CS3001
CS3002

Precision Low-voltage Amplifier; DC to 2 kHz

Features

- Low Offset: 10 µV Max
- Low Drift: 0.05 µV/°C Max
- Low Noise
  - 6 nV/√Hz @ 0.5 Hz
  - 0.1 to 10 Hz = 125 nVp-p
  - 1/f corner @ 0.08 Hz
- Open-loop Voltage Gain
  - 300 dB Typical
  - 200 dB Minimum
- Rail-to-rail Output Swing
- Slew Rate: 5 V/µs
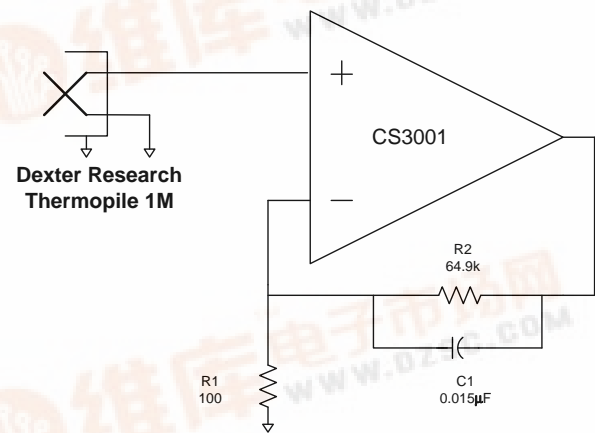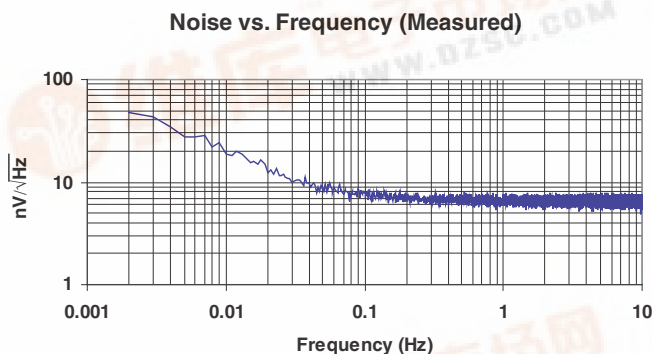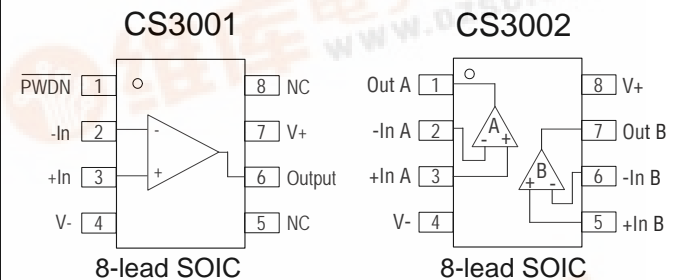
Applications

- Thermocouple/Thermopile Amplifiers
- Load Cell and Bridge Transducer Amplifiers
- Precision Instrumentation
- Battery-powered Systems

Description

The CS3001 single amplifier and the CS3002 dual amplifier are designed for precision amplification of low-level signals and are ideally suited to applications that require very high closed-loop gains. These amplifiers achieve excellent offset stability, super-high open-loop gain, and low noise over time and temperature. The devices also exhibit excellent CMRR and PSRR. The common mode input range includes the negative supply rail. The amplifiers operate with any total supply voltage from 2.7 V to 6.7 V (±1.35 V to ±3.35 V).

Pin Configurations

CS3001

PWDN	1	8 NC
-In	2	7 V+
+In	3	6 Output
V-	4	5 NC

8-lead SOIC

CS3002

Out A	1	8 V+
-In A	2	7 Out B
+In A	3	6 -In B
V-	4	5 +In B

8-lead SOIC

Noise vs. Frequency (Measured)

nV/√Hz vs. Frequency (Hz)

CS3001 circuit

Dexter Research
Thermopile 1M

R2 64.9k
C1 0.015µF
R1 100

Thermopile Amplifier with a Gain of 650 V/V

TABLE OF CONTENTS

LIST OF FIGURES

1. CHARACTERISTICS AND SPECIFICATIONS

ELECTRICAL CHARACTERISTICS V+ = +5 V, V- = 0V, VCM = 2.5 V (Note 1)

Parameter			Min	Typ	Max	Unit
			CS3001/CS3002			
Input Offset Voltage	(Note 2)	•	-	-	±10	µV
Average Input Offset Drift	(Note 2)	•	-	±0.01	±0.05	µV/ºC
Long Term Input Offset Voltage Stability				(Note 3)		
Input Bias Current	T_A = 25º C		-	±100	-	pA
		•	-	-	±1000	pA
Input Offset Current	T_A = 25º C		-	±200	-	pA
		•	-	-	±2000	pA
Input Noise Voltage Density R_S = 100 Ω, f_0 = 1 Hz			-	6		$nV/\sqrt{Hz}$
R_S = 100 Ω, f_0 = 1 kHz			-	6		$nV/\sqrt{Hz}$
Input Noise Voltage 0.1 to 10 Hz			-	125		nV_{p-p}
Input Noise Current Density f_0 = 1 Hz			-	100		$fA/\sqrt{Hz}$
Input Noise Current 0.1 to 10 Hz			-	1.9		pA_{p-p}
Input Common Mode Voltage Range		•	-0.1	-	(V+)-1.25	V
Common Mode Rejection Ratio (dc)	(Note 4)	•	115	120	-	dB
Power Supply Rejection Ratio		•	120	136	-	dB
Large Signal Voltage Gain R_L = 2 kΩ to V+/2	(Note 5)	•	200	300	-	dB
Output Voltage Swing R_L = 2 kΩ to V+/2		•	+4.7	-	-	V
R_L = 100 kΩ to V+/2				+4.99		V
Slew Rate R_L = 2 k, 100 pF				5	-	V/µs
Overload Recovery Time			-	100	-	µs
Supply Current CS3001		•	-	2.1	2.8	mA
CS3002		•	-	3.6	4.8	mA
$\overline{PWDN}$ active (CS3001 Only)	(Note 6)	•			15	µA
$\overline{PWDN}$ Threshold	(Note 6)	•	(V+) -1.0	-	-	V
Start-up Time	(Note 7)	•	-	9	12	ms

Notes: 1. Symbol "•" denotes specification applies over -40 to +85 ° C.

2. This parameter is guaranteed by design and laboratory characterization. Thermocouple effects prohibit accurate measurement of these parameters in automatic test systems.

3. 1000-hour life test data @ 125 °C indicates randomly distributed variation approximately equal to measurement repeatability of 1 µV.

4. Measured within the specified common mode range limits.

5. Guaranteed within the output limits of (V+ -0.3 V) to (V- +0.3 V). Tested with proprietary production test method.

6. $\overline{PWDN}$ input has an internal pullup resistor to V+ of approximately 800 kΩ and is the major source of current consumption when $\overline{PWDN}$ is active low.

7. The device has a controlled start-up behavior due to its complex open loop gain characteristics. Start-up time applies when supply voltage is applied or when PDWN is released.

ABSOLUTE MAXIMUM RATINGS

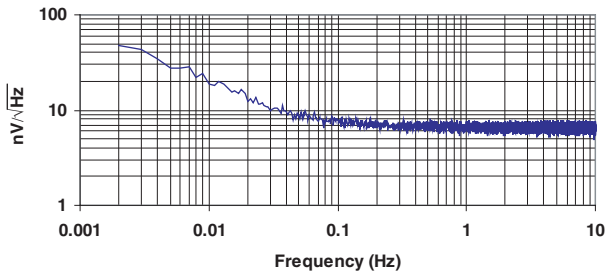| Parameter		Min	Typ	Max	Unit
Supply Voltage	[(V+) - (V-)]			6.8	V
Input Voltage		V- -0.3		V+ +0.3	V
Storage Temperature Range		-65		+150	°C

2. TYPICAL PERFORMANCE PLOTS

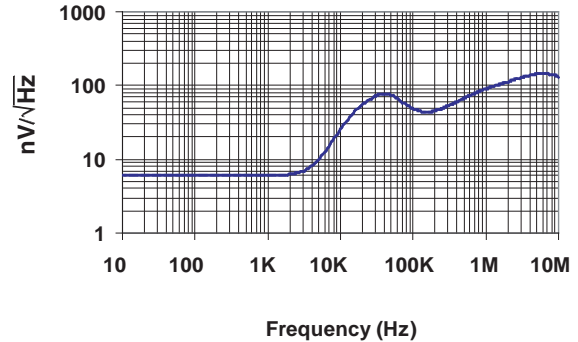Figure 1. Noise vs. Frequency (Measured)

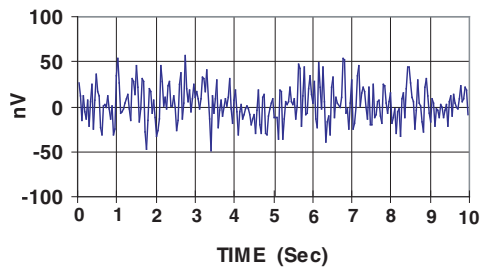

Figure 2. Noise vs. Frequency
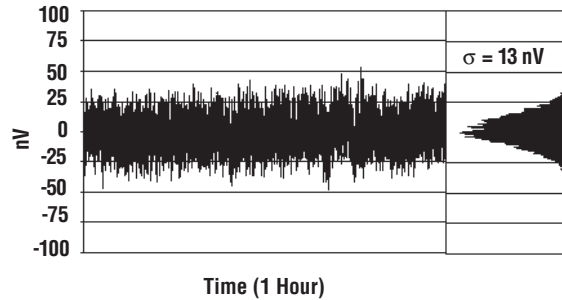

Figure 3. 0.01 Hz to 10 Hz Noise

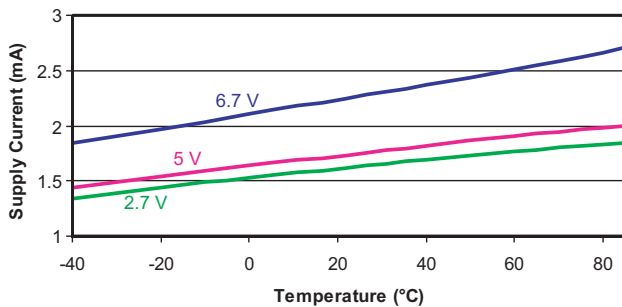Figure 4. Offset Voltage Stability (DC to 3.2 Hz)

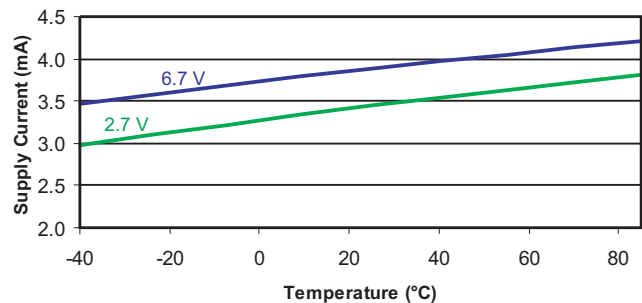Figure 5. Supply Current vs. Temperature, CS3001

Figure 6. Supply Current vs. Temperature, CS3002

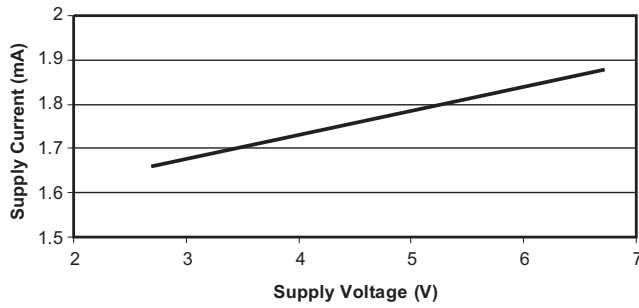## Typical Performance Plots (Cont.)

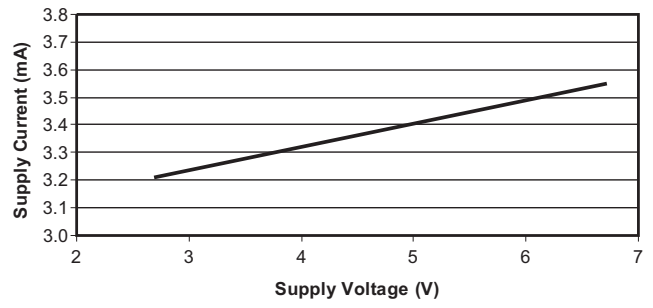Figure 7. Supply Current vs. Voltage, CS3001

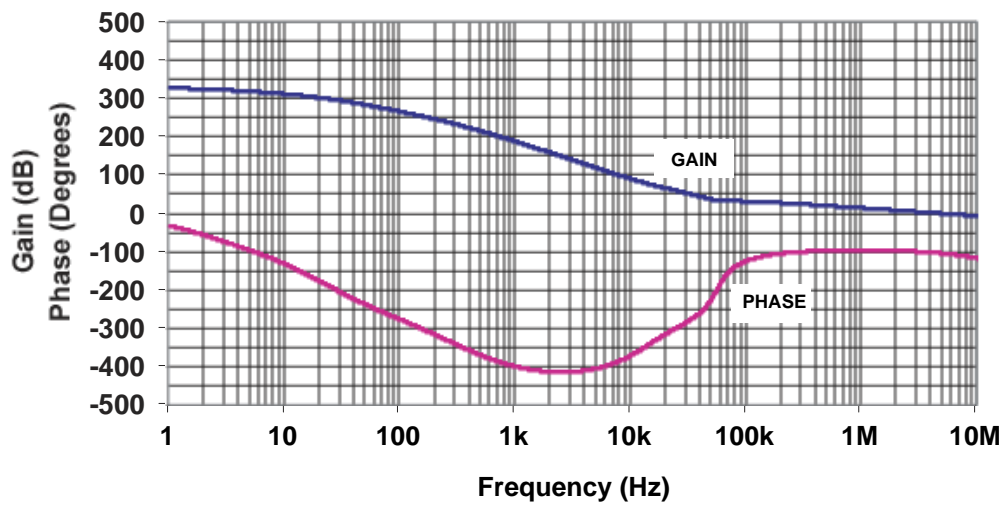Figure 8. Supply Current vs. Voltage, CS3002

Figure 9. Open-loop Gain and Phase vs. Frequency

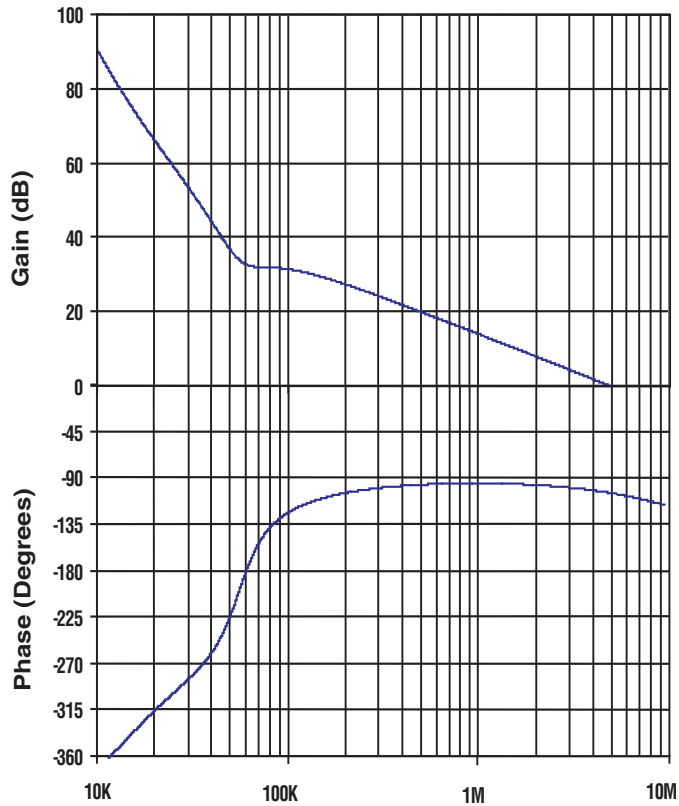## Typical Performance Plots (Cont.)

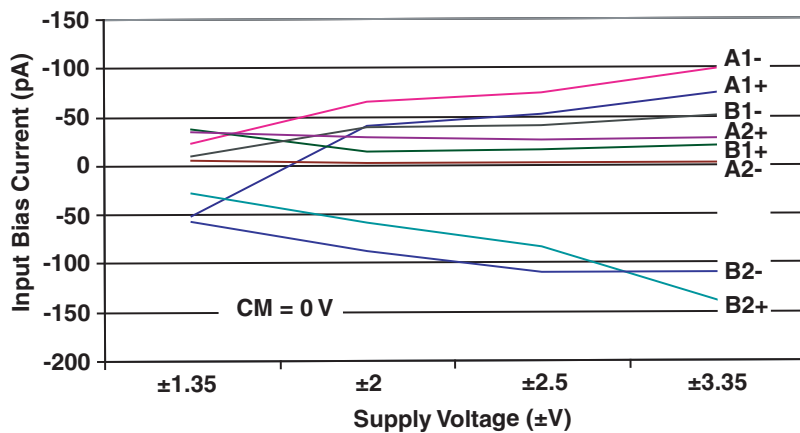**Figure 10. Open-loop Gain and Phase vs. Frequency (Expanded)**

Figure 11. Input Bias Current vs. Supply Voltage
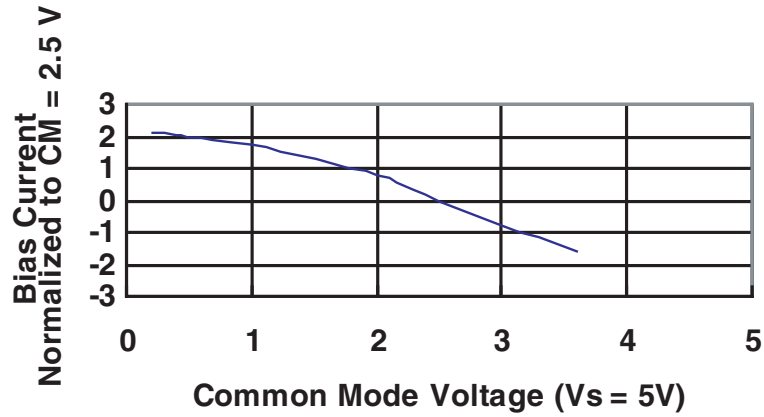
Typical Performance Plots (Cont.)

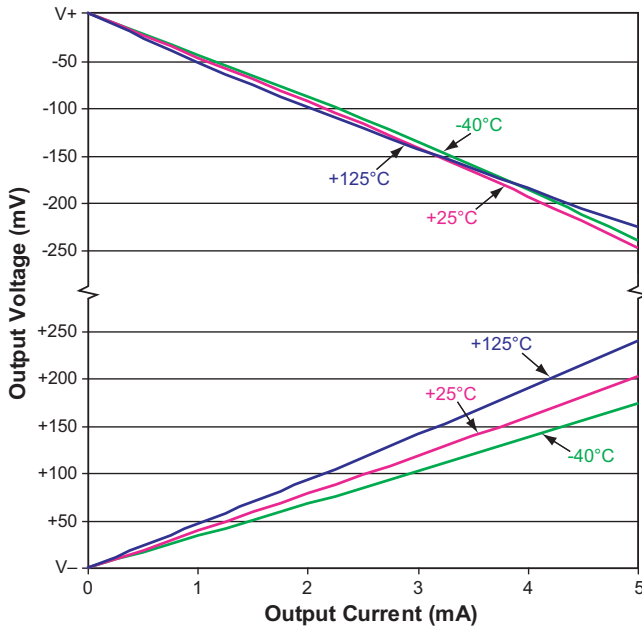**Figure 12. Input Bias Current vs. Common Mode Voltage**

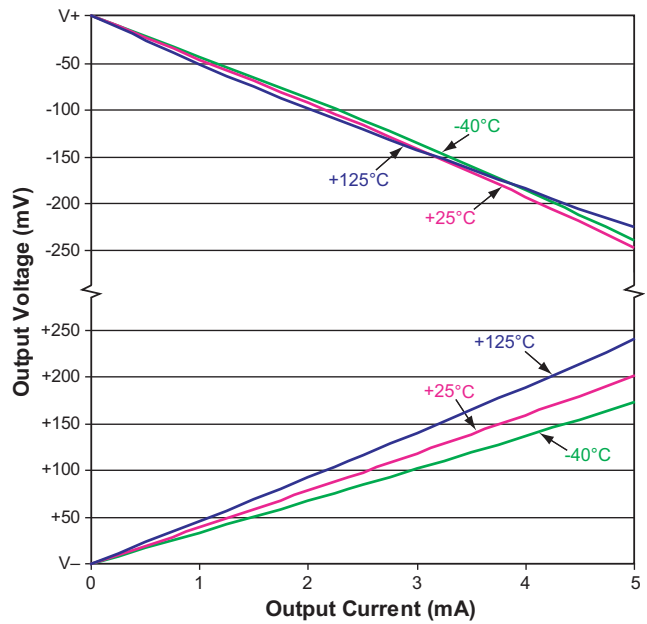**Figure 13. Voltage Swing vs. Output Current (2.7 V)**

Figure 14. Voltage Swing vs. Output Current (5 V)

3. CS3001/CS3002 OVERVIEW

The CS3001/CS3002 amplifiers are designed for precision measurement of signals from DC to 2 kHz when operating from a supply voltage of +2.7 V to +6.7 V ($\pm$ 1.35 to $\pm$ 3.35 V). The amplifiers are designed with a patented architecture that utilizes multiple amplifier stages to yield very high open loop gain at frequencies of 10 kHz and below. The amplifiers yield low noise and low offset drift while consuming relatively low supply current. An increase in noise floor above 2 kHz is the result of intermediate stages of the amplifier being operated at very low currents. The amplifiers are intended for amplifying small signals with large gains in applications where the output of the amplifier can be band-limited to frequencies below 2 kHz.

3.1 Open-loop Gain and Phase Response

Figure 15 illustrates the open loop gain and phase response of the CS3001/CS3002. The gain slope of the amplifier is about –100 dB/decade between 500 Hz and 60 kHz and transitions to –20 dB/decade between 60 kHz and its unity gain crossover frequency at about 4.8 MHz. Phase margin at unity gain is about 70 degrees; gain margin is about 20 dB.
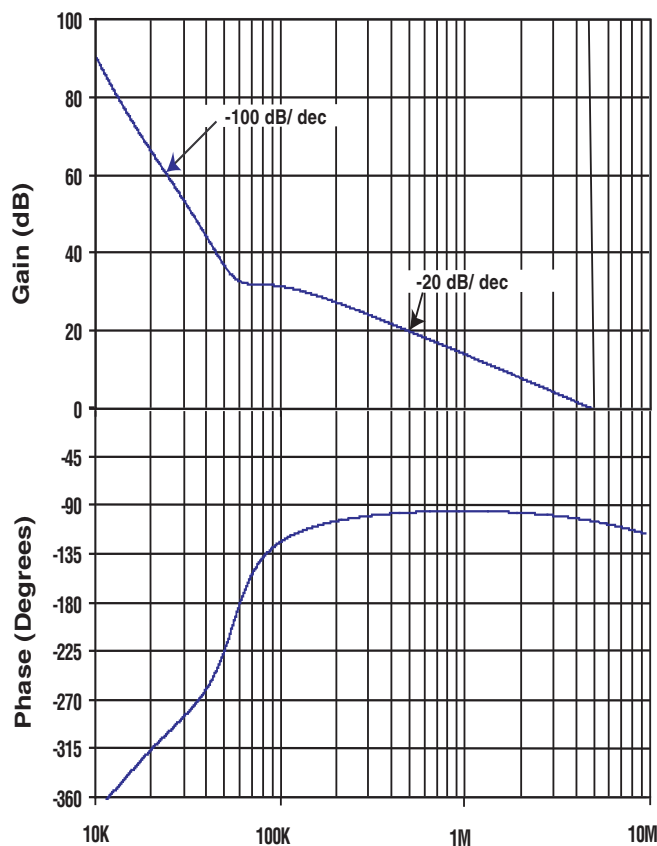

Figure 15. CS3001/CS3002 Open-loop Gain and Phase Response

3.2   Open-loop Gain and Stability Compensation

3.2.1   Discussion

The CS3001 and CS3002 achieve ultra-high open loop gain. Figure 16 illustrates the amplifier in a non-inverting gain configuration. The open loop gain and phase plots indicate that the amplifier is stable for closed-loop gains less than 50 V/V and R1 ≤ 100 Ohms. For a gain of 50, the phase margin is between 40° and 60° depending upon the loading conditions. As shown in Figure 17, on page 10, the operational amplifier has an input capacitance at the + and – signal inputs of typically 50 pF. This capacitance adds an additional pole in the loop gain transfer function at a frequency of $f = 1/(2\pi R^*C_{in})$ where R is the parallel combination of R1 and R2 (R1 ∥ R2). A higher value for R produces a pole at a lower frequency, thus reducing the phase margin. R1 is recommended to be less than or equal to 100 ohms, which results in a pole at 30 MHz or higher. If a higher value of R1 is desired, a compensation capacitor (C2) should be added in parallel with R2. C2 should be chosen such that $R2^*C2 \geq R1^*C_{in}$.
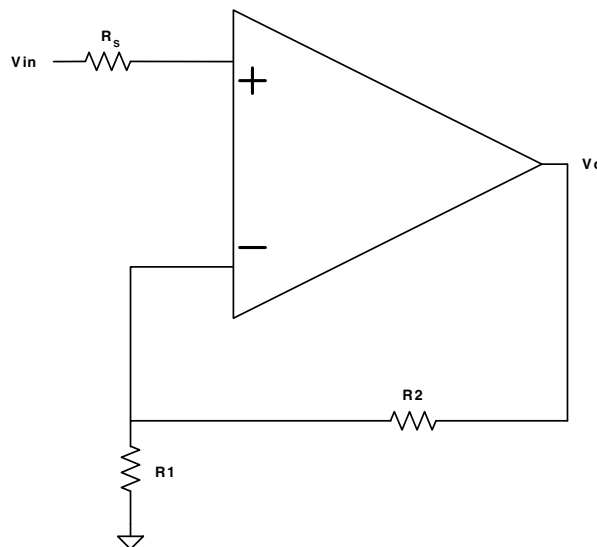

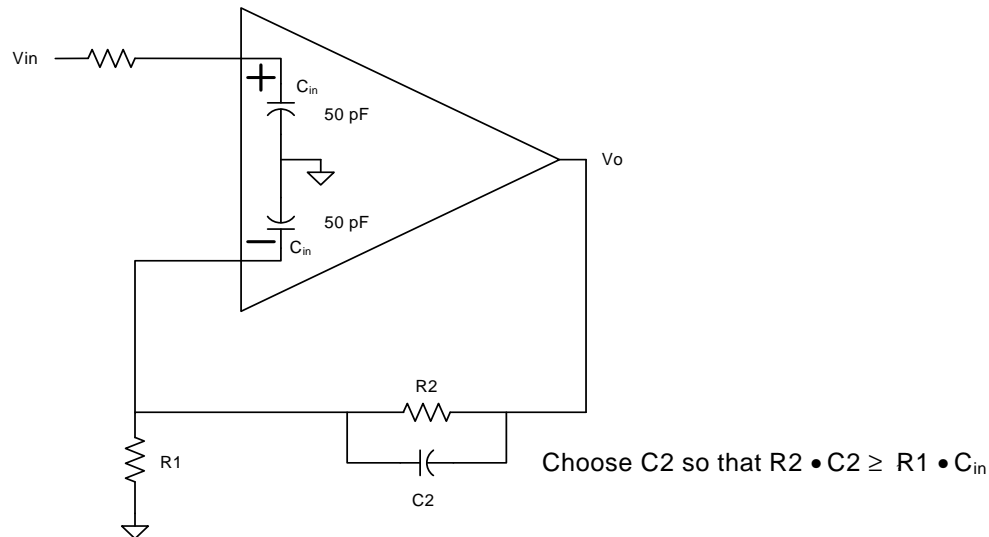**Figure 16. Non-inverting Gain Configuration**

Figure 17. Non-inverting Gain Configuration with Compensation

The feedback capacitor C2 is required for closed-loop gains greater than 50 V/V. The capacitor introduces a pole and a zero in the loop gain transfer function,

$$T = \frac{-\left(1 + \dfrac{s}{z_1}\right)}{\left(1 + \dfrac{s}{p_1}\right)} A_{ol}$$

$$P_1 = \frac{1}{2\pi(R_1 \parallel R_2)C_2} \cong \frac{1}{2\pi(R_1 C_2)} \qquad \text{for} \qquad R_2 \gg R_1$$

$$Z_1 = \frac{1}{2\pi(A \times R_1)C_2} \qquad \text{where} \qquad |A| = \frac{R_2}{R_1}$$

$$Z_1 = \frac{1}{2\pi(R_2)C_2}$$

This indicates that the separation of the pole and the zero is governed by the closed loop gain. It is required that the zero falls on the steep slope (–100 dB/decade) of the loop gain plot so that there is some gain higher than 0 dB (typically 20 dB) at the hand-over frequency (the frequency at which the slope changes from – 100 dB/decade to –20 dB/decade).

The loop gain plot shown in Figure 18 illustrates the unity gain configuration, and indicates how this is modified when using the amplifier in a higher gain configuration with compensation. If it is configured for higher gain, for example, 60 dB, the x–axis will move up by 60 dB (line B). Capacitor C2 adds a zero and a pole. The modified plot indicates the effects of introducing the pole and zero due to capacitor C2. The pole can be located at any frequency higher than the hand-over frequency, the zero has to be at a frequency lower than the hand-over frequency so as to provide adequate gain mar-

gin. The separation between the pole and the zero is governed by the closed loop gain. The zero (z_1) occurs at the intersection of the –100 dB/decade and –80 dB/decade slopes. The point X in the figure should be at closed loop gain plus 20 dB gain margin. The value for C2 = 1/(2π R1 P1). Setting the pole of the filter to P1 = 1 MHz works very well and is independent of gain. As the closed loop gain is changed, the zero location is also modified if R1 remains fixed. Capacitor C2 can be increased in value to limit the amplifier's rising noise above 2 kHz.
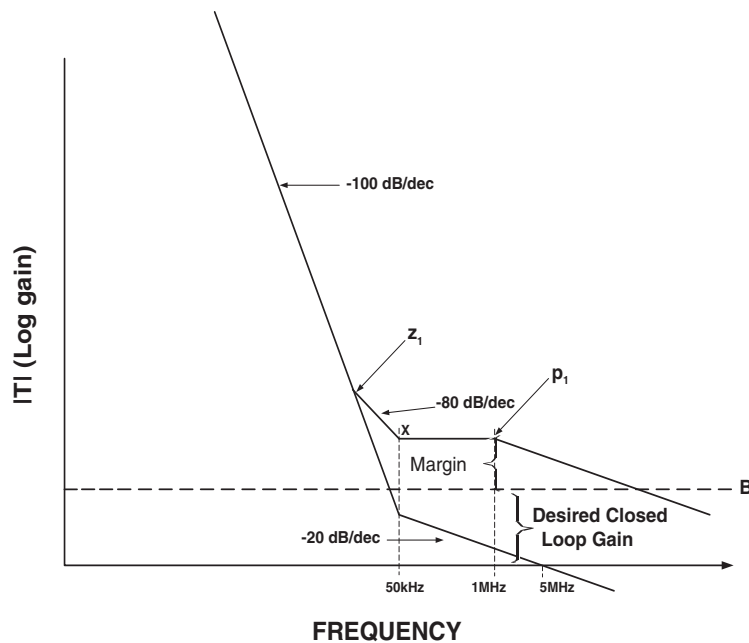

Figure 18. Loop Gain Plot: Unity Gain and with Pole-zero Compensation

3.2.2 Gain Calculations Summary and Recommendations

Condition #1: |Av| ≤ 50 and R1 ≤ 100 Ω

The Opamp is inherently stable for $|Av| \leq 50$ and $R1 \leq 100 \, \Omega$. No C2 compensation capacitor across R2 is required.

- $|Av| = 1$ configuration has 70° phase margin and 20 dB gain margin.

- $|Av| = 50$ configuration has phase margin between 40° for $C_{LOAD} \leq 100 \, pF$ and 60° for $C_{LOAD} = 0 \, pF$.

Condition #2: |Av| ≤ 50 and R1 > 100 Ω

Compensation capacitor C2 across R2 is required. Calculate C2 using the following formula:

- $C2 \geq (R1 \bullet C_{in}) / R2$, where $Cin = 50 \, pF$

Condition #3: |Av| > 50

Compensation capacitor C2 across R2 is required. Calculate and verify a value for C2 using the following steps.

Calculate the Compensation Capacitor Value:

1) Calculate a value for C2 using the following formula:

   $C2 = 1 / [2\pi (R1||R2) \bullet P1]$, where $P1 = 1 \, MHz$

   To simplify the calculation, set the pole of the filter to $P1 = 1 \, MHz$. P1 must be set higher than the opamp's internal 50 kHz crossover frequency.

2) Calculate a second value for C2 using the following formula:

   $C2 \geq (R1 \bullet C_{in}) / R2$, where $Cin = 50 \, pF$

3) Use the larger of the two values calculated in steps 1 & 2.

Verify the Opamp Compensation:

Verify the opamp compensation using the open-loop gain and phase response Bode plot in Figure 15. Plot the calculated closed loop gain transfer function and verify the following design criteria are met:

- Pole P1 > opamp internal 50 kHz crossover frequency

  - $P1 = 1 / [2\pi (R1||R2) \bullet C2]$, where $P1 = 1 \, MHz$

  - To simplify the calculation, set the pole to $P1 = 1 \, MHz$.

- Z1 < opamp internal 50 kHz crossover frequency

  - $Z1 = 1 / (2\pi R2 \bullet C2)$

- Gain margin above the open-loop gain transfer function is required. A gain margin of +20 dB above the open loop gain transfer function is optimal.

3.3 Powerdown (PDWN)

The CS3001 single amplifier provides a powerdown function on pin 1. If this pin is left open the amplifier will operate normally. If the powerdown is asserted low, the amplifier will go into a low power state. There is a pull-up resistor (approximately 800 kΩ) inside the amplifier from pin 1 to the V+ supply. The current through this pull-up resistor is the main source of current drain in the powerdown state.

3.4 Applications

The CS3001 and CS3002 amplifiers are optimum for applications that require high gain and low drift. Figure 19 illustrates a thermopile amplifier with a gain of 650 V/V. The thermopile outputs only a few millivolts when subjected to infrared radiation. The amplifier is compensated and bandlimited by C1 in combination with R2.

Figure 20, on page 13 illustrates a load cell bridge amplifier with a gain of 768 V/V. The load cell is excited with +5 V and has a 1 mV/V sensitivity. Its full scale output signal is amplified to produce a fully differential ± 3.8 V into the CS5510/12 A/D converter. This circuit operates from +5 V.
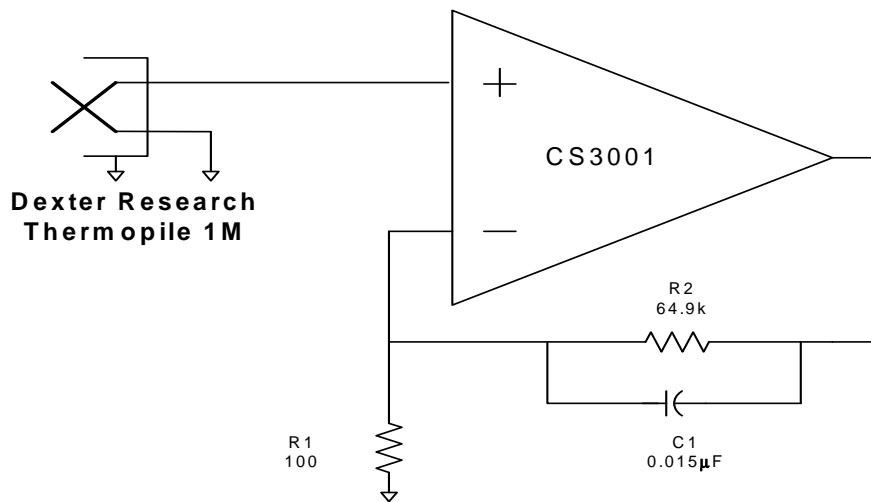
Figure 19. Thermopile Amplifier with a Gain of 650 V/V
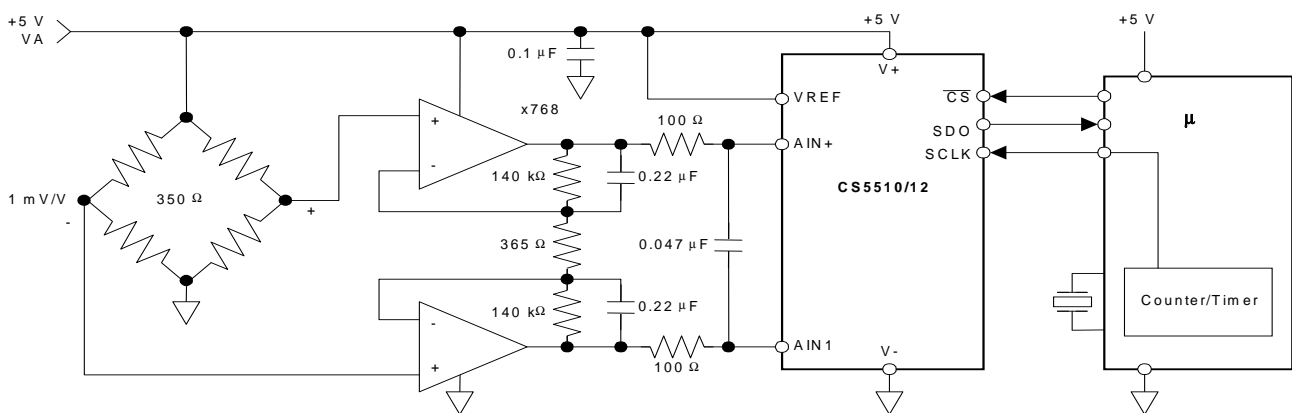
Figure 20. Load Cell Bridge Amplifier and A/D Converter

4. PACKAGE DRAWING

8L SOIC (150 MIL BODY) PACKAGE DRAWING
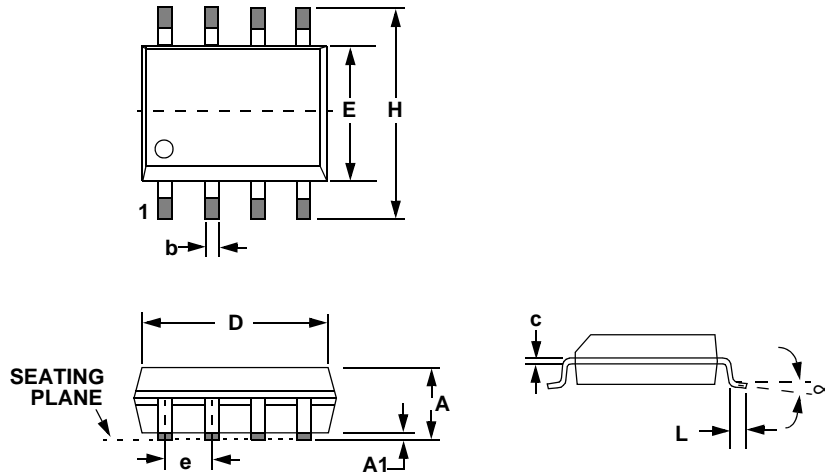
	INCHES		MILLIMETERS	
DIM	**MIN**	**MAX**	**MIN**	**MAX**
A	0.053	0.069	1.35	1.75
A1	0.004	0.010	0.10	0.25
B	0.013	0.020	0.33	0.51
C	0.007	0.010	0.19	0.25
D	0.189	0.197	4.80	5.00
E	0.150	0.157	3.80	4.00
e	0.040	0.060	1.02	1.52
H	0.228	0.244	5.80	6.20
L	0.016	0.050	0.40	1.27
∝	0°	8°	0°	8°

JEDEC #: MS-012

5. ORDERING INFORMATION

Model	Temperature	Package
CS3001-ISZ (lead free)	-40 to +85 °C	8-pin SOIC (Lead Free)
CS3002-ISZ (lead free)		

6. ENVIRONMENTAL, MANUFACTURING, & HANDLING INFORMATION

Model Number	Peak Reflow Temp	MSL Rating*	Max Floor Life
CS3001-ISZ (lead free)	260 °C	2	365 Days
CS3002-ISZ (lead free)			

* MSL (Moisture Sensitivity Level) as specified by IPC/JEDEC J-STD-020.

7. REVISION HISTORY

Revision	Date	Changes
F3	OCT 2004	Added lead-free device ordering information.
F4	AUG 2005	Added MSL specifications. Updated legal notice. Added leaded (Pb) devices.
F5	AUG 2006	Updated *Typical Performance Plots*.
F6	SEP 2006	Corrected error in Ordering Information section.
F7	NOV 2007	Added additional information regarding open-loop and gain stability compensation.
F8	OCT 2008	Minor, cosmetic correction to caption for Figure 10.
F9	JUL 2009	Removed lead-containing devices from ordering information.

Contacting Cirrus Logic Support

For all product questions and inquiries contact a Cirrus Logic Sales Representative.

To find the one nearest to you go to www.cirrus.com