

## FEATURES

- 11.5 to 20 dB gain range
- 0.5 dB step size  $\pm 0.1$  dB
- 150  $\Omega$  differential input and output
- 6 dB noise figure @ maximum gain
- OIP3 of 50 dBm at 200 MHz
- 3 dB bandwidth of 700 MHz
- Multiple control interface options
  - Parallel 6-bit control interface
  - Serial peripheral interface
  - Gain step up/down interface
- Wide input dynamic range
- High performance power mode
- Power-down control
- Single 5 V supply operation
- 24-Lead LFCSP 4 x 4 mm package

## APPLICATIONS

- Differential ADC drivers
- High IF sampling receivers
- High output power IF amplification
- Instrumentation

## GENERAL DESCRIPTION

The ADL5201 is a digitally controlled, variable gain wide bandwidth amplifier that provides precise gain control, high IP3 and low noise figure. The excellent distortion performance and high signal bandwidth makes the ADL5201 an excellent gain control device for a variety of receiver applications.

For wide input dynamic range applications, the ADL5201 provides a broad 31.5 dB gain range with 0.5 dB resolution. The gain is adjustable through multiple gain control interface options: parallel, serial peripheral interface, or gain step up/down.

Using a high speed SiGe process and incorporating proprietary distortion cancellation techniques, the ADL5201 achieves better than 50 dBm output IP3 at frequencies approaching 200 MHz for all gain settings.

## FUNCTIONAL BLOCK DIAGRAM

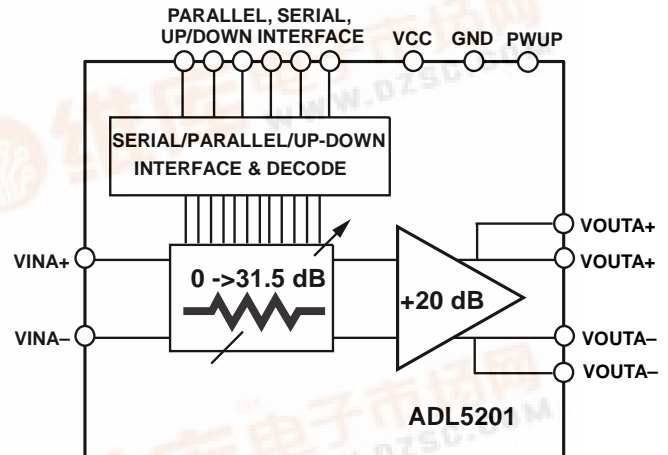


Figure 1.

The ADL5201 is powered on by applying the appropriate logic level to the PWUP pin. The quiescent current of the ADL5201 is typically 80 mA. It may be configured for higher quiescent current of 110 mA, in high performance power mode, for more demanding applications. When powered down, the ADL5201 consumes less than 9 mA and offers excellent input to output isolation. The gain setting is preserved when powered down.

Fabricated on an ADI's high speed SiGe process, the ADL5201 provides precise gain adjustment capabilities with good distortion performance. The ADL5201 amplifier comes in a compact, thermally enhanced 4 x 4mm 24-lead LFCSP package and operates over the temperature range of  $-40^{\circ}\text{C}$  to  $+85^{\circ}\text{C}$ .

### Rev. PrD

Information furnished by Analog Devices is believed to be accurate and reliable. However, no responsibility is assumed by Analog Devices for its use, nor for any infringements of patents or other rights of third parties that may result from its use. Specifications subject to change without notice. No license is granted by implication or otherwise under any patent or patent rights of Analog Devices. Trademarks and registered trademarks are the property of their respective owners.



**TABLE OF CONTENTS**

Features .....	1	ESD Caution.....	6
Functional Block Diagram .....	1	Pin Configuration and Function Descriptions.....	7
General Description .....	1	Digital Interface Overview .....	8
Revision History .....	2	Typical Performance Characteristics .....	9
Specifications.....	3	Outline Dimensions .....	10
Absolute Maximum Ratings.....	6	Ordering Guide.....	10
Thermal Resistance .....	6		

**REVISION HISTORY**

10/10—Rev. PrD

10/10—Rev. PrC

9/10—Rev. PrB

9/10—Rev. PrA

## SPECIFICATIONS

$V_S = 5\text{ V}$ ,  $T = 25^\circ\text{C}$ ,  $Z_S = Z_L = 150\Omega$  at 100MHz,  $PM = 0\text{ V}$ , 2 V p-p differential output unless otherwise noted.

Table 1.

Parameter	Conditions	Min	Typ	Max	Unit
<b>DYNAMIC PERFORMANCE</b>					
-3 dB Bandwidth	$V_{OUT} < 2\text{ V p-p}$ (5.2dBm)		700		MHz
Slew Rate			TBD		V/nsec
<b>INPUT STAGE</b>					
Maximum Input Swing	Pins VIN+ and VIN- Gain Code = 111111		8		V p-p
Differential Input Resistance	Differential		150		$\Omega$
Common-Mode Input Voltage			1.5		V
CMRR	Gain Code = 000000		TBD		dB
<b>GAIN</b>					
Maximum Voltage Gain	Gain Code = 000000		20		dB
Minimum Voltage Gain	Gain Code = 111111		-11.5		dB
Gain Step Size			0.5		dB
Gain Flatness	30 MHz < $f_c$ < 200MHz		TBD		dB
Gain Temperature Sensitivity	Gain Code = 000000		TBD		mdB/ $^\circ\text{C}$
Gain Step Response	For $V_{IN} = 0.2\text{V}$ , Gain Code 111111to 000000		15		ns
Gain Conformance Error	Normalized to 10dB gain step		$\pm 0.03$		dB
Phase Conformance Error	Normalized to 10dB gain step		1.0		deg
<b>OUTPUT STAGE</b>					
Output Voltage Swing	Pins OUT+ and OUT- At P1dB, Gain Code = 000000		10		V p-p
Differential Output Resistance	Differential		150		$\Omega$
<b>NOISE/HARMONIC PERFORMANCE</b>					
46 MHz [High Performance Power Mode]					
Noise Figure	Gain Code = 000000, LP = Low		7.6		dB
Second Harmonic	$V_{OUT} = 2\text{ V p-p}$		-90		dBc
Third Harmonic	$V_{OUT} = 2\text{ V p-p}$		-100		dBc
Output IP3			47.1		dBm
Output 1 dB Compression Point			19.0		dBm
46 MHz [Nominal Power Mode]					
Noise Figure	Gain Code = 000000, PM = High		TBD		dB
Second Harmonic	$V_{OUT} = 2\text{ V p-p}$		-90		dBc
Third Harmonic	$V_{OUT} = 2\text{ V p-p}$		-92		dBc
Output IP3			TBD		dBm
Output 1 dB Compression Point			TBD		dBm
<b>NOISE/HARMONIC PERFORMANCE</b>					
70 MHz [High Performance Power Mode]					
Noise Figure	Gain Code = 000000, LP = Low		7.4		dB
Second Harmonic	$V_{OUT} = 2\text{ V p-p}$		-95		dBc
Third Harmonic	$V_{OUT} = 2\text{ V p-p}$		-100		dBc
Output IP3			46.9		dBm
Output 1 dB Compression Point			19.9		dBm

Parameter	Conditions	Min	Typ	Max	Unit
70 MHz [Nominal Power Mode] Noise Figure Second Harmonic Third Harmonic Output IP3 Output 1 dB Compression Point	Gain Code = 000000, PM = High  $V_{OUT} = 2\text{ V p-p}$ $V_{OUT} = 2\text{ V p-p}$		TBD -90 -96		dB dBc dBc dBm dBm
NOISE/HARMONIC PERFORMANCE 140 MHz [High Performance Power Mode] Noise Figure Second Harmonic Third Harmonic Output IP3 Output 1 dB Compression Point	Gain Code = 000000, LP = Low  $V_{OUT} = 2\text{ V p-p}$ $V_{OUT} = 2\text{ V p-p}$		6.8 -90 -96 47 20.1		dB dBc dBc dBm dBm
140 MHz [Nominal Power Mode] Noise Figure Second Harmonic Third Harmonic Output IP3 Output 1 dB Compression Point	Gain Code = 000000, PM = High  $V_{OUT} = 2\text{ V p-p}$ $V_{OUT} = 2\text{ V p-p}$		TBD -90 -94 TBD TBD		dB dBc dBc dBm dBm
NOISE/HARMONIC PERFORMANCE 170 MHz [High Performance Power Mode] Noise Figure Second Harmonic Third Harmonic Output IP3 Output 1 dB Compression Point	Gain Code = 000000, LP = Low  $V_{OUT} = 2\text{ V p-p}$ $V_{OUT} = 2\text{ V p-p}$		6.8 -84 -94 47.2 20.1		dB dBc dBc dBm dBm
170 MHz [Nominal Power Mode] Noise Figure Second Harmonic Third Harmonic Output IP3 Output 1 dB Compression Point	Gain Code = 000000, PM = High  $V_{OUT} = 2\text{ V p-p}$ $V_{OUT} = 2\text{ V p-p}$		TBD -80 -93 TBD TBD		dB dBc dBc dBm dBm
NOISE/HARMONIC PERFORMANCE 240 MHz [High Performance Power Mode] Noise Figure Second Harmonic Third Harmonic Output IP3 Output 1 dB Compression Point	Gain Code = 000000, LP = Low  $V_{OUT} = 2\text{ V p-p}$ $V_{OUT} = 2\text{ V p-p}$		7.0 -78 -95 46.7 20.1		dB dBc dBc dBm dBm
240 MHz [Nominal Power Mode] Noise Figure Second Harmonic Third Harmonic Output IP3 Output 1 dB Compression Point	Gain Code = 000000, PM = High  $V_{OUT} = 2\text{ V p-p}$ $V_{OUT} = 2\text{ V p-p}$		TBD -77 -95 TBD TBD		dB dBc dBc dBm dBm

[查询"ADL5201"供应商](#)

Parameter	Conditions	Min	Typ	Max	Unit
NOISE/HARMONIC PERFORMANCE 300 MHz [High Performance Power Mode]	Gain Code = 000000, LP = Low				
Noise Figure			7.6		dB
Second Harmonic	$V_{OUT} = 2\text{ V p-p}$		-78		dBc
Third Harmonic	$V_{OUT} = 2\text{ V p-p}$		-90		dBc
Output IP3			45.6		dBm
Output 1 dB Compression Point			19.8		dBm
300 MHz [Nominal Power Mode]	Gain Code = 000000, PM = High				
Noise Figure			TBD		dB
Second Harmonic	$V_{OUT} = 2\text{ V p-p}$		-77		dBc
Third Harmonic	$V_{OUT} = 2\text{ V p-p}$		-87		dBc
Output IP3			TBD		dBm
Output 1 dB Compression Point			TBD		dBm
NOISE/HARMONIC PERFORMANCE 380 MHz [High Performance Power Mode]	Gain Code = 000000, LP = Low				
Noise Figure			7.8		dB
Second Harmonic	$V_{OUT} = 2\text{ V p-p}$		-73		dBc
Third Harmonic	$V_{OUT} = 2\text{ V p-p}$		-80		dBc
Output IP3			TBD		dBm
Output 1 dB Compression Point			18.8		dBm
380 MHz [Nominal Power Mode]	Gain Code = 000000, PM = High				
Noise Figure			TBD		dB
Second Harmonic	$V_{OUT} = 2\text{ V p-p}$		-74		dBc
Third Harmonic	$V_{OUT} = 2\text{ V p-p}$		-80		dBc
Output IP3			TBD		dBm
Output 1 dB Compression Point			TBD		dBm
ENABLE INTERFACE	Pin PWUP				
Enable Threshold	Minimum voltage to enable the device			1.4	V
PWUP Input Bias Current			TBD		nA
GAIN CONTROL INTERFACE	Digital pins				
$V_{IH}$	Minimum voltage for a logic high	1.4			V
$V_{IL}$	Maximum voltage for a logic low			0.8	V
Maximum Input Bias Current			TBD		nA
POWER-INTERFACE					
Supply Voltage		4.5		5.5	V
Quiescent Current	PM = Low (High Performance Power Mode)		110		mA
	PM = High (Nominal Power Mode)		80		mA
Power Down Current	PWUP Low		18		mA

## ABSOLUTE MAXIMUM RATINGS

Table Summary

Table 2.

Parameter	Rating
Supply Voltage, $V_{POS}$	5.5 V
PWUP, Digital Pins	-0.6 to ( $V_{POS} + 0.6V$ )
Input Voltage, $V_{IN+}$ , $V_{IN-}$	-0.6 to +3.1V
Internal Power Dissipation	TBD mW
$\theta_{JA}$ (Exposed paddle soldered down)	TBD°C/W
$\theta_{JA}$ (Exposed paddle not soldered down)	TBD°C/W
$\theta_{JC}$ (At exposed paddle)	TBD°C/W
Maximum Junction Temperature	TBD°C
Operating Temperature Range	-40°C to +85°C
Storage Temperature Range	-65°C to +150°C

Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## THERMAL RESISTANCE

$\theta_{JA}$  is specified for the worst-case conditions, that is, a device soldered in a circuit board for surface-mount packages.

Table 3. Thermal Resistance

Package Type	$\theta_{JA}$	$\theta_{JC}$	Unit

## ESD CAUTION



**ESD (electrostatic discharge) sensitive device.** Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

## PIN CONFIGURATION AND FUNCTION DESCRIPTIONS

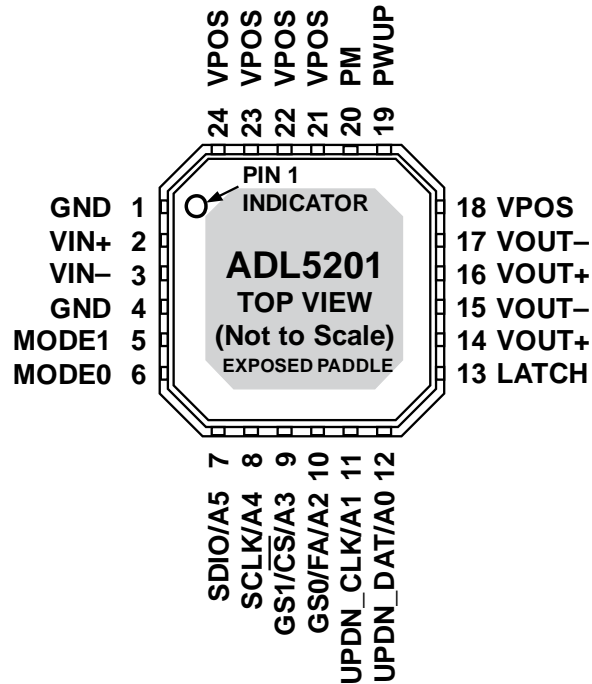


Figure 2.

Table 4. Pin Function Descriptions

Pin No.	Mnemonic	Description
1, 4, EP <sup>1</sup>	GND	Ground
2	VIN+	positive input.
3	VIN-	negative input.
5	MODE1	Mode control parallel, SPI, up/down (MSB)
6	MODE0	Mode control parallel, SPI, up/down (LSB)
7	SDIO/A5	Multifunction pin: Serial data input/output (bidirectional pin) in Parallel mode, this is bit 5. (MSB)
8	SCLK/A4	Multifunction pin: Serial clock input. In parallel mode this bit 4.
9	GS1/ $\overline{\text{CS}}$ /A3	Multifunction pin: MSB for gain step function, chip select and bit 3 in parallel operation.
10	GS0/FA/A2	Multifunction pin: LSB for gain step function, a logic high enables fast attack mode and in parallel mode this pin is bit 2.
11	UPDN_CLK/A1	Multifunction pin: Clock input for up down function. In parallel mode this pin is bit 1.
12	UPDN_DAT/A0	Multifunction pin: Data pin for up down function. In parallel mode this is bit 0 (LSB)
13	LATCH	Latch, a low input results in gain change. A high input results in no gain change.
14, 16	VOUT+	Positive output.
15, 17	VOUT-	Negative output.
18, 21, 23, 24	VPOS	Positive power supply.
19	PWUP	Power up pin. A logic high enables the part.
20	PM	High performance power mode (active high), Nominal power mode (low)

<sup>1</sup> Exposed Paddle

## DIGITAL INTERFACE OVERVIEW

The ADL5201 DVGA has three digital control interface options:

- Parallel Control Interface
- Serial Peripheral Interface
- Gain Step Up/Down Interface

The digital control interface selection is made via 2 digital pins, MODE1 and MODE0, as shown in Table 5. There are two common digital control pins, PM and PWUP. PM selects between two power modes. PWUP is a power up pin. The gain code used is 6 bit binary.

Physical pins are shared between 3 interfaces resulting in as many as 3 different functions per digital pin (see Table 4).

**Table 5. Digital control interface selection truth table**

MODE1	MODE0	Interface
0	0	Parallel
0	1	Serial (SPI)
1	0	Up/Down
1	1	Up/Down

### Parallel Digital Interface

The parallel digital interface uses 6 gain control bits and a latch pin. The latch pin controls whether the input data latch is transparent or latched. In transparent mode, gain changes as input gain control bits change. In latched mode, gain is determined by the latched gain setting and does not change with changing input gain control bits.

### Serial Peripheral Interface (SPI)

The SPI uses 3 pins (SDIO, SCLK and  $\overline{CS}$ ). The SPI data register consists of 2 bytes: 6 gain control bits, 2 attenuation step size address bits, 1 read/write bit, and 7 do not care bits.

The SPI uses a bidirectional pin, SDIO, for writing to the SPI register and for reading from the SPI register. In order to write to the SPI register  $\overline{CS}$  needs to be pulled low and 16 clock pulses must be applied.

In order to read the SPI register value, the R/W bit needs to be set high,  $\overline{CS}$  needs to be pulled low, and the part clocked. Once the register has been read out the R/W bit needs to be set low and SPI put in write mode.

SPI fast attack mode is controlled by FA pin. A logic high on the FA pin results in an attenuation selected by FA1 and FA0 bits in the SPI register.

**Table 6. SPI 2-bit attenuation step size truth table**

FA1	FA0	Step Size (dB)
0	0	2
0	1	4
1	0	8
1	1	16

### UP/DOWN Interface

The UP/DOWN interface uses two digital pins to control the gain. Gain is increased by a clock pulse on UPDN\_CLK (rising and falling edges) when UPDN\_DAT is high. Gain is decreased by a clock pulse on UPDN\_CLK when UPDN\_DAT is low. Reset is detected by a rising edge latching data having one polarity with the falling edge latching the opposite polarity. Reset results in minimum gain code 111111<sub>bin</sub>.

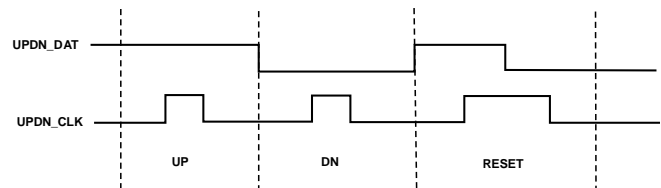


Figure 3. UP/DOWN Timing

The step size is selectable by pins GS1 and GS0. The default step size is 0.5dB. The gain code count will rail at the top and bottom of the control range.

**Table 7. Step size control truth table**

GS1	GS0	Step Size (dB)
0	0	0.5
0	1	1
1	0	2
1	1	4

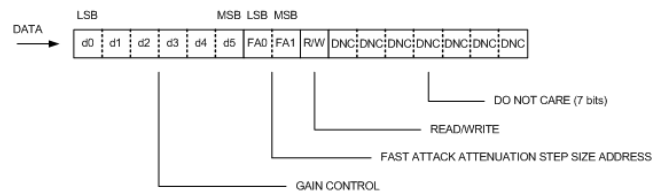


Figure 4. 16 bit SPI Register



# TYPICAL PERFORMANCE CHARACTERISTICS

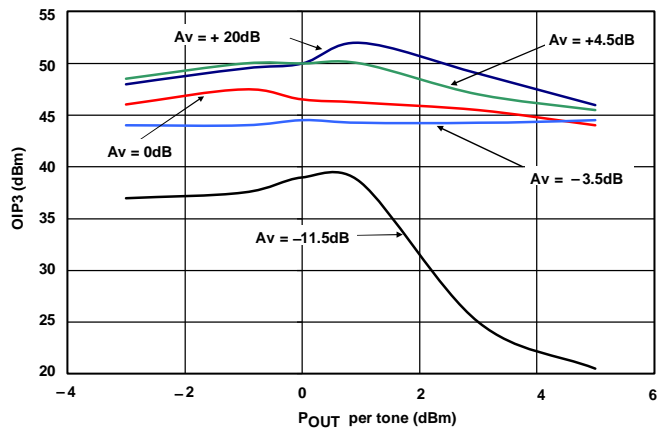


Figure 5. OIP3 Vs. Power @ 5 Gains

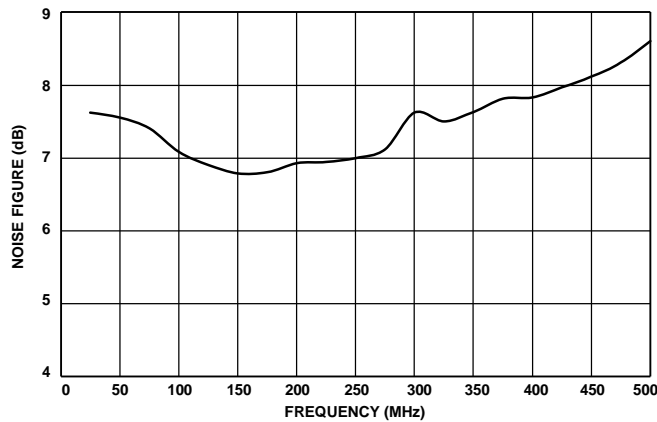


Figure 8. Noise Figure Vs. Frequency at Max Gain

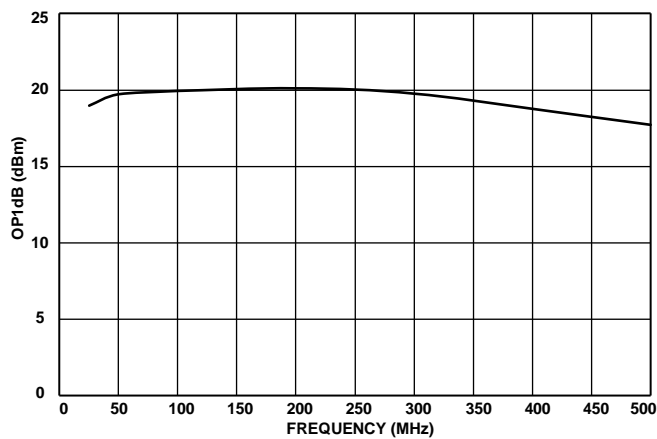


Figure 6. P1dB Vs. Frequency at Max Gain

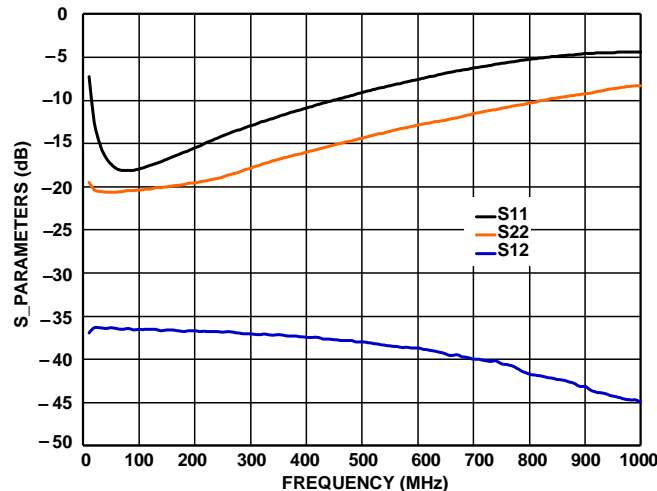


Figure 9. S11, S12 and S22 Vs. Frequency

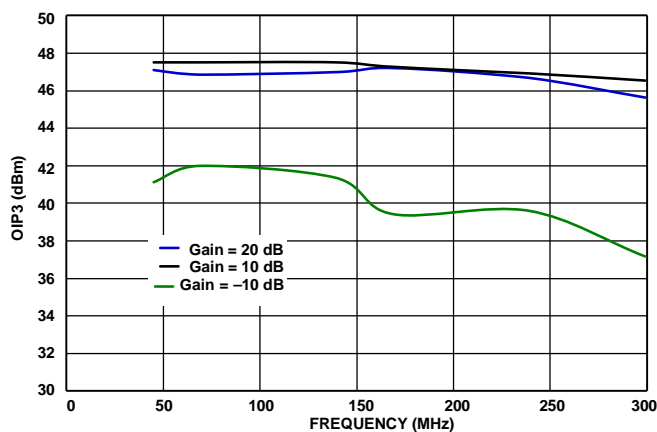


Figure 7. OIP3 Vs. Gain and Frequency

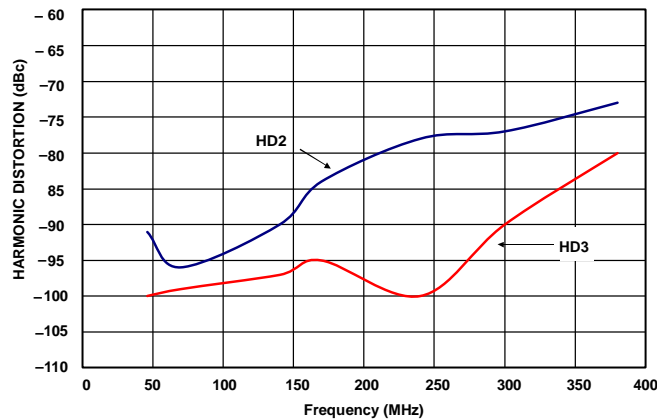


Figure 10. Harmonic Distortion Vs. Frequency 2Vp-p Out

## OUTLINE DIMENSIONS

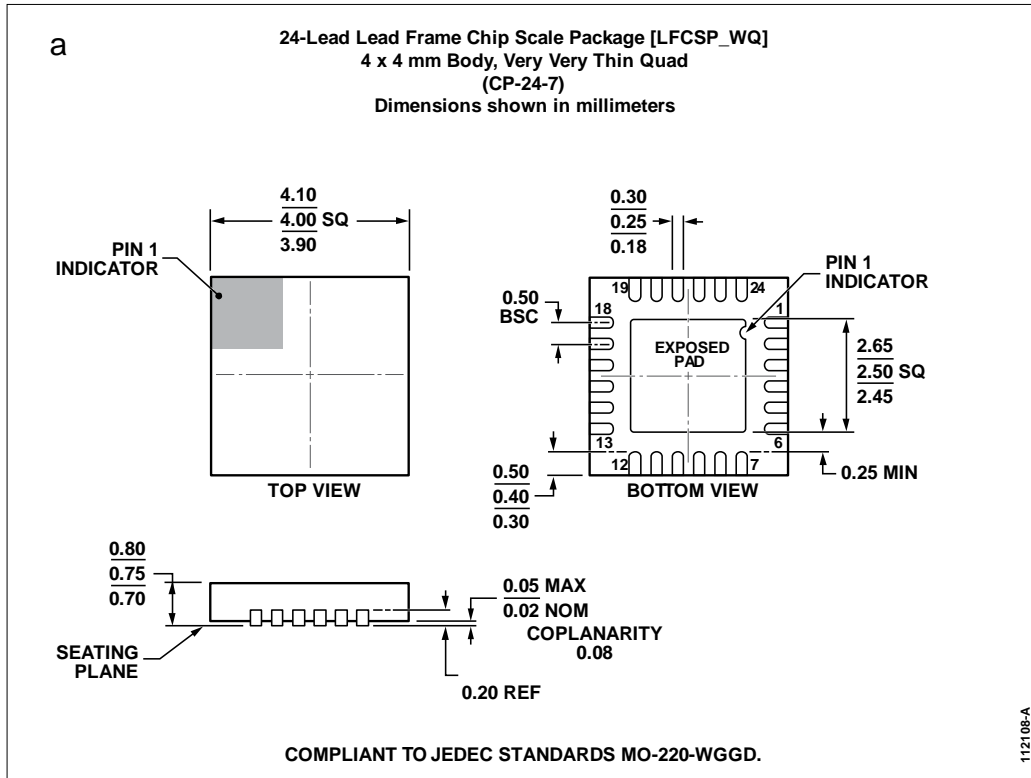


Figure 11. 24-Lead Lead Frame Chip Scale Package [LFCSP\_WQ]  
4 mm × 4 mm Body, Very Thin Quad  
(CP-24-7)  
Dimensions shown in millimeters

## ORDERING GUIDE

Model	Temperature Range	Package Description	Package Option
ADL5201XCPZ-R7 <sup>1</sup>	-40°C to +85°C	24 Lead LFCSP_WQ, 7" Reel	CP-24-7
ADL5201XCPZ-WP <sup>1</sup>	-40°C to +85°C	24 Lead LFCSP_WQ, Waffle Pack	CP-24-7
ADL5201-EVALZ <sup>1</sup>	-40°C to +85°C	Evaluation Board	

<sup>1</sup> Z = RoHS Compliant Part