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Stand-Alone Synchronous Switch-Mode Lithium Phosphate Battery Charger with Low Ia

Check for Samples: bq24620

FEATURES

- 300 kHz NMOS-NMOS Synchronous Buck Converter
- Stand-alone Charger Designed Specifically for Lithium Phosphate
- 5V–28V VCC Operating Range, Support 1-7 Battery Cells
- High-Accuracy Voltage and Current Regulation
 - ±0.5% Charge Voltage Accuracy
 - ±3% Charge Current Accuracy
- Integration
 - Internal Loop Compensation
 - Internal Soft Start
- Safety
 - Input Over-Voltage Protection
 - Battery Thermistor Sense Suspend Charge at Hot/Cold Charge Suspend and Automatically I_{CHARGE}/8 at WARM/COOL
 - Battery Detection
 - Built-in Safety Timer
 - Charge Over-Current Protection
 - Battery Short Protection
 - Battery Over-Voltage Protection
 - Thermal Shutdown
- Status Outputs
 - Adapter Present
 - Charger Operation Status
- Charge Enable Pin
- 6V Gate Drive for Synchronous Buck Converter
- 30ns Driver Dead-time and 99.95% Max Effective Duty Cycle
- 16-Pin 3.5×3.5-mm QFN Package
- Energy Star Low Iq
 - < 15 μA Off-State Battery Discharge Current
 - < 1.5 mA Off-State Input Quiescent Current</p>

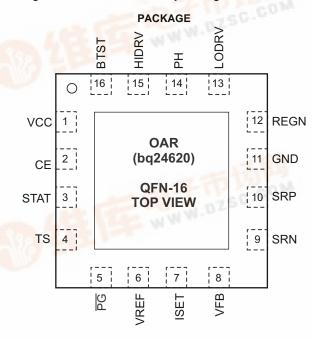
APPLICATIONS

- Power Tool and Portable Equipment
- Personal Digital Assistants
- Handheld Terminals
- Industrial and Medical Equipment
- Netbook, Mobile Internet Device and Ultra-Mobile PC

DESCRIPTION

The bq24620 is highly integrated switch-mode battery charge controller designed specifically for Lithium Phosphate battery. It offers a constant-frequency synchronous PWM controller with high accuracy current and voltage regulation, charge preconditioning, termination, and charge status monitoring.

The bq24620 charges the battery in three phases: preconditioning, constant current, and constant voltage. Charge is terminated when the current reaches a minimum level. An internal charge timer provides a safety backup. The bq24620 automatically restarts the charge cycle if the battery voltage falls below an internal threshold, and enters a low-quiescent current sleep mode when the input voltage falls below the battery voltage.





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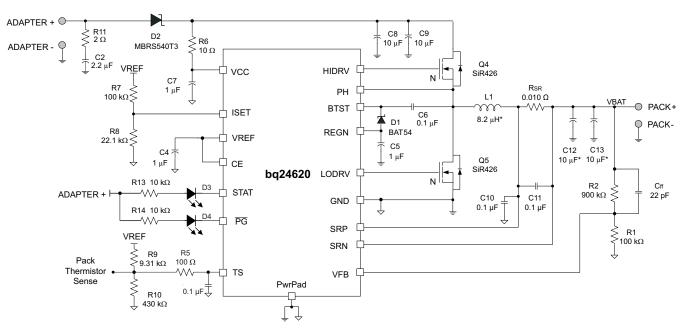




This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

TYPICAL APPLICATION



NOTE: VIN=28V, BAT=5-cell Li-Phosphate, I_{charge}=3A, I_{pre-charge}=0.125A, I_{term}=0.3A

Figure 1. Typical System Schematic

ORDERING INFORMATION

| PART NUMBER | IC MARKING | PACKAGE | ORDERING NUMBER (Tape and Reel) | QUANTITY |
|-------------|------------|-----------------------|------------------------------------|----------|
| bq24620 | OAR | 16-Pin 3.5×3.5 mm QFN | bq24620RVAR | 3000 |
| | OAR | | bq24620RVAT | 250 |

PACKAGE THERMAL DATA(1)

| PACKAGE | $\theta_{\sf JP}$ | θ_{JA} | T _A = 25°C POWER RATING | DERATING FACTOR ABOVE T _A = 25°C |
|---------------|-------------------|---------------|---------------------------------------|--|
| QFN – RVA (2) | 4.0°C/W | 43.8°C/W | 2.28W | 0.0228 W/°C |

⁽¹⁾ This data is based on using the JEDEC High-K board and the exposed die pad is connected to a Cu pad on the board. This is connected to the ground plane by a 2×2 via matrix. θ_{JA} has 5% improvement by 3x3 via matrix.

⁽²⁾ For the most current package and ordering information, see the Package Option Addendum at the end of this document, or see the TI Web site at www.ti.com.

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ABSOLUTE MAXIMUM RATINGS(1) (2) (3)

over operating free-air temperature range (unless otherwise noted)

| | | VALUE | UNIT |
|---|--|-------------|------|
| | VCC, SRP, SRN, CE, STAT, \overline{PG} | -0.3 to 33 | V |
| | PH | -2 to 36 | V |
| Voltage renge | VFB | -0.3 to 16 | V |
| Voltage range | REGN, LODRV, TS | -0.3 to 7 | V |
| | BTST, HIDRV with respect to GND | -0.3 to 39 | V |
| | VREF, ISET | -0.3 to 3.6 | V |
| Maximum difference voltage | SRP-SRN | -0.5 to 0.5 | V |
| Junction temperature range, T _J | | -40 to 155 | °C |
| Storage temperature range, T _{stg} | | -55 to 155 | °C |

⁽¹⁾ Stresses beyond those listed under absolute maximum ratings may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under recommended operating conditions is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

RECOMMENDED OPERATING CONDITIONS

| | | | VALUE | UNIT |
|------------------|---|--|-------------|------|
| | | VCC, SRP, SRN, CE, STAT, \overline{PG} | -0.3 to 28 | V |
| | Voltage range PH VFB REGN, LODRV, TS | -2 to 30 | V | |
| | Voltage reage | VFB | -0.3 to 14 | V |
| | voltage range | REGN, LODRV, TS | -0.3 to 6.5 | V |
| | | BTST, HIDRV with respect to GND | -0.3 to 34 | V |
| | | ISET | -0.3 to 3.3 | V |
| | | VREF | 3.3 | V |
| | Maximum difference voltage | SRP-SRN | -0.2 to 0.2 | V |
| TJ | Junction temperature range | | 0 to 125 | °C |
| T _{stg} | Storage temperature range | | -55 to 155 | °C |

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All voltages are with respect to GND if not specified. Currents are positive into, negative out of the specified terminal. Consult Packaging Section of the data book for thermal limitations and considerations of packages.

⁽³⁾ Must have a series resistor between battery pack to VFB if Battery Pack voltage is expected to be greater than 16V. Usually the resistor divider top resistor will take care of this.



ELECTRICAL CHARACTERISTICS

 $5.0V \le V(VCC) \le 28V$, $0^{\circ}C < T_J < +125^{\circ}C$, typical values are at $T_A = 25^{\circ}C$, with respect to GND unless otherwise noted

| | PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|--------------------------|--|---|-------------------------------|-------------------------|------|----------|
| OPERATING | CONDITIONS | | | | | |
| V _{VCC_OP} | VCC Input voltage operating range | | 5.0 | | 28.0 | V |
| QUIESCENT | CURRENTS | | | | , | |
| I _{BAT} | Total battery discharge current (sum of currents into VCC, BTST, PH, SRP, SRN, VFB), VFB ≤2.1 V | V _{VCC} < V _{SRN} , V _{VCC} > V _{UVLO} (SLEEP) | | | 15 | μА |
| | | V _{VCC} > V _{SRN} , V _{VCC} > V _{UVLO} CE = LOW (IC quiescent current) | | 1 | 1.5 | |
| I _{AC} | Adapter supply current (current into VCC pin) | $V_{VCC} > V_{SRN}$, $V_{VCC} > V_{VCCLOW}$, CE = HIGH, charge done | | 2 | 5 | mA |
| | | $V_{VCC} > V_{SRN}$, $V_{VCC} > V_{VCCLOW}$, CE = HIGH, Charging, Qg_total = 20 nC, V_{VCC} =20V | | 12 | | |
| CHARGE VO | OLTAGE REGULATION | | | | | |
| V_{FB} | Feedback regulation voltage | | | 1.8 | | V |
| | Charge voltage regulation accuracy | $T_J = 0$ °C to 85°C $T_J = -40$ °C to 125°C | -0.5% -0.7% | | 0.5% | |
| I _{VFB} | Input leakage current into VFB pin | VFB = 1.8 V | 070 | | 100 | nA |
| | REGULATION – FAST CHARGE | | | | .00 | |
| V _{ISET} | ISET voltage range | | 0 | | 2 | V |
| VISET | SRP–SRN current sense voltage range | V _{IREG} CHG = V _{SRP} - V _{SRN} | 0 | | 100 | mV |
| K _{ISET} | Charger current set factor amps of charge current per volt on ISET pin) | $R_{SENSE} = 10 \text{ m}\Omega$ | 0 | 5 | 100 | A/V |
| | charge carrent per voit on 102 i pini | V _{IREG CHG} = 40 mV | -3% | | 3% | |
| | | V _{IREG_CHG} = 40 mV | -4% | | 4% | |
| | Charge current regulation accuracy | V _{IREG_CHG} = 20 mV | -25% | | 25% | |
| | | V _{IREG_CHG} = 3.11V V _{IREG_CHG} = 1.5 mV (V _{SRN} > 3.1V) | -40% | | 40% | |
| 1 | Leakage current in to ISET Pin | V _{ISET} = 2 V | -40 / ₆ | | 100 | nA |
| I _{ISET} | REGULATION - PRECHARGE | VISET = Z V | | | 100 | IIA |
| CORRENT R | | P = 10 m0 \/FR < \/ | 50 | 125 | 200 | mA |
| CHARGE TE | Precharge current | $R_{SENSE} = 10 \text{ m}\Omega, VFB < V_{LOWV}$ | 50 | 120 | 200 | IIIA |
| CHARGE IE | ERMINATION Termination current range | P - 10 m0 | | 1 /10 | | A |
| K _{TERM} | Termination current range Termination current set factor (amps of termination current per yell on ISET pin) | $R_{SENSE} = 10 \text{ m}\Omega$ | | I _{CHARGE} /10 | | A/V |
| | termination current per volt on ISET pin) | \(\text{ - 10 m\/} | -10% | | 10% | |
| | Termination autrent accuracy | $V_{ITERM} = 10 \text{ mV}$ $V_{ITERM} = 5 \text{ mV}$ | | | 25% | |
| | Termination current accuracy | | -25% | | | |
| | Deglitch time for termination (both | V _{ITERM} = 1.5 mV | -45% | 100 | 45% | ms |
| + | edge) Termination qualification time | V > V and I | | 250 | | me |
| t _{QUAL} | · | V _{BAT} > V _{RECH} and I _{CHARGE} < I _{TERM} Discharge current once termination is detected | | 230 | | ms m^ |
| INDUT LIND | Termination qualification time | , , | | | | mA |
| | ER-VOLTAGE LOCK-OUT COMPARATOR | <u> </u> | 2.05 | 2.05 | 4 | 1/ |
| V _{UVLO} | AC under voltage hystoresis falling | Measure on VCC | 3.65 | 3.85 | 4 | V |
| V _{UVLO_HYS} | AC under-voltage hysteresis, falling | | | 350 | | mV |
| ACC FOMA | COMPARATOR | Managers on VCC | | 4.4 | | |
| | Falling threshold, disable charge | Measure on VCC | | 4.1 | 4.5 | V |
| el EED CO | Rising threshold, resume charge | OTECTION) | | 4.35 | 4.5 | V |
| | IPARATOR (REVERSE DISCHARGING PR | | 40 | 400 | 450 | |
| V _{SLEEP _FALL} | SLEEP falling threshold | V _{VCC} – V _{SRN} to enter SLEEP | 40 | 100 | 150 | mV |
| V _{SLEEP_HYS} | SLEEP hysteresis | V00 felling halow 00th 11 1 2 2 | | 500 | | mV |
| | SLEEP rising delay | VCC falling below SRN, delay to pull up PG | | 1 | | μs |
| | SLEEP falling delay | VCC rising above SRN, delay to pull down PG | | 30 | | ms |
| | SLEEP rising shutdown deglitch | VCC falling below SRN, Delay to enter SLEEP mode | | 100 | | ms |



ELECTRICAL CHARACTERISTICS (continued)

 $5.0 \text{V} \leq \text{V(VCC)} \leq 28 \text{V}, \ 0^{\circ}\text{C} < \text{T}_{\text{J}} < +125^{\circ}\text{C}, \text{typical values are at T}_{\text{A}} = 25^{\circ}\text{C}, \ \text{with respect to GND unless otherwise noted}$

| | PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|-----------------------|---|--|-------|------------------------|-------|------|
| | SLEEP falling powerup deglitch | VCC rising above SRN, Delay to come out of SLEEP mode | | 30 | | ms |
| BAT LOWV | COMPARATOR | | | | | |
| V_{LOWV} | LOWV rising threshold (Precharge to Fast Charge) | Measured on VFB pin | 0.333 | 0.35 | 0.367 | V |
| V_{LOWV_HYS} | LOWV hysteresis | | | 100 | | mV |
| | LOWV rising deglitch | VFB falling below V _{LOWV} | | 25 | | ms |
| | LOWV falling deglitch | VFB rising above V _{LOWV} + V _{LOWV_HYS} | | 25 | | ms |
| RECHARGE | COMPARATOR | | | | | |
| V_{RECHG} | Recharge threshold (with respect to V_{REG}) | Measured on VFB pin | 110 | 125 | 140 | mV |
| | Recharge rising deglitch | VFB decreasing below V _{RECHG} | | 10 | | ms |
| | Recharge falling deglitch | VFB increasing above V _{RECHG} | | 10 | | ms |
| BAT OVER-V | OLTAGE COMPARATOR | | | | | |
| V_{OV_RISE} | Over-voltage rising threshold | As percentage of V _{FB} | | 108% | | |
| V_{OV_FALL} | Over-voltage falling threshold | As percentage of V _{FB} | | 105% | | |
| INPUT OVER | -VOLTAGE COMPARATOR (ACOV) | | | | | |
| V_{ACOV} | AC over-voltage rising threshold on VCC | | 31.04 | 32 | 32.96 | V |
| V _{ACOV_HYS} | AC over-voltage falling hysteresis | | | 1000 | | mV |
| | AC Over-Voltage Rising Deglitch | Delay to changing the STAT pins | | 1 | | ms |
| | AC Over-Voltage Falling Deglitch | Delay to changing the STAT pins | | 1 | | ms |
| THERMAL S | HUTDOWN COMPARATOR | | | | | |
| T _{SHUT} | Thermal shutdown rising temperature | Temperature increasing | | 145 | | °C |
| | Thermal shutdown hysteresis | | | 15 | | °C |
| T _{SHUT_HYS} | Thermal shutdown rising deglitch | Temperature increasing | | 100 | | μS |
| | Thermal shutdown falling deglitch | Temperature decreasing | | 10 | | ms |
| THERMISTO | R COMPARATOR | | | | , | |
| V_{LTF} | Cold temperature rising threshold | Charger suspended below this temperature | 72.5% | 73.5% | 74.5% | |
| V _{LTF_HYS} | Cold temperature hysteresis | | 0.2% | 0.4% | 0.6% | |
| V _{COOL} | Cool Temperature rising threshold | Charger enabled, cuts back to I _{CHARGE} /8 below this temperature | 70.2% | 70.7% | 71.2% | |
| V _{COOL_HYS} | Cool temperature hysteresis | | 0.2% | 0.6% | 1.0% | |
| V_{WARM} | Warm temperature rising threshold | Charger cuts back to I _{CHARGE} /8 above this temperature | 47.5% | 48% | 48.5% | |
| V _{WARM_HYS} | Warm temperature hysteresis | | 1.0% | 1.2% | 1.4% | |
| V_{HTF} | Hot temperature rising threshold | Charger suspended above this temperature before initiating charge | 36.2% | 37% | 37.8% | |
| V _{TCO} | Cut-off temperature rising threshold | Charger suspended above this temperature during initiating charge | 33.7% | 34.4% | 35.1% | |
| | Deglitch time for Temperature Out of Range Detection | $V_{TS} > V_{LTF}$, or $V_{TS} < V_{TCO}$, or $V_{TS} < V_{HTF}$ | | 400 | | ms |
| | Deglitch time for Temperature in Valid Range Detection | $V_{TS} < V_{LTF} - V_{LTF_HYS}$ or $V_{TS} > V_{TCO}$, or $V_{TS} > V_{HTF}$ | | 20 | | ms |
| | Deglitch time for current reduction to I _{CHARGE} /8 due to warm or cool temperature | $V_{TS} > V_{COOL}$, or $V_{TS} < V_{WARM}$ | | 25 | | ms |
| | Deglitch time to charge at I _{CHARGE} from I _{CHARGE} /8 when resuming from warm or cool temperatures | V _{TS} < V _{COOL} - V _{COOL_HYS} , or V _{TS} > V _{WARM} - V _{WARM_HYS} | | 25 | | ms |
| | Charge current due to warm or cool temperatures | $V_{COOL} < V_{TS} < V_{LTF}$, or $V_{WARM} < V_{TS} < V_{HTF}$, or $V_{WARM} < V_{TS} < V_{TCO}$ | | I _{CHARGE} /8 | | |

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ELECTRICAL CHARACTERISTICS (continued)

 $5.0V \le V(VCC) \le 28V$, $0^{\circ}C < T_{J} < +125^{\circ}C$, typical values are at $T_{A} = 25^{\circ}C$, with respect to GND unless otherwise noted

| | PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|---------------------------|--|--|-------|------|-------|------|
| CHARGE OVE | ER-CURRENT COMPARATOR (CYCLE-B | Y-CYCLE) | | | | |
| | Charge over-current falling threshold | Current rising, in non-synchronous mode, measure on V _(SRP-SRN) , V _{SRP} < 2 V | | 45.5 | | mV |
| V | Charge over-current failing threshold | Current rising, as percentage of $V_{(IREG_CHG)}$, in synchronous mode, $V_{SRP} > 2.2V$ | | 160% | | |
| V _{oc} | Charge over-current threshold floor | $\begin{array}{l} \mbox{Minimum OCP threshold in synchronous mode,} \\ \mbox{measure on V}_{(\mbox{SRP-SRN})}, \mbox{V}_{\mbox{SRP}} > 2.2 \mbox{V} \end{array}$ | | 50 | | mV |
| | Charge over-current threshold ceiling | Maximum OCP threshold in synchronous mode, measure on V _(SRP-SRN) , V _{SRP} > 2.2V | | 180 | | mV |
| CHARGE UNI | DER-CURRENT COMPARATOR (CYCLE- | BY-CYCLE) | | | | |
| V _{ISYNSET} | Charge under-current falling threshold | Switch from STNCH to NON-SYNCH, V _{SSP} > 2.2 V | 1 | 5 | 9 | mV |
| BATTERY SH | ORTED COMPARATOR (BATSHORT) | | | | | |
| V _{BATSHT} | BAT Short falling threshold, forced non-syn mode | V _{SRP} falling | | 2 | | ٧ |
| V _{BATSHT HYS} | BAT short rising hysteresis | | | 200 | | mV |
| V _{BATSHT_DEG} | Deglitch on both edge | | | 1 | | μS |
| | E CURRENT COMPARATOR | - | | | | |
| V _{LC} | Average low charge current falling threshold | Measure on V _(SRP-SRN) , forced into non-synchronous mode | | 1.25 | | mV |
| V _{LC_HYS} | Low charge current rising hysteresis | | | 1.25 | | mV |
| V _{LC DEG} | Deglitch on both edge | | | 1 | | μS |
| VREF REGUL | .ATOR | - | | | * | |
| V _{VREF REG} | VREF regulator voltage | V _{VCC} > V _{UVLO} (0 – 35 mA Load) | 3.267 | 3.3 | 3.333 | V |
| I _{VREF LIM} | VREF current limit | V _{VREF} = 0 V, V _{VCC} > V _{UVLO} | 35 | | | mA |
| | | REGN REGULATOR | | | I | |
| V _{REGN REG} | REGN regulator voltage | V _{VCC} > 10 V, CE = HIGH (0 – 40 mA Load) | 5.7 | 6.0 | 6.3 | V |
| I _{REGN_LIM} | REGN current limit | V _{REGN} = 0 V, V _{VCC} > V _{UVLO} | 40 | | | mA |
| | D. J. (1) | SAFETY TIMER | 4440 | 4000 | 0400 | |
| T _{PRECHG} | Precharge safety timer range ⁽¹⁾ | Precharge time before fault occurs | 1440 | 1800 | 2160 | sec |
| T _{CHARGE} | Internal fast charge safety timer ⁽¹⁾ | | 4.25 | 5 | 5.75 | Hr |
| BATTERY DE | | | | | | |
| t _{WAKE} | Wake timer | Max time charge is enabled | | 500 | 000 | ms |
| I _{WAKE} | Wake Current | $R_{SENSE} = 10 \text{ m}\Omega$ | 50 | 125 | 200 | mA |
| t _{DISCHARGE} | Discharge timer | Max time discharge current is applied | | 1 | | sec |
| DISCHARGE | Discharge current | | | 8 | | mA |
| I _{FAULT} | Fault current after a timeout fault | | | 2 | | mA |
| V_{WAKE} | Wake threshold (w.r.t. V _{REG}) | Voltage on VFB to detect battery absent during Wake | | 125 | | mV |
| V _{DISCH} | Discharge threshold | Voltage on VFB to detect battery absent during Discharge | | 0.35 | | V |
| PWM HIGH S | IDE DRIVER (HIDRV) | | | | т | |
| R _{DS_HI_ON} | High Side driver (HSD) turn-on resistance | V _{BTST} - V _{PH} = 5.5 V | | 3.3 | 6 | Ω |
| R _{DS_HI_OFF} | High Side driver turn-off resistance | $V_{BTST} - V_{PH} = 5.5 \text{ V}$ | | 1 | 1.3 | Ω |
| V _{BTST_REFRESH} | Bootstrap refresh comparator threshold voltage | $V_{BTST} - V_{PH}$ when low side refresh pulse is requested | 4 | 4.2 | | V |
| PWM LOW SI | DE DRIVER (LODRV) | | | | | |
| R _{DS_LO_ON} | Low side driver (LSD) turn-on resistance | | | 4.1 | 7 | Ω |
| R _{DS_LO_OFF} | Low side driver turn-off resistance | | | 1 | 1.4 | Ω |
| PWM DRIVER | RS TIMING | | | | | |
| | Driver dead time | Dead time when switching between LSD and HSD, no load at LSD and HSD | | 30 | | ns |
| | | | | | | |

(1) Verified by design

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ELECTRICAL CHARACTERISTICS (continued)

 $5.0V \le V(VCC) \le 28V$, $0^{\circ}C < T_{J} < +125^{\circ}C$, typical values are at $T_{\Delta} = 25^{\circ}C$, with respect to GND unless otherwise noted

| | PARAMETER | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|--------------------------|--|--|-----|-----|----------|------|
| PWM OSCILL | ATOR | | | | <u>'</u> | |
| V _{RAMP_HEIGHT} | PWM ramp height | As percentage of VCC | | 7% | | |
| | PWM switching frequency ⁽²⁾ | | 255 | 300 | 345 | kHz |
| | INTERNAI | SOFT START (8 steps to regulation current I _{CHARGE} |) | | | |
| | Soft start steps | | | 8 | | step |
| | Soft start step time | | | 1.6 | | ms |
| CHARGER SE | CTION POWER-UP SEQUENCING | | | | | |
| | Charge-enable delay after power-up | Delay from when CE = 1 to when the charger is allowed to turn on | | 1.5 | | s |
| LOGIC IO PIN | CHARACTERISTICS | | | | | |
| V _{IN_LO} | CE input low threshold voltage | | | | 0.8 | V |
| V _{IN_HI} | CE input high threshold voltage | | 2.1 | | | V |
| V _{BIAS_CE} | CE input bias current | V = 3.3 V (CE has internal 1MΩ pulldown resistor) | | | 6 | μА |
| V _{OUT_LO} | STAT, PG output low saturation voltage | Sink current = 5 mA | | | 0.5 | V |
| I _{OUT HI} | Leakage Current | V = 32V | | | 1.2 | μA |

⁽²⁾ Verified by design



TYPICAL CHARACTERISTICS

Table 1. Table of Graphs

| | Figure |
|--|-----------|
| REF REGN and PG Power Up (CE=1) | Figure 2 |
| Charge Enable | Figure 3 |
| Current Soft-Start (CE=1) | Figure 4 |
| Charge Disable | Figure 5 |
| Continuous Conduction Mode Switching Waveforms | Figure 6 |
| Cycle-by-Cycle Synchronous to Nonsynchronous | Figure 7 |
| Battery Insertion | Figure 8 |
| Battery to Ground Short Protection | Figure 9 |
| Efficiency vs Output Current | Figure 10 |

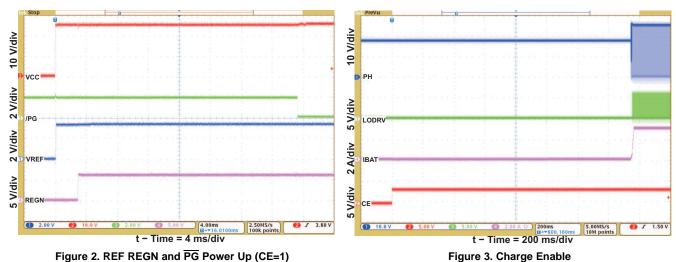


Figure 2. REF REGN and PG Power Up (CE=1)

10 V/div 5 V/div 2 V/div 2 A/div 0μs -2.76000μs 2.50GS/s 100k points 3 1.20 V t - Time = 4 μs/div

Figure 4. Current Soft-Start (CE=1)

t - Time = 4 ms/div

Figure 5. Charge Disable

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10 V/div

5 V/div

2 A/div

5 V/div

CE

LODRY

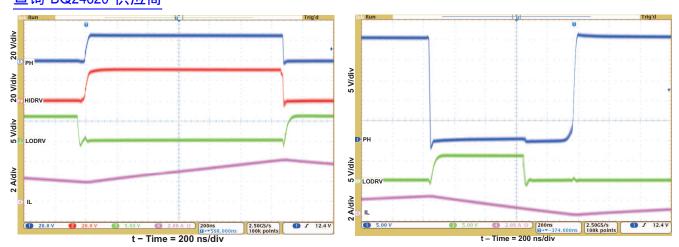


Figure 6. Continuous Conduction Mode Switching Waveform

Figure 7. Cycle-by-Cycle Synchronous to Nonsynchronous

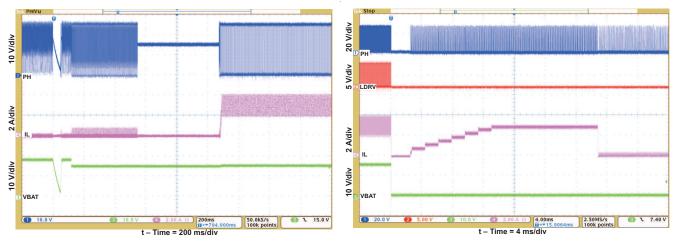


Figure 8. Battery Insertion

Figure 9. Battery to GND Short Protection

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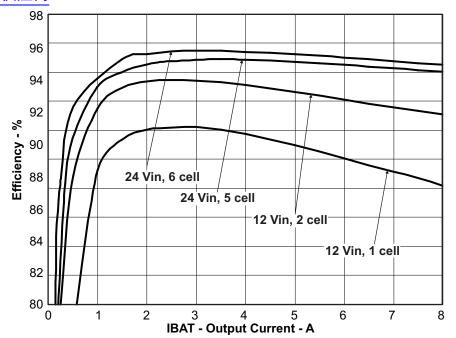


Figure 10. Efficiency vs Output Current

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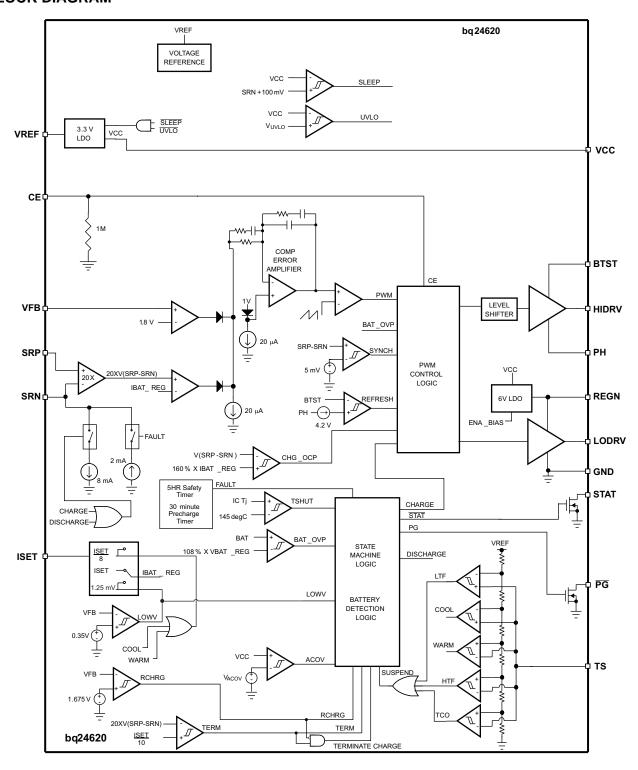
PIN FUNCTIONS

| | PIN | |
|-----|----------|---|
| NO. | NAME | FUNCTION DESCRIPTION |
| 1 | VCC | IC power positive supply. Connect, through a 10 Ω resistor to the common-source (diode-OR) point: source of high-side P-channel MOSFET and source of reverse-blocking power P-channel MOSFET. Or connect through a 10 Ω resistor to the cathode of the input diode. Place a 1- μ F ceramic capacitor from VCC to GND pin close to the IC. |
| 2 | CE | Charge-enable active-HIGH logic input. HI enables charge. LO disables charge. It has an internal $1M\Omega$ pull-down resistor. |
| 3 | STAT | Open-drain charge status pin to indicate various charger operation (See Table 3) |
| 4 | TS | Temperature qualification voltage input for battery pack negative temperature coefficient thermistor. Program the hot and cold temperature window with a resistor divider from VREF to TS to GND. |
| 5 | PG | Open-drain power-good status output. The transistor turns on when a valid VCC is detected. It is turned off in the sleep mode. PG can be used to drive a LED or communicate with a host processor. It can be used to drive ACFET and BATFET. |
| 6 | VREF | 3.3V regulated voltage output. Place a 1-μF ceramic capacitor from VREF to GND pin close to the IC. This voltage could be used for programming of voltage and current regulation and for programming the TS threshold. |
| 7 | ISET | Charge current set input. The voltage of ISET pin programs the charge current regulation, pre-charge current and termination current set-point. |
| 8 | VFB | Output voltage analog feedback adjustment. Connect the output of a resistive voltage divider from the battery terminals to this node to adjust the output battery regulation voltage. |
| 9 | SRN | Charge current sense resistor, negative input. A 0.1-μF ceramic capacitor is placed from SRN to SRP to provide differential-mode filtering. An optional 0.1-μF ceramic capacitor is placed from SRN pin to GND for common-mode filtering. |
| 10 | SRP | Charge current sense resistor, positive input. A 0.1-μF ceramic capacitor is placed from SRN to SRP to provide differential-mode filtering. A 0.1-μF ceramic capacitor is placed from SRP pin to GND for common-mode filtering. |
| 11 | GND | Low-current sensitive analog/digital ground. On PCB layout, connect with PowerPad underneath the IC. |
| 12 | REGN | PWM low side driver positive 6V supply output. Connect a $1-\mu F$ ceramic capacitor from REGN to PGND pin, close to the IC. Use for low side driver and high-side driver bootstrap voltage by connecting a small signal Schottky diode from REGN to BTST. |
| 13 | LODRV | PWM low side driver output. Connect to the gate of the low-side power MOSFET with a short trace. |
| 14 | PH | PWM high side driver negative supply. Connect to the Phase switching node (junction of the low-side power MOSFET drain, high-side power MOSFET source, and output inductor). Connect the 0.1μF bootstrap capacitor from PH to BTST. |
| 15 | HIDRV | PWM high side driver output. Connect to the gate of the high-side power MOSFET with a short trace. |
| 16 | BTST | PWM high side driver negative supply. Connect to the Phase switching node (junction of the low-side power MOSFET drain, high-side power MOSFET source, and output inductor). Connect the 0.1μF bootstrap capacitor from SW to BTST |
| | PowerPad | Exposed pad beneath the IC. Always solder PowerPad to the board, and have vias on the PowerPad plane star-connecting to GND and ground plane for high-current power converter. It also serves as a thermal pad to dissipate the heat. |

Product Folder Link(s): bq24620

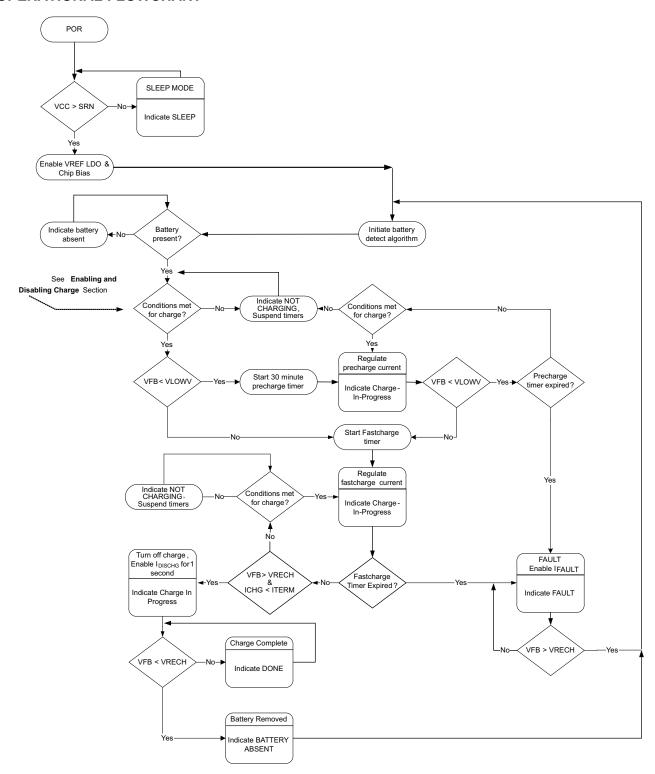


BLOCK DIAGRAM



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OPERATIONAL FLOWCHART





DETAILED DESCRIPTION

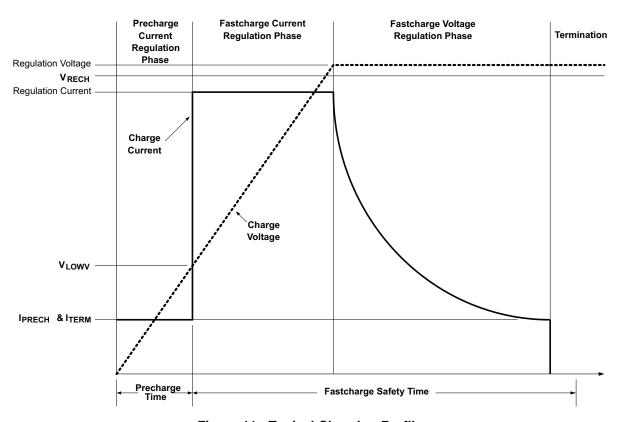


Figure 11. Typical Charging Profile

BATTERY VOLTAGE REGULATION

The bq24620 uses a high accuracy voltage bandgap and regulator for the charging voltage. The charge voltage is programmed via a resistor divider from the battery to ground, with the midpoint tied to the VFB pin. The voltage at the VFB pin is regulated to 1.8V, giving Equation 1 for the regulation voltage:

$$V_{BAT} = 1.8 \text{ V} \times \left[1 + \frac{R2}{R1}\right] \tag{1}$$

where R2 is connected from VFB to the battery and R1 is connected from VFB to GND

BATTERY CURRENT REGULATION

The ISET1 input sets the maximum charging current. Battery current is sensed by resistor R_{SR} connected between SRP and SRN. The full-scale differential voltage between SRP and SRN is 100mV. Thus, for a 10m Ω sense resistor, the maximum charging current is 10A. Equation 2 is for charge current

$$I_{CHARGE} = \frac{V_{ISET}}{20 \times R_{SR}}$$
 (2)

 V_{ISET} , The input voltage range of ISET is between 0 and 2V. The SRP and SRN pins are used to sense voltage across R_{SR} with default value of $10m\Omega$. However, resistors of other values can also be used. A larger sense resistor will give a larger sense voltage, a higher regulation accuracy; but, at the expense of higher conduction loss.

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PRECHARGE

On power-up, if the battery voltage is below the V_{LOWV} threshold, the bq24620 applies 125mA to the battery⁽¹⁾ The precharge feature is intended to revive deeply discharged cells. If the V_{LOWV} threshold is not reached within 30 minutes of initiating precharge, the charger turns off and a FAULT is indicated on the status pins.

CHARGE TERMINATION, RECHARGE, AND SAFETY TIMER

The bq24620 monitors the charging current during the voltage regulation phase. Termination is detected while the voltage on the VFB pin is higher than the V_{RECH} threshold AND the charge current is less than the I_{TERM} threshold, which is 1/10th of programmed charge current, as calculated in Equation 3:

$$I_{TERM} = \frac{V_{ISET}}{200 \times R_{SR}}$$
 (3)

As a safety backup, the bq24620 also provides an internal 5 hour charge timer for fast charge.

A new charge cycle is initiated when one of the following conditions occur:

- The battery voltage falls below the recharge threshold.
- A power-on-reset (POR) event occurs.
- CE is toggled.

POWER UP

The bg24620 uses a SLEEP comparator to determine the source of power on the VCC pin, since VCC can be supplied either from the battery or the adapter. If the VCC voltage is greater than the SRN voltage, bq24620 will enable the ACFET and disable BATFET. If all other conditions are met for charging, bq24620 will then attempt to charge the battery (See Enabling and Disabling Charging). If the SRN voltage is greater than VCC, indicating that the battery is the power source, bq24620 enters a low quiescent current (<15µA) SLEEP mode to minimize current drain from the battery.

If VCC is below the UVLO threshold, the device is disabled.

ENABLE AND DISABLE CHARGING

The following conditions have to be valid before charge is enabled:

- CE is HIGH.
- The device is not in VCCLOWV mode.
- The device is not in SLEEP mode (i.e., VCC > SRN).
- The VCC voltage is lower than the AC over-voltage threshold (VCC $< V_{ACOV}$).
- 30 ms delay is complete after initial power-up.
- The REGN LDO and VREF LDO voltages are at the correct levels.
- Thermal Shut (TSHUT) is not valid.
- TS fault is not detected.

One of the following conditions will stop on-going charging

- CE is LOW.
- Adapter is removed, causing the device to enter VCCLOWV or SLEEP mode.
- Adapter voltage is less than 100mV above battery.
- Adapter is over voltage.
- The REGN or VREF LDOs are overloaded.
- TSHUT IC temperature threshold is reached (145°C on rising-edge with 15°C hysteresis).
- TS voltage goes out of range indicating the battery temperature is too hot or too cold.
- Safety timer times out.

(1) 125mA (assuming a 10mΩ sense resistor. 1.25mV will be regulated across SRP-SRN, regardless of the value of the sense resistor.)



AUTOMATIC INTERNAL SOFT-START CHARGER CURRENT

The charger automatically soft-starts the charger regulation current every time the charger goes into fast-charge to ensure there is no overshoot or stress on the output capacitors or the power converter. The soft-start consists of stepping-up the charge regulation current into 8 evenly divided steps up to the programmed charge current. Each step lasts around 1.6ms, for a typical rise time of 12.8ms. No external components are needed for this function.

CONVERTER OPERATION

The synchronous buck PWM converter uses a fixed frequency voltage mode with feed-forward control scheme. A type III compensation network allows using ceramic capacitors at the output of the converter. The compensation input stage is connected internally between the feedback output (FBO) and the error amplifier input (EAI). The feedback compensation stage is connected between the error amplifier input (EAI) and error amplifier output (EAO). The LC output filter is selected to give a resonant frequency of 10 kHz – 15 kHz for bq24620, where resonant frequency, f_o, is given by:

$$f_{o} = \frac{1}{2\pi\sqrt{L_{o}C_{o}}} \tag{4}$$

An internal saw-tooth ramp is compared to the internal EAO error control signal to vary the duty-cycle of the converter. The ramp height is 7% of the input adapter voltage making it always directly proportional to the input adapter voltage. This cancels out any loop gain variation due to a change in input voltage, and simplifies the loop compensation. The ramp is offset by 300mV in order to allow zero percent duty-cycle when the EAO signal is below the ramp. The EAO signal is also allowed to exceed the saw-tooth ramp signal in order to get a 100% duty-cycle PWM request. Internal gate drive logic allows achieving 99.95% duty-cycle while ensuring the N-channel upper device always has enough voltage to stay fully on. If the BTST pin to PH pin voltage falls below 4.2V for more than 3 cycles, then the high-side n-channel power MOSFET is turned off and the low-side n-channel power MOSFET is turned on to pull the PH node down and recharge the BTST capacitor. Then the high-side driver returns to 100% duty-cycle operation until the (BTST-PH) voltage is detected to fall low again due to leakage current discharging the BTST capacitor below the 4.2 V, and the reset pulse is reissued.

The fixed frequency oscillator keeps tight control of the switching frequency under all conditions of input voltage, battery voltage, charge current, and temperature, simplifying output filter design and keeping it out of the audible noise region. Also see *Application Information* for how to select Inductor, capacitor and MOSFET.

SYNCHRONOUS AND NON-SYNCHRONOUS OPERATION

The charger operates in synchronous mode when the SRP-SRN voltage is above 5mV (0.5A inductor current for a $10m\Omega$ sense resistor). During synchronous mode, the internal gate drive logic ensures there is break-before-make complimentary switching to prevent shoot-through currents. During the 30ns dead time where both FETs are off, the body-diode of the low-side power MOSFET conducts the inductor current. Having the low-side FET turn-on keeps the power dissipation low, and allows safely charging at high currents. During synchronous mode the inductor current is always flowing and converter operates in continuous conduction mode (CCM), creating a fixed two-pole system.

The charger operates in non-synchronous mode when the SRP-SRN voltage is below 5mV (0.5A inductor current for a $10m\Omega$ sense resistor). The charger is forced into non-synchronous mode when battery voltage is lower than 2V or when the average SRP-SRN voltage is lower than 1.25mV.

During non-synchronous operation, the body-diode of lower-side MOSFET can conduct the positive inductor current after the high-side n-channel power MOSFET turns off. When the load current decreases and the inductor current drops to zero, the body diode will be naturally turned off and the inductor current will become discontinuous. This mode is called Discontinuous Conduction Mode (DCM). During DCM, the low-side n-channel power MOSFET will turn-on for around 80ns when the bootstrap capacitor voltage drops below 4.2V, then the low-side power MOSFET will turn-off and stay off until the beginning of the next cycle, where the high-side power MOSFET is turned on again. The 80ns low-side MOSFET on-time is required to ensure the bootstrap capacitor is always recharged and able to keep the high-side power MOSFET on during the next cycle. This is important for battery chargers, where unlike regular dc-dc converters, there is a battery load that maintains a voltage and can both source and sink current. The 80ns low-side pulse pulls the PH node (connection between high and low-side MOSFET) down, allowing the bootstrap capacitor to recharge up to the REGN LDO value. After the 80ns, the low-side MOSFET is kept off to prevent negative inductor current from occurring.

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At very low currents during non-synchronous operation, there may be a small amount of negative inductor current during the 80ns recharge pulse. The charge should be low enough to be absorbed by the input capacitance. Whenever the converter goes into zero percent duty-cycle, the high-side MOSFET does not turn on, and the low-side MOSFET does not turn on (only 80ns recharge pulse) either, and there is almost no discharge from the battery.

During the DCM mode the loop response automatically changes and has a single pole system at which the pole is proportional to the load current, because the converter does not sink current, and only the load provides a current sink. This means at very low currents the loop response is slower, as there is less sinking current available to discharge the output voltage.

CYCLE-BY-CYCLE CHARGE UNDER CURRENT

If the SRP-SRN voltage decreases below 5mV (The charger is also forced into non-synchronous mode when the average SRP-SRN voltage is lower than 1.25mV), the low side FET will be turned off for the remainder of the switching cycle to prevent negative inductor current. During DCM, the low-side FET will only turn on for at around 80ns when the bootstrap capacitor voltage drops below 4.2V to provide refresh charge for the bootstrap capacitor. This is important to prevent negative inductor current from causing a boost effect in which the input voltage increases as power is transferred from the battery to the input capacitors and lead to an over-voltage stress on the VCC node and potentially cause damage to the system.

INPUT OVER VOLTAGE PROTECTION (ACOV)

ACOV provides protection to prevent system damage due to high input voltage. Once the adapter voltage reaches the ACOV threshold, charge is disabled and the battery is switched to system instead of adapter.

INPUT UNDER VOLTAGE LOCK OUT (UVLO)

The system must have a minimum VCC voltage to allow proper operation. This VCC voltage could come from either input adapter or battery, if a conduction path exists from the battery to VCC through the high side NMOS body diode. When VCC is below the UVLO threshold, all circuits in the IC are disabled.

BATTERY OVER-VOLTAGE PROTECTION

The converter will not allow the high-side FET to turn-on until the BAT voltage goes below 105% of the regulation voltage. This allows one-cycle response to an over-voltage condition – such as occurs when the load is removed or the battery is disconnected. An 8mA current sink from SRP/SRN to PGND is on only during charge and allows discharging the stored output inductor energy that is transferred to the output capacitors. BATOVP will also suspend the safety timer.

CYCLE-BY-CYCLE CHARGE OVER-CURRENT PROTECTION

The charger has a secondary cycle-to-cycle over-current protection. It monitors the charge current, and prevents the current from exceeding 160% of the programmed charge current. The high-side gate drive turns off when the over-current is detected, and automatically resumes when the current falls below the over-current threshold.

THERMAL SHUTDOWN PROTECTION

The QFN package has low thermal impedance, which provides good thermal conduction from the silicon to the ambient, to keep junctions temperatures low. As added level of protection, the charger converter turns off and self-protects whenever the junction temperature exceeds the TSHUT threshold of 145°C. The charger stays off until the junction temperature falls below 130°C. Then the charger will soft-start again if all other enable charge conditions are valid. Thermal shutdown will also suspend the safety timer.

TEMPERATURE QUALIFICATION

The controller continuously monitors battery temperature by measuring the voltage between the TS pin and GND. A negative temperature coefficient thermistor (NTC) and an external voltage divider typically develop this voltage. The controller compares this voltage against its internal thresholds to determine if charging is allowed. To initiate a charge cycle, the battery temperature must be within the V(LTF) to V(HTF) thresholds. If battery temperature is outside of this range, the controller suspends charge and the safety timer and waits until the battery temperature is within the V(LTF) to V(HTF) range. During the charge cycle the battery temperature must



be within the V(LTF) to V(TCO) thresholds. If battery temperature is outside of this range, the controller suspends charge and safety timer and waits until the battery temperature is within the V(LTF) to V(HTF) range. If the battery temperature is between the V(LTF) and the V(COOL) thresholds or between the V(HTF) and V(WARM) thresholds, charge is automatically reduced to $I_{CHARGE}/8$. To avoid early termination during COOL/WARM condition, set $I_{TERM} \le I_{CHARGE}/10$. The controller suspends charge by turning off the PWM charge FETs. Figure 12 and Figure 13 summarizes the operation.

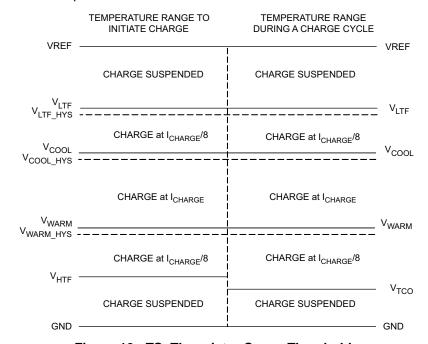


Figure 12. TS, Thermistor Sense Thresholds

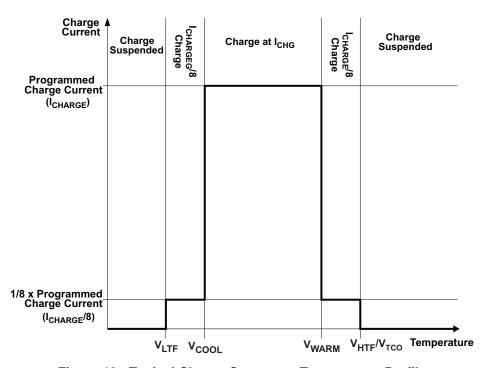


Figure 13. Typical Charge Current vs Temperature Profile

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Assuming a 103AT NTC thermistor on the battery pack as shown in the Typical System Schematic, the value RT1 and RT2 can be determined by using Equation 5 and Equation 6:

$$RT2 = \frac{V_{VREF} \times RTH_{COOL} \times RTH_{WARM} \times \left(\frac{1}{V_{COOL}} - \frac{1}{V_{WARM}}\right)}{RTH_{WARM} \times \left(\frac{V_{VREF}}{V_{WARM}} - 1\right) - RTH_{COOL} \times \left(\frac{V_{VREF}}{V_{COOL}} - 1\right)}$$

$$RT1 = \frac{\frac{V_{VREF}}{V_{COOL}} - 1}{\frac{1}{RT2} + \frac{1}{RTH_{COOL}}}$$
(5)

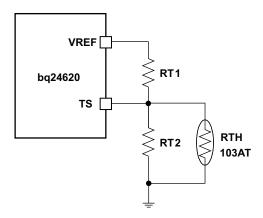


Figure 14. TS Resistor Network

For example, 103AT NTC thermistor is used to monitor the battery pack temperature. Select $T_{COOL} = 0^{\circ}C$, $T_{WARM} = 60^{\circ}C$. From the calculation and select standard 5% resistor value. We can get $R_{T1} = 2.2k\Omega$, $R_{T2} = 6.8k\Omega$, and T_{COLD} is -17°C (target -20°C); T_{HOT} is 77°C (target 75°C), and $T_{CUT-OFF}$ is 86°C (target 80°C). A small RC filter is suggested to protect TS pin from system-level ESD.

Timer Fault Recovery

The bq24620 provides a recovery method to deal with timer fault conditions. The following summarizes this method:

Condition 1: The battery voltage is above the recharge threshold and a timeout fault occurs.

Recovery Method: The timer fault will clear when the battery voltage falls below the recharge threshold, and battery detection will begin. Taking CE low or a POR condition will also clear the fault.

Condition 2: The battery voltage is below the RECHARGE threshold and a timeout fault occurs.

Recovery Method: Under this scenario, the bq24620 applies the IFAULT current to the battery. This small current is used to detect a battery removal condition and remains on as long as the battery voltage stays below the recharge threshold. If the battery voltage goes above the recharge threshold, the bq24620 disables the fault current and executes the recovery method described in Condition 1. Taking CE low or a POR condition will also clear the fault.

PG Output

The open drain \overline{PG} (power good) indicates whether the VCC voltage is valid or not. The open drain FET turns on whenever bq24620 has a valid VCC input (not in UVLO or ACOV or SLEEP mode). The \overline{PG} pin can be used to drive an LED or communicate to the host processor.

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CE (Charge Enable)

The CE digital input is used to disable or enable the charge process. A high-level signal on this pin enables charge, provided all the other conditions for charge are met (see *Enabling and Disabling Charge*). A high to low transition on this pin also resets all timers and fault conditions. There is an internal 1 M Ω pulldown resistor on the CE pin, so if CE is floated the charge will not turn on.

INDUCTOR, CAPACITOR, AND SENSE RESISTOR SELECTION GUIDELINES

The bq24620 provides internal loop compensation. With this scheme, best stability occurs when the LC resonant frequency, f_o, is approximately 10kHz – 15kHz per Equation 7:

$$f_{o} = \frac{1}{2\pi\sqrt{L_{o}C_{o}}} \tag{7}$$

Table 2 provides a summary of typical LC components for various charge currents

Table 2. Typical Inductor, Capacitor, and Sense Resistor Values as a Function of Charge Current

| CHARGE CURRENT | 2A | 4A | 6A | 8A | 10A |
|---------------------|--------|--------|--------|--------|--------|
| Output Inductor Lo | 8.2 μΗ | 8.2 μH | 5.6 μΗ | 4.7 μΗ | 4.7 μΗ |
| Output Capacitor Co | 20 μF | 20 μF | 20 μF | 40 μF | 40 μF |
| Sense Resistor | 10 mΩ |

CHARGE STATUS OUTPUTS

The open-drain STAT outputs indicate various charger operations as shown in Table 3. These status pins can be used to drive LEDs or communicate with the host processor. Note that OFF indicates that the open-drain transistor is turned off.

Table 3. STAT Pin Definition for bq24620

| CHARGE STATE | STAT |
|---|----------------|
| Charge in progress | ON |
| Charge complete (PG=LOW) | OFF |
| Sleep mode (PG=HIGH) | OFF |
| Charge suspend, timer fault, ACOV, battery absent | BLINK (0.5 Hz) |

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BATTERY DETECTION

For applications with removable battery packs, bq24620 provides a battery absent detection scheme to reliably detect insertion or removal of battery packs. CE needs to be HIGH to enable battery detection function.

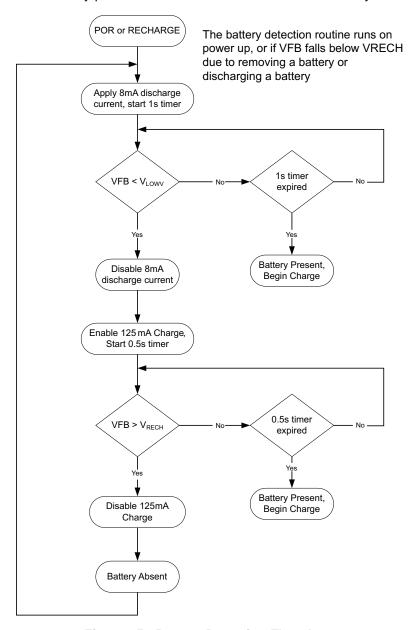


Figure 15. Battery Detection Flowchart

Once the device has powered up, an 8mA discharge current will be applied to the SRN terminal. If the battery voltage falls below the LOWV threshold within 1 second, the discharge source is turned off, and the charger is turned on at low charge current (125mA). If the battery voltage gets up above the recharge threshold within 500ms, there is no battery present and the cycle restarts. If either the 500ms or 1 second timer time out before the respective thresholds are hit, a battery is detected and a charge cycle is initiated.

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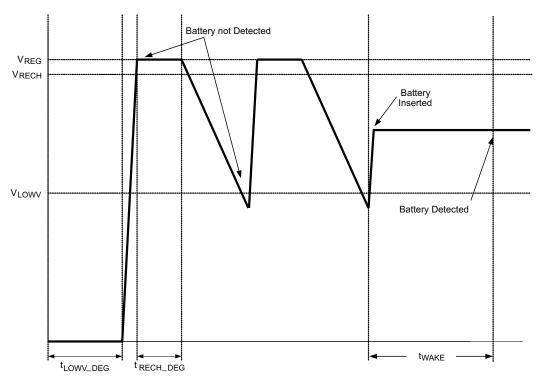


Figure 16. Battery Detect Timing Diagram

Care must be taken that the total output capacitance at the battery node is not so large that the discharge current source cannot pull the voltage below the LOWV threshold during the 1 second discharge time. The maximum output capacitance can be calculated as seen in Equation 8:

$$C_{MAX} = \frac{I_{DISCH} \times t_{DISCH}}{1.425 \times \left[1 + \frac{R_2}{R_1}\right]}$$
(8)

Where C_{MAX} is the maximum output capacitance, I_{DISCH} is the discharge current, t_{DISCH} is the discharge time, and R_2 and R_1 are the voltage feedback resistors from the battery to the VFB pin. The 1.425 factor is the difference between the RECHARGE and the LOWV thresholds at the VFB pin.

EXAMPLE

For a 3-cell Li+ charger, with R2 = 500k, R1 = 100k (giving 10.8V for voltage regulation), $I_{DISCH} = 8mA$, $t_{DISCH} = 1$ second,

$$C_{MAX} = \frac{8mA \times 1sec}{1.425 \times \left[1 + \frac{500k}{100k}\right]} = 930 \ \mu F$$
(9)

Based on these calculations, no more than 930 μF should be allowed on the battery node for proper operation of the battery detection circuit.



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Component List for Typical System Circuit of Figure 1

| PART DESIGNATOR | QTY | DESCRIPTION |
|------------------|-----|---|
| Q4, Q5 | 2 | N-channel MOSFET, 40 V, 30 A, PowerPAK SO-8, Vishay-Siliconix, SiR426DN |
| D1 | 1 | Diode, Dual Schottky, 30 V, 200 mA, SOT23, Fairchild, BAT54C |
| D2 | 1 | Schottky Diode, 40V, 5A, SMC, ON Semiconductor, MBRS540T3 |
| R _{SR} | 2 | Sense Resistor, 10 mΩ, 1%, 1 W, 2010, Vishay-Dale, WSL2010R0100F |
| L1 | 1 | Inductor, 6.8 μH, 5.5 A, Vishay-Dale, IHLP2525CZ |
| C8, C9, C12, C13 | 4 | Capacitor, Ceramic, 10 μF, 35 V, 10%, X7R |
| C2 | 1 | Capacitor, Ceramic, 2.2µF, 50 V, 10%, X7R |
| C4, C5 | 2 | Capacitor, Ceramic, 1 μF, 16V, 10%, X7R |
| C7 | 1 | Capacitor, Ceramic, 1µF, 50 V, 10%, X7R |
| C1, C6, C11 | 4 | Capacitor, Ceramic, 0.1 μF, 16 V, 10%, X7R |
| C _{ff} | 1 | Capacitor, Ceramic, 22 pF, 35 V, 10%, X7R |
| C10 | 1 | Capacitor, Ceramic, 0.1 μF, 50V, 10% |
| R1, R7 | 2 | Resistor, Chip, 100 k Ω , 1/16W, 0.5% |
| R2 | 1 | Resistor, Chip, 900 k Ω , 1/16W, 0.5% |
| R8 | 1 | Resistor, Chip, 22.1 kΩ, 1/16W, 0.5% |
| R9 | 1 | Resistor, Chip, 9.31 kΩ, 1/16W, 1% |
| R10 | 1 | Resistor, Chip, 430 k Ω , 1/16W, 1% |
| R11 | 1 | Resistor, Chip, 2Ω, 1W, 5% |
| R13, R14 | 2 | Resistor, Chip, 10 k Ω , 1/16W, 5% |
| R5 | 1 | Resistor, Chip, 100 Ω , 1/16W, 0.5% |
| R6 | 1 | Resistor, Chip, 10 Ω, 1W, 5% |
| D3, D4 | 2 | LED Diode, Green, 2.1V, 10mΩ, Vishay-Dale, WSL2010R0100F |

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APPLICATION INFORMATION

Inductor Selection

The bq24620 has 300kHz switching frequency to allow the use of small inductor and capacitor values. Inductor saturation current should be higher than the charging current (I_{CHARGE}) plus half the ripple current (I_{RIPPLE}):

$$I_{SAT} \ge I_{CHG} + (1/2)I_{RIPPLE}$$
 (10)

The inductor ripple current depends on input voltage (V_{IN}), duty cycle ($D=V_{OUT}/V_{IN}$), switching frequency (f_s) and inductance (L):

$$I_{RIPPLE} = \frac{V_{IN} \times D \times (1 - D)}{f_{S} \times L}$$
(11)

The maximum inductor ripple current happens with D = 0.5. For example, the battery charging voltage range is from 2.8V to 14.4V for 4-cell battery pack. For 20V adapter voltage, 10V battery voltage gives the maximum inductor ripple current.

Usually inductor ripple is designed in the range of (20–40%) maximum charging current as a trade-off between inductor size and efficiency for a practical design.

The bq24620 has cycle-by-cycle charge under current protection (UCP) by monitoring charging current sensing resistor to prevent negative inductor current. The Typical UCP threshold is 5mV falling edge corresponding to 0.5A falling edge for a $10m\Omega$ charging current sensing resistor.

Input Capacitor

Input capacitor should have enough ripple current rating to absorb input switching ripple current. The worst case RMS ripple current is half of the charging current when duty cycle is 0.5. If the converter does not operate at 50% duty cycle, then the worst case capacitor RMS current I_{CIN} occurs where the duty cycle is closest to 50% and can be estimated by the following equation:

$$I_{CIN} = I_{CHG} \times \sqrt{D \times (1 - D)}$$
(12)

Low ESR ceramic capacitor such as X7R or X5R is preferred for input decoupling capacitor and should be placed to the drain of the high side MOSFET and source of the low side MOSFET as close as possible. Voltage rating of the capacitor must be higher than normal input voltage level. 25V rating or higher capacitor is preferred for 20V input voltage. 20µF capacitance is suggested for typical of 3-4A charging current.

Output Capacitor

Output capacitor also should have enough ripple current rating to absorb output switching ripple current. The output capacitor RMS current I_{COUT} is given:

$$I_{COUT} = \frac{I_{RIPPLE}}{2 \times \sqrt{3}} \approx 0.29 \times I_{RIPPLE}$$
(13)

The output capacitor voltage ripple can be calculated as follows:

$$\Delta V_{o} = \frac{V_{OUT}}{8LCf_{s}^{2}} \left(1 - \frac{V_{OUT}}{V_{IN}} \right)$$
(14)

At certain input/output voltage and switching frequency, the voltage ripple can be reduced by increasing the output filter LC.

The bq24620 has internal loop compensator. To get good loop stability, the resonant frequency of the output inductor and output capacitor should be designed between 10 kHz and 15 kHz. The preferred ceramic capacitor is 25V, X7R or X5R for 4-cell application.

Power MOSFETs Selection

Two external N-channel MOSFETs are used for a synchronous switching battery charger. The gate drivers are internally integrated into the IC with 6V of gate drive voltage. 30V or higher voltage rating MOSFETs are preferred for 20V input voltage and 40V MOSFETs are preferred for 20-28V input voltage.

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Figure-of-merit (FOM) is usually used for selecting proper MOSFET based on a tradeoff between the conduction loss and switching loss. For top side MOSFET, FOM is defined as the product of a MOSFET's on-resistance, R_{DS(ON)}, and the gate-to-drain charge, Q_{GD}. For bottom side MOSFET, FOM is defined as the product of the MOSFET's on-resistance, $R_{DS(ON)}$, and the total gate charge, Q_G .

$$FOM_{top} = R_{DS(on)} \times Q_{GD} \qquad FOM_{bottom} = R_{DS(on)} \times Q_{G}$$
(15)

The lower the FOM value, the lower the total power loss. Usually lower R_{DS(ON)} has higher cost with the same package size.

The top-side MOSFET loss includes conduction loss and switching loss. It is a function of duty cycle (D=V_{OUT}/V_{IN}), charging current (I_{CHARGE}), MOSFET's on-resistance R_{DS(ON)}), input voltage (V_{IN}), switching frequency (F), turn on time (t_{on}) and turn off time (t_{toff}) :

$$P_{top} = D \times I_{CHG}^{2} \times R_{DS(on)} + \frac{1}{2} \times V_{IN} \times I_{CHG} \times (t_{on} + t_{off}) \times f_{S}$$
(16)

The first item represents the conduction loss. Usually MOSFET R_{DS(ON)} increases by 50% with 100°C junction temperature rise. The second term represents the switching loss. The MOSFET turn-on and turn off times are given by:

$$t_{on} = \frac{Q_{SW}}{I_{on}}, t_{off} = \frac{Q_{SW}}{I_{off}}$$
(17)

where Q_{sw} is the switching charge, I_{on} is the turn-on gate driving current and loff is the turn-off gate driving current. If the switching charge is not given in MOSFET datasheet, it can be estimated by gate-to-drain charge (Q_{GD}) and gate-to-source charge (Q_{GS}) :

$$Q_{SW} = Q_{GD} + \frac{1}{2} \times Q_{GS}$$
 (18)

Gate driving current total can be estimated by REGN voltage (V_{REGN}), MOSFET plateau voltage (V_{plt}), total turn-on gate resistance (Ron) and turn-off gate resistance Roff) of the gate driver:

$$I_{on} = \frac{V_{REGN} - V_{plt}}{R_{on}}, I_{off} = \frac{V_{plt}}{R_{off}}$$
(19)

The conduction loss of the bottom-side MOSFET is calculated with the following equation when it operates in synchronous continuous conduction mode:

$$P_{\text{bottom}} = (1 - D) \times I_{\text{CHG}}^2 \times R_{\text{DS(on)}}$$
(20)

If the SRP-SRN voltage decreases below 5mV (The charger is also forced into non-synchronous mode when the average SRP-SRN voltage is lower than 1.25mV), the low side FET will be turned off for the remainder of the switching cycle to prevent negative inductor current.

As a result all the freewheeling current goes through the body-diode of the bottom-side MOSFET. The maximum charging current in non-synchronous mode can be up to 0.9A (0.5A typ) for a 10mΩ charging current sensing resistor considering IC tolerance. Choose the bottom-side MOSFET with either an internal Schottky or body diode capable of carrying the maximum non-synchronous mode charging current.

MOSFET gate driver power loss contributes to the dominant losses on controller IC, when the buck converter is switching. Choosing the MOSFET with a small Q_{q_total} will reduce the IC power loss to avoid thermal shut down.

$$P_{ICLoss_driver} = V_{IN} \cdot Q_{g_total} \cdot f_s$$
(21)

Where Q_{q total} is the total gate charge for both upper and lower MOSFET at 6V V_{REGN}.

The VREF load current is another component on VCC input current (Do not overload VREF) where total IC loss can be described by following equations:

$$P_{VREF} = (V_{IN} - V_{VREF}) \cdot I_{VREF}$$

$$P_{ICLOSS} = P_{ICLOSS_driver} + P_{VREF} + P_{Quiescent}$$
(22)



Input Filter Design

During adapter hot plug-in, the parasitic inductance and input capacitor from the adapter cable form a second order system. The voltage spike at VCC pin maybe beyond IC maximum voltage rating and damage IC. The input filter must be carefully designed and tested to prevent over voltage event on VCC pin.

There are several methods to damping or limit the over voltage spike during adapter hot plug-in. An electrolytic capacitor with high ESR as an input capacitor can damp the over voltage spike well below the IC maximum pin voltage rating. A high current capability TVS Zener diode can also limit the over voltage level to an IC safe level. However these two solutions may not have low cost or small size.

A cost effective and small size solution is shown in Figure 17. The R1 and C1 are composed of a damping RC network to damp the hot plug-in oscillation. As a result the over voltage spike is limited to a safe level. D1 is used for reverse voltage protection for VCC pin (it can be the input schottky diode or the body diode of input ACFET). C2 is VCC pin decoupling capacitor and it should be place to VCC pin as close as possible. The R2 and C2 form a damping RC network to further protect the IC from high dv/dt and high voltage spike. C2 value should be less than C1 value so R1 can dominant the equivalent ESR value to get enough damping effect for hot plug-in. R1 and R2 package must be sized enough to handle inrush current power loss according to resistor manufacturer's datasheet. The filter components value always need to be verified with real application and minor adjustments may need to fit in the real application circuit.

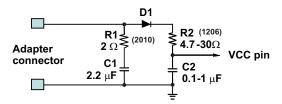


Figure 17. Input Filter

PCB Layout

The switching node rise and fall times should be minimized for minimum switching loss. Proper layout of the components to minimize high frequency current path loop (see Figure 18) is important to prevent electrical and magnetic field radiation and high frequency resonant problems. Here is a PCB layout priority list for proper layout. Layout PCB according to this specific order is essential.

- 1. Place input capacitor as close as possible to switching MOSFET's supply and ground connections and use shortest copper trace connection. These parts should be placed on the same layer of PCB instead of on different layers and using vias to make this connection.
- 2. The IC should be placed close to the switching MOSFET's gate terminals and keep the gate drive signal traces short for a clean MOSFET drive. The IC can be placed on the other side of the PCB of switching MOSFETs.
- 3. Place inductor input terminal to switching MOSFET's output terminal as close as possible. Minimize the copper area of this trace to lower electrical and magnetic field radiation but make the trace wide enough to carry the charging current. Do not use multiple layers in parallel for this connection. Minimize parasitic capacitance from this area to any other trace or plane.
- 4. The charging current sensing resistor should be placed right next to the inductor output. Route the sense leads connected across the sensing resistor back to the IC in same layer, close to each other (minimize loop area) and do not route the sense leads through a high-current path (see Figure 19 for Kelvin connection for best current accuracy). Place decoupling capacitor on these traces next to the IC.
- 5. Place output capacitor next to the sensing resistor output and ground.
- 6. Output capacitor ground connections need to be tied to the same copper that connects to the input capacitor ground before connecting to system ground.
- 7. Route analog ground separately from power ground and use single ground connection to tie charger power ground to charger analog ground. Just beneath the IC use analog ground copper pour but avoid power pins to reduce inductive and capacitive noise coupling. Connect analog ground to GND. Connect analog ground and power ground together using PowerPAD as the single ground connection point. Or using a 0Ω resistor to tie analog ground to power ground (PowerPAD should tie to analog ground in this case). A star-connection

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- under PowerPAD is highly recommended.
- 8. It is critical that the exposed PowerPAD on the backside of the IC package be soldered to the PCB ground. Ensure that there are sufficient thermal vias directly under the IC, connecting to the ground plane on the other layers.
- 9. Decoupling capacitors should be placed next to the IC pins and make trace connection as short as possible.
- 10. All via size and number should be enough for a given current path.

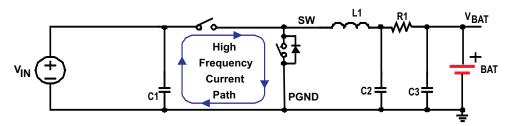


Figure 18. High Frequency Current Path

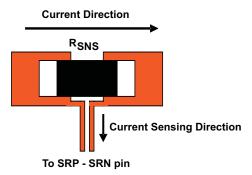


Figure 19. Sensing Resistor PCB Layout

Refer to the EVM design (SLUU410) for the recommended component placement with trace and via locations. For the QFN information, refer to SCBA017 and SLUA271.

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PACKAGE OPTION ADDENDUM

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PACKAGING INFORMATION

| Orderable Device | Status ⁽¹⁾ | Package Type | Package Drawing | Pins | Package Qty | e Eco Plan ⁽²⁾ | Lead/Ball Finish | MSL Peak Temp ⁽³⁾ |
|------------------|-----------------------|-----------------|--------------------|------|----------------|---------------------------|------------------|------------------------------|
| BQ24620RVAR | ACTIVE | VQFN | RVA | 16 | 3000 | Green (RoHS & no Sb/Br) | CU NIPDAU | Level-2-260C-1 YEAR |
| BQ24620RVAT | ACTIVE | VQFN | RVA | 16 | 250 | Green (RoHS & no Sb/Br) | CU NIPDAU | Level-2-260C-1 YEAR |

⁽¹⁾ The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined.

Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

Pb-Free (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

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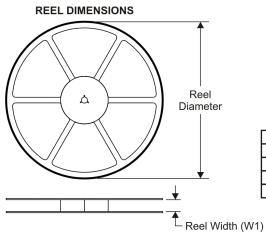
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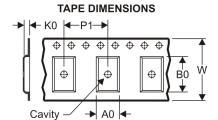


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TAPE AND REEL INFORMATION





| | Dimension designed to accommodate the component width |
|----|---|
| B0 | Dimension designed to accommodate the component length |
| K0 | Dimension designed to accommodate the component thickness |
| W | Overall width of the carrier tape |
| P1 | Pitch between successive cavity centers |

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE

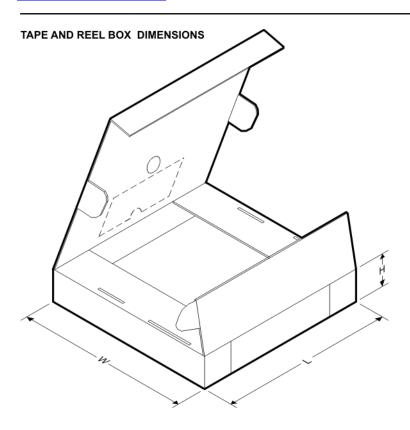


*All dimensions are nominal

| Device | Package Type | Package Drawing | | SPQ | Reel Diameter (mm) | Reel Width W1 (mm) | A0 (mm) | B0 (mm) | K0 (mm) | P1 (mm) | W (mm) | Pin1 Quadrant |
|-------------|-----------------|--------------------|----|------|--------------------------|--------------------------|------------|------------|------------|------------|-----------|------------------|
| BQ24620RVAR | VQFN | RVA | 16 | 3000 | 330.0 | 12.4 | 3.75 | 3.75 | 1.15 | 8.0 | 12.0 | Q1 |
| BQ24620RVAT | VQFN | RVA | 16 | 250 | 180.0 | 12.4 | 3.75 | 3.75 | 1.15 | 8.0 | 12.0 | Q1 |

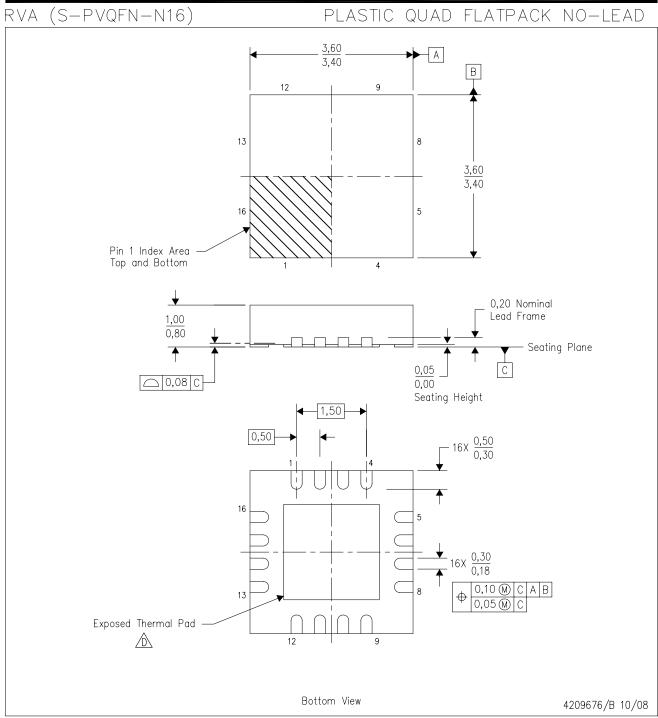
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*All dimensions are nominal

| Device | Package Type | Package Drawing | Pins | SPQ | Length (mm) | Width (mm) | Height (mm) |
|-------------|--------------|-----------------|------|------|-------------|------------|-------------|
| BQ24620RVAR | VQFN | RVA | 16 | 3000 | 346.0 | 346.0 | 29.0 |
| BQ24620RVAT | VQFN | RVA | 16 | 250 | 190.5 | 212.7 | 31.8 |



NOTES: A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.

- B. This drawing is subject to change without notice.
- C. QFN (Quad Flatpack No-Lead) package configuration.
- The package thermal pad must be soldered to the board for thermal and mechanical performance.



THERMAL PAD MECHANICAL DATA



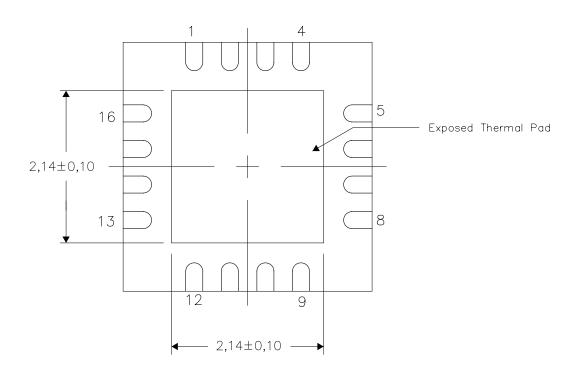
RVA (S-PVQFN-N16)

THERMAL INFORMATION

This package incorporates an exposed thermal pad that is designed to be attached directly to an external heatsink. The thermal pad must be soldered directly to the printed circuit board (PCB). After soldering, the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to the appropriate copper plane shown in the electrical schematic for the device, or alternatively, can be attached to a special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).

For information on the Quad Flatpack No—Lead (QFN) package and its advantages, refer to Application Report, QFN/SON PCB Attachment, Texas Instruments Literature No. SLUA271. This document is available at www.ti.com.

The exposed thermal pad dimensions for this package are shown in the following illustration.



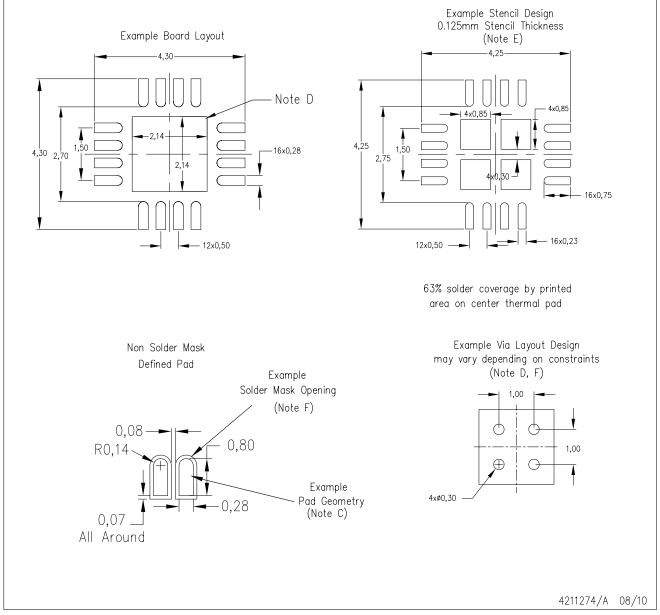
Bottom View

NOTE: All linear dimensions are in millimeters

Exposed Thermal Pad Dimensions

RVA (S-PVQFN-N16)

PLASTIC QUAD FLATPACK NO-LEAD



NOTES:

- A. All linear dimensions are in millimeters.
- B. This drawing is subject to change without notice.
- C. Publication IPC-7351 is recommended for alternate designs.
- D. This package is designed to be soldered to a thermal pad on the board. Refer to Application Note, Quad Flat—Pack QFN/SON PCB Attachment, Texas Instruments Literature No. SLUA271, and also the Product Data Sheets for specific thermal information, via requirements, and recommended board layout. These documents are available at www.ti.com http://www.ti.com.
- E. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC 7525 for stencil design considerations.
- F. Customers should contact their board fabrication site for minimum solder mask web tolerances between signal pads.



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