# FAIRCHILD

SEMICONDUCTOR

# 74VHC163 4-Bit Binary Counter with Synchronous Clear

### **General Description**

The VHC163 is an advanced high-speed CMOS device fabricated with silicon gate CMOS technology. It achieves the high-speed operation similar to equivalent Bipolar Schottky TTL while maintaining the CMOS low power dissipation.

The VHC163 is a high-speed synchronous modulo-16 binary counter. This device is synchronously presettable for application in programmable dividers and has two types of Count Enable inputs plus a Terminal Count output for versatility in forming multistage counters. The <u>CLK</u> input is active on the rising edge. Both PE and MR inputs are active on low logic level. Presetting is synchronous to rising edge of CLK and the Clear function of the VHC163 is synchronous to CLK. Two enable inputs (ENP and ENT) and Carry Output are provided to enable easy cascading of counters, which facilitates easy implementation of n-bit counters without using external gates.

An input protection circuit insures that 0V to 7V can be applied to the input pins without regard to the supply voltage. This device can be used to interface 5V to 3V systems and two supply systems such as battery backup. This circuit prevents device destruction due to mismatched supply and input voltages.

September 1995

Revised August 2001

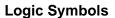
#### Features

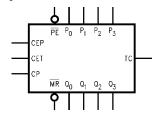
- High speed: f<sub>MAX</sub> = 185 MHz (typ) at V<sub>CC</sub> = 5V
- Low power dissipation:  $I_{CC} = 4 \mu A (max)$  at  $T_A = 25^{\circ}C$
- Synchronous counting and loading
- High-speed synchronous expansion
- $\blacksquare \text{ High noise immunity: } V_{NIH} = V_{NIL} = 28\% V_{CC} \text{ (min)}$
- Power down protection is provided on all inputs.
- Low noise: V<sub>OLP</sub> = 0.8V (max)
- Pin and function compatible with 74HC163

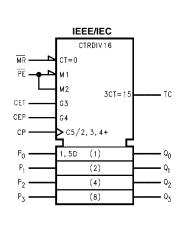
### **Ordering Code:**

Order Number	Package Number	Package Description
74VHC163M	M16A	16-Lead Small Outline Integrated Circuit (SOIC), JEDEC MS-012, 0.150" Narrow
74VHC163SJ	M16D	16-Lead Small Outline Package (SOP), EIAJ TYPE II, 5.3mm Wide
74VHC163MTC	MTC16	16-Lead Thin Shrink Small Outline Package (TSSOP), JEDEC MO-153, 4.4mm Wide
74VHC163N	N16E	16-Lead Plastic Dual-In-Line Package (PDIP), JEDEC MS-001, 0.300" Wide

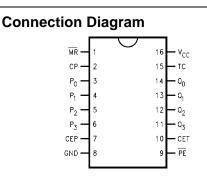
Surface mount packages are also available on Tape and Reel. Specify by appending the suffix letter "X" to the ordering code.







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### **Functional Description**

The VHC163 counts in modulo-16 binary sequence. From state 15 (HHHH) it increments to state 0 (LLLL). The clock inputs of all flip-flops are driven in parallel through a clock buffer. Thus all changes of the Q outputs occur as a result of, and synchronous with, the LOW-to-HIGH transition of the CP input signal. The circuits have four fundamental modes of operation, in order of precedence: synchronous reset, parallel load, count-up and hold. Four control inputs-Synchronous Reset (MR), Parallel Enable (PE), Count Enable Parallel (CEP) and Count Enable Trickle (CET)-determine the mode of operation, as shown in the Mode Select Table. A LOW signal on MR overrides counting and parallel loading and allows all outputs to go LOW on the next rising edge of CP. A LOW signal on PE overrides counting and allows information on the Parallel Data (P<sub>n</sub>) inputs to be loaded into the flip-flops on the next rising edge of CP. With PE and MR HIGH, CEP and CET permit counting when both are HIGH. Conversely, a LOW signal on either CEP or CET inhibits counting.

The VHC163 uses D-type edge-triggered flip-flops and changing the MR, PE, CEP and CET inputs when the CP is in either state does not cause errors, provided that the recommended setup and hold times, with respect to the rising edge of CP, are observed.

The Terminal Count (TC) output is HIGH when CET is HIGH and counter is in state 15. To implement synchro-

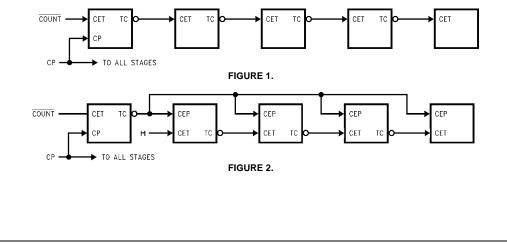
#### **Pin Descriptions**

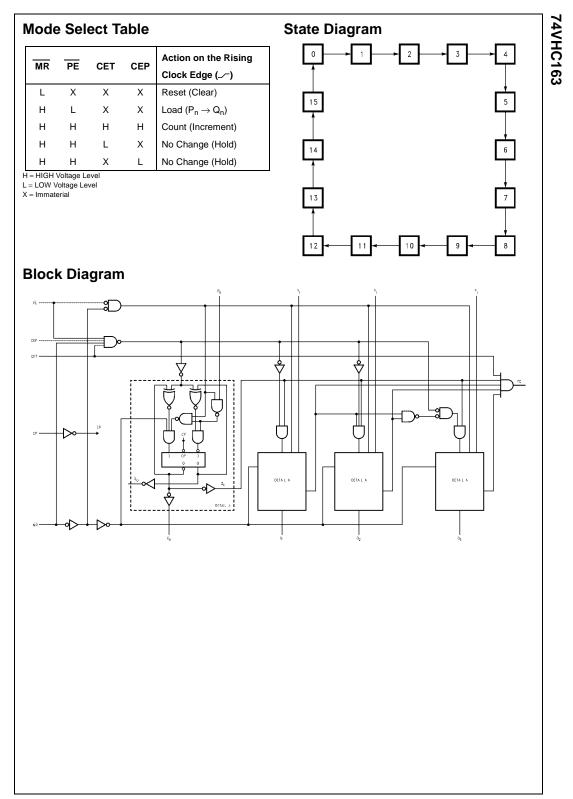
Pin Names	Description
CEP	Count Enable Parallel Input
CET	Count Enable Trickle Input
СР	Clock Pulse Input
MR	Synchronous Master Reset Input
P <sub>0</sub> -P <sub>3</sub>	Parallel Data Inputs
PE	Parallel Enable Inputs
Q <sub>0</sub> -Q <sub>3</sub>	Flip-Flop Outputs
тс	Terminal Count Output

nous multistage counters, the TC outputs can be used with the CEP and CET inputs in two different ways.

Figure 1 shows the connections for simple ripple carry, in which the clock period must be longer than the CP to TC delay of the first stage, plus the cumulative CET to TC delays of the intermediate stages, plus the CET to CP setup time of the last stage. This total delay plus setup time sets the upper limit on clock frequency. For faster clock rates, the carry lookahead connections shown in Figure 2 are recommended. In this scheme the ripple delay through the intermediate stages commences with the same clock that causes the first stage to tick over from max to min in the Up mode, or min to max in the Down mode, to start its final cycle. Since this final cycle takes 16 clocks to complete, there is plenty of time for the ripple to progress through the intermediate stages. The critical timing that limits the clock period is the CP to TC delay of the first stage plus the CEP to CP setup time of the last stage. The TC output is subject to decoding spikes due to internal race conditions and is therefore not recommended for use as a clock or asynchronous reset for flip-flops, registers or counters.

Logic Equations: Count Enable = CEP • CET •  $\overrightarrow{PE}$ TC = Q<sub>0</sub> • Q<sub>1</sub> • Q<sub>2</sub> • Q<sub>3</sub> • CET





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### Absolute Maximum Ratings(Note 1)

Supply Voltage (V <sub>CC</sub> )	-0.5V to +7.0V
DC Input Voltage (V <sub>IN</sub> )	-0.5V to +7.0V
DC Output Voltage (V <sub>OUT</sub> )	$-0.5 V$ to $V_{CC} + 0.5 V$
Input Diode Current (I <sub>IK</sub> )	–20 mA
Output Diode Current (I <sub>OK</sub> )	±20 mA
DC Output Current (I <sub>OUT</sub> )	±25 mA
DC V <sub>CC</sub> /GND Current (I <sub>CC</sub> )	±50 mA
Storage Temperature (T <sub>STG</sub> )	$-65^{\circ}C$ to $+150^{\circ}C$
Lead Temperature (T <sub>L</sub> )	
(Soldering, 10 seconds)	260°C

#### **Recommended Operating** Conditions (Note 2)

Supply Voltage (V <sub>CC</sub> )	2.0V to +5.5V
Input Voltage (V <sub>IN</sub> )	0V to +5.5V
Output Voltage (V <sub>OUT</sub> )	0V to V <sub>CC</sub>
Operating Temperature (T <sub>OPR</sub> )	$-40^{\circ}C$ to $+85^{\circ}C$
Input Rise and Fall Time $(t_r, t_f)$	

 $V_{CC}=3.3V\pm0.3V$ 0 ~ 100 ns/V  $V_{CC}=5.0V\pm0.5V$ 0 ~ 20 ns/V Note 1: Absolute Maximum Ratings are values beyond which the device may be damaged or have its useful life impaired. The databook specifications should be met, without exception, to ensure that the system design is

reliable over its power supply, temperature, and output/input loading vari-ables. Fairchild does not recommend operation outside databook specifications.

Note 2: Unused inputs must be held HIGH or LOW. They may not float.

# **DC Electrical Characteristics**

Symbol	Parameter	V <sub>CC</sub>	$T_A = 25^{\circ}C$		$T_A = -40^{\circ}C$ to $+85^{\circ}C$		Units	Conditions		
	Parameter	(V)	Min	Тур	Max	Min	Max	Units	Conditions	
V <sub>IH</sub>	HIGH Level	2.0	1.50			1.50		V		
	Input Voltage	3.0 - 5.5	$0.7  V_{CC}$			0.7 V <sub>CC</sub>		v		
V <sub>IL</sub>	LOW Level	2.0			0.50		0.50	V		
	Input Voltage	3.0 - 5.5			0.3 V <sub>CC</sub>		0.3 V <sub>CC</sub>	v		
V <sub>OH</sub>	HIGH Level	2.0	1.9	2.0		1.9			$V_{IN} = V_{IH}$	I <sub>OH</sub> = -50 μA
	Output Voltage	3.0	2.9	3.0		2.9		V	or V <sub>IL</sub>	
		4.5	4.4	4.5		4.4				
		3.0	2.58			2.48		V		$I_{OH} = -4 \text{ mA}$
		4.5	3.94			3.80		v		$I_{OH} = -8 \text{ mA}$
V <sub>OL</sub>	LOW Level	2.0		0.0	0.1		0.1		$V_{IN} = V_{IH}$	$I_{OL} = 50 \ \mu A$
	Output Voltage	3.0		0.0	0.1		0.1	V	or V <sub>IL</sub>	
		4.5		0.0	0.1		0.1			
		3.0			0.36		0.44	V		$I_{OL} = 4 \text{ mA}$
		4.5			0.36		0.44	v		$I_{OL} = 8 \text{ mA}$
I <sub>IN</sub>	Input Leakage Current	0 - 5.5			±0.1		±1.0	μΑ	V <sub>IN</sub> = 5.5V	or GND
I <sub>CC</sub>	Quiescent Supply Current	5.5			4.0		40.0	μΑ	$V_{IN} = V_{CC}$	or GND

# **Noise Characteristics**

Symbol	Parameter	v <sub>cc</sub>	$T_A = 25^{\circ}C$		Units	Conditions	
Cymbol	i alamotor	(V) Typ		Limits	onno		
V <sub>OLP</sub>	Quiet Output Maximum	5.0	0.4	0.8	V	C <sub>1</sub> = 50 pF	
(Note 3)	Dynamic V <sub>OL</sub>	5.0	0.4	0.0	v	CL = 30 βi	
V <sub>OLV</sub>	Quiet Output Minimum	5.0	-0.4	-0.8	V	C <sub>1</sub> = 50 pF	
(Note 3)	Dynamic V <sub>OL</sub>	5.0	-0.4	-0.0	v	CL = 30 βi	
V <sub>IHD</sub>	Minimum HIGH Level	5.0		3.5	V	C 50 pE	
(Note 3)	Dynamic Input Voltage	5.0		3.5	v	C <sub>L</sub> = 50 pF	
V <sub>ILD</sub>	Maximum LOW Level	5.0		1.5	V	C <sub>1</sub> = 50 pF	
(Note 3)	Dynamic Input Voltage	5.0		1.5	v	CL = 50 μF	

Note 3: Parameter guaranteed by design.

Symbol Paramet	Paramotor	V <sub>cc</sub>		$T_A = 25^{\circ}C$		T <sub>A</sub> = -40°	-40° to +85°C		Conditions	
	Farameter	(V)	Min	Тур	Max	Min	Max	Units	Conditions	
t <sub>PLH</sub>	Propagation Delay Time (CP–Q <sub>n</sub> )	Propagation Delay	22402		8.3	12.8	1.0	15.0		$C_L = 15 \text{ pF}$
t <sub>PHL</sub>		$3.3\pm0.3$		10.8	16.3	1.0	18.5	ns	$C_L = 50 \text{ pF}$	
		$5.0 \pm 0.5$		4.9	8.1	1.0	9.5	ns	$C_L = 15 \text{ pF}$	
		$5.0 \pm 0.5$		6.4	10.1	1.0	11.5	115	$C_L = 50 \text{ pF}$	
<sup>t</sup> PLH	Propagation Delay	$3.3 \pm 0.3$		8.7	13.6	1.0	16.0	ns	$C_L = 15 \text{ pF}$	
PHL	Time (CP-TC, Count)	$5.5 \pm 0.5$		11.2	17.1	1.0	19.5	115	$C_L = 50 \text{ pF}$	
		$5.0 \pm 0.5$		4.9	8.1	1.0	9.5	ns	C <sub>L</sub> = 15 pF	
		$5.0 \pm 0.5$		6.4	10.1	1.0	11.5		$C_L = 50 \text{ pF}$	
PLH	Propagation Delay	$3.3 \pm 0.3$		11.0	17.2	1.0	20.0	ns	$C_L = 15 \text{ pF}$	
PHL	HL Time (CP-TC, Load)	$3.3 \pm 0.3$		13.5	20.7	1.0	23.5		$C_L = 50 \text{ pF}$	
		$5.0 \pm 0.5$		6.2	10.3	1.0	12.0	ns	C <sub>L</sub> = 15 pF	
		5.0 ± 0.5		7.7	12.3	1.0	14.0	113	$C_L = 50 \text{ pF}$	
PLH	Propagation Delay	$3.3 \pm 0.3$		7.5	12.3	1.0	14.5	ns	C <sub>L</sub> = 15 pF	
PHL	Time (CET–TC)	5.5 ± 0.5		10.5	15.8	1.0	18.0	115	$C_L = 50 \text{ pF}$	
		$5.0 \pm 0.5$		4.9	8.1	1.0	9.5	ns	C <sub>L</sub> = 15 pF	
		5.0 ± 0.5		6.4	10.1	1.0	11.5	113	C <sub>L</sub> = 50 pF	
MAX	Maximum Clock	$3.3 \pm 0.3$	80	130		70		MHz	C <sub>L</sub> = 15 pF	
	Frequency	5.5 ± 0.5	55	85		50		101112	$C_L = 50 \text{ pF}$	
		$5.0 \pm 0.5$	135	185		115		MHz	C <sub>L</sub> = 15 pF	
		$0.0 \pm 0.0$	95	125		85		IVII IZ	$C_L = 50 \text{ pF}$	
PIN	Input Capacitance			4	10		10	pF	V <sub>CC</sub> = Open	
C <sub>PD</sub>	Power Dissipation			23				рF	(Note 4)	
Capacitance				23		1		рг	(11010 4)	

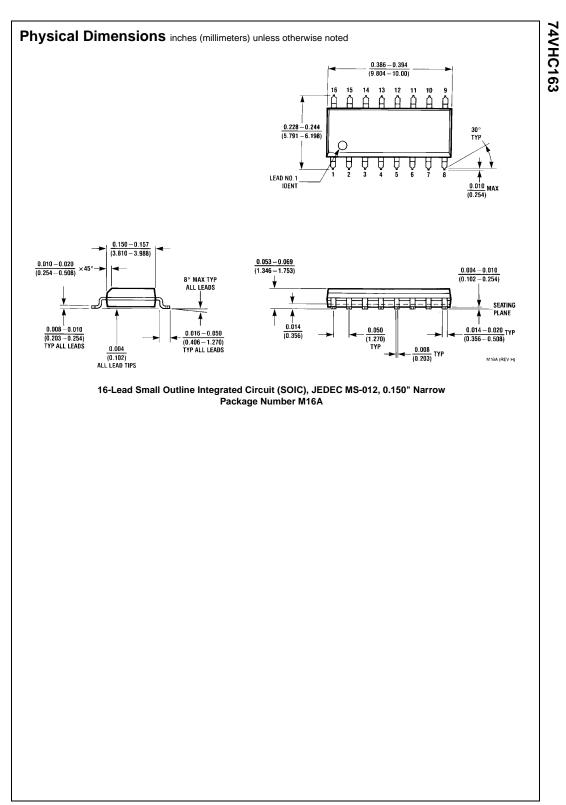
Note 4: CPD is defined as the value of the internal equivalent capacitance which is calculated from the operating current consumption without load. Average operating current can be obtained by the equation:  $I_{CC}$  (opr) =  $C_{PD}$  \*  $V_{CC}$  \*  $f_{IN}$  +  $I_{CC}.$ 

When the outputs drive a capacitive load, total current consumption is the sum of  $C_{PD}$ , and  $\Delta I_{CC}$  which is obtained from the following formula:

 $\Delta I_{CC} = F_{CP} \bullet V_{CC} \left( \frac{C_{QO}}{2} + \frac{C_{Q1}}{4} + \frac{C_{Q2}}{8} + \frac{C_{Q3}}{16} + \frac{C_{TC}}{16} \right)$ C<sub>Q0</sub>-C<sub>Q3</sub> and C<sub>TC</sub> are the capacitances at Q0–Q3 and TC, respectively. F<sub>CP</sub> is the input frequency of the CP.

Symbol	-	V <sub>cc</sub>	$T_A = 25^{\circ}C$		$T_A = -40^{\circ}C$		
	Parameter	(Note 5) (V)	Тур	Guarant	eed Minimum	Uni	
	Minimum Setup Time	3.3		5.5	6.5		
	(P <sub>n</sub> -CP)	5.0		4.5	4.5	ns	
t <sub>S</sub>	Minimum Setup Time	3.3		8.0	9.5		
	(PE –CP)	5.0		5.0	6.0	n	
t <sub>S</sub>	Minimum Setup Time	3.3		7.5	9.0	ns	
	(CEP or CET-CP)	5.0		5.0	6.0		
t <sub>S</sub>	Minimum Setup Time	3.3		4.0	4.0	ns	
	(MR –CP)	5.0		3.5	3.5		
t <sub>H</sub>	Minimum Hold Time	3.3		1.0	1.0	ns	
	(P <sub>n</sub> –CP)	5.0		1.0	1.0	T S	
t <sub>H</sub>	Minimum Hold Time	3.3		1.0	1.0		
	(PE –CP)	5.0		1.0	1.0	n	
t <sub>H</sub>	Minimum Hold Time	3.3		1.0	1.0	n	
	(CEP or CET-CP)	5.0		1.0	1.0	ri;	
t <sub>H</sub>	Minimum Hold Time	3.3		1.0	1.0	n	
	(MR –CP)	5.0		1.5	1.5	n	
t <sub>W</sub> (L)	Minimum Pulse Width	3.3		5.0	5.0	~	
t <sub>W</sub> (H)	CP (Count)	5.0		5.0	5.0	n	

Note 5:  $V_{CC}$  is  $3.3\pm0.3V$  or  $5.0\pm0.5V$ 



# 查询"74VHC163MTCX"供应商

