# 2.5V and 3.3V LVCMOS Clock **Fanout Buffer**

The MPC9456 is a 2.5V and 3.3V compatible 1:10 clock distribution buffer designed for low-voltage mid-range to high-performance telecom, networking and computing applications. Both 3.3V, 2.5V and dual supply voltages are supported for mixed-voltage applications. The MPC9456 offers 10 low-skew outputs and a differential LVPECL clock input. The outputs are configurable and support 1:1 and 1:2 output to input frequency ratios. The MPC9456 is specified for the extended temperature range of -40 to 85°C.

#### **Features**

- Configurable 10 outputs LVCMOS clock distribution buffer
- Compatible to single, dual and mixed 3.3V/2.5V voltage supply
- Wide range output clock frequency up to 250 MHz
- Designed for mid-range to high-performance telecom, networking and computer applications
- Supports high-performance differential clocking applications
- Max. output skew of 200 ps (150 ps within one bank)
- Selectable output configurations per output bank
- Tristable outputs
- 32 ld LQFP package
- Ambient operating temperature range of –40 to 85°C

#### **Functional Description**

The MPC9456 is a full static design supporting clock frequencies up to 250 MHz. The signals are generated and retimed on-chip to ensure minimal skew between the three output banks.

# MPC9456

LOW VOLTAGE SINGLE OR **DUAL SUPPLY 2.5V AND 3.3V** LVCMOS CLOCK **DISTRIBUTION BUFFER** 



**FA SUFFIX** LQFP PACKAGE CASE 873A-02

Each of the three output banks can be individually supplied by 2.5V or 3.3V supporting mixed voltage applications. The FSELx pins choose between division of the input reference frequency by one or two. The frequency divider can be set individually for each of the three output banks. The MPC9456 can be reset and the outputs are disabled by deasserting the MR/OE pin (logic high state). Asserting MR/OE will enable the outputs.

All control inputs accept LVCMOS signals while the outputs provide LVCMOS compatible levels with the capability to drive terminated 50  $\Omega$  transmission lines. The clock input is low voltage PECL compatible for differential clock distribution support. Please consult the MPC9446 specification for a full CMOS compatible device. For series terminated transmission lines, each of the MPC9456 outputs can drive one or two traces giving the devices an effective fanout of 1:20. The device is packaged in a 7x7 mm<sup>2</sup> 32-lead LQFP package.

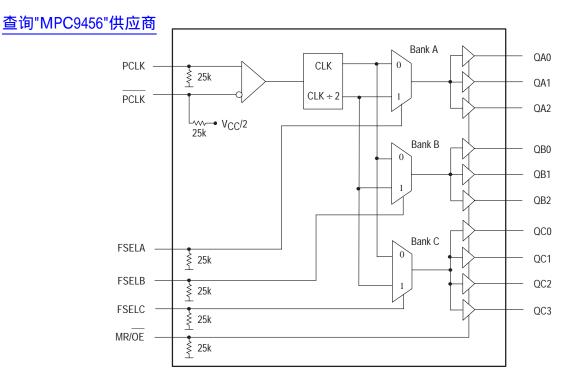


Figure 1. MPC9456 Logic Diagram

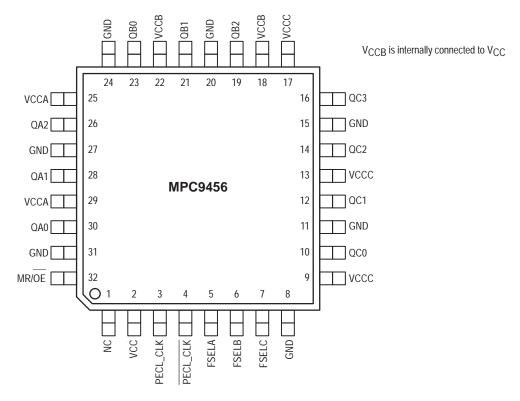


Figure 2. Pinout: 32-Lead Package Pinout (Top View)

#### 查询"MPC9456"供应商 Table 1: Pin Configuration

Pin	I/O	Туре	Function
PECL_CLK, PECL_CLK	Input	LVPECL	Differential clock reference Low voltage positive ECL input
FSELA, FSELB, FSELC	Input	LVCMOS	Output bank divide select input
MR/OE	Input	LVCMOS	Internal reset and output tristate control
GND		Supply	Negative voltage supply output bank (GND)
V <sub>CCA</sub> , V <sub>CCB</sub> *, V <sub>CCC</sub>		Supply	Positive voltage supply for output banks
VCC		Supply	Positive voltage supply core (VCC)
QA0 - QA2	Output	LVCMOS	Bank A outputs
QB0 - QB2	Output	LVCMOS	Bank B outputs
QC0 - QC3	Output	LVCMOS	Bank C outputs

VCCB is internally connected to VCC.

#### **Table 2: Supported Single and Dual Supply Configurations**

Supply voltage configuration	V <sub>CC</sub> a	V <sub>CCA</sub> b	V <sub>CCB</sub> c	VCCC <sub>d</sub>	GND
3.3V	3.3V	3.3V	3.3V	3.3V	0V
Mixed voltage supply	3.3V	3.3V or 2.5V	3.3V	3.3V or 2.5V	0 V
2.5V	2.5V	2.5V	2.5V	2.5V	0 V

- a. VCC is the positive power supply of the device core and input circuitry. VCC voltage defines the input threshold and levels
- b.  $V_{CCA}$  is the positive power supply of the bank A outputs.  $V_{CCA}$  voltage defines bank A output levels
- c.  $V_{CCB}$  is the positive power supply of the bank B outputs.  $V_{CCB}$  voltage defines bank B output levels.  $V_{CCB}$  is internally connected to  $V_{CCB}$ .
- d. V<sub>CCC</sub> is the positive power supply of the bank C outputs. V<sub>CCC</sub> voltage defines bank C output levels

# **Table 3: Function Table (Controls)**

Control	Default	0	1
FSELA	0	fQA0:2 = fREF	f <sub>QA0:2</sub> = f <sub>REF</sub> ÷ 2
FSELB	0	f <sub>QB0:2</sub> = f <sub>REF</sub>	f <sub>QB0:2</sub> = f <sub>REF</sub> ÷ 2
FSELC	0	fQC0:3 = fREF	fQC0:3 = fREF ÷ 2
MR/OE	0	Outputs enabled	Internal reset Outputs disabled (tristate)

### Table 4: Absolute Maximum Ratings<sup>a</sup>

Symbol	Characteristics	Min	Max	Unit	Condition
VCC	Supply Voltage	-0.3	4.6	V	
V <sub>IN</sub>	DC Input Voltage	-0.3	V <sub>CC</sub> +0.3	V	
VOUT	DC Output Voltage	-0.3	V <sub>CC</sub> +0.3	V	
IN	DC Input Current		±20	mA	
IOUT	DC Output Current		±50	mA	
TS	Storage temperature	-40	125	°C	

a. Absolute maximum continuos ratings are those maximum values beyond which damage to the device may occur. Exposure to these conditions or conditions beyond those indicated may adversely affect device reliability. Functional operation under absolute-maximum-rated conditions is not implied.

#### **Table 5: General Specifications**

Symbol	Characteristics	Min	Тур	Max	Unit	Condition
VTT	Output Termination Voltage		V <sub>CC</sub> ÷ 2		V	
MM	ESD Protection (Machine Model)	200			V	
HBM	ESD Protection (Human Body Model)	2000			V	
LU	Latch-Up Immunity	200			mA	
C <sub>PD</sub>	Power Dissipation Capacitance		10		pF	Per output
C <sub>IN</sub>	Input Capacitance		4.0		pF	

Table 6: DC Characteristics (V<sub>CC</sub> = V<sub>CCA</sub> = V<sub>CCB</sub> = V<sub>CCC</sub> = 3.3V  $\pm$  5%, T<sub>A</sub> = -40 to +85°C)

Symbol	Characteristics		Min	Тур	Max	Unit	Condition
VIH	Input high voltage		2.0		V <sub>CC</sub> + 0.3	V	LVCMOS
VIL	Input low voltage		-0.3		0.8	V	LVCMOS
VPP	Peak-to-peak input voltage	PCLK	250			mV	LVPECL
VCMRa	Common Mode Range	PCLK	1.1		V <sub>CC</sub> -0.6	V	LVPECL
I <sub>IN</sub>	Input current <sup>b</sup>				200	μΑ	V <sub>IN</sub> =GND or V <sub>IN</sub> =V <sub>CC</sub>
VOH	Output High Voltage		2.4			V	I <sub>OH</sub> =-24 mA <sup>C</sup>
VOL	Output Low Voltage				0.55 0.30	V V	I <sub>OL</sub> = 24mA <sup>b</sup> I <sub>OL</sub> = 12mA
Z <sub>OUT</sub>	Output impedance			14 - 17		Ω	
IccQd	Maximum Quiescent Supply Current				2.0	mA	All V <sub>CC</sub> Pins

- V<sub>CMR</sub> (DC) is the crosspoint of the differential input signal. Functional operation is obtained when the crosspoint is within the V<sub>CMR</sub> range
  and the input swing lies within the V<sub>PP</sub> (DC) specification.
- b. Input pull-up / pull-down resistors influence input current.
- c. The MPC9456 is capable of driving  $50\Omega$  transmission lines on the incident edge. Each output drives one  $50\Omega$  parallel terminated transmission line to a termination voltage of  $V_{TT}$ . Alternatively, the device drives up to two  $50\Omega$  series terminated transmission lines.
- d. ICCO is the DC current consumption of the device with all outputs open and the input in its default state or open.

Table 7: AC Characteristics (VCC = VCCA = VCCB = VCCC =  $3.3V \pm 5\%$ , T<sub>A</sub> = -40 to  $+85^{\circ}$ C)<sup>a</sup>

Symbol	Characteristics	Min	Тур	Max	Unit	Condition
fref	Input Frequency	0		250 <sup>b</sup>	MHz	
fMAX	Maximum Output Frequency ÷1 output ÷2 output	0 0		250 <sup>b</sup> 125	MHz MHz	FSELx=0 FSELx=1
VPP	Peak-to-peak input voltage PCLK	500		1000	mV	LVPECL
VCMRC	Common Mode Range PCLK	1.3		V <sub>CC</sub> -0.8	V	LVPECL
<sup>t</sup> P, REF	Reference Input Pulse Width	1.4			ns	
t <sub>r</sub> , t <sub>f</sub>	PCLK Input Rise/Fall Time			1.0 <sup>d</sup>	ns	0.8 to 2.0V
<sup>t</sup> PLH <sup>t</sup> PHL	Propagation delay CCLK to any Q CCLK to any Q	2.2 2.2	2.8 2.8	4.45 4.2	ns ns	
<sup>t</sup> PLZ, HZ	Output Disable Time			10	ns	
<sup>t</sup> PZL, LZ	Output Enable Time			10	ns	
t <sub>sk(O)</sub>	Output-to-output Skew Within one bank Any output bank, same output divider Any output, Any output divider			150 200 350	ps ps ps	
t <sub>sk(PP)</sub>	Device-to-device Skew			2.25	ns	
tSK(P)	Output pulse skew <sup>e</sup>			200	ps	
DCQ	Output Duty Cycle ÷1 output ÷2 output	47 45	50 50	53 55	% %	DC <sub>REF</sub> = 50% DC <sub>REF</sub> = 25%-75%
t <sub>r</sub> , t <sub>f</sub>	Output Rise/Fall Time	0.1		1.0	ns	0.55 to 2.4V

- a. AC characteristics apply for parallel output termination of  $50\Omega$  to V<sub>TT</sub>.
- b. The MPC9456 is functional up to an input and output clock frequency of 350 MHz and is characterized up to 250 MHz.
- c. V<sub>CMR</sub> (AC) is the crosspoint of the differential input signal. Normal AC operation is obtained when the crosspoint is within the V<sub>CMR</sub> range and the input swing lies within the V<sub>PP</sub> (AC) specification.
- d. Violation of the 1.0 ns maximum input rise and fall time limit will affect the device propagation delay, device-to-device skew, reference input pulse width, output duty cycle and maximum frequency specifications.
- e. Output pulse skew is the absolute difference of the propagation delay times: | t<sub>DLH</sub> t<sub>DHL</sub> |.

Table 8: DC Characteristics ( $V_{CC} = V_{CCA} = V_{CCB} = V_{CCC} = 2.5V \pm 5\%$ ,  $T_A = -40$  to +85°C)

Symbol	Characteristics		Min	Тур	Max	Unit	Condition
VIH	Input high voltage		1.7		V <sub>CC</sub> + 0.3	V	LVCMOS
V <sub>IL</sub>	Input low voltage		-0.3		0.7	V	LVCMOS
VPP	Peak-to-peak input voltage	PCLK	250			mV	LVPECL
VCMRa	Common Mode Range	PCLK	1.1		V <sub>CC</sub> -0.7	V	LVPECL
Vон	Output High Voltage		1.8			V	I <sub>OH</sub> =-15 mA <sup>b</sup>
V <sub>OL</sub>	Output Low Voltage				0.6	V	I <sub>OL</sub> = 15 mA
Z <sub>OUT</sub>	Output impedance			17 - 20 <sup>b</sup>		Ω	
I <sub>IN</sub>	Input current <sup>C</sup>				±200	μΑ	V <sub>IN</sub> =GND or V <sub>IN</sub> =V <sub>CC</sub>
ICCQd	Maximum Quiescent Supply Current				2.0	mA	All V <sub>CC</sub> Pins

- V<sub>CMR</sub> (DC) is the crosspoint of the differential input signal. Functional operation is obtained when the crosspoint is within the V<sub>CMR</sub> range
  and the input swing lies within the V<sub>PP</sub> (DC) specification.
- b. The MPC9456 is capable of driving 50Ω transmission lines on the incident edge. Each output drives one 50Ω parallel terminated transmission line to a termination voltage of V<sub>TT</sub>. Alternatively, the device drives up to two 50Ω series terminated transmission lines per output.
- c. Input pull-up / pull-down resistors influence input current.
- d. ICCQ is the DC current consumption of the device with all outputs open and the input in its default state or open.

Table 9: AC Characteristics (VCC = VCCA = VCCB = VCCC = 2.5V  $\pm$  5%, TA = -40 to +85°C)<sup>a</sup>

Symbol	Characteristics	Min	Тур	Max	Unit	Condition
fref	Input Frequency	0		250b	MHz	
fMAX	Maximum Output Frequency ÷1 output ÷2 output	0 0		250 <sup>b</sup> 125	MHz MHz	FSELx=0 FSELx=1
VPP	Peak-to-peak input voltage PCLK	500		1000	mV	LVPECL
VCMRC	Common Mode Range PCLK	1.1		V <sub>CC</sub> -0.7	V	LVPECL
<sup>t</sup> P, REF	Reference Input Pulse Width	1.4			ns	
t <sub>r</sub> , t <sub>f</sub>	PCLK Input Rise/Fall Time			1.0 <sup>d</sup>	ns	0.7 to 1.7V
tPLH tPHL	Propagation delay PCLK to any Q PCLK to any Q	2.6 2.6		5.6 5.5	ns ns	
<sup>t</sup> PLZ, HZ	Output Disable Time			10	ns	
<sup>t</sup> PZL, LZ	Output Enable Time			10	ns	
t <sub>sk(O)</sub>	Output-to-output Skew Within one bank Any output bank, same output divider Any output, Any output divider			150 200 350	ps ps ps	
t <sub>sk(PP)</sub>	Device-to-device Skew			3.0	ns	
tSK(P)	Output pulse skew <sup>e</sup>			200	ps	
DCQ	Output Duty Cycle ÷1 or ÷2 output	45	50	55	%	DC <sub>REF</sub> = 50%
t <sub>r</sub> , t <sub>f</sub>	Output Rise/Fall Time	0.1		1.0	ns	0.6 to 1.8V

- a. AC characteristics apply for parallel output termination of  $50\Omega$  to V<sub>TT</sub>.
- b. The MPC9456 is functional up to an input and output clock frequency of 350 MHz and is characterized up to 250 MHz.
- c. V<sub>CMR</sub> (AC) is the crosspoint of the differential input signal. Normal AC operation is obtained when the crosspoint is within the V<sub>CMR</sub> range and the input swing lies within the V<sub>PP</sub> (AC) specification.
- d. Violation of the 1.0 ns maximum input rise and fall time limit will affect the device propagation delay, device-to-device skew, reference input pulse width, output duty cycle and maximum frequency specifications.
- e. Output pulse skew is the absolute difference of the propagation delay times: | t<sub>pLH</sub> t<sub>pHL</sub> |.

# Freescale Semiconductor, Inc.

# 查询"MPC9456"供应商

Table 10: AC Characteristics ( $V_{CC}$  = 3.3V  $\pm$  5%,  $V_{CCA}$  =  $V_{CCB}$  =  $V_{CCC}$  = 2.5V  $\pm$  5% or 3.3V  $\pm$  5%,  $T_A$  = -40 to +85°C)a b

Symbol	Characteristics	Min	Тур	Max	Unit	Condition
t <sub>sk(O)</sub>	Output-to-output Skew Within one bank Any output bank, same output divide Any output, Any output divide			150 250 350	ps ps ps	
t <sub>sk(PP)</sub>	Device-to-device Skew			2.5	ns	
tPLH,HL	Propagation delay PCLK to any C		See 3.3V to	able		
tSK(P)	Output pulse skew <sup>C</sup>			250	ps	
DCQ	Output Duty Cycle ÷1 or ÷2 output	45	50	55	%	DC <sub>REF</sub> = 50%

- a. AC characteristics apply for parallel output termination of  $50\Omega$  to V<sub>TT</sub>.
- b. For all other AC specifications, refer to 2.5V or 3.3V tables according to the supply voltage of the output bank.
- c. Output pulse skew is the absolute difference of the propagation delay times: | t<sub>pLH</sub> t<sub>pHL</sub> |.

#### **APPLICATIONS INFORMATION**

#### **Driving Transmission Lines**

The MPC9456 clock driver was designed to drive high speed signals in a terminated transmission line environment. To provide the optimum flexibility to the user the output drivers were designed to exhibit the lowest impedance possible. With an output impedance of less than  $20\Omega$  the drivers can drive either parallel or series terminated transmission lines. For more information on transmission lines the reader is referred to application note AN1091. In most high performance clock networks point-to-point distribution of signals is the method of choice. In a point-to-point scheme either series terminated or parallel terminated transmission lines can be used. The parallel technique terminates the signal at the end of the line with a  $50\Omega$  resistance to  $V_{\rm CC} \div 2$ .

This technique draws a fairly high level of DC current and thus only a single terminated line can be driven by each output of the MPC9456 clock driver. For the series terminated case however there is no DC current draw, thus the outputs can drive multiple series terminated lines. Figure 3. "Single versus Dual Transmission Lines" illustrates an output driving a single series terminated line versus two series terminated lines in parallel. When taken to its extreme the fanout of the MPC9456 clock driver is effectively doubled due to its capability to drive multiple lines.

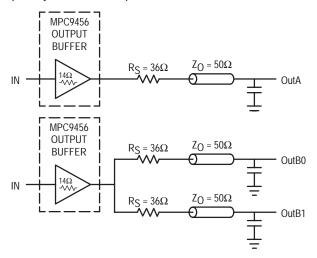


Figure 3. Single versus Dual Transmission Lines

The waveform plots in Figure 4. "Single versus Dual Line Termination Waveforms" show the simulation results of an output driving a single line versus two lines. In both cases the drive capability of the MPC9456 output buffer is more than sufficient to drive  $50\Omega$  transmission lines on the incident edge. Note from the delay measurements in the simulations a delta of only 43ps exists between the two differently loaded outputs. This suggests that the dual line driving need not be used exclusively to maintain the tight output-to-output skew of the MPC9456. The output waveform in Figure 4. "Single versus Dual Line Termination Waveforms" shows a step in the waveform, this step is caused by the impedance mismatch seen looking into the driver. The parallel combination of the  $36\Omega$  series resistor plus the output

impedance does not match the parallel combination of the line impedances. The voltage wave launched down the two lines will equal:

$$\begin{array}{l} V_L = V_S \; (\; Z_0 \div (R_S + R_0 + Z_0)) \\ Z_0 = \; 50\Omega \; || \; 50\Omega \\ R_S = \; 36\Omega \; || \; 36\Omega \\ R_0 = \; 14\Omega \\ V_L = \; 3.0 \; (\; 25 \div (18 + 14 + 25)) \\ = \; 1.31V \end{array}$$

At the load end the voltage will double, due to the near unity reflection coefficient, to 2.5V. It will then increment towards the quiescent 3.0V in steps separated by one round trip delay (in this case 4.0ns).

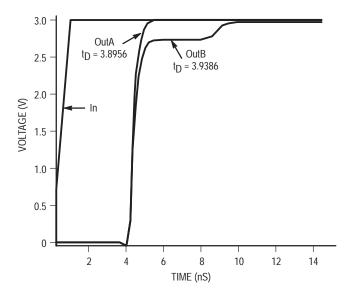


Figure 4. Single versus Dual Waveforms

Since this step is well above the threshold region it will not cause any false clock triggering, however designers may be uncomfortable with unwanted reflections on the line. To better match the impedances when driving multiple lines the situation in Figure 5. "Optimized Dual Line Termination" should be used. In this case the series terminating resistors are reduced such that when the parallel combination is added to the output buffer impedance the line impedance is perfectly matched.

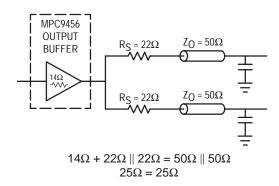
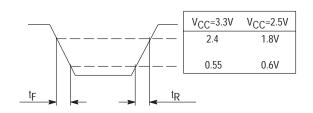


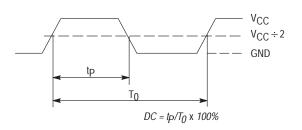
Figure 5. Optimized Dual Line Termination

# 查询"MPC9456"供应商 Differential Pulse Generator $Z = 50\Omega$ $R_T = 50\Omega$ $V_{CC} - 2V$ MPC9456 DUT $Z_0 = 50\Omega$ $Z_0 = 50\Omega$ $Z_0 = 50\Omega$

Figure 6. PCLK MPC9456 AC test reference for  $V_{CC}$  = 3.3V and  $V_{CC}$  = 2.5V



**Figure 7. Output Transition Time Test Reference** 



The time from the PLL controlled edge to the non controlled edge, divided by the time between PLL controlled edges, expressed as a percentage

Figure 9. Output Duty Cycle (DC)

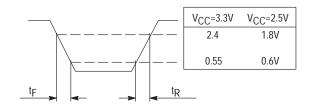


Figure 11. Output Transition Time test reference

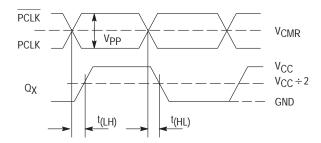
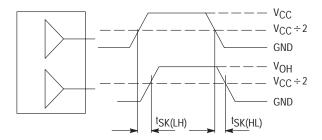


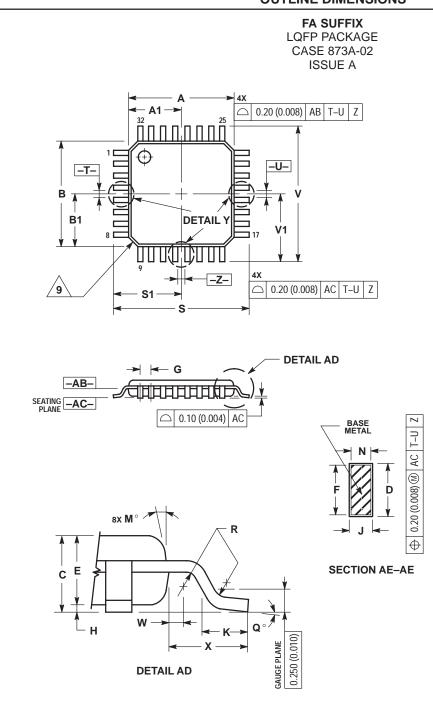
Figure 8. Propagation delay (tpD) test reference

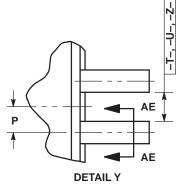


The pin-to-pin skew is defined as the worst case difference in propagation delay between any similar delay path within a single device

Figure 10. Output-to-output Skew tSK(O)

#### **OUTLINE DIMENSIONS**





- DIMENSIONING AND TOLERANCING PER ANSI
- Y14.5M, 1982. CONTROLLING DIMENSION: MILLIMETER.
- DATUM PLANE -AB- IS LOCATED AT BOTTOM
   OF LEAD AND IS COINCIDENT WITH THE LEAD OF LEAD AND IS COINCIDENT WITH THE LEAD WHERE THE LEAD EXITS THE PLASTIC BODY AT THE BOTTOM OF THE PARTING LINE.

  DATUMS -T-, -U-, AND -Z- TO BE DETERMINED AT DATUM PLANE -AB-.

  DIMENSIONS S AND V TO BE DETERMINED AT SEATING PLANE -AC-.

  DIMENSIONS A AND B DO NOT INCLUDE MOLD PROTEINSION ALL QUARDLE PROTEINSION IS

- PROTRUSION. ALLOWABLE PROTRUSION IS 0.250 (0.010) PER SIDE. DIMENSIONS A AND B DO INCLUDE MOLD MISMATCH AND ARE DETERMINED AT DATUM PLANE -AB-
- 7. DIMENSION D DOES NOT INCLUDE DAMBAR PROTRUSION. DAMBAR PROTRUSION SHALL NOT CAUSE THE D DIMENSION TO EXCEED 0.520 (0.020).
- MINIMUM SOLDER PLATE THICKNESS SHALL BE
   0.0076 (0.0003).

   EXACT SHAPE OF EACH CORNER MAY VARY

   CONTROL OF THE CONTROL OF THE
- FROM DEPICTION.

	MILLIN	METERS	INC	HES	
DIM	MIN	MAX	MIN	MAX	
Α	7.000	BSC	0.276	BSC	
A1	3.500	BSC	0.138	BSC	
В	7.000	BSC	0.276	BSC	
B1	3.500	BSC	0.138	BSC	
С	1.400	1.600	0.055	0.063	
D	0.300	0.450	0.012	0.018	
E	1.350	1.450	0.053	0.057	
F	0.300	0.400	0.012	0.016	
G	0.800	BSC	0.031 BSC		
Н	0.050	0.150	0.002	0.006	
J	0.090	0.200	0.004	0.008	
K	0.500	0.700	0.020	0.028	
M	12°	REF	12° REF		
N	0.090	0.160	0.004	0.006	
P	0.400		0.016	BSC	
Q	1°	5°	1°	5°	
R	0.150	0.250	0.006	0.010	
S	9.000	BSC	0.354 BSC		
S1	4.500 BSC		0.177	BSC	
V	9.000 BSC		0.354 BSC		
V1	4.500 BSC		0.177 BSC		
W	0.200	REF	0.008	REF	
Х	1.000	REF	0.039	REF	

MPC9456

reescale Semiconductor, Inc.

查询"MPC9456"供应商

**NOTES** 

**NOTES** 

Motorola reserves the right to make changes without further notice to any products herein. Motorola makes no warranty, representation or guarantee regarding the suitability of its products for any particular purpose, nor does Motorola assume any liability arising out of the application or use of any product or circuit, and specifically disclaims any and all liability, including without limitation consequential or incidental damages. "Typical" parameters which may be provided in Motorola data sheets and/or specifications can and do vary in different applications and actual performance may vary over time. All operating parameters, including "Typicals" must be validated for each customer application by customer's technical experts. Motorola does not convey any license under its patent rights nor the rights of others. Motorola products are not designed, intended, or authorized for use as components in systems intended for surgical implant into the body, or other applications intended to support or sustain life, or for any other application in which the failure of the Motorola product could create a situation where personal injury or death may occur. Should Buyer purchase or use Motorola products for any such unintended or unauthorized application, Buyer shall indemnify and hold Motorola and its officers, employees, subsidiaries, affiliates, and distributors harmless against all claims, costs, damages, and expenses, and reasonable attorney fees arising out of, directly or indirectly, any claim of personal injury or death associated with such unintended or unauthorized use, even if such claim alleges that Motorola was negligent regarding the design or manufacture of the part. Motorola, Inc. is an Equal Opportunity/Affirmative Action Employer. MOTOROLA and the logo are registered in the US Patent & Trademark Office. All other product or service names are the property of their respective owners.

© Motorola, Inc. 2002.

How to reach us:

USA/EUROPE/Locations Not Listed: Motorola Literature Distribution; P.O. Box 5405, Denver, Colorado 80217. 1-303-675-2140 or 1-800-441-2447

JAPAN: Motorola Japan Ltd.; SPS, Technical Information Center, 3-20-1, Minami-Azabu. Minato-ku, Tokyo 106-8573 Japan. 81-3-3440-3569

ASIA/PACIFIC: Motorola Semiconductors H.K. Ltd.; Silicon Harbour Centre, 2 Dai King Street, Tai Po Industrial Estate, Tai Po, N.T., Hong Kong. 852–26668334

Technical Information Center: 1-800-521-6274

HOME PAGE: http://www.motorola.com/semiconductors/

