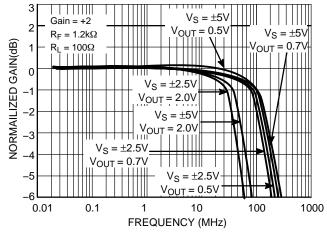


Figure 1. Frequency Response: Gain (dB) vs. Frequency Av = +2.0, R_L = 100 Ω



http://onsemi.com

MARKING DIAGRAMS



SO-8 D SUFFIX CASE 751





SC-70-6 (SC-88) SQ SUFFIX CASE 419B





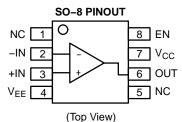
SOT23-6 (TSOP-6) SN SUFFIX CASE 318G



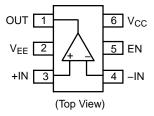
YA1, N2501 = NCS2501

A = Assembly Location
L = Wafer Lot

Y = Year
W = Work Week
M = Date Code
■ Pb-Free Package



SOT23-6/SC70-6 PINOUT



ORDERING INFORMATION

See detailed ordering and shipping information in the package dimensions section on page 13 of this data sheet.

者MFWNCTION PRSCRIPTION 商

Pin	Pin	77.27.01		
(SO-8)	(SOT23/SC70)	Symbol	Function	Equivalent Circuit
6	1	OUT	Output	V _{CC} ESD OUT
4	2	V_{EE}	Negative Power Supply	
3	3	+IN	Non-inverted Input	V _{CC} ESD -IN V _{EE}
2	4	-IN	Inverted Input	See Above
7	6	V _{CC}	Positive Power Supply	
8	5	EN	Enable	EN ESD V _{EE}
1, 8	N/A	NC	No Connect	

ENABLE PIN TRUTH TABLE

	High*	Low
Enable	Enabled	Disabled

^{*}Default open state

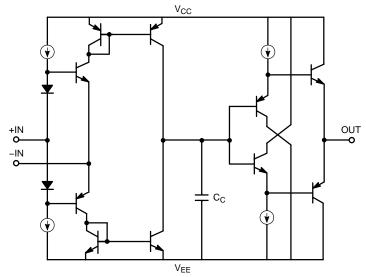


Figure 2. Simplified Device Schematic

查询"NCS2501SQT2**经"(興啦)喬S**

Chara	Value	
ESD Human Body Model Machine Model Charged Device Mod	2.0 kV (Note 1) 200 V 1.0 kV	
Moisture Sensitivity (No	Level 1	
Flammability Rating	Oxygen Index: 28 to 34	UL 94 V-0 @ 0.125 in

- 1. 0.8 kV between the input pairs +IN and -IN pins only. All other pins are 2.0 kV.
- 2. For additional information, see Application Note AND8003/D.

MAXIMUM RATINGS

Parameter	Symbol	Rating	Unit
Power Supply Voltage	V _S	11	V _{DC}
Input Voltage Range	VI	≤V _S	V _{DC}
Input Differential Voltage Range	V _{ID}	≤V _S	V _{DC}
Output Current	Io	100	mA
Maximum Junction Temperature (Note 3)	TJ	150	°C
Operating Ambient Temperature	T _A	-40 to +85	°C
Storage Temperature Range	T _{stg}	-60 to +150	°C
Power Dissipation	P _D	(See Graph)	mW
Thermal Resistance, Junction–to–Air SO–8 SC70–6 SOT23–6	$R_{ hetaJA}$	172 215 154	°C/W

Maximum ratings are those values beyond which device damage can occur. Maximum ratings applied to the device are individual stress limit values (not normal operating conditions) and are not valid simultaneously. If these limits are exceeded, device functional operation is not implied, damage may occur and reliability may be affected.

3. Power dissipation must be considered to ensure maximum junction temperature (T_J) is not exceeded.

MAXIMUM POWER DISSIPATION

The maximum power that can be safely dissipated is limited by the associated rise in junction temperature. For the plastic packages, the maximum safe junction temperature is 150°C. If the maximum is exceeded momentarily, proper circuit operation will be restored as soon as the die temperature is reduced. Leaving the device in the "overheated" condition for an extended period can result in device damage.

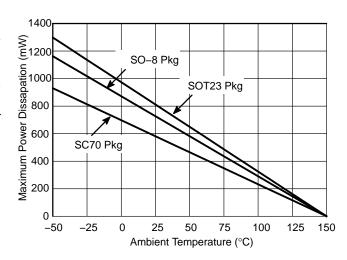


Figure 3. Power Dissipation vs. Temperature

Symbol	Characteristic	Conditions	Min	Тур	Max	Unit
FREQUEN	CY DOMAIN PERFORMANCE			•		•
BW	Bandwidth 3.0 dB Small Signal 3.0 dB Large Signal	$A_V = +2.0, V_O = 0.5 V_{p-p}$ $A_V = +2.0, V_O = 2.0 V_{p-p}$		200 140		MHz
GF _{0.1dB}	0.1 dB Gain Flatness Bandwidth	A _V = +2.0		30		MHz
dG	Differential Gain	$A_V = +2.0$, $R_L = 150 \Omega$, $f = 3.58 \text{ MHz}$		0.02		%
dP	Differential Phase	$A_V = +2.0$, $R_L = 150 \Omega$, $f = 3.58 \text{ MHz}$		0.1		٥
TIME DOM	AIN RESPONSE					
SR	Slew Rate	$A_V = +2.0, V_{step} = 2.0 V$		450		V/μs
t _s	Settling Time 0.01% 0.1%	$A_V = +2.0, V_{step} = 2.0 V$ $A_V = +2.0, V_{step} = 2.0 V$		35 18		ns
t _r t _f	Rise and Fall Time	$(10\%-90\%) A_V = +2.0, V_{step} = 2.0 V$		5.0		ns
t _{ON}	Turn-on Time			900		ns
t _{OFF}	Turn-off Time			500		ns
HARMONIC	C/NOISE PERFORMANCE					
THD	Total Harmonic Distortion	$f = 5.0 \text{ MHz}, V_O = 2.0 V_{p-p}, R_L = 150 \Omega$		-55		dB
HD2	2nd Harmonic Distortion	$f = 5.0 \text{ MHz}, V_O = 2.0 V_{p-p}$		-67		dBc
HD3	3rd Harmonic Distortion	$f = 5.0 \text{ MHz}, V_O = 2.0 V_{p-p}$		-57		dBc
IP3	Third-Order Intercept	$f = 10 \text{ MHz}, V_O = 2.0 V_{p-p}$		35		dBm
SFDR	Spurious-Free Dynamic Range	$f = 5.0 \text{ MHz}, V_O = 2.0 V_{p-p}$		58		dBc
e _N	Input Referred Voltage Noise	f = 1.0 MHz		4.0		nV/√Hz
i _N	Input Referred Current Noise	f = 1.0 MHz, Inverting f = 1.0 MHz, Non–Inverting		15 15		pA/√Hz

DC.EI.ECTRICAL CHARACTERISTICS (V_{CC} = +5.0 V, V_{EE} = -5.0 V, T_A = -40°C to +85°C, R_L = 100 Ω to GND, R_F = 1.2 k Ω , R_C = +2.0, Enable is left open, unless otherwise specified).

Symbol	Characteristic	Conditions	Min	Тур	Max	Unit
DC PERFO	RMANCE		<u>. </u>			
Vos	Offset Voltage		-4.0	±0.7	+4.0	mV
$\Delta V_{IO}/\Delta T$	Input Offset Voltage Temperature Coefficient			6.0		μV/°C
I _{IB}	Input Bias Current	+Input (Non-Inverting), $V_O = 0 \text{ V}$ -Input (Inverting), $V_O = 0 \text{ V}$ (Note 4)	-4.0 -4.0	±2.0 ±0.4	+4.0 +4.0	μΑ
$\Delta I_{\text{IB}}/\Delta T$	Input Bias Current Temperature Coefficient	+Input (Non-Inverting), $V_O = 0 \text{ V}$ -Input (Inverting), $V_O = 0 \text{ V}$		±40 ±10		nA/°C
V_{IH}	Input High Voltage (Enable) (Note 4)		V _{CC} -1.5 V			V
V_{IL}	Input Low Voltage (Enable) (Note 4)				V _{CC} -3.5 V	V
NPUT CHA	ARACTERISTICS					
V_{CM}	Input Common Mode Voltage Range (Note 4)		±3.0	±4.0		V
CMRR	Common Mode Rejection Ratio	(See Graph)	50	55	65	dB
R _{IN}	Input Resistance	+Input (Non-Inverting) -Input (Inverting)		4.0 350		Ω
C _{IN}	Differential Input Capacitance			1.0		pF
OUTPUT C	HARACTERISTICS				<u>, </u>	
R _{OUT}	Output Resistance			0.02		Ω
Vo	Output Voltage Swing		±3.0	±3.5		V
I _O	Output Current		±60	±100		mA
POWER SU	JPPLY		<u>.</u>		<u>.</u>	
Vs	Operating Voltage Supply Range			10		V
I _{S,ON}	Power Supply Current – Enabled	V _O = 0 V	0.5	1.1	2.0	mA
I _{S,OFF}	Power Supply Current – Disabled	V _O = 0 V	0	0.11	0.3	mA
PSRR	Power Supply Rejection Ratio	(See Graph)	50	60	70	dB

^{4.} Guaranteed by design and/or characterization.

EXECUTE: CHARACTICINES ICS (V_{CC} = +2.5 V, V_{EE} = -2.5 V, T_A = -40°C to +85°C, R_L = 100 Ω to GND, R_F = 1.2 k Ω , A_V = +2.0, Enable is left open, unless otherwise specified).

Symbol	Characteristic	Conditions	Min	Тур	Max	Unit
REQUEN	CY DOMAIN PERFORMANCE					
BW	Bandwidth 3.0 dB Small Signal 3.0 dB Large Signal	$A_V = +2.0, V_O = 0.5 V_{p-p}$ $A_V = +2.0, V_O = 1.0 V_{p-p}$		180 130		MHz
GF _{0.1dB}	0.1 dB Gain Flatness Bandwidth	A _V = +2.0		15		MHz
dG	Differential Gain	$A_V = +2.0$, $R_L = 150 \Omega$, $f = 3.58 \text{ MHz}$		0.02		%
dP	Differential Phase	$A_V = +2.0$, $R_L = 150 \Omega$, $f = 3.58 \text{ MHz}$		0.1		۰
TIME DOM	AIN RESPONSE					
SR	Slew Rate	$A_V = +2.0, V_{step} = 1.0 V$		350		V/μs
t _s	Settling Time 0.01% 0.1%	$A_V = +2.0$, $V_{step} = 1.0 \text{ V}$ $A_V = +2.0$, $V_{step} = 1.0 \text{ V}$		40 18		ns
t _r t _f	Rise and Fall Time	(10%–90%) A _V = +2.0, V _{step} = 1.0 V		8.0		ns
t _{ON}	Turn-on Time			900		ns
t _{OFF}	Turn-off Time			500		ns
HARMONIC	C/NOISE PERFORMANCE					
THD	Total Harmonic Distortion	$f = 5.0 \text{ MHz}, V_{O} = 1.0 V_{p-p}, R_{L} = 150 \Omega$		-55		dB
HD2	2nd Harmonic Distortion	$f = 5.0 \text{ MHz}, V_O = 1.0 V_{p-p}$		-67		dBc
HD3	3rd Harmonic Distortion	$f = 5.0 \text{ MHz}, V_O = 1.0 V_{p-p}$		-57		dBc
IP3	Third-Order Intercept	$f = 10 \text{ MHz}, V_O = 1.0 V_{p-p}$		35		dBm
SFDR	Spurious-Free Dynamic Range	$f = 5.0 \text{ MHz}, V_O = 1.0 V_{p-p}$		58		dBc
e _N	Input Referred Voltage Noise	f = 1.0 MHz		4.0		nV/√H:
i _N	Input Referred Current Noise	f = 1.0 MHz, Inverting f = 1.0 MHz, Non–Inverting		15 15		pA/√H:

2GFLECTRICALS CHARACTICALS (V_{CC} = +2.5 V, V_{EE} = -2.5 V, T_A = -40°C to +85°C, R_L = 100 Ω to GND, R_F = 1.2 k Ω , A_V = +2.0, Enable is left open, unless otherwise specified).

Symbol	Characteristic	Conditions	Min	Тур	Max	Unit
DC PERFO	RMANCE		•			
Vos	Offset Voltage		-4.0	± 0.5	+4.0	mV
$\Delta V_{IO}/\Delta T$	Input Offset Voltage Temperature Coefficient			6.0		μV/°C
I _{IB}	Input Bias Current	+Input (Non-Inverting), $V_O = 0 \text{ V}$ -Input (Inverting), $V_O = 0 \text{ V}$ (Note 5)	-4.0 -4.0	± 2.0 ± 0.4	+4.0 +4.0	μΑ
$\Delta I_{\text{IB}}/\Delta T$	Input Bias Current Temperature Coefficient	+Input (Non-Inverting), $V_O = 0 \text{ V}$ -Input (Inverting), $V_O = 0 \text{ V}$		±40 ±10		nA/°C
V _{IH}	Input High Voltage (Enable) (Note 5)		V _{CC} -1.5 V			V
V _{IL}	Input Low Voltage (Enable) (Note 5)				V _{CC} -3.5 V	V
NPUT CHA	RACTERISTICS					
V _{CM}	Input Common Mode Voltage Range (Note 5)		±1.3	± 1.5		V
CMRR	Common Mode Rejection Ratio	(See Graph)	50	55	65	dB
R _{IN}	Input Resistance	+Input (Non-Inverting) -Input (Inverting)		4.0 350		MΩ
C _{IN}	Differential Input Capacitance			1.0		pF
OUTPUT C	HARACTERISTICS					
R _{OUT}	Output Resistance			0.02		Ω
Vo	Output Voltage Swing		±1.1	±1.4		V
Ιο	Output Current		±40	±80		mA
POWER SU	IPPLY					
Vs	Operating Voltage Supply Range			5.0		V
I _{S,ON}	Power Supply Current – Enabled	V _O = 0 V	0.5	0.9	1.9	mA
I _{S,OFF}	Power Supply Current – Disabled	V _O = 0 V	0	0.05	0.3	mA
PSRR	Power Supply Rejection Ratio	(See Graph)	50	60	70	dB

5. Guaranteed by design and/or characterization.

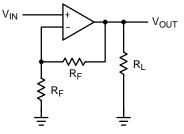


Figure 4. Typical Test Setup (A_V = +2.0, R_F = 1.8 k Ω or 1.2 k Ω or 1.0 k Ω , R_L = 100 Ω)

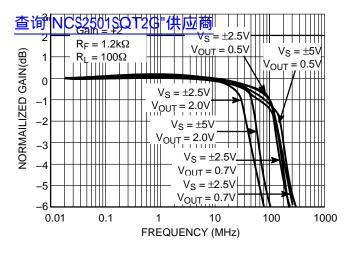


Figure 5. Frequency Response: Gain (dB) vs. Frequency Av = +2.0

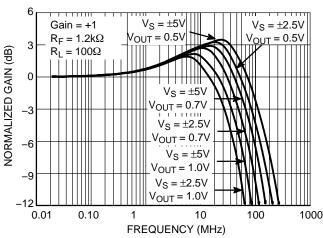


Figure 6. Frequency Response: Gain (dB) vs. Frequency Av = +1.0

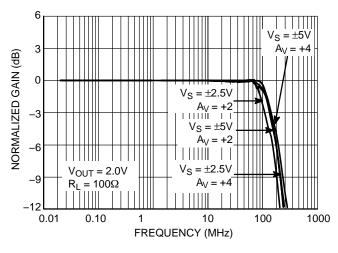


Figure 7. Large Signal Frequency Response Gain (dB) vs. Frequency

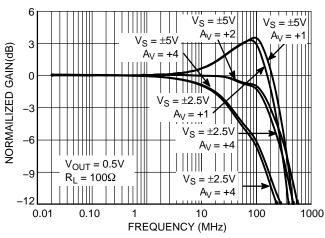


Figure 8. Small Signal Frequency Response Gain (dB) vs. Frequency

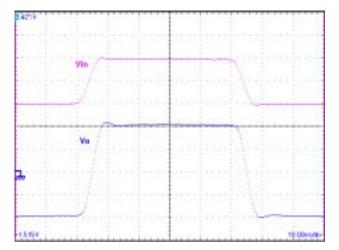


Figure 9. Small Signal Step Response Vertical: 500 mV/div Horizontal: 10 ns/div

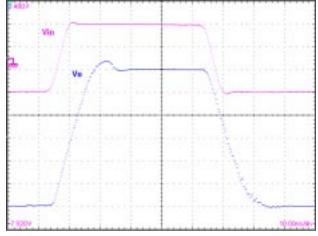
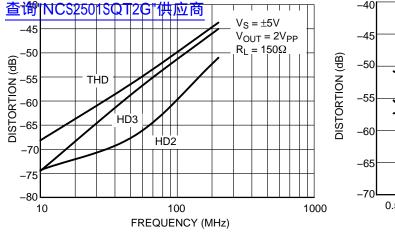


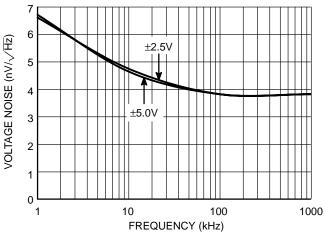
Figure 10. Large Signal Step Response Vertical: 500 mV/div Horizontal: 10 ns/div



 $V_{S} = \pm 5V$ V_{S

Figure 11. THD, HD2, HD3 vs. Frequency

Figure 12. THD, HD2, HD3 vs. Output Voltage



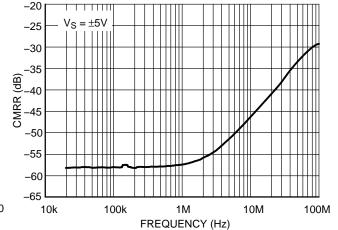
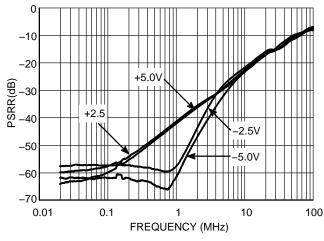


Figure 13. Input Referred Noise vs. Frequency

Figure 14. CMRR vs. Frequency



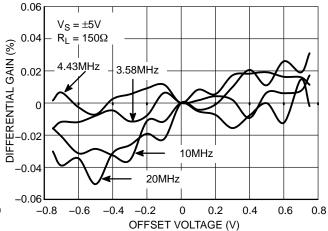
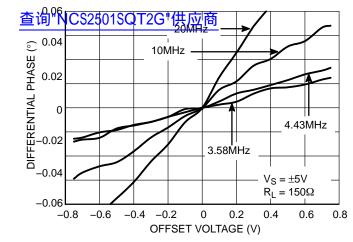


Figure 15. PSRR vs. Frequency

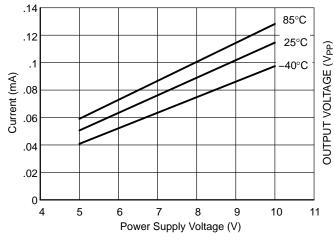
Figure 16. Differential Gain



1.4
1.3
1.2
25°C
1.1
1.0
0.9
0.8
0.7
0.6
4 5 6 7 8 9 10 11
Power Supply Voltage (V)

Figure 17. Differential Phase

Figure 18. Supply Current vs. Power Supply vs. Temperature (Enabled)



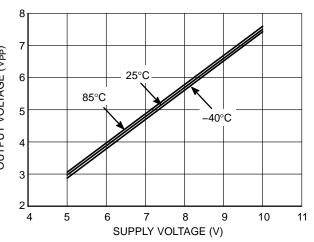
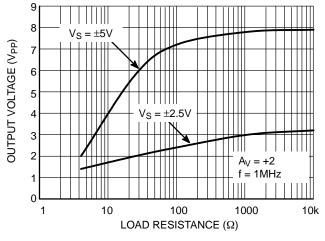


Figure 19. Supply Current vs. Power Supply vs. Temperature (Disabled)

Figure 20. Output Voltage Swing vs. Supply Voltage



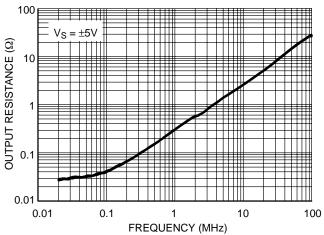


Figure 21. Output Voltage Swing vs. Load Resistance

Figure 22. Output Impedance vs. Frequency

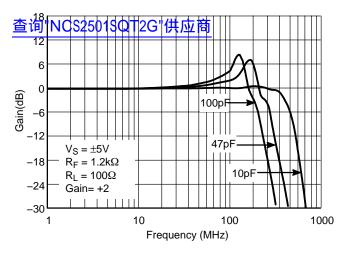


Figure 23. Frequency Response vs. CL

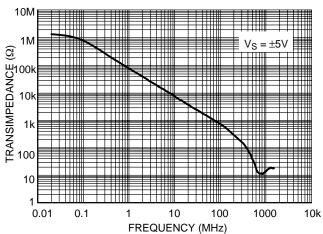


Figure 24. Transimpedance (ROL) vs. Frequency

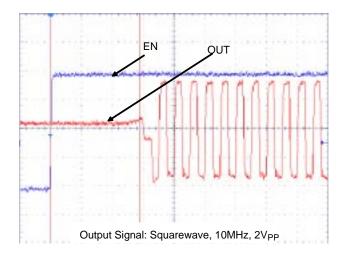


Figure 25. Turn ON Time Delay Horizontal: 4 ns / Div Vertical: 10mV/Div

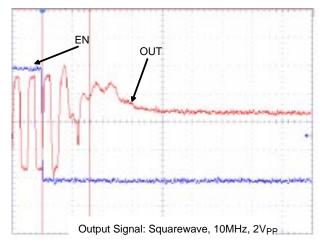


Figure 26. Turn OFF Time Delay Horizontal: 4 ns / Div Vertical: 10mV/Div

General Design Considerations

performance video and data acquisition systems. For current feedback architecture, its closed—loop bandwidth depends on the value of the feedback resistor. The closed—loop bandwidth is not a strong function of gain, as is for a voltage feedback amplifier, as shown in Figure 27.

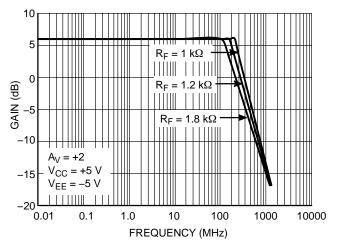


Figure 27. Frequency Response vs. R_F

The -3.0 dB bandwidth is, to some extent, dependent on the power supply voltages. By using lower power supplies, the bandwidth is reduced, because the internal capacitance increases. Smaller values of feedback resistor can be used at lower supply voltages, to compensate for this affect.

Feedback and Gain Resistor Selection for Optimum Frequency Response

A current feedback operational amplifier's key advantage is the ability to maintain optimum frequency response independent of gain by using appropriate values for the feedback resistor. To obtain a very flat gain response, the feedback resistor tolerance should be considered as well. Resistor tolerance of 1% should be used for optimum flatness. Normally, lowering RF resistor from its recommended value will peak the frequency response and extend the bandwidth while increasing the value of RF resistor will cause the frequency response to roll off faster. Reducing the value of RF

resistor too far below its recommended value will cause overshoot, ringing, and eventually oscillation.

Since each application is slightly different, it is worth some experimentation to find the optimal RF for a given circuit. A value of the feedback resistor that produces ~ 0.1 dB of peaking is the best compromise between stability and maximal bandwidth. It is not recommended to use a current feedback amplifier with the output shorted directly to the inverting input.

Printed Circuit Board Layout Techniques

Proper high speed PCB design rules should be used for all wideband amplifiers as the PCB parasitics can affect the overall performance. Most important are stray capacitances at the output and inverting input nodes as it can effect peaking and bandwidth. A space (3/16" is plenty) should be left around the signal lines to minimize coupling. Also, signal lines connecting the feedback and gain resistors should be short enough so that their associated inductance does not cause high frequency gain errors. Line lengths less than 1/4" are recommended.

Video Performance

This device designed to provide good performance with NTSC, PAL, and HDTV video signals. Best performance is obtained with back terminated loads as performance is degraded as the load is increased. The back termination reduces reflections from the transmission line and effectively masks transmission line and other parasitic capacitances from the amplifier output stage.

ESD Protection

This device is protected against electrostatic discharge (ESD) on all pins as specified in the attributes table. Note: Human Body Model for +IN and -IN pins are rated at 0.8 kV while all other pins are rated at 2.0 kV. Under closed-loop operation, the ESD diodes have no effect on circuit performance. However, under certain conditions the ESD diodes will be evident. If the device is driven into a slewing condition, the ESD diodes will clamp large differential voltages until the feedback loop restores closed-loop operation. Also, if the device is powered down and a large input signal is applied, the ESD diodes will conduct.

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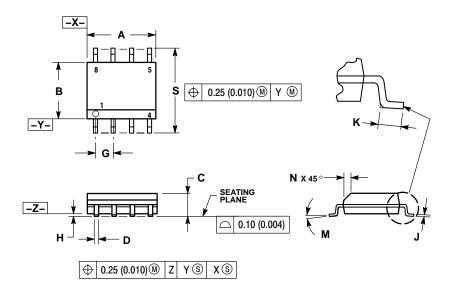
Device	Package	$Shipping^\dagger$
NCS2501SQT2*	SC70-6 (SC88)	3000 Tape & Reel
NCS2501SQT2G*	SC70-6 (SC88) (Pb-Free)	3000 Tape & Reel
NCS2501SNT1	SOT23-6 (TSOP-6)	3000 Tape & Reel
NCS2501SNT1G	SOT23-6 (TSOP-6) (Pb-Free)	3000 Tape & Reel
NCS2501D*	SO-8	98 Units/Rail
NCS2501DR2*	SO-8	2500 Tape & Reel
NCS2501DG*	SO-8 (Pb-Free)	98 Units/Rail
NCS2501DR2G*	SO-8 (Pb-Free)	2500 Tape & Reel

[†]For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specifications Brochure, BRD8011/D.

^{*}Contact ON Semiconductor for ordering information.

PACKAGE DIMENSIONS

SO-8 **D SUFFIX** CASE 751-07 **ISSUE AF**



NOTES:

- NOTES:

 1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.

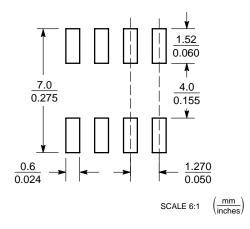
 2. CONTROLLING DIMENSION: MILLIMETER. 3. DIMENSION A AND B DO NOT INCLUDE MOLD PROTRUSION.
- MAXIMUM MOLD PROTRUSION 0.15 (0.006) PER SIDE.
- PER SIDE.

 5. DIMENSION D DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.127 (0.005) TOTAL IN EXCESS OF THE D DIMENSION AT MAXIMUM MATERIAL CONDITION.

 6. 751–01 THRU 751–06 ARE OBSOLETE. NEW STANDARD IS 751–07.

	MILLIN	IETERS	RS INCHES	
DIM	MIN	MAX	MIN	MAX
Α	4.80	5.00	0.189	0.197
В	3.80	4.00	0.150	0.157
С	1.35	1.75	0.053	0.069
D	0.33	0.51	0.013	0.020
G	1.27	BSC	0.05	0 BSC
Н	0.10	0.25	0.004	0.010
J	0.19	0.25	0.007	0.010
K	0.40	1.27	0.016	0.050
М	0 °	8 °	0 °	8 °
N	0.25	0.50	0.010	0.020
S	5.80	6.20	0.228	0.244

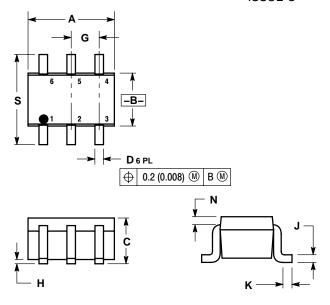
SOLDERING FOOTPRINT*



^{*}For additional information on our Pb-Free strategy and soldering details, please download the ON Semiconductor Soldering and Mounting Techniques Reference Manual, SOLDERRM/D.

PACKAGE DIMENSIONS

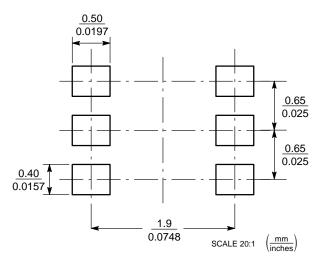
SC-70-6 (SC-88) **SQ SUFFIX** CASE 419B-02 ISSUE U



- NOTES:
 1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
 2. CONTROLLING DIMENSION: INCH.
 3. 419B-01 OBSOLETE, NEW STANDARD 419B-02.

	INC	HES	MILLIN	IETERS
DIM	MIN	MAX	MIN	MAX
Α	0.071	0.087	1.80	2.20
В	0.045	0.053	1.15	1.35
С	0.031	0.043	0.80	1.10
D	0.004	0.012	0.10	0.30
G	0.026	BSC	0.65 BSC	
Н		0.004		0.10
J	0.004	0.010	0.10	0.25
K	0.004	0.012	0.10	0.30
N	0.008 REF		0.20 REF	
S	0.079	0.087	2 00	2 20

SOLDERING FOOTPRINT*



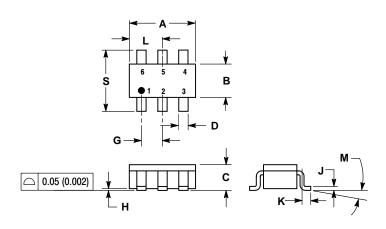
*For additional information on our Pb–Free strategy and soldering details, please download the ON Semiconductor Soldering and Mounting Techniques Reference Manual, SOLDERRM/D.

查询"NCS2501SQT2G"供应商

PACKAGE DIMENSIONS

SOT23-6 (TSOP-6) **SN SUFFIX** CASE 318G-02

ISSUE M



NOTES:

- NOTES.

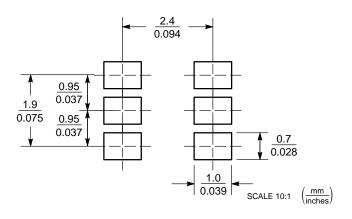
 1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.

 2. CONTROLLING DIMENSION: MILLIMETER.

 3. MAXIMUM LEAD THICKNESS INCLUDES
- LEAD FINISH THICKNESS. MINIMUM LEAD THICKNESS IS THE MINIMUM THICKNESS
- OF BASE MATERIAL.
 DIMENSIONS A AND B DO NOT INCLUDE
 MOLD FLASH, PROTRUSIONS, OR GATE

	MILLIN	IETERS	INC	HES
DIM	MIN	MAX	MIN	MAX
Α	2.90	3.10	0.1142	0.1220
В	1.30	1.70	0.0512	0.0669
С	0.90	1.10	0.0354	0.0433
D	0.25	0.50	0.0098	0.0197
G	0.85	1.05	0.0335	0.0413
Н	0.013	0.100	0.0005	0.0040
J	0.10	0.26	0.0040	0.0102
K	0.20	0.60	0.0079	0.0236
L	1.25	1.55	0.0493	0.0610
M	0 °	10 °	0 °	10°
S	2.50	3.00	0.0985	0.1181

SOLDERING FOOTPRINT*



*For additional information on our Pb-Free strategy and soldering details, please download the ON Semiconductor Soldering and Mounting Techniques Reference Manual, SOLDERRM/D.

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