

# LM98555 CCD Driver

### **General Description**

The LM98555 is a highly integrated driver circuit intended for CCD driving applications. It combines 25 drivers of varying drive strengths into one chip to provide a complete CCD driving solution. Due to this one-chip integration, optimal skew control is achieved for this demanding application.

### Features

- All CCD drivers integrated into one package
- High strength drivers designed specifically for CCD loads
- Ability to scale clock driver strength
- Skew specifications guaranteed
- Separate input and output power supplies
- **Functional Description**

- CMOS process technology
- 64-pin TSSOP package with extended power handling capability

# **Key Specifications**

Supply Voltage	Inputs	3.0 to 5.5V
	Drivers	4.5 to 5.8V
Maximum Output Skew	Between P1A	0.5 ns
	and P2A	
	outputs	
Maximum Power		2.0W
Dissipation		

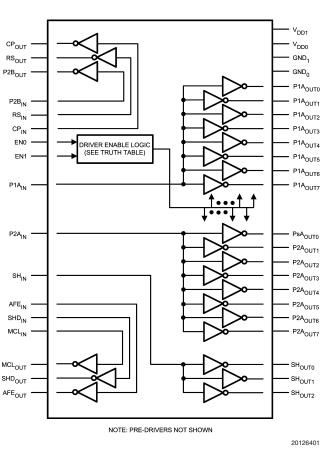


FIGURE 1. Functional Block Diagram

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**N198555** 

# **Ordering Information**

L-<u>M98555"供应商</u> Commercial Temperature Range NS Package

LM98555CCMH

64-Pin Exposed Pad TSSOP

### **Connection Diagram**

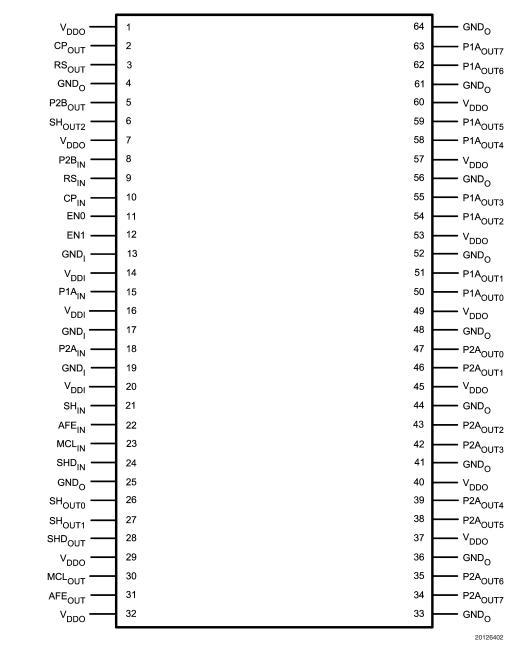


FIGURE 2. TSSOP Package Pinout

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Symbol	<del>8555"供</del> 供应	Туре	Description
Driver inpu			
P2B <sub>IN</sub>	8	Input	CMOS logic input for the P2B driver.
RS <sub>IN</sub>	9	Input	CMOS logic input for the RS driver.
CPIN	10	Input	CMOS logic input for the CP driver.
P1A <sub>IN</sub>	15	Input	CMOS logic input for the P1A ganged (8) driver set.
P2A <sub>IN</sub>	18	Input	CMOS logic input for the P2A ganged (8) driver set.
SHIN	21	Input	CMOS logic input for the SH ganged (3) driver set.
AFEIN	22	Input	CMOS logic input for the AFE driver.
MCLIN	23	Input	CMOS logic input for the MCL driver.
SHDIN	24	Input	CMOS logic input for the SHD driver.
Driver Outp	outs	I	1
SHD <sub>OUT</sub>	28	Output;	Driver output for the SHD <sub>IN</sub> input signal.
		Low-Strength	
MCLOUT	30	Output;	Driver output for the MCL <sub>IN</sub> input signal.
		Low-Strength	
AFE <sub>OUT</sub>	31	Output;	Driver output for the AFE <sub>IN</sub> input signal.
		Low-Strength	
CPOUT	2	Output;	Driver output for the $\mbox{CP}_{\rm IN}$ input signal. Typically used to drive the Clamp
		Low-Strength	Gate input of the CCD.
RS <sub>OUT</sub>	3	Output;	Driver output for the $RS_{IN}$ input signal. Typically used to drive the Reset
		Low-Strength	Gate input of the CCD.
P2B <sub>OUT</sub>	5	Output;	Driver output for the P2B <sub>IN</sub> input signal.
		Low-Strength	
P2A <sub>OUT0</sub>	47	Output;	Ganged driver outputs for the P2A <sub>IN</sub> input. Typically the user may join
P2A <sub>OUT1</sub>	46	TRI-STATE®; High-Strength	together these outputs to drive the $\phi$ 2 clock input of the CCD. Some of these outputs may be disabled using the EN(1:0) inputs - see the
P2A <sub>OUT2</sub>	43	l ligh-Strength	Functional Description section.
P2A <sub>OUT3</sub>	42		
P2A <sub>OUT4</sub>	39		
P2A <sub>OUT5</sub>	38		
P2A <sub>OUT6</sub>	35		
P2A <sub>OUT7</sub>	34		
P1A <sub>OUT0</sub>	50	Output;	Ganged driver outputs for the $P1A_{IN}$ input. Typically the user may join
P1A <sub>OUT1</sub>	51	TRI-STATE; High-Strength	together these outputs to drive the $\phi$ 1 clock input of the CCD. Some of these outputs may be disabled using the EN(1:0) inputs - see the
P1A <sub>OUT2</sub>	54	nigh-Strength	Functional Description section.
P1A <sub>OUT3</sub>	55		
P1A <sub>OUT4</sub>	58		
P1A <sub>OUT5</sub>	59		
P1A <sub>OUT6</sub>	62		
P1A <sub>OUT7</sub>	63		
SH <sub>OUT0</sub>	26	Output;	Ganged driver outputs for the SH <sub>IN</sub> input signal. Typically used to drive the
SH <sub>OUT1</sub>	27	Low-Strength	Shift Gate input of the CCD.
SH <sub>OUT2</sub>	6		
Logic Input			-
EN0	11	Input	Driver enable control. Some of the P1A and P2A drivers can be disabled
EN1	12		using these inputs. See the Functional Description section.

98555"供[ Symbol	Pin	Туре	Description
Power & G			
V <sub>DDI</sub>	14	Power	V <sub>DD</sub> for pre-drivers.
	16		
	20		
V <sub>DDO</sub>	1	Power	V <sub>DD</sub> for final-stage driver.
_	7		
	29		
	32		
	37		
	40		
	45		
	49		
	53		
	57		
	60		
GND	13	Ground	Ground connection for all circuitry other than the Final-Stage Drive
	17		
	19		
GND <sub>O</sub>	4	Ground	Ground connection for the Final-Stage Drivers.
	25		
	33		
	36		
	41		
	44		
	48		
	52		
	56		
	61		
	64		

# Absolute Maximum Ratings (Note 1)

If 面視小人的。有效。 please contact the National Semiconductor Sales Office/ Distributors for availability and specifications.

Supply Voltage	-0.5V to 6.2V
Package Power Rating at 25°C	
(Note 2)	2.0 Watts
Voltage on Any Input or Output Pin	–0.5V to $V_{\rm DD}\text{+}0.5\text{V}$
DC Input Current at Any Pin	25 mA
DC Package Input Current	50 mA
Storage Temperature	–65°C to +150°C
Lead temperature (Soldering, 10	
sec.)	300°C
ESD Susceptibility	
Human Body Model	2000V
Machine Model	200V

# **Operating Conditions**

Supply Voltage	
V <sub>DDI</sub>	+3.0V to +5.5V
Supply Voltage	
V <sub>DDO</sub>	+4.5V to +5.8V
Ambient Temperature (T <sub>A</sub> )	0 to 70°C
Operating Frequency	30 MHz
Power Dissipation (Note 3)	2.0W

### **Package Thermal Resistances**

Package	θ <sub>J-A</sub> (Note 4)	θ <sub>J-PAD</sub> (Thermal Pad)
64-Lead Exposed Pad TSSOP	36.8°C / W	6.2°C / W

# **DC Electrical Characteristics**

The following specifications apply for GND = 0V,  $V_{DDI}$  = 3.3V,  $V_{DDO}$  = 5.0V, unless noted otherwise. Boldface limits apply for T<sub>A</sub>= T<sub>MIN</sub> to T<sub>MAX</sub>; all other limits T<sub>A</sub>= 25°C

Symbol	Parameter	Conditions	Min	Typical	Max	Units
I <sub>I</sub>	Logic 1 Input Current	$V_{I} = V_{DDI}$	-1	0.004	1	μA
	Logic 0 Input Current	$V_1 = GND_1$	-1	0.006	1	μA
V <sub>IT</sub>	Input Threshold	V <sub>DDI</sub> = 3.3V	1.41	1.57	1.75	V
	Input Threshold	$V_{DDI} = 5.0V$		2.48		V
	Input Threshold Hysteresis	V <sub>DDI</sub> = 3.3V	-72	11	100	mV
$\Delta V_{IT}$	Input Threshold Variation	Between P1A, P2A inputs	-100		100	mV
R <sub>o</sub>	Output Impedance P1A and P2A Outputs	$I_{LOAD} = 525 \text{ mA}$ $R_{O} = (V_{DDO} - V_{O})/I_{OH} \text{ or}$ $R_{O} = V_{O}/I_{OL}$		6.1	9.9	Ω
R <sub>o</sub>	Output Impedance All Other Outputs	$I_{LOAD} = 280 \text{ mA}$ $R_{O} = (V_{DDO} - V_{O})/I_{OH} \text{ or}$ $R_{O} = V_{O}/I_{OL}$		10.2	17.4	Ω

## **AC Electrical Characteristics**

The following specifications apply for GND = 0V,  $V_{DDI}$  = 3.3V,  $V_{DDO}$  = 5.0V, unless noted otherwise. Boldface limits apply for  $T_A = T_{MIN}$  to  $T_{MAX}$ ; all other limits  $T_A = 25^{\circ}C$ 

Symbol	Parameter	ter Conditions		Typical	Max	Units	
t <sub>PHL</sub>	Prop Delay: High-to-Low	$CL = 220 \text{ pF}, \text{ R}_{L} = 10\Omega$	3.06	4.6	6.55	ns	
	P1A and P2A Outputs	(Note 5)					
t <sub>PHL</sub>	Prop Delay: High-to-Low	$CL = 82 \text{ pF}, R_L = 10\Omega$		4.1		ns	
	CP, RS, P2B Outputs	(Note 5)					
		(Note 7)					
t <sub>PLH</sub>	Prop Delay: Low-to-High	$CL = 220 \text{ pF}, \text{ R}_{L} = 10\Omega$	3.38	4.9	6.68	ns	
	P1A and P2A Outputs	(Note 6)					
t <sub>PLH</sub>	Prop Delay: Low-to-High	$CL = 82 \text{ pF}, \text{ R}_{L} = 10\Omega$		4.2		ns	
	CP, RS, P2B Outputs	(Note 6)					
		(Note 7)					
t <sub>skew</sub>	Prop Delay Skew High-to-Low	Between any P1A or P2A		109	387	ps	
		Outputs on a Single Unit				-	
	Prop Delay Skew Low-to-High	$C_{L} = 220 \text{ pF}, R_{L} = 10\Omega$		157	490		

Important Note: Not all drivers can be loaded to the highest specified load at the same time without violating the maximum power dissipation limit. The system design must guarantee that the maximum power dissipation specification is never exceeded.

### AC Electrical Characteristics (Continued)

"LNATO 8 7555 (Character at the second which the safety of the device cannot be guaranteed. They are not meant to imply that the device should be operated at these limits.

**Note 2:** Package power rating assumes the exposed thermal pad is soldered to the printed circuit board as recommended, with significant heat spreading provided by vias to internal or bottom heat dissipation planes or pad. If this is not the case, then the package power rating should be reduced. See the Thermal Guidelines in the applications section for more information.

Note 3: This is the power dissipated on-chip due to all currents flowing through the device - both DC and AC. This operating condition will be violated if all driver outputs are fully loaded and operating at the same time at the rated F<sub>MAX</sub>. The system design must constrain the chip's operating conditions (loads, power supply, number of parallel drivers enabled, frequency of operation) to make certain that this limit is never exceeded.

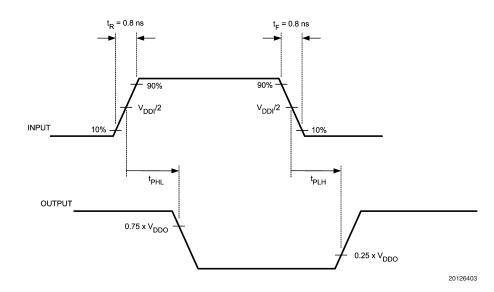
Note 4: Package thermal resistance for junction to ambient is based on a 5.5 inch by 3 inch, 4 layer printed circuit board, with thermal vias connecting the heat sinking pad to a full internal ground plane. Tests were done in still air, with a power dissipation of 2.0 W, at an ambient temperature of 22°C.

Note 5: Propagation Delay High-to-Low with output low trigger voltage at  $V_{\text{DDO}} \ensuremath{^{+}0.75}$  .

Note 6: Propagation Delay Low-to-High with output high trigger voltage at V<sub>DDO</sub>\*0.25.

Note 7: Typical values determined from characterization testing only. Not production tested or guaranteed.

### **Test Conditions**





# **Application Information**

The No. 1985 Solution of the package. Clock driver/buffer for high speed CCD applications. It provides high performance low impedance drivers, with optimized low skew performance of the P1 and P2 outputs. Enable inputs allow use of two, four, six, or all eight P1 and P2 drivers to optimize the amount of drive for the application. The 64 pin thermally enhanced TSSOP provides excellent power handling through the use of an exposed heat transfer pad on the underside of the package.

#### THERMAL GUIDELINES

The LM98555's maximum power dissipation limit, shown in the Operating Conditions section, must be strictly adhered to. The product's multiple high-strength drivers, with their ability to drive a wide-range of loads, make it possible to be within spec on each output and yet violate the aggregate maximum power dissipation limit for the total product. Special caution must be paid to this by limiting the chip's operating conditions (loads, power supply, number of parallel drivers enabled, frequency of operation) to make certain that the maximum power dissipation limit is never exceeded.

Thermal characterization of the device has been done to provide reference points under specific conditions.  $\theta$  junction to ambient was measured using a 5.5 inch by 3 inch, 4 layer PCB. The thermal contact pad on the board was connected using vias to a full ground plane on one of the internal layers. The recommended thermal pad is shown in *Figure 4*.

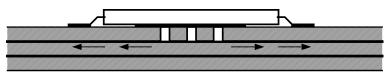
Exposed thermal pad mounting area. Ο 0 Ο Ο Ο 0 Ο Ο 3.81 mm 0 Ο Ο Ο 5.81 mm Vias are 0.3 mm diameter at 1.2 mm pitch. Recommended via plating of 1 oz copper.

LM98555

#### FIGURE 4. Exposed Pad Land Pattern

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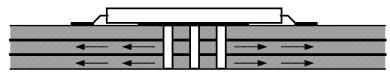
The vias shown provide a path for heat to flow from the pad to a heat sinking or dissipating area of the printed circuit board. The following figures show several typical examples of how this can be done, and illustrate how heat is conducted away from the IC to larger areas where it is dissipated.



Vias couple thermal energy to internal ground plane to transfer heat away from package.

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Vias couple thermal energy to internal ground planes and heat spreader pad on bottom layer to transfer heat away from package.

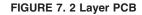
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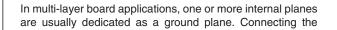




Vias couple thermal energy to copper plane on bottom layer to transfer heat away from package.

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thermal pad to this ground plane with vias will usually provide adequate heat management. In 2 layer boards, it is

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### Application Information (Continued)

**THEOREM 1** a large heat spreading pad on the opposite side of the board. The vias will provide a good thermal connection between the pad under the IC, and the heat spreading pad on the bottom of the board. Thermal modelling can be done using the  $\theta$  junction to pad information provided, to calculate the required area of copper based on the ambient temperature of the system, and the calculated amount of thermal dissipation in the LM98555.

### POWER DISSIPATION

The amount of power dissipated in the device can be determined by considering the following factors:

- Power dissipated delivering energy to the load capacitance
- Power dissipated delivering energy to parasitic capacitance
- · Power dissipated due to leakage in the IC

The amount of power dissipated due to leakage is very small in this CMOS device. Most of the power will be due to the load capacitance being switched, with a small additional amount caused by the parasitic capacitance of the output circuitry, output pins, and PCB traces. A typical parasitic capacitance would be on the order of 5 pF. Since the load capacitance will be on the order of 100 pF or more, this usually dominates the power dissipation calculation. The following equation can be used to calculate the power dissipation due to capacitive switching of the loads:

P = Sum[Output Frequency x Load Capacitance x Output Voltage Squared] (summed for all outputs)

#### INPUT SIGNALS

Care should be taken to match the trace lengths between timing signals that require low skew. Usually, the P1A and P2A signals will be the most critical. In some applications, the timing of P2B with respect to P1A and P2A can also be important, and that input trace should also be carefully designed.

Trace shape and width should also be carefully controlled. The trace geometry will determine the characteristic impedance of each trace. The impedance should be set to give reasonable immunity to noise coupling into the trace. With a known trace impedance, the signals can be terminated using a series resistor at the source that is equal to the characteristic impedance. This will provide a signal with minimum overshoot and ringing, and will contribute to better performance of the final signal reaching the CCD.

#### OUTPUT CONNECTIONS AND LOADING EXAMPLES

The LM98555 can be used with a wide variety of different CCD sensors. The P1Aoutx and P2Aoutx outputs can be selectively enabled to provide 2, 4, 6, or 8 drivers. This allows the available drive strength to be optimized for the sensor and application. Connecting multiple outputs together in parallel as shown in the typical application circuit provides lower drive impedance as needed to suit the load being driven. When driving smaller loads, lower switching noise will be generated if the minimum necessary outputs are enabled and used.

The output signal traces should also be designed for a known impedance. Source terminating resistors should be

used in series with each output to provide good matching to the trace characteristic impedance. The resistors should be located as close as possible to each output pin. If multiple outputs will be combined to drive a single load pin, the output signals should be combined after the termination resistors. This will provide the best summing of adjacent outputs. The combined signal should then pass through an EMI type ferrite bead. This component can be selected to change the bandwidth or shape of the clocking signal to achieve the best CCD transfer efficiency.

Several other techniques will also help maintain signal quality, and minimize timing differences between critical signals. Vias should not be used for critical timing signals. These can add impedance discontinuities that will affect the waveform quality. Traces should have gradual bends and avoid sharp changes in direction that can also introduce impedance discontinuities.

#### SELECTIVE DRIVER ENABLING

With the Enable pins, the user has the capability to enable only the drivers that are required for the application, thus eliminating unnecessary outputs switching. The following table shows the details.

EN1	EN0	Driver-set State
0	0	P1Aout(1:0) and P2Aout(1:0) are enabled;
		all others disabled.
0	1	P1Aout(3:0) and P2Aout(3:0) are enabled;
		all others disabled.
1	0	P1Aout(5:0) and P2Aout(5:0) are enabled;
		all others disabled.
1	1	All P1Aout and P2Aout drivers are enabled.
Note: The disabled drivers' outputs are in TRI-STATE.		

#### **POWER AND GROUND - PLANES VERSUS BUSES**

The best performance will be achieved by using planes rather than traces for power and ground. Planes provide lower electrical and thermal impedance. Ground bounce and ringing are reduced, electromagnetic emissions are minimized and the best thermal performance will be realized.

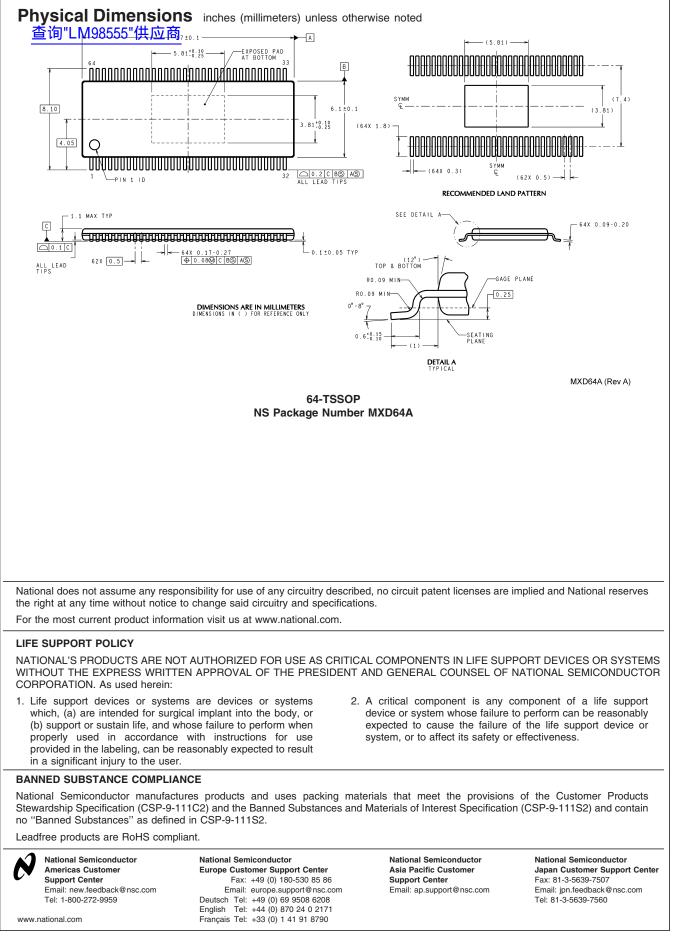
A single common ground plane should be used for all power and signal domains.

Another circuit board layer can be used to provide power to the various circuitry. Different power buses can be provided by isolated planes within this layer of the circuit board.

#### EMI MANAGEMENT

Good EMI control will be achieved by addressing the following items:

- · Provide proper source termination of output signals
- · Limit length of output traces
- Ensure adequate power supply decoupling
- Provide power and ground planes as much as possible
- Provide common ground plane for all signals, especially between LM98555 outputs and load CCD
- · Enable and use the minimum number of outputs needed



LM98555 CCD Driver