General Description

Features

 SmartWiper Control Provides Accelerated Wiper Motion

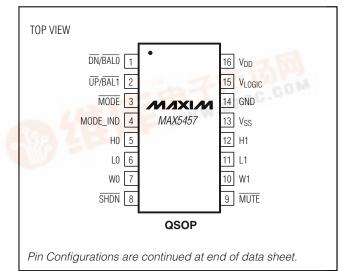
- Debounced Pushbutton Interface with Internal Pullup Resistors
- Logarithmic Taper with 2dB Steps Between Taps
- Single +2.7V to +5.5V or Dual ±2.7V Supply Operation
- Low 0.5µA Standby Supply Current
- Clickless Switching
- ♦ 10kΩ End-to-End Fixed Resistance Value
- Mute Function to -90dB (typ)
- Power-On Reset to -12dB Wiper Position
- ♦ 32 Tap Positions for Each Wiper
- Small 16-Pin QSOP/TQFN Packages

Ordering Information

PART	TEMP RANGE	PIN- PACKAGE	PKG CODE
MAX5456EEE	-40°C to +85°C	16 QSOP	E16-1
MAX5456ETE*	-40°C to +85°C	16 TQFN	T1644-4
MAX5457EEE	-40°C to +85°C	16 QSOP	E16-1
MAX5457ETE*	-40°C to +85°C	16 TQFN	T1644-4

*Future product—contact factory for availability.

Pin Configurations



on _____

The MAX5456/MAX5457 dual, logarithmic taper digital potentiometers feature a simple pushbutton interface that controls volume and balance in audio applications. Each potentiometer has 32 tap points and replaces mechanical potentiometers. Refer to the MAX5408–MAX5411 data sheet for SPI™ versions of the MAX5456/MAX5457.

Use the MAX5456/MAX5457 digital inputs with momentary contact single-pole/single-throw (SPST) pushbutton switches. Each input includes internal debounce circuitry and a $50k\Omega$ pullup resistor.

The MAX5456/MAX5457 advance the wiper setting once per button push. Maxim's proprietary SmartWiper™ control eliminates the need for a microcomputer to increase the wiper transition rate. Holding the control input low for more than 1s advances the wiper at a rate of 4Hz for 4s and 16Hz per second thereafter.

The MAX5456/MAX5457 provide temperature coefficients of 50ppm/°C end-to-end and 5ppm/°C ratiometric and a nominal resistance of $10k\Omega$ per potentiometer. An integrated click/pop suppression feature minimizes the audible noise generated by wiper transitions. The typical total harmonic distortion plus noise (THD+N) for these devices is 0.01%.

The MAX5457 features a 3-button interface with a MODE input that toggles between volume- and balancecontrol modes. An LED output indicates volume or balance mode. The MAX5456 features a 4-button interface with separate inputs for up and down volume controls and left and right balance controls.

The MAX5456/MAX5457 are available in 16-pin QSOP and 16-pin TQFN packages and are specified over the extended (-40°C to +85°C) temperature range.



Typical Application Circuits and Selector Guide appear at end of data sheet.

SPI is a trademark of Motorola, Inc. SmartWiper is a trademark of Maxim Integrated Products, Inc.

_ Maxim Integrated Products 1

For pricing, delivery, and ordering information, please contact Maxim/Dallas Direct! at 1888-629-4642, or visit Maxim's website at www.maxim-ic.com.

ABSOLUTE MAXIMUM RATINGS

(MAX5456) SHDN. MUTE, VOLUP, VOLDN.

BAL_ to GND	0.3V to (V _{LOGIC} + 0.3V)
(MAX5457) SHDN, MUTE, UP/BAL1, I	DN/BALO, MODE,
MODE_IND to GND	0.3V to $(V_{LOGIC} + 0.3V)$
H_, L_, and W_ to V _{SS}	0.3V to (V _{DD} + 0.3 V)
V _{DD} to GND	0.3V to +6V
V _{DD} to V _{SS}	0.3V to +6V
VLOGIC to GND	0.3V to +6V
VLOGIC to VSS	0.3V to +6V
Vss to GND	3.0V to +0.3V

Peak Current into H_, L_, and W Average Current into H_, L_, and W	
Input and Output Latchup Immunity	±200mA
Continuous Power Dissipation ($T_A = +70^{\circ}C$)	
16-Pin QSOP (derate 8.3mW/°C above +70°C)6	66.7mW
16-Pin TQFN (derate 16.9mW/°C above +70°C)134	49.1mW
Operating Temperature Range40°C to	с +85°С
Junction Temperature	+150°C
Storage Temperature Range60°C to	+150°C
Lead Temperature (soldering, 10s)	+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

ELECTRICAL CHARACTERISTICS

 $(V_{DD} = V_{LOGIC} = +2.7V$ to +5.5V, $V_{SS} = 0V$, GND = 0V, $V_{H_{-}} = V_{DD}$, $V_{L_{-}} = V_{SS}$, $T_A = T_{MIN}$ to T_{MAX} . Typical values are at $T_A = +25^{\circ}C$, unless otherwise specified.) (Note 1)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	МАХ	UNITS
End-to-End Resistance	R	Figures 1, 2	7	10	13	kΩ
Maximum Bandwidth	f CUTOFF	From H_ to W_, $C_{LOAD} = 10 pF$		100		kHz
Absolute Ratio Tolerance		No load at the output of the wiper, $W_{-} = -6dB$		±0.25		dB
Tap-to-Tap Tolerance				±0.1		dB
T		$V_{DD} = 5V, V_{H_{-}} = (V_{DD} / 2) + 1V_{RMS},$ f = 1kHz, tap = -6dB, V _{L_} = V_{DD} / 2, R _L = ∞		0.01		
Total Harmonic Distortion Plus Noise	THD+N	$ \begin{array}{l} V_{DD}=3V,V_{SS}=0V,V_{L}=1.5V,\\ V_{H}_=1.5V+1V_{RMS},f=1kHz,R_{L}=10k\Omega \text{ to}\\ (V_{DD}/2),C_{L}=5pF,tap=-6dB \end{array} $		0.23		%
Channel-to-Channel Isolation				-100		dB
Interchannel Matching		f = 20Hz to $20kHz$, tap = $-6dB$		±0.5		dB
Mute Attenuation				-90		dB
Power-Supply Rejection Ratio	PSRR			-80		dB
Wiper Resistance	Rw			1000	1700	Ω
Wiper Capacitance	Cw			10		pF
H Terminal Capacitance	CH			5		pF
L Terminal Capacitance	CL			7		pF
End-to-End Resistance Temperature Coefficient				50		ppm/°C
Ratiometric Resistance Temperature Coefficient				5		ppm/°C
Output Noise	en	20Hz to 20kHz		0.95		μV _{RMS}
PUSHBUTTON CONTACT INPUT	S (UP/BAL1,	DN/BAL0, MUTE, VOLUP, VOLDN, BAL0, BAL	1, MOD	Ē)		•
Internal Pullup Resistor	Rpullup		32	50	65	kΩ
Single Pulse-Width Input	tipw	Figure 5	22.5			ms
Repetitive Input Pulse High Time	tHPW	Figure 5	40			ms
Timeout Period	tws	Click/pop suppression inactive		32		ms

ELECTRICAL CHARACTERISTICS (continued)

 $(V_{DD} = V_{LOGIC} = +2.7V$ to +5.5V, $V_{SS} = 0V$, GND = 0V, $V_{H_{-}} = V_{DD}$, $V_{L_{-}} = V_{SS}$, $T_A = T_{MIN}$ to T_{MAX} . Typical values are at $T_A = +25^{\circ}C$, unless otherwise specified.) (Note 1)

PARAMETER	SYMBOL	CONDITIONS	MIN	ΤΥΡ	MAX	UNITS
First Autoincrement Point				1		S
First Autoincrement Rate				4		Hz
Second Autoincrement Point				4		S
Second Autoincrement Rate				16		Hz
DIGITAL INPUTS (VLOGIC > 4.5	V)		•			
Input High Voltage	VIH		2.4			V
Input Low Voltage	VIL				0.8	V
Input Leakage Current		Inputs floating			±1	μA
Input Capacitance				5		рF
DIGITAL INPUTS (VLOGIC < 4.5	V)		•			
Input High Voltage	VIH		0.7 x VLOGIC			V
Input Low Voltage	VIL				0.3 x V _{LOGIC}	V
Input Leakage Current		Inputs floating			±1	μA
Input Capacitance				5		pF
POWER SUPPLIES						
Supply Voltage	VDD		2.7		5.5	V
Negative Power Supply	V _{SS}		-2.7		0	V
Supply-Voltage Difference		V _{DD} - V _{SS}			5.5	V
Active Supply Current	IDD	(Note 2)			100	μA
Standby Supply Current	ISTBY	V_{DD} = +5.5V, V_{SS} = 0V, V_{LOGIC} = 2.7V (Note 3) V_{LOGIC} = V_{DD} = +2.7V, V_{SS} = -2.7V (Note 3)		2 0.5	10 1	μA
Shutdown Supply Current	I _{SHDN}	(Note 4)			1	μA
Power-Up Time	tPU			10		ms
Logic Standby Voltage	VLOGIC		2.7		V _{DD}	V
Logic Active Supply Current	ILOGIC	(Note 2)			160	μA
Logic Standby Supply Current	LOGICSTBY	(Note 3)		0.5	1	μA
Logic Shutdown Current	ILOGICSHDN	(Note 4)			1	μA
DIGITAL OUTPUT, MODE_IND						
		$V_{LOGIC} = 2.7V, I_{SINK} = 10mA$			0.4	
Output Low Voltage	V _{OL}	V _{LOGIC} = 5.5V, I _{SINK} = 10mA	Ī		0.2	V
Output Leakage Current	Ì			0.1	10	μA
Output Capacitance			T	3		pF
Maximum Sink Current			l	150		mA

Note 1: Parameters are 100% production tested at +85°C and limits through temperature are guaranteed by design.

Note 2: Supply current measured with the supply on and a button pushed.

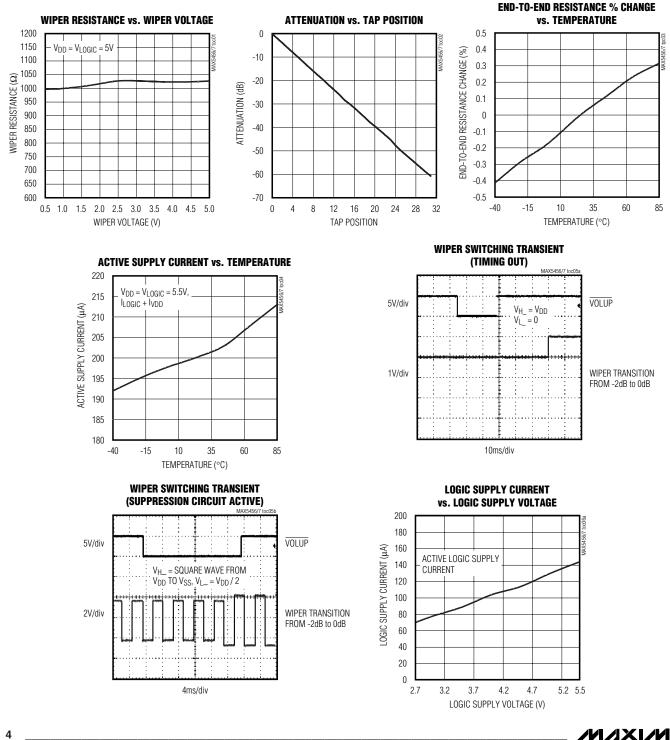
Note 3: Supply current measured with the power on, no button pushed, and the wiper position fixed.

Note 4: This is the measured current with SHDN low and MODE_IND unconnected.



Typical Operating Characteristics

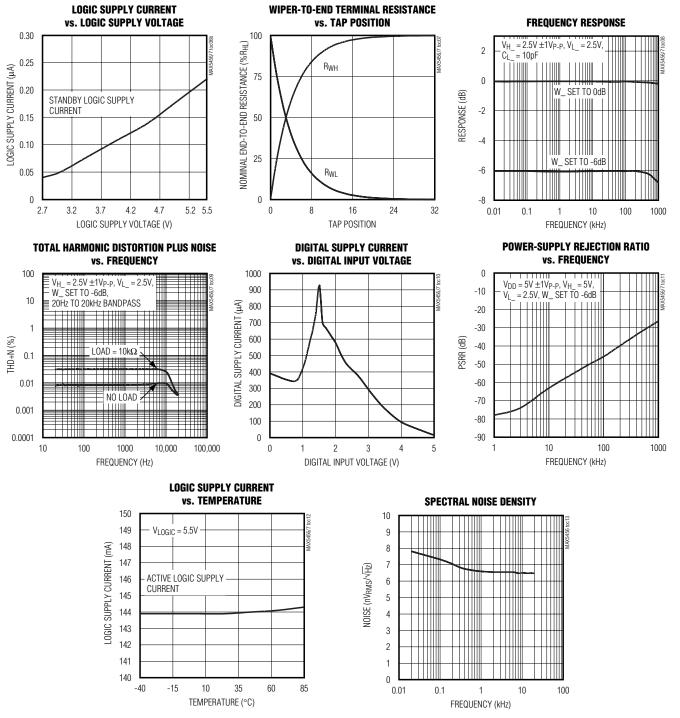
(V_{DD} = V_{LOGIC} = +2.7V to +5.5V, V_{SS} = 0V, GND = 0V, V_H = V_{DD}, V_L = V_{SS}, T_A = T_{MIN} to T_{MAX}. Typical values are at T_A = +25°C, unless otherwise specified.)



4



 $(V_{DD} = V_{LOGIC} = +2.7V \text{ to } +5.5V, V_{SS} = 0V, \text{GND} = 0V, V_{H_{-}} = V_{DD}, V_{L_{-}} = V_{SS}, T_A = T_{MIN} \text{ to } T_{MAX}$. Typical values are at $T_A = +25^{\circ}C$, unless otherwise specified.)



Pin Description

	PIN MAX5457 MAX5456				
MAX	5457			NAME	FUNCTION
TQFN	QSOP	TQFN	QSOP		
1	3	_		MODE	Volume/Balance Control. Each transition from high to low toggles between volume and balance modes. $\overline{\text{MODE}}$ is pulled high internally with a 50k Ω resistor to V _{LOGIC} . On power-up, the MAX5457 is in volume-control mode.
2	4	_	_	MODE_IND	Volume-Control/Balance-Control Mode Indicator Open-Drain Output. Connect to an LED through a resistor to V_{LOGIC} . When the LED is on, the MAX5457 is in balance-control mode. When the LED is off, the MAX5457 is in volume-control mode. See the <i>Mode Indicator, MODE_IND</i> section for more detail.
3	5	3	5	HO	Potentiometer 0 High Terminal. H0 and L0 terminals can be reversed.
4	6	4	6	LO	Potentiometer 0 Low Terminal. L0 and H0 terminals can be reversed.
5	7	5	7	WO	Potentiometer 0 Wiper Terminal
6	8	6	8	SHDN	Active-Low Shutdown Input. In shutdown mode, the MAX5456/MAX5457 store the last wiper settings. The wipers move to the L end of the resistor string, and the H end of the resistor string disconnects from the signal input. Terminating shutdown mode restores the wipers to their previous settings.
7	9	7	9	MUTE	Mute Input. When $\overline{\text{MUTE}}$ is low, the wiper goes to the highest attenuation setting (see Table 1). $\overline{\text{MUTE}}$ is internally pulled up with 50k Ω to V _{LOGIC} .
8	10	8	10	W1	Potentiometer 1 Wiper Terminal
9	11	9	11	L1	Potentiometer 1 Low Terminal. L1 and H1 terminals can be reversed.
10	12	10	12	H1	Potentiometer 1 High Terminal. H1 and L1 terminals can be reversed.
11	13	11	13	V _{SS}	Negative Power Supply. Bypass with 0.1µF to ground.
12	14	12	14	GND	Ground
13	15	13	15	VLOGIC	Digital Logic Power Supply. Bypass with 0.1µF to ground.
14	16	14	16	VDD	Analog Power Supply. Bypass with 0.1µF to ground.
15	1			DN/BAL0	Downward Volume/Channel 0 Balance-Control Input. In volume mode, pressing $\overline{\text{DN}/\text{BAL0}}$ moves both wipers towards the L terminals. In balance mode, pressing $\overline{\text{DN}/\text{BAL0}}$ moves the balance towards channel 0. $\overline{\text{DN}/\text{BAL0}}$ is internally pulled up with 50k Ω to V _{LOGIC} .
16	2	_	_	UP/BAL1	Upward Volume/Channel 1 Balance-Control Input. In volume mode, pressing UP/BAL1 moves both wipers towards the H terminals. In balance mode, pressing UP/BAL1 moves the balance towards channel 1. UP/BAL1 is internally pulled up with 50k Ω to V _{LOGIC} .
—	_	1	3	BAL1	Channel 1 Balance-Control Input. Pressing $\overline{BAL1}$ moves the balance towards channel 1. $\overline{BAL1}$ is internally pulled up with $50k\Omega$ to V _{LOGIC} .
	_	2	4	BALO	Channel 0 Balance-Control Input. Pressing $\overline{BAL0}$ moves the balance towards channel 0. $\overline{BAL0}$ is internally pulled up with $50k\Omega$ to V _{LOGIC} .
	_	15	1	VOLDN	Downward Volume-Control Input. Pressing $\overline{\text{VOLDN}}$ moves both wipers towards the L terminals. $\overline{\text{VOLDN}}$ is internally pulled up with 50k Ω to V _{LOGIC} .
_	_	16	2	VOLUP	Upward Volume-Control Input. Pressing $\overline{\text{VOLUP}}$ moves both wipers towards the H terminals. $\overline{\text{VOLUP}}$ is internally pulled up with 50k Ω to V _{LOGIC} .

M/XI/M

Detailed Description

The MAX5456/MAX5457 dual, logarithmic taper digital potentiometers feature a simple pushbutton interface that controls volume and balance in audio applications. Each potentiometer has 32 tap points and replaces mechanical potentiometers (see the *Functional Diagrams*).

Up and Down Interface

The MAX5456/MAX5457 interface with momentary contact SPST switches. All switch inputs are internally debounced and pulled up to V_{LOGIC} through 50k Ω resistors. The wiper setting advances once per button press up to 1s. Maxim's SmartWiper control circuitry allows the wiper to advance at a rate of 4Hz when an input is held low from 1s up to 4s, and at a rate of 16Hz if the contact is maintained for greater than 4s (see Table 2). The SmartWiper control eliminates the need for a microcomputer to increase the wiper transition rate.

The MAX5456 features independent control inputs for volume and balance control while the MAX5457 MODE input toggles between volume and balance control. Each transition of MODE from high to low toggles the MAX5457 between volume-control and balance-control modes. MODE is internally pulled high with a 50k Ω resistor to VLOGIC.

Volume Control

In volume-control mode, the MAX5456/MAX5457s' wipers move simultaneously, maintaining the balance separation between each wiper (Figure 3a).

When either wiper reaches the maximum tap position (position closest to H_), further commands to increase the volume are ignored. Balance separation is maintained in the maximum volume configuration (Figure 3b).

When either wiper reaches the minimum tap position (position closest to L_), further commands to decrease the volume adjust the other wiper until it also reaches the minimum tap position (Figure 3c).

Increasing the volume from this minimum position restores the original balance separation of the wipers (Figure 3d).

When both wipers are in the 31st tap position (-62dB attenuation), further commands to VOLDN place the wipers in the mute position (see Table 1). VOLUP or MUTE pulses return wipers to position 31.

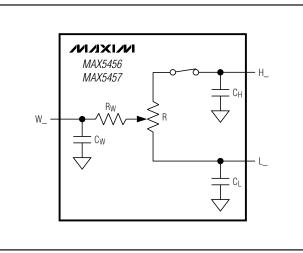


Figure 1. Potentiometer Model (Active)

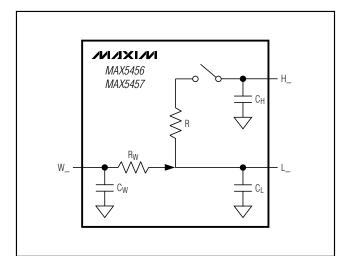


Figure 2. Potentiometer Model (Shutdown)

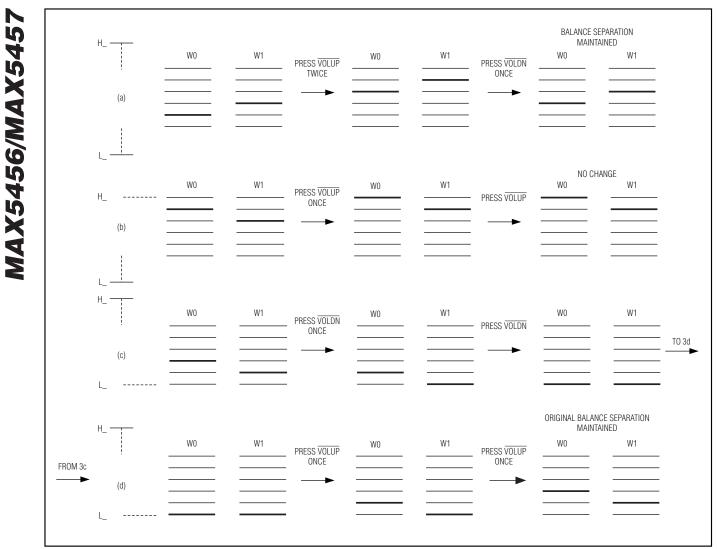


Figure 3. Volume-Control Operation

Table 1. Wiper Posit	ion and Attenuation
----------------------	---------------------

POSITION	ATTENUATION (dB)
0	0
1	2
2	4
	:
6 (POR)	12
	:
30	60
31	62
32 (mute)	>90
8	

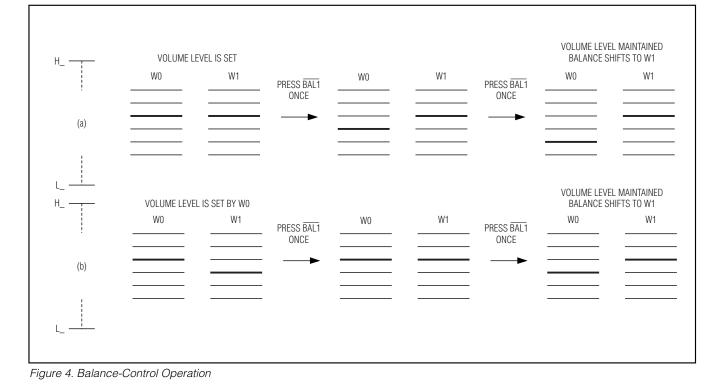
Balance Control

In balance-control mode, the MAX5456/MAX5457 adjust the balance between channel 0 and channel 1 while maintaining the set volume. For example, if the volume of channel 0 equals the volume of channel 1, forcing the balance towards channel 1 increases the attenuation of channel 0 (Figure 4a). If channel 1 is at a higher attenuation than channel 0, adjusting the balance to channel 1 moves channel 1's wiper up to the same wiper position as channel 0 before attenuating channel 0 (Figure 4b).

To control the wiper quickly with a logic signal, maintain pulses at least 22.5ms wide and separated by at least 40ms.

Table 2. Wiper Action vs. PushbuttonContact Duration

CONTACT DURATION	WIPER ACTION
t < 22.5ms	No motion (debouncing).
22.5ms < t ≤ 1s	Wiper changes position once.
1s < t ≤ 4s	Wiper changes position at a rate of 4Hz.
t > 4s	Wiper changes position at a rate of 16Hz.



Click/Pop Suppression

The click/pop suppression feature reduces the audible noise (clicks and pops) that result from wiper transitions. The MAX5456/MAX5457 minimize this noise by allowing the wiper position changes only when $V_{H_{-}} = V_{L_{-}}$. Thus, the wiper changes position only when the voltage at L_ is the same as the voltage at the corresponding H_. Each wiper has its own suppression and timeout circuitry (see Figure 5a). The MAX5456/MAX5457 change wiper position after 32ms or when $V_{H_{-}} = V_{L}$, whichever occurs first (see Figure 5b).

The suppression circuitry monitors left and right channels separately. In volume-control mode, when the first wiper changes position, the second wiper has 32ms to change or it will be forced to change.

Power-On Reset

The power-on comparators monitor V_{DD} - V_{SS} and V_{LOGIC} - GND. A power-on reset is initiated when either of the supplies is brought back to normal operating voltage. The power-on-reset feature sets both wipers to -12dB. Power-on reset places the MAX5457 in volume-control mode.

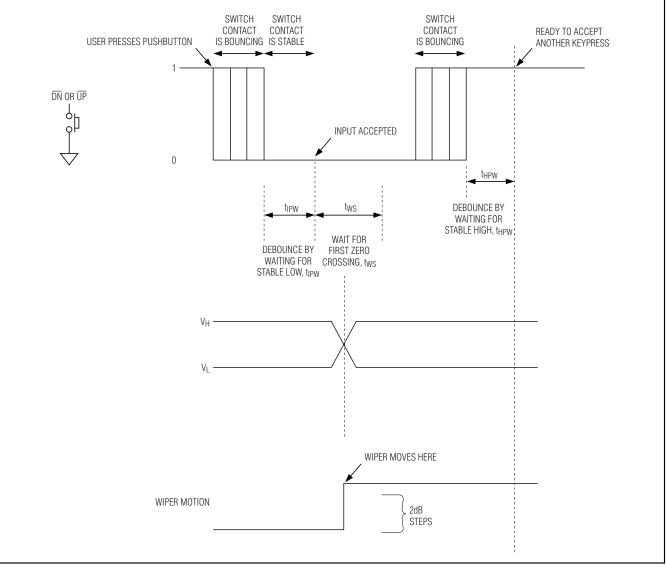


Figure 5a. Wiper Transition Timing Diagram

Shutdown, SHDN

Upon entering shutdown mode, the MAX5456/MAX5457 store the last wiper settings. The wipers move to the L_ end of the resistor string, and the H_ end of the resistor string disconnects from the signal input. Terminating shutdown mode restores the wipers to their previous settings (see Figure 2). Shutdown does not affect the state of MODE_IND.

function forces both wipers to maximum attenuation (-90dB typ). Deactivating the mute function returns the wipers to their previous settings. Pressing VOLUP also deactivates mute, setting the wipers to their previous positions. MUTE is internally pulled high with a 50k Ω resistor to VLOGIC. When both wipers are in the 31st tap position (-62dB attenuation), further commands to VOLDN place the wipers in the mute position (see Table 1). VOLUP or MUTE pulses return the wipers to position 31.

Mute Function, MUTE

The MAX5456/MAX5457 feature a mute function. Successive pulses on MUTE toggle its setting. Activating the mute

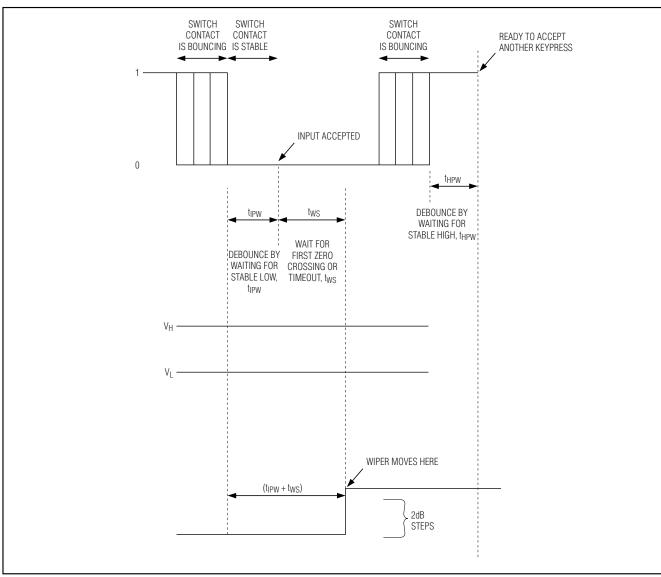


Figure 5b. Wiper Transition Timing Diagram

MAX5456/MAX5457

Mode Control, MODE

The MAX5457 $\overline{\text{MODE}}$ input toggles between volumeand balance-control modes. Force $\overline{\text{MODE}}$ low to toggle between volume-control and balance-control modes. For example, driving $\overline{\text{MODE}}$ low once while in volumecontrol mode, switches the MAX5457 to balance-control mode. Driving mode low once again, switches the MAX5457 back to volume-control mode. $\overline{\text{MODE}}$ is internally pulled high with a 50k Ω resistor to V_{LOGIC}. The MAX5457 powers up in volume-control mode.

Mode Indicator, MODE_IND

MODE_IND is the volume-control and balance-control mode indicator with an open-drain output. Connect MODE_IND to an LED through a pullup resistor to V_{LOGIC}. When the LED is on, the MAX5457 is in balance-control mode. When the LED is off, the MAX5457 is in volume-control mode. See the *Mode Control, MODE* section for more detail on switching between modes. Shutdown does not affect the state of MODE_IND.

Multiple Button Pushes

The MAX5456/MAX5457 do not respond to simultaneous button pushes. Pushing more than one button at the same time stops the wipers in their present states. Only a single button push configures the device. Additionally, a 40ms blocking period affects all other inputs when releasing any input forced low. The MAX5456/MAX5457 do not respond to any logic input until the blocking period ends. If multiple wiper-control buttons are pressed, all wiper-control connections must be released before the part will respond to further commands.

Applications Information

Stereo Volume/Balance Control

Figure 6 shows a volume/balance application using the MAX5457. The op amp is connected in a follower (noninverting gain) configuration to isolate the potentiometer's wiper impedance from the load and provide drive capability. Connect the W_ of the MAX5457 to the positive input of a noninverting gain amp. The pushbutton potentiometers attenuate the input signals. Use the MODE input to switch between volume-control and balance-control modes.

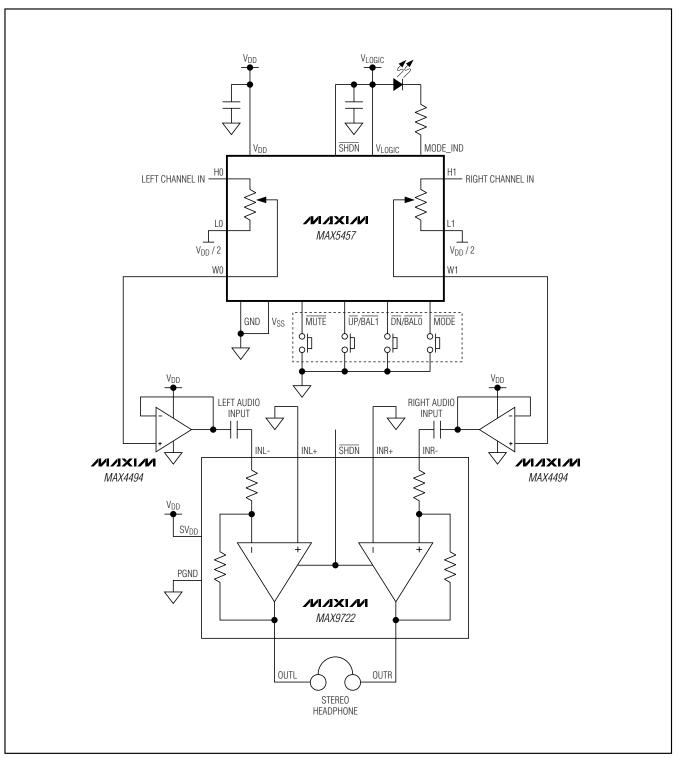


Figure 6. Volume/Balance Control



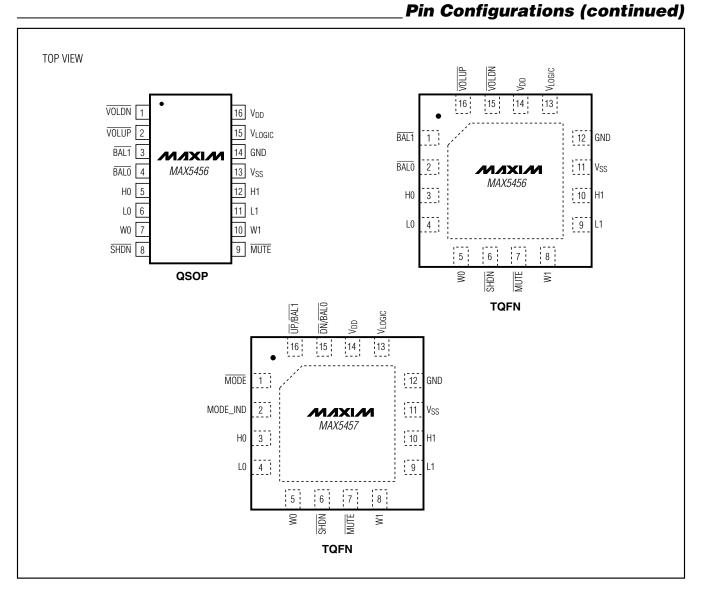
PART	INTERFACE	PKG. CODE
MAX5456EEE	4-Button	E16-1
MAX5456ETE*	4-Button	T1644-4
MAX5457EEE	3-Button	E16-1
MAX5457ETE*	3-Button	T1644-4

Selector Guide

Chip Information

TRANSISTOR COUNT: 15,395 PROCESS: CMOS

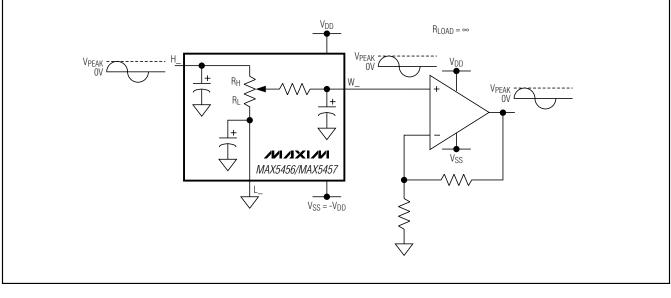
*Future product—contact factory for availability.



VDD $R_{\text{LOAD}} = \infty$ VPEAK VDD/2Z V_{PEAK} V_{DD} / 2 V_{DD} \downarrow W V_{PEAK} V_{DD} / 2 Rı + M/XI/M MAX5456/MAX5457 1 5 Voo

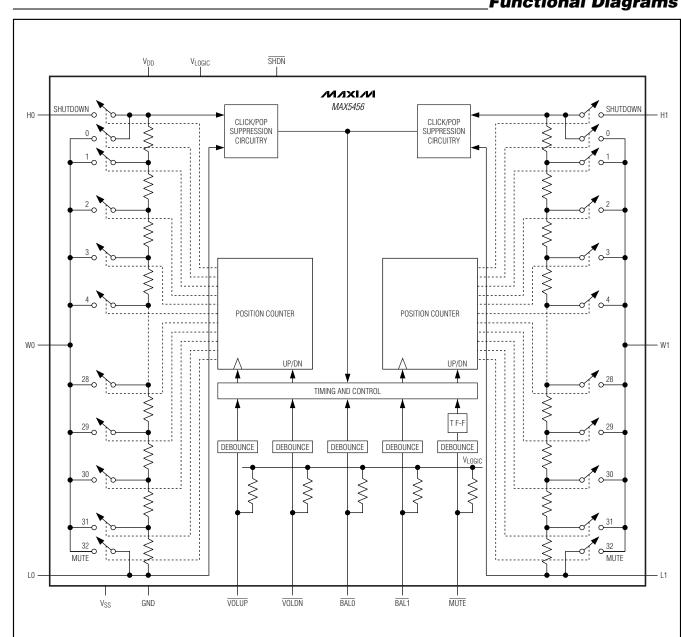
Typical Application Circuit (Single Supply)

Typical Application Circuit (Dual Supplies)

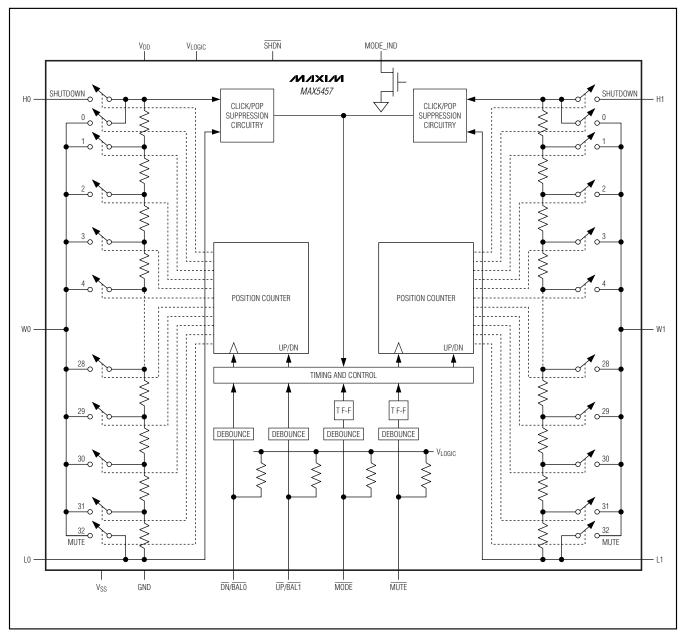


MAX5456/MAX5457

Stereo Audio Taper Potentiometers with **Pushbutton Interface**



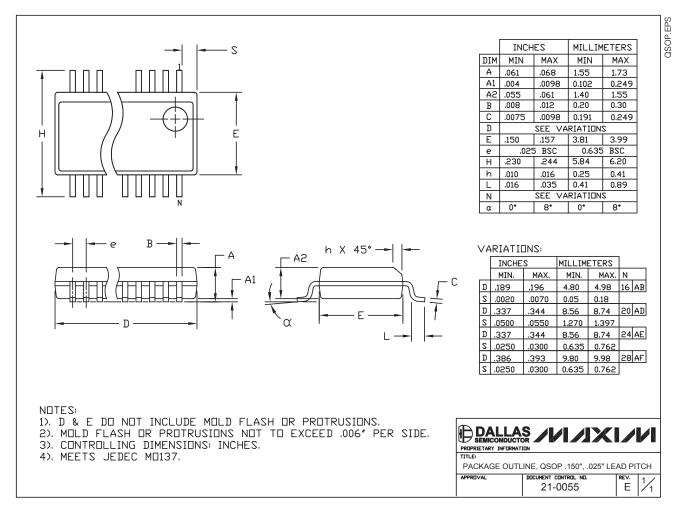
Functional Diagrams



_Functional Diagrams (continued)

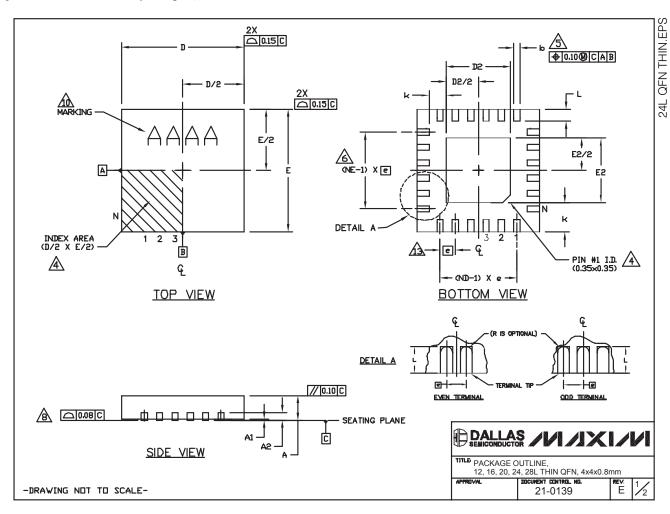
Package Information

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information, go to **www.maxim-ic.com/packages**.)



Package Information (continued)

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information, go to <u>www.maxim-ic.com/packages</u>.)



Package Information (continued)

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information, go to **www.maxim-ic.com/packages**.)

					MDN	DIME	INSII	SNE									E	XPD3	SED	PAD	VAR	IATI	DNS								
PKG	14	2L 4×	4	16	5L 4x	4	20	L 4x	4	24L 4×4		IL 4×4			24L 4×4		4 28L 4×4		28L 4×		28L 4×4	< 4	5	PKG.		D2			E2		DOWN BONDS
REF.	MIN.	NDM.	MAX.	MIN.	NDM.	MAX.	MIN.	NDM.	MAX.	MIN.	NDM.	MAX.	MIN.	NDM.	MAX.	i	CODES	MIN.	NDM.	MAX.	MIN.	NDM.	MAX.	ALLOVE							
A	0.70	0.75	0.80	0.70	0.75	0.80	0.70	0.75	0.80	0.70	0.75	0.80	0.70	0.75	0.80		T1244-3	1.95	2.10	2.25	1.95	2.10	2.25	YES							
A1	0.0	0.02	0.05	0.0	0.02	0.05	0.0	0.02	0.05	0.0	0.02	0.05	0.0	0.02	0.05	Ľ	T1244-4	1.95	2.10	2.25	1.95	2.10	2.25	ND							
A2	(.20 RE	F	0	.20 RE	F	0.	20 RE	F	0	20 RE	F	C	20 RE	F	Ľ	T1644-3	1.95	2.10	2.25	1.95	2.10	2.25	YES							
b	0.25	0.30	0.35	0.25	0.30	0.35	0.20	0.25	0.30	0.18	0.23	0.30	0.15	0.20	0.25	Ľ	T1644-4	1.95	2.10	2.25	1.95	2.10	2.25	ND							
D	3,90	4.00	4.10	3.90	4.00	4.10	3.90	4.00	4.10	3.90	4.00	4.10	3.90	4.00	4.10	- H	T2044-2	1.95	2.10	2.25	1.95	2.10	2.25	YES							
E		4.00	4.10	3.90		4.10	3.90		4.10	3.90		4.10	3.90		4.10	- F	T2044-3	1.95	2.10	2.25	1.95	2.10	2.25	ND							
e		D.80 BS			.65 BS			50 BS			.50 BS	1		.40 BS		- F	T2444-2	1.95	2.10	2.25	1.95	2.10	2.25	YES							
ĸ	0.25	-	-	0.25	-	-	0.25	-	-	0.25	-	-	0.25	-		- E	T2444-3	2.45	2.60	2.63	2.45	2.60	2.63	YES							
L	0.45	0.00	0.65	0.45	0.55	0.65	0.45	0.55	0.65	0.30	0.40	0.50	0.30	0.40	0.50	- F	T2444-4	2.45	2.60	2.63	2.45	2.60	2.63	ND							
N	<u> </u>	12			16		20 24 28		Ľ	T2844-1	2.50	2.60	2.70	2.50	2.60	2.70	ND														
ND	<u> </u>	3			4			5		<u> </u>	6			7																	
NE	<u> </u>	3			4			5		<u> </u>	6	_		7																	
Jedec Var.		₩GGB			VGGC			/GGD-:	l <u> </u>		WGGD-	-2		WGGE																	
	the te Jesd 9	RMINAL	.#1 ID PP-012	ENTIFIE 2. DETA	of teri Er and NLS of Termin	TERMI TERMIN	NAL NU	IDENTI	FIER AI	re opt	IONAL,	BUT M	UST B	LOCA	ted with	HIN															
A	DIMENS		APPLIE												0.30 m	m															
Δ	ND AN	D NE F	EFER .	to the	E NUMB	er of	TERMI	WLS C	IN EAC	HDA	ND E S	SIDE RE	ESPECT	IVELY.																	
767	DEPOP	ULATION	IS PO	SSIBL	EINA	SYMME	TRICAL	FASHK	DN.																						
		NARITY	APPLIE	s to "	THE EX	POSED	HEAT :	SINK S	LUG AS	S WELL	. AS TI	HE TER	MINALS																		
7.	COPLA					0220	EXCEP1	FOR	T2444	-3, T2	444-4	AND T	2844-	1.																	
7.		IG CON	FORMS	TO JE	EDEC M	UZZU.																									
7. <u>8</u> 9.	DRAWI				EDEC M Orienta			ICE ON	JLY.																						
7. 8. 9.		G IS FC	OR PAC	KAGE (TION R	EFERE	ICE ON	NLY.																						
7. 9. 11. C	DRAWI IARKING	G IS FO ARITY S	OR PAC	KAGE (NOT EX	ORIENTA	TION R 0.08mm	EFERE	ICE ON	NLY.																						
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7. 9. 11. C 12. W	DRAWIN IARKING OPLAN (ARPAG EAD CI) IS FO ARITY S E SHAL ENT ERLI	DR PAC SHALL N L NOT NES TO	KAGE (NOT EX EXCEE) BE A	ORIENTA	.TION R).08mm 0mm : POSII	EFEREN	DEFIN	ied by	BASIC	: Dimed	ISION *	'e", ±().05.									X								
7. 9. 11. C 12. W	DRAWIN IARKING OPLAN (ARPAG EAD CI) IS FO ARITY S E SHAL ENT ERLI	DR PAC SHALL N L NOT NES TO	KAGE (NOT EX EXCEE) BE A	ORIENTA (CEED (IND 0.1 NT TRUE	.TION R).08mm 0mm : POSII	EFEREN	DEFIN	ied by	BASIC	; Dimen	ision "	'e", ±().05.				LD PAC	KAGE	OUTLI	NE,										
7. 9. 11. C 12. W	DRAWIN IARKING OPLAN (ARPAG EAD CI) IS FO ARITY S E SHAL ENT ERLI	DR PAC SHALL N L NOT NES TO	KAGE (NOT EX EXCEE) BE A	ORIENTA (CEED (IND 0.1 NT TRUE	.TION R).08mm 0mm : POSII	EFEREN	DEFIN	ied by	BASIC	: Dimen	ISION *	'e", ±().05.			тנт	LD PAC	KAGE	OUTLI 24, 28L		QFN, 4									

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