

**FUJITSU**

查询“MB8264A”供应商

# MOS 65,536-BIT DYNAMIC RANDOM ACCESS MEMORY

**MB 8264A-10**  
**MB 8264A-12**  
**MB 8264A-15**

## 65,536-BIT DYNAMIC RANDOM ACCESS MEMORY

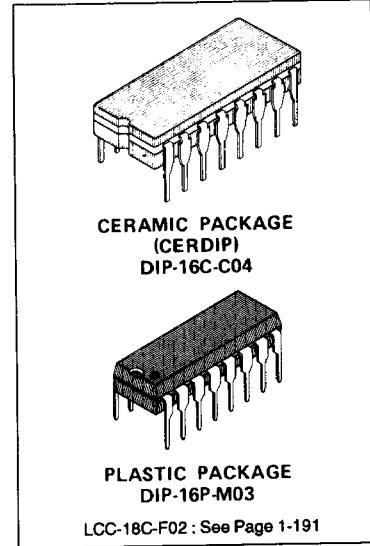
The Fujitsu MB 8264A is a fully decoded, dynamic random access memory organized as 65,536 one-bit words. The design is optimized for high-speed, high performance applications such as mainframe memory, buffer memory, peripheral storage and environments where low power dissipation and compact layout is required.

Multiplexed row and column address inputs permit the MB 8264A to be housed in a standard 16 pin DIP and 18 pad LCC. Pin-outs conform to the JEDEC approved pin out.

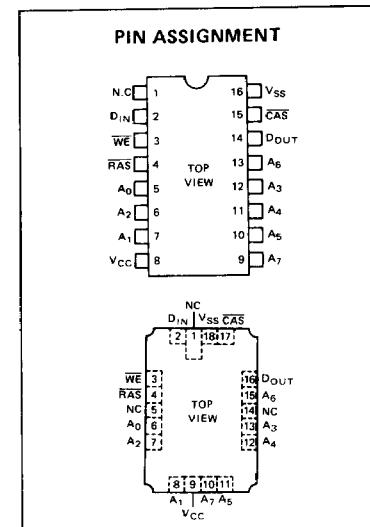
The MB 8264A is fabricated using silicon gate NMOS and Fujitsu's advanced Double-Layer Polysilicon process. This process, coupled with single-transistor memory storage cells, permits maximum circuit density and minimal chip size. Dynamic circuitry is employed in the design, including the sense amplifiers.

Clock timing requirements are non-critical, and power supply tolerance is very wide. All inputs and output are TTL compatible.

- 65,536 x 1 RAM, 16 pin DIP/18 pad LCC
- Silicon-gate, Double Poly NMOS, single transistor cell
- Row access time,
  - 100 ns max (MB 8264A-10)
  - 120 ns max (MB 8264A-12)
  - 150 ns max (MB 8264A-15)
- Cycle time,
  - 190 ns min (MB 8264A-10)
  - 230 ns min (MB 8264A-12)
  - 260 ns min (MB 8264A-15)
- Single +5V Supply,  $\pm 10\%$  tolerance
- Low power (active)
  - 275 mW max (MB 8264A-10)
  - 248 mW max (MB 8264A-12)
  - 220 mW max (MB 8264A-15)
  - 22 mW Standby (max)
- 2ms/128 refresh cycles
- RAS-only and Hidden refresh capability
- Read-Modify-Write and Page-Mode capability
- Common I/O capability using Early Write operation
- Output unlatched at cycle end allows extended page boundary and two-dimensional chip select
- On-chip latches for Addresses and Data-in
- $t_{AR}$ ,  $t_{WCR}$ ,  $t_{DHR}$  are eliminated
- Standard 16-pin Ceramic (Cerdip)  
DIP: Surfix-Z  
Standard 16-pin Plastic  
DIP: Surfix-P  
Standard 18-pad Ceramic  
LCC: Surfix-TV



LCC-18C-F02 : See Page 1-191



## ABSOLUTE MAXIMUM RATINGS (See NOTE)

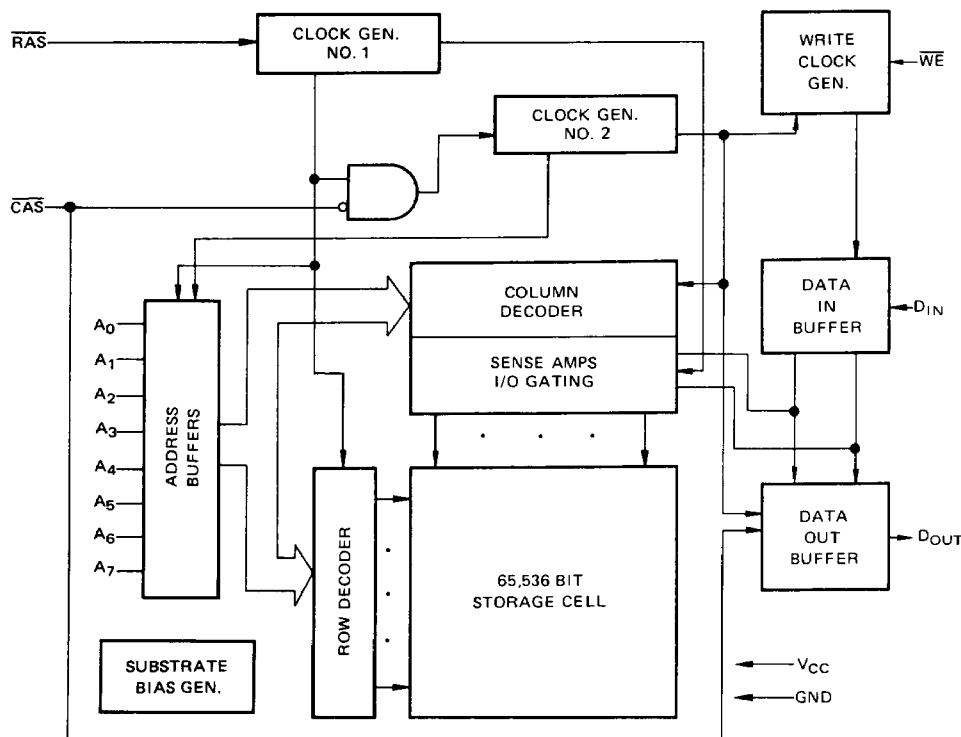
Rating	Symbol	Value	Unit
Voltage on any pin relative to V <sub>SS</sub>	V <sub>IN</sub> , V <sub>OUT</sub>	-1 to +7	V
Voltage on V <sub>CC</sub> supply relative to V <sub>SS</sub>	V <sub>CC</sub>	-1 to +7	V
Storage temperature	Ceramic	-55 to +150	°C
	Plastic	-55 to +125	°C
Power dissipation	P <sub>D</sub>	1.0	W
Short circuit output current		50	mA

**NOTE:** Permanent device damage may occur if ABSOLUTE MAXIMUM RATINGS are exceeded. Functional operation should be restricted to the conditions as detailed in the operational sections of this data sheet. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

This device contains circuitry to protect the inputs against damage due to high static voltages or electric fields. However, it is advised that normal precautions be taken to avoid application of any voltage higher than maximum rated voltages to this high impedance circuit.

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Fig. 1 – MB 8264A BLOCK DIAGRAM



## CAPACITANCE ( $T_A = 25^\circ\text{C}$ )

Parameter	Symbol	Typ	Max	Unit
Input Capacitance $A_0 \sim A_7, D_{IN}$	$C_{IN1}$		5	pF
Input Capacitance $\bar{RAS}, \bar{CAS}, \bar{WE}$	$C_{IN2}$		8	pF
Output Capacitance $D_{OUT}$	$C_{OUT}$		7	pF

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## RECOMMENDED OPERATING CONDITIONS

(Referenced to  $V_{SS}$ )

Parameter	Symbol	Min	Typ	Max	Unit	Operating Temperature
Supply Voltage	$V_{CC}$ $V_{SS}$	4.5 0	5.0 0	5.5 0	V V	
Input High Voltage, all inputs	$V_{IH}$	2.4		6.5	V	$0^{\circ}C$ to $+70^{\circ}C$
Input Low Voltage, all inputs	$V_{IL}$ *	-1.0		0.8	V	

Note \* : The device can withstand undershoots to the -2V level with a pulse width of 20 ns.

## DC CHARACTERISTICS

(Recommended operating conditions unless otherwise noted.)

Parameter	Symbol	Min	Max	Unit
OPERATING CURRENT *	$I_{CC1}$		50	mA
			45	
			40	
STANDBY CURRENT Standby Power supply current ( $\overline{RAS} = \overline{CAS} = V_{IH}$ )	$I_{CC2}$		4	mA
REFRESH CURRENT *	$I_{CC3}$		38	mA
			35	
			31	
PAGE MODE CURRENT *	$I_{CC4}$		35	mA
			32	
			28	
INPUT LEAKAGE CURRENT Input leakage current, any input ( $0V \leq V_{IN} \leq 5.5V$ , $V_{CC}=5.5V$ , $V_{SS}=0V$ , all other pins not test=0V)	$I_{IL}$	-10	10	$\mu A$
OUTPUT LEAKAGE CURRENT (Data out is disabled, $0V \leq V_{OUT} \leq 5.5V$ )	$I_{OL}$	-10	10	$\mu A$
OUTPUT LEVELS Output high voltage ( $I_{OH} = -5mA$ ) Output low voltage ( $I_{OL} = 4.2mA$ )	$V_{OH}$ $V_{OL}$	2.4 0.4		V V

Note \* :  $I_{CC}$  is dependent on output loading and cycle rates. Specified values are obtained with the output open.

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### AC CHARACTERISTICS

(Recommended operating conditions unless otherwise noted.)

NOTES 1,2,3

Parameter	NOTES	Symbol	M8 8264A-10		M8 8264A-12		M8 8264A-15		Unit
			Min	Max	Min	Max	Min	Max	
Time between Refresh		$t_{REF}$		2		2		2	ms
Random Read/Write Cycle Time		$t_{RC}$	190		230		260		ns
Read-Write Cycle Time		$t_{RWC}$	230		265		280		ns
Page Mode Cycle Time		$t_{PC}$	105		120		145		ns
Page Mode Read-Write Cycle Time		$t_{PRWC}$	135		155		180		ns
Access Time from RAS	4 6	$t_{RAC}$		100		120		150	ns
Access Time from CAS	5 6	$t_{CAC}$		50		60		75	ns
Output Buffer Turn Off Delay		$t_{OFF}$	0	30	0	35	0	40	ns
Transition Time		$t_T$	3	50	3	50	3	50	ns
RAS Precharge Tim		$t_{RP}$	80		100		100		ns
RAS Pulse Width		$t_{RAS}$	100	10000	120	10000	150	10000	ns
RAS Hold Time		$t_{RSH}$	50		60		75		ns
CAS Precharge Time (Page mode only)		$t_{CP}$	45		50		60		ns
CAS Precharge Time (All cycles except page mode)		$t_{CPN}$	20		20		25		ns
CAS Pulse Width		$t_{CAS}$	50	10000	60	10000	75	10000	ns
CAS Hold Time		$t_{CSH}$	100		120		150		ns
RAS to CAS Delay Tim	7 8	$t_{RCD}$	20	50	20	60	25	75	ns
CAS to RAS Precharge Time		$t_{CRP}$	0		0		0		ns
Row Address Set Up Time		$t_{ASR}$	0		0		0		ns
Row Address Hold Time		$t_{RAH}$	10		10		15		ns
Column Address Set Up Time		$t_{ASC}$	0		0		0		ns
Column Address Hold Time		$t_{CAH}$	15		15		20		ns
Read Command Set Up Time		$t_{RCS}$	0		0		0		ns
Read Command Hold Time Referenced to CAS	10	$t_{RCH}$	0		0		0		ns
Read Command Hold Time Referenced to RAS	10	$t_{RRH}$	20		20		20		ns
Write Command Set Up Time	9	$t_{WCS}$	0		0		0		ns
Write Command Hold Time		$t_{WCH}$	20		25		30		ns
Write Command Pulse Width		$t_{WP}$	20		25		30		ns
Write Command to RAS Lead Time		$t_{RWL}$	35		40		45		ns
Write Command to CAS Lead Time		$t_{CWL}$	35		40		45		ns
Data In Set Up Time		$t_{DS}$	0		0		0		ns
Data In Hold Time		$t_{DH}$	20		25		30		ns
CAS to WE Delay	9	$t_{CWD}$	40		50		60		ns
RAS to WE Delay	9	$t_{RWD}$	90		110		120		ns
RAS Precharge to CAS Hold Time (RAS-only refresh)		$t_{RPC}$	20		20		20		ns

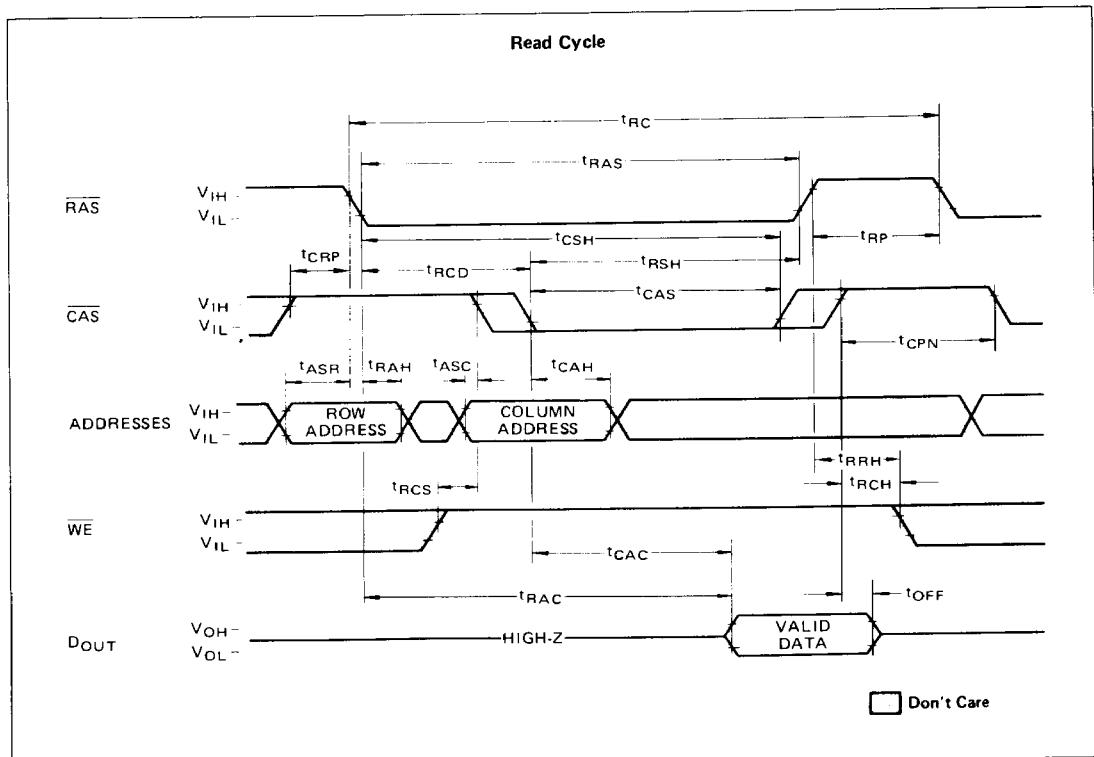
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### Notes:

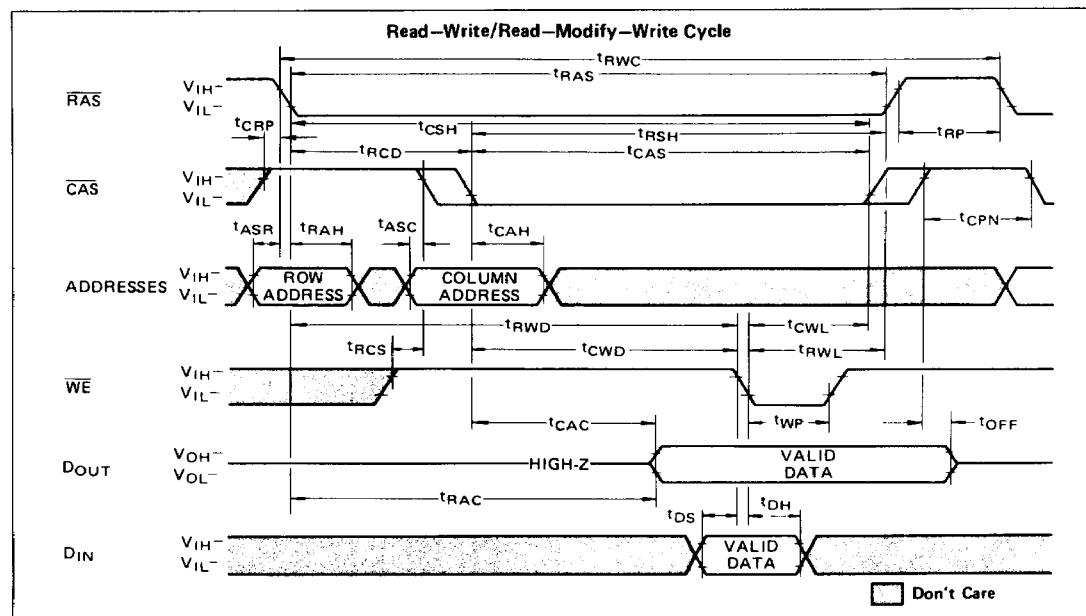
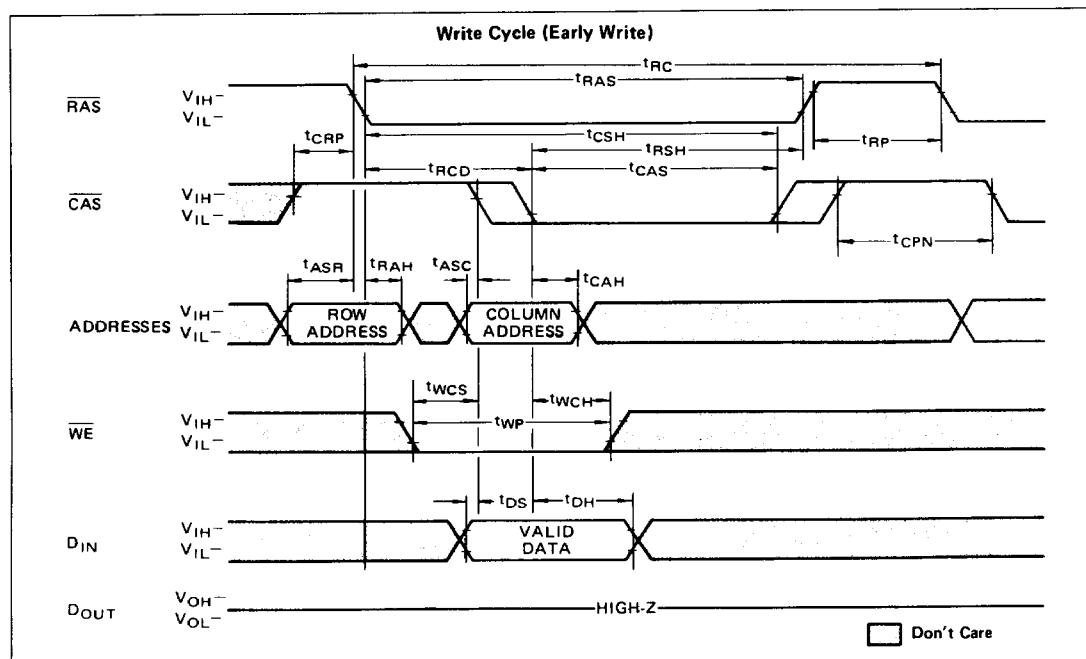
- 1 An initial pause of 200  $\mu$ s is required after power-up followed by any 8 RAS cycles before proper device operation is achieved.
- 2 AC characteristics assume  $t_T = 5\text{ns}$ .
- 3  $V_{IH}$  (min) and  $V_{IL}$  (max) are reference levels for measuring timing of input signals. Also, transition times are measured between  $V_{IH}$  (min) and  $V_{IL}$  (max).
- 4 Assumes that  $t_{RCD} \leq t_{RCO}$  (max). If  $t_{RCD}$  is greater than the maximum recommended value shown in this table,  $t_{RAC}$  will increase by the amount that  $t_{RCD}$  exceeds the value shown.
- 5 Assumes that  $t_{RCD} \geq t_{RCO}$  (max).
- 6 Measured with a load equivalent to 2 TTL loads and 100 pF.
- 7 Operation within the  $t_{RCO}$  (max) limit insures that  $t_{RAC}$  (max) can be met.  $t_{RCO}$  (max) is specified as a

reference point only; if  $t_{RCO}$  is greater than the specified  $t_{RCO}$  (max) limit, then access time is controlled exclusively by  $t_{CAC}$ .

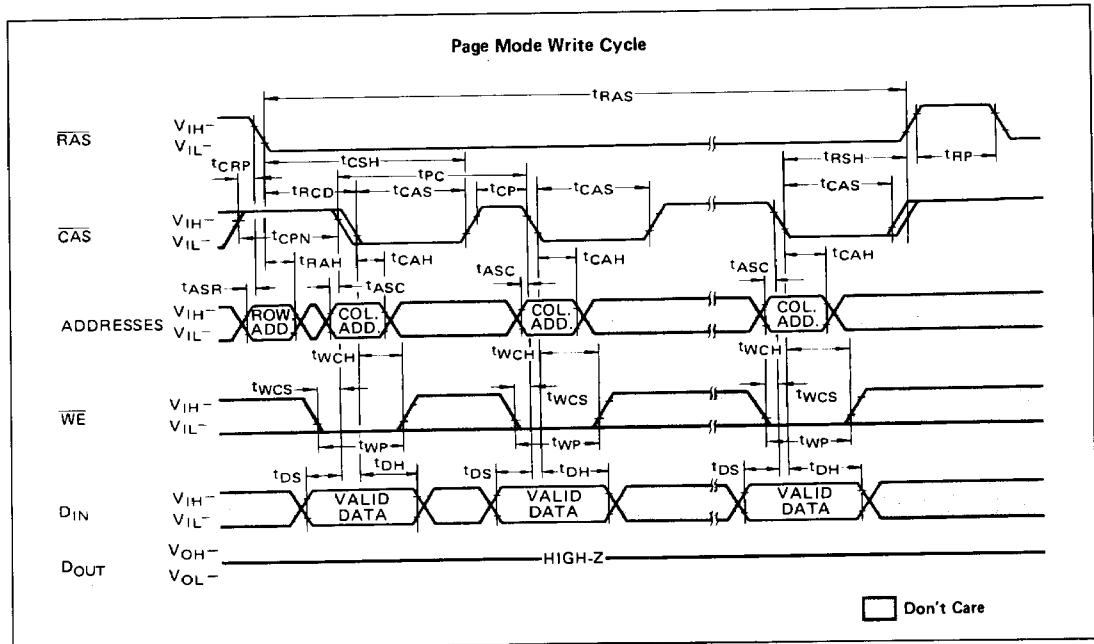
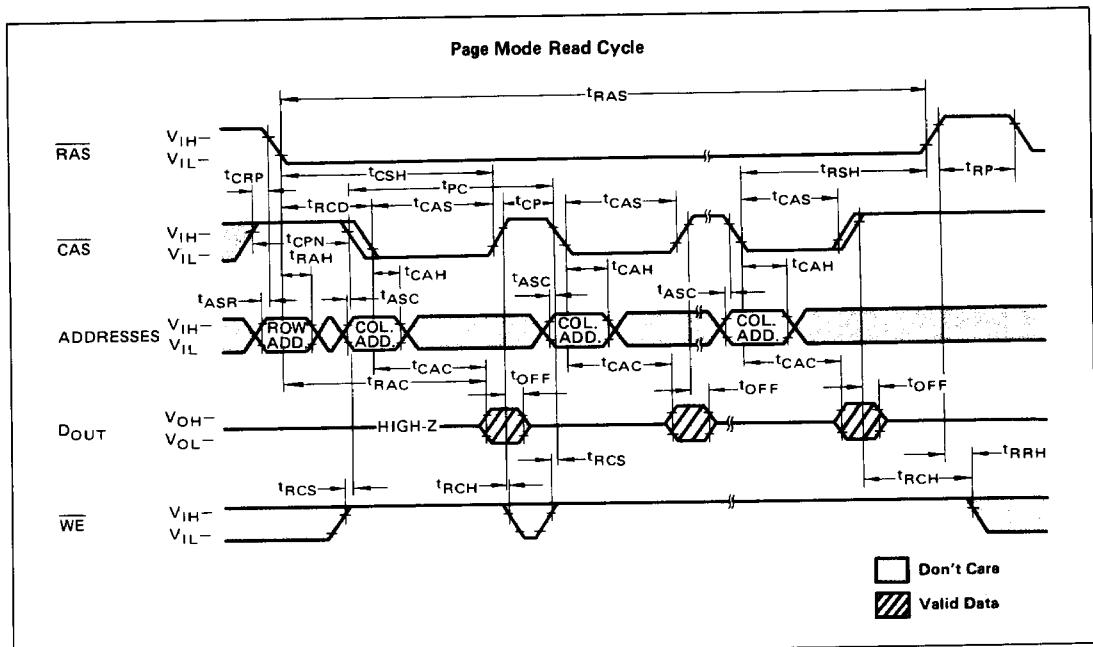
- 8  $t_{RCO}$  (min) =  $t_{RAH}$  (min) +  $2t_T$  ( $t_T=5\text{ns}$ ) +  $t_{ASC}$  (min)
- 9  $t_{WCS}$ ,  $t_{CWD}$  and  $t_{RWD}$  are not restrictive operating parameters. They are included in the data sheet as electrical characteristics only. If  $t_{WCS} \geq t_{WCS}$  (min) the cycle is an early write cycle and the data out pin will remain open circuit (high impedance) throughout entire cycle.  
If  $t_{CWD} \geq t_{CWD}$  (min) and  $t_{RWD} \geq t_{RWD}$  (min), the cycle is a read-write cycle and data out will contain data read from the selected cell. If neither of the above sets of conditions is satisfied the condition of the data out is indeterminate.
- 10 Either  $t_{RRH}$  or  $t_{RCH}$  must be satisfied for a read cycle.



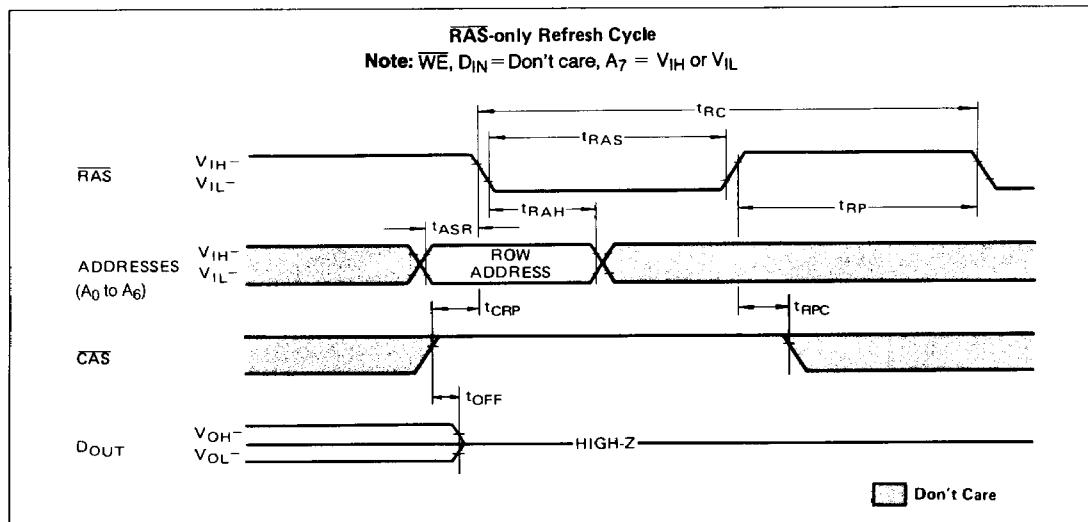
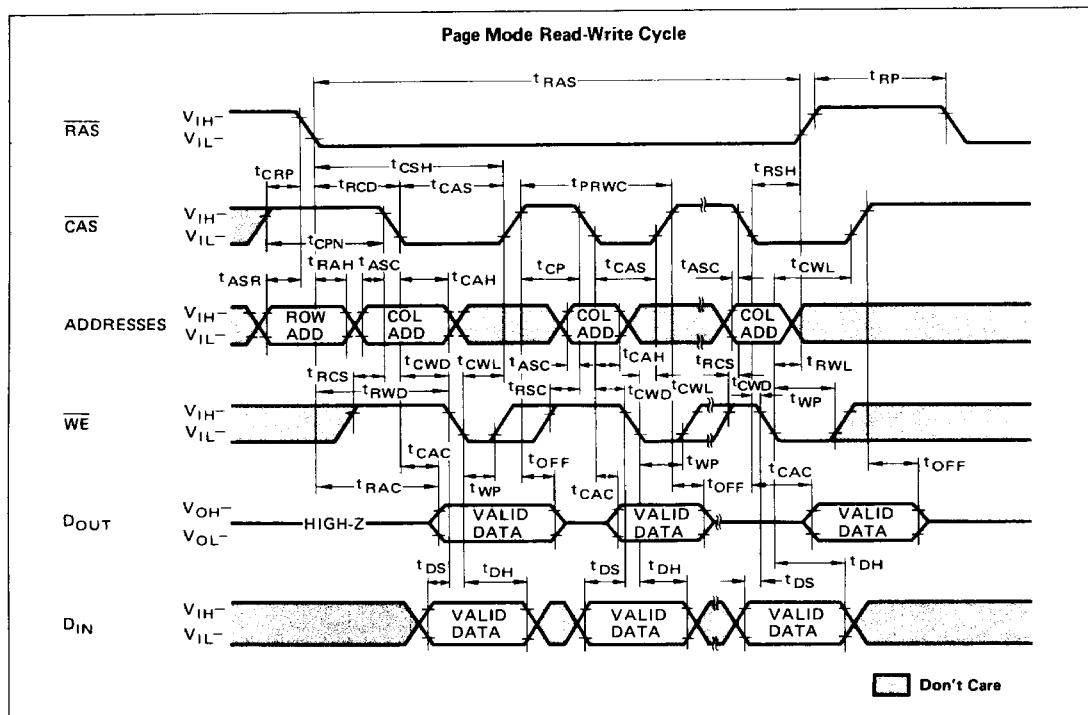
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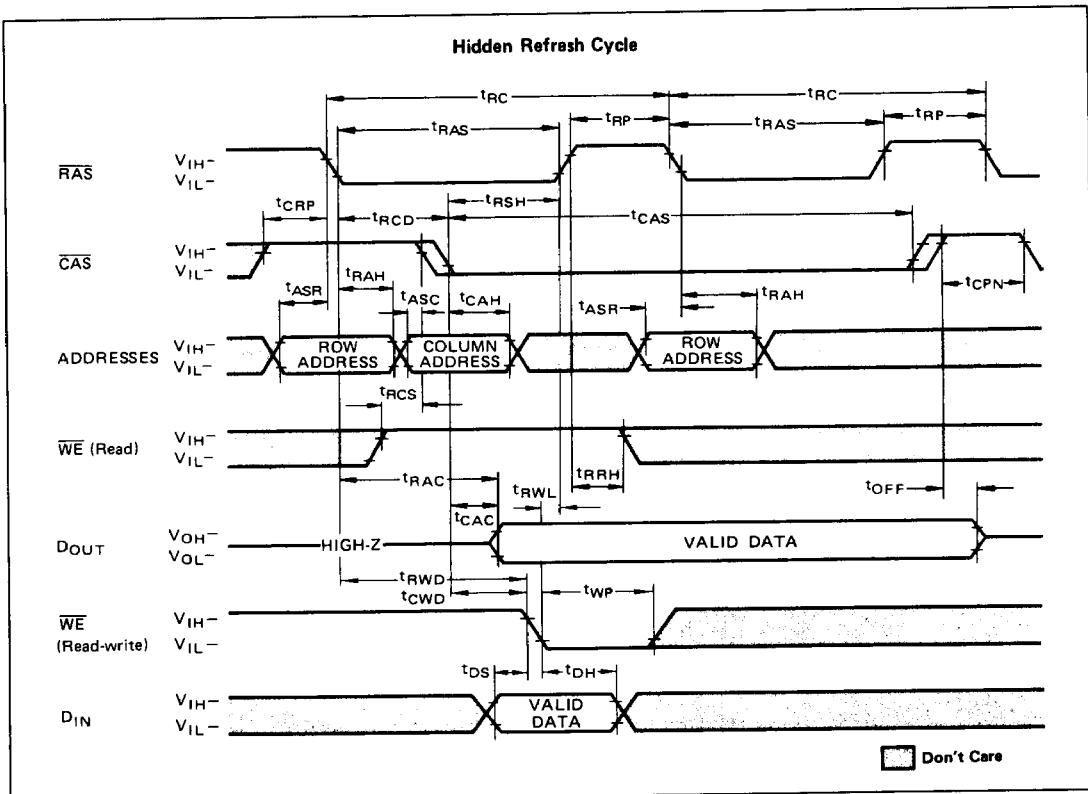
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## DESCRIPTION

### Address Inputs:

A total of sixteen binary input address bits are required to decode any 1 of 65536 storage cell locations within the MB 8264A. Eight row-address bits are established on the input pins (A<sub>0</sub> through A<sub>7</sub>) and latched with the Row Address Strobe (RAS). The eight column-address bits are established on the input pins and latched with the Column Address Strobe (CAS). All input addresses must be stable on or before the falling edge of RAS. CAS is internally inhibited (or "gated") by RAS to permit triggering of CAS as soon as the Row Address Hold Time

(t<sub>RAH</sub>) specification has been satisfied and the address inputs have been changed from row-addresses to column-addresses.

### Write Enable:

The read mode or write mode is selected with the WE input. A high on WE selects read mode and low selects write mode. Data input is disabled when read mode is selected.

### Data Input:

Data is written into the MB 8264A during a write or read-write cycle. The later falling edge of WE or CAS is a strobe for

the Data In (D<sub>IN</sub>) register. In a write cycle, if WE is brought low (write mode) before CAS, D<sub>IN</sub> is strobed by CAS, and the set-up and hold times are referenced to CAS. In a read-write cycle, WE can be low after CAS has been low and CAS to WE Delay Time (t<sub>CWD</sub>) has been satisfied. Thus D<sub>IN</sub> is strobed by WE, and set-up and hold times are referenced to WE.

### Data Output:

The output buffer is three-state TTL compatible with a fan-out of two standard TTL loads. Data-out is the same polarity as data-in. The output is in a

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high impedance state until CAS is brought low. In a read cycle, or read-write cycle, the output is valid after t<sub>RAC</sub> from the falling edge of RAS when t<sub>RCD</sub> (max) is satisfied, or after t<sub>CAC</sub> from the falling edge of CAS when the transition occurs after t<sub>RCD</sub> (max). Data remains valid until CAS is returned to a high. In a write cycle the identical sequence occurs, but data is not valid.

### Page Mode:

Page-mode operation permits strobing the row-address into the MB 8264A while maintaining RAS at a low throughout all successive memory oper-

ations in which the row addresses don't change. Thus the power dissipated by the falling edge of RAS is saved. Further, access and cycle times are decreased because the time normally required to strobe a new row addresses are eliminated.

### RAS-only Refresh

Refresh of the dynamic memory cells is accomplished by performing a memory cycle at each of the 128 row-addresses ( $A_0 \sim A_6$ ) at least every two milliseconds. During refresh, either V<sub>IL</sub> or V<sub>IH</sub> is permitted for  $A_7$ . RAS-only refresh avoids any output during refresh

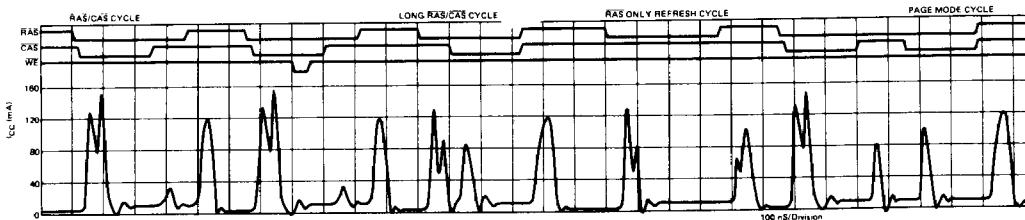
because the output buffer is in a high impedance state unless CAS is brought low. Strobing each of 128 row-addresses with RAS will cause all bits in each row to be refreshed. Further RAS-only refresh results in a substantial reduction in power dissipation.

### Hidden Refresh:

RAS-only refresh cycle may take place while maintaining valid output data. This feature is referred to as Hidden Refresh.

Hidden Refresh is performed by holding CAS as V<sub>IL</sub> from a previous memory read cycle.

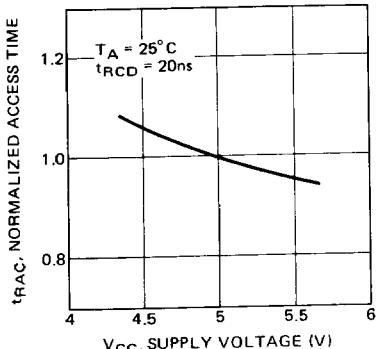
Fig. 2 – CURRENT WAVE FORM ( $V_{CC} = 5.5V$ ,  $T_A = 25^\circ C$ )



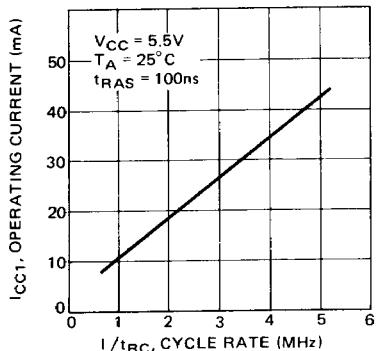
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## TYPICAL CHARACTERISTICS CURVES

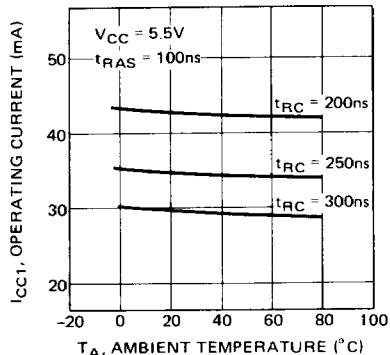
**Fig. 3 – NORMALIZED ACCESS TIME  
vs SUPPLY VOLTAGE**



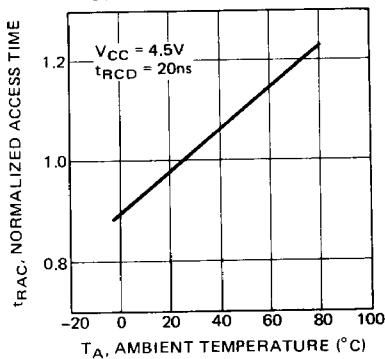
**Fig. 5 – OPERATING CURRENT  
vs CYCLE RATE**



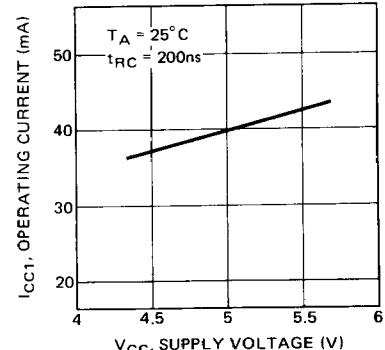
**Fig. 7 – OPERATING CURRENT  
vs AMBIENT TEMPERATURE**



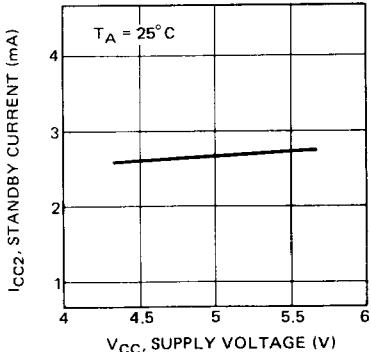
**Fig. 4 – NORMALIZED ACCESS TIME  
vs AMBIENT TEMPERATURE**



**Fig. 6 – OPERATING CURRENT  
vs SUPPLY VOLTAGE**

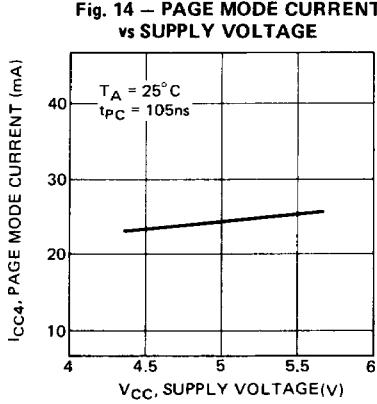
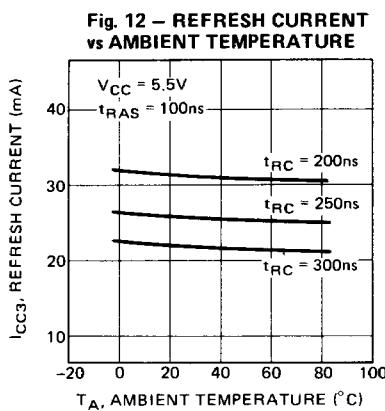
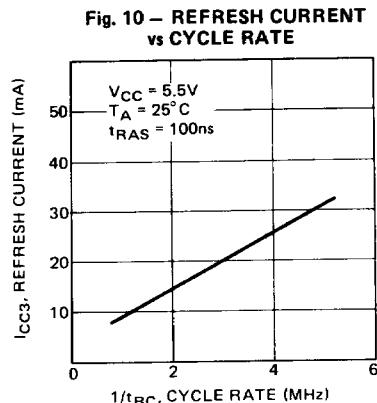
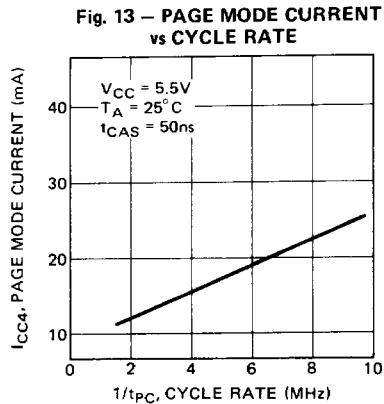
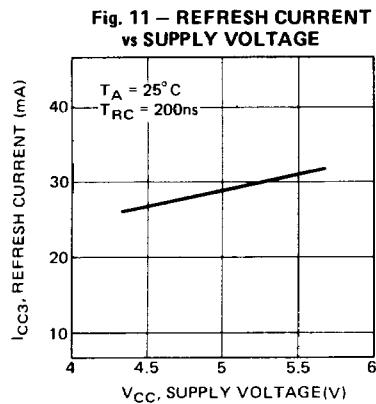
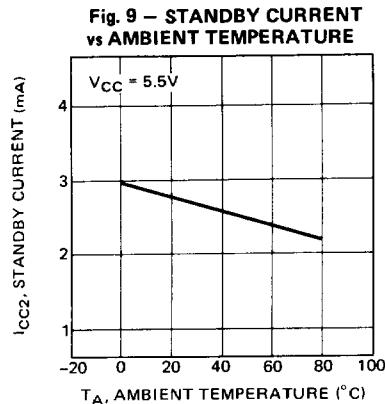


**Fig. 8 – STANDBY CURRENT  
vs SUPPLY VOLTAGE**



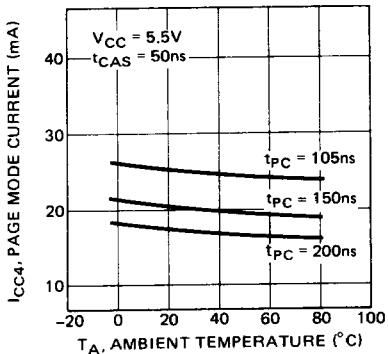
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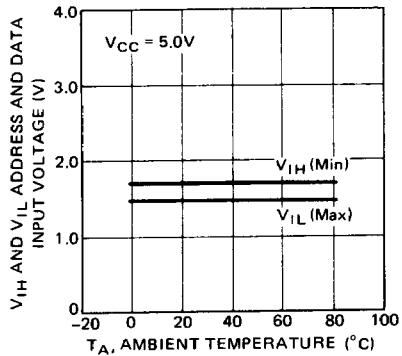


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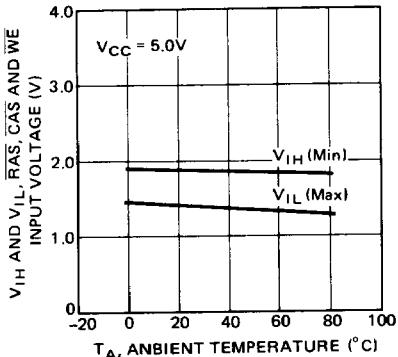
**Fig. 15 – PAGE MODE CURRENT  
vs AMBIENT TEMPERATURE**



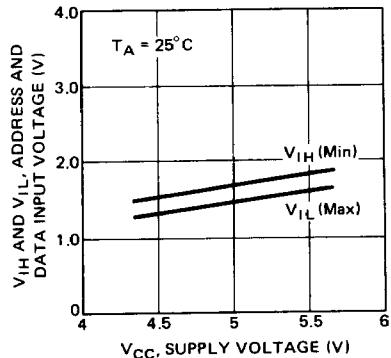
**Fig. 17 – ADDRESS AND DATA INPUT VOLTAGE  
vs AMBIENT TEMPERATURE**



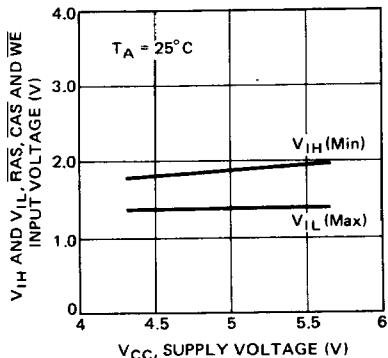
**Fig. 19 – RAS, CAS AND WE VOLTAGE  
vs AMBIENT TEMPERATURE**



**Fig. 16 – ADDRESS AND DATA INPUT VOLTAGE  
vs SUPPLY VOLTAGE**



**Fig. 18 – RAS, CAS AND WE INPUT VOLTAGE  
vs SUPPLY VOLTAGE**



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Fig. 20 – CURRENT WAVE FORM DURING POWER UP

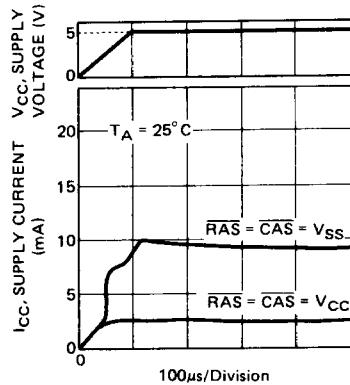
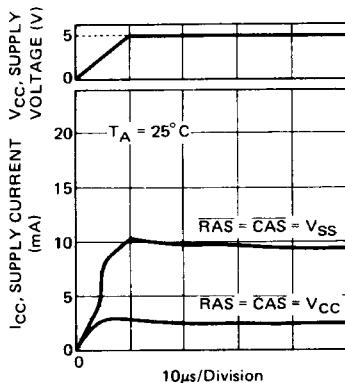


Fig. 21 – CURRENT WAVE FORM DURING POWER UP  
(ON MEMORY BOARD)

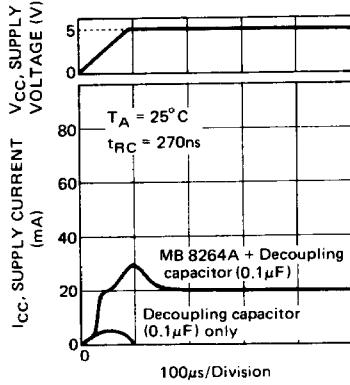
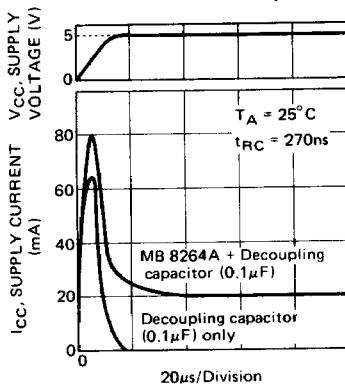
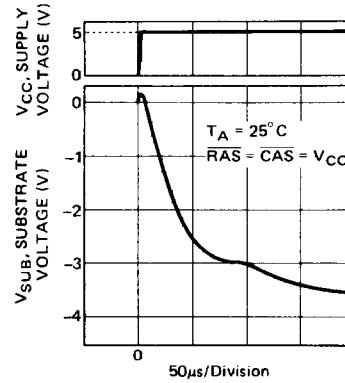


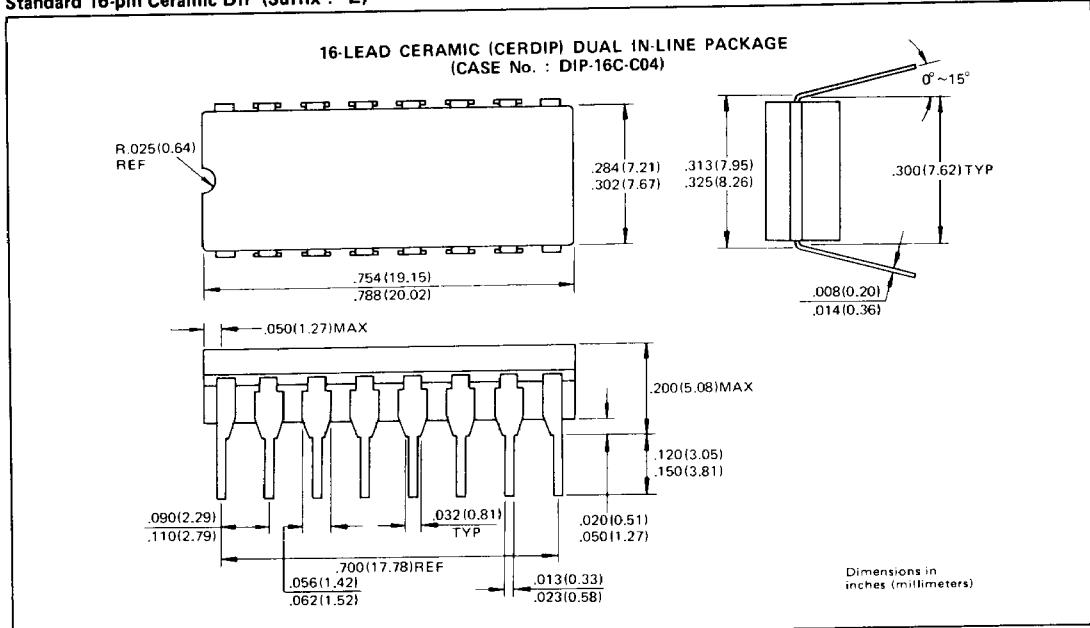
Fig. 22 – SUBSTRATE VOLTAJE  
vs SUPPLY VOLTAGE (DURING POWER UP)



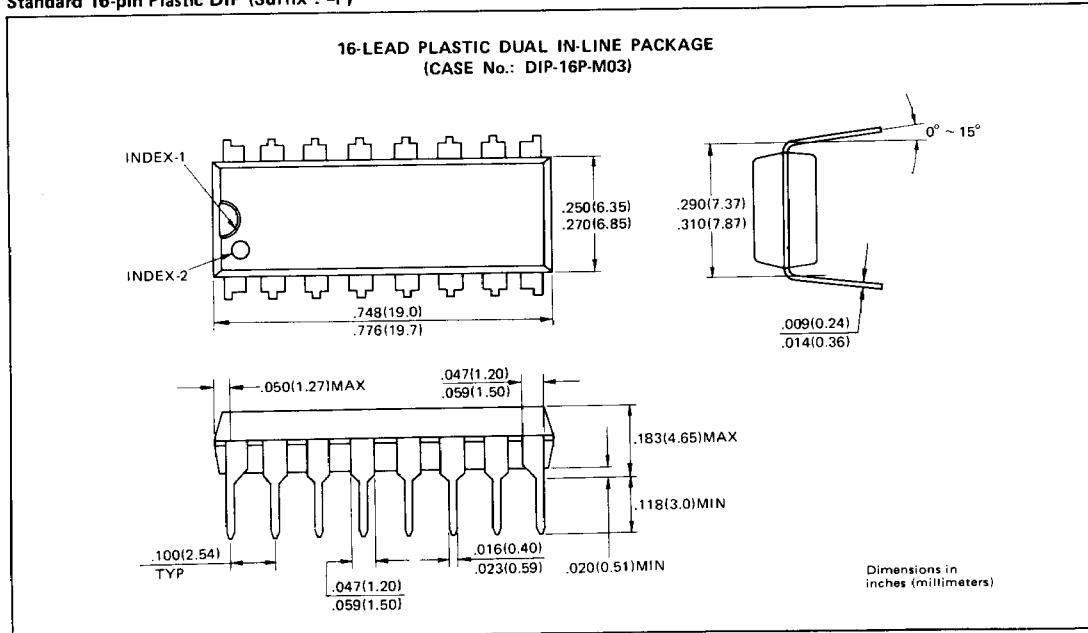
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## PACKAGE DIMENSIONS

Standard 16-pin Ceramic DIP (Suffix : -Z)



Standard 16-pin Plastic DIP (Suffix : -P)



**FUJITSU**   **MB 8264A-10**  
**MB 8264A-12**  
**MB 8264A-15**

[查询"MB8264A"供应商](#)

## PACKAGE DIMENSIONS

Standard 18-pad Ceramic LCC (Surfix : -TV)

