



## **ISOLATED RS-485 PROFIBUS TRANSCEIVER**

Check for Samples: ISO1176

#### **FEATURES**

- 4000-V<sub>PEAK</sub> Isolation, 560-V<sub>peak</sub> V<sub>IORM</sub>
  - UL 1577, IEC 60747-5-2 (VDE 0884, Rev. 2),
     IEC 61010-1, IEC 60950-1 and CSA
     Approved
- Bus-Pin ESD Protection
  - 16 kV HBM Between Bus Pins and GND2
  - 6 kV HBM Between Bus Pins and GND1
- Meets or Exceeds the Requirements of EN 50170 and TIA/EIA-485
- Signaling Rates up to 40 Mbps
- Differential Output Exceeds 2.1 V (54 Ω Load)

- Low Bus Capacitance 10 pF (MAX)
- 50 kV/μs Typical Transient Immunity
- Failsafe Receiver for Bus Open, Short, Idle
- 3.3-V Inputs are 5-V Tolerant

#### **APPLICATIONS**

- Profibus
- Factory Automation
- Networked Sensors
- Motor/Motion Control
- HVA and Building Automation Networks
- Networked Security Stations

#### **DESCRIPTION**

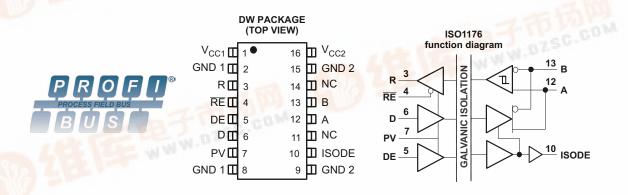
The ISO1176 is an isolated differential line transceiver designed for use in PROFIBUS applications. The device is ideal for long transmission lines since the ground loop is broken to provide for operation with a much larger common mode voltage range. The symmetrical isolation barrier of each device is tested to provide 2500 Vrms of isolation between the line transceiver and the logic level interface.

The galvanically isolated differential bus transceiver is an integrated circuit designed for bi-directional data communication on multipoint bus-transmission lines. The transceiver combines a galvanically isolated differential line driver and differential input line receiver. The driver has an active-high enable with isolated enable-state output on the ISODE pin (pin 10) to facilitate direction control. The driver differential outputs and the receiver differential inputs connect internally to form a differential input/output (I/O) bus port that is designed to offer minimum loading to the bus allowing up to 160 nodes.

The PV pin (pin 7) is provided as a full-chip enable option. All device outputs become high impedance when a logic low is applied to the PV pin. For more information, see the function tables in the device information section.

Any cabled I/O can be subjected to electrical noise transients from various sources. These noise transients can cause damage to the transceiver and/or near-by sensitive circuitry if they are of sufficient magnitude and duration. The ISO1176 can significantly reduce the risk of data corruption and damage to expensive control circuits

The device is characterized for operation over the ambient temperature range of -40°C to 85°C.





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These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

#### **ABSOLUTE MAXIMUM RATINGS**

over operating junction temperature range unless otherwise noted(1)

|  |                |                         |  |                  | VALUE     | UNIT |
|--|----------------|-------------------------|--|------------------|-----------|------|
| V <sub>CC1</sub> ,<br>V <sub>CC2</sub> | Supply voltage | e <sup>(2)</sup>        |  |                  | -0.5 to 7 | V    |
| Vo                                     | Voltage at any | bus I/O terminal        |  |                  | -9 to 14  | V    |
| VI                                     | Voltage input  | at any D, DE or RE      |  | -0.5 to 7        | V         |      |
| Io                                     | Receiver outp  |                         | ±10                                      | mA               |           |      |
|  |                | Human Body<br>Model     |  | Bus pins to GND1 | ±6        |      |
|  |                |                         | JEDEC Standard 22, Test Method A114-C.01 | Bus pins to GND2 | ±16       |      |
| ESD                                    | Electrostatic  | Wiodei                  |  | All pins         | ±4        | kV   |
| LOD                                    | discharge      | Charged Device<br>Model | JEDEC Standard 22, Test Method C101      | All pins         | ±1        |      |
|  |                | Machine model           | ANSI/ESDS5.2-1996                        | All pins         | ±200      | V    |
| TJ                                     | Maximum jund   |                         | 170                                      | °C               |           |      |

<sup>(1)</sup> Stresses beyond those listed under absolute maximum ratings may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under recommended operating conditions is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability. All voltage values are with respect to the network ground terminal unless otherwise noted.

#### RECOMMENDED OPERATING CONDITIONS

|                 |   |                     | MIN                  | TYP MAX              | UNIT     |
|-----------------|---|---------------------|----------------------|----------------------|----------|
| V               | Logic side supply voltage, V <sub>CC1</sub> (with | respect to GND1)    | 3.15                 | 5.5                  | <b>\</b> |
| V <sub>CC</sub> | Bus side supply voltage, V <sub>CC2</sub> (with   | respect to GND2)    | 4.75                 | 5.25                 | V        |
| $V_{CM}$        | Voltage at either bus I/O terminal                | A, B                | <b>-7</b>            | 12                   | ٧        |
| V               | Lligh level input voltage                         | PV, RE              | 2                    | V <sub>CC1</sub>     | <b>V</b> |
| $V_{IH}$        | High-level input voltage                          | D, DE               | 0.7 V <sub>CC1</sub> |                      | V        |
| V               | Law law diameter alta as                          | PV, RE              | 0                    | 0.8                  | <b>V</b> |
| V <sub>IL</sub> | Low-level input voltage                           | D, DE               |                      | 0.3 V <sub>CC1</sub> | V        |
| $V_{ID}$        | Differential input voltage                        | A with respect to B | -12                  | 12                   | V        |
|                 | Output ourroat                                    | Driver              | -70                  | 70                   | ^ ~      |
| IO              | Output current                                    | Receiver            | -8                   | 8                    | mA       |
|                 | Input pulse width                                 |                     | 10                   |                      | ns       |
| $T_{J}$         | Operating junction temperature                    |                     | -40                  | 150                  | °C       |

#### **SUPPLY CURRENT**

over recommended operating conditions (unless otherwise noted)

|                  | PARAMETER                       |                                 | TEST CONDITIONS                  | MIN | TYP | MAX | UNIT |
|------------------|---------------------------------|---------------------------------|----------------------------------|-----|-----|-----|------|
|                  |                                 |                                 | DE at 0 V                        |     | 4   | 6   |      |
|                  | 3 V                             | DE at V <sub>CC1</sub> , 2 Mbps |                                  | 5   |     | mA  |      |
|                  | Logic side RMS supply current   |                                 | DE at V <sub>CC1</sub> , 25 Mbps |     | 6   |     |      |
| I <sub>CC1</sub> | Logic side Kivio supply current |                                 | DE at 0 V                        |     | 7   | 10  |      |
|                  |                                 | 5.5 V                           | DE at V <sub>CC1</sub> , 2 Mbps  |     | 8   |     | mA   |
|                  |                                 |                                 | DE at V <sub>CC1</sub> , 25 Mbps |     | 11  |     |      |

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<sup>(2)</sup> All voltage values except differential I/O bus voltages are with respect to the referenced network ground terminal and are peak voltage values.



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#### **SUPPLY CURRENT (continued)**

over recommended operating conditions (unless otherwise noted)

| PARAMETER |  |        | TEST CONDITIONS                             | MIN | TYP | MAX | UNIT |
|-----------|--|--------|---|-----|-----|-----|------|
|           |  |        | DE at 0 V                                   |     | 15  | 18  |      |
| $I_{CC2}$ | I <sub>CC2</sub> Bus side RMS supply current | 5.25 V | DE at V <sub>CC1</sub> , 2 Mbps, 54 Ω load  |     | 70  |     | mA   |
|           |  |        | DE at V <sub>CC1</sub> , 25 Mbps, 54 Ω load |     | 75  |     |      |

#### ISODE-PIN ELECTRICAL CHARACTERISTICS

over recommended operating conditions (unless otherwise noted)

|                               | PARAMETER                  | TEST CONDITIONS          | MIN                    | TYP | MAX | UNIT |
|-------------------------------|----------------------------|--------------------------|------------------------|-----|-----|------|
| V <sub>OH</sub> High-level or | High level output valte as | $I_{OH} = -8 \text{ mA}$ | $V_{CC2} - 0.8$        | 4.6 |     | \/   |
|                               | High-level output voltage  | $I_{OH} = -20 \mu A$     | V <sub>CC2</sub> – 0.1 | 5   |     | V    |
| V                             | Love lovel output voltage  | I <sub>OL</sub> = 8 mA   |                        | 0.2 | 0.4 | \/   |
| V <sub>OL</sub>               | Low-level output voltage   | I <sub>OL</sub> = 20 μA  |                        | 0   | 0.1 | V    |

#### **DRIVER ELECTRICAL CHARACTERISTICS**

over recommended operating conditions (unless otherwise noted)

|                       | PARAMETER   | TEST (   | CONDITIONS                                 | MIN   | TYP      | MAX             | UNIT                |  |
|-----------------------|---|--|--|-------|----------|-----------------|---------------------|--|
| V <sub>OD</sub>       | Open-circuit differential output voltage                                | V <sub>A</sub> – V <sub>B</sub>  , Figure                                  | 1  | 1.5   |          | $V_{CC2}$       | V                   |  |
|                       | Ota a de la tata d'Alama d'al andre de la tata                          | See Figure 2 and   | Figure 6                                   | 2.1   |          |                 |                     |  |
| $ V_{OD(SS)} $        | Steady-state differential output voltage magnitude                      | Common-mode loading with V <sub>test</sub> from –7 V to 12 V, See Figure 3 |  | 2.1   |          |                 | V                   |  |
| ΔV <sub>OD(SS)</sub>  | Change in steady-state differential output voltage between logic states | $R_L = 54 \Omega$ , See F  | igure 4 andFigure 5                        | -0.2  |          | 0.2             | V                   |  |
| V <sub>OC(SS)</sub>   | Steady-state common-mode output voltage                                 |  |  | 2     |          | 3               |                     |  |
| $\Delta V_{OC(SS)}$   | Change in steady-state common-mode output voltage                       | $R_L = 54 \Omega$ , See Figure 4 and Figure 5                              |  | -0.2  |          | 0.2             | ٧                   |  |
| V <sub>OC(PP)</sub>   | Peak-to-peak common-mode output voltage                                 |  |  |       | 0.5      |                 |                     |  |
| V <sub>OD(RING)</sub> | Differential output voltage over and under shoot                        | See Figure 6 and Figure 10   |  |       |          | 10%             | V <sub>OD(pp)</sub> |  |
| V <sub>I(HYS)</sub>   | Input voltage hysteresis  | See Figure 7   |  |       | 150      |                 | mV                  |  |
|                       | land to summer to   | D, DE at 0 V or V <sub>CC1</sub>   |  | -10   |          | 10              | ^                   |  |
| I <sub>I</sub>        | Input current   | PV <sup>(1)</sup> at 0 V or V <sub>CC1</sub>                               |  |       |          | 120             | μΑ                  |  |
| I <sub>O(OFF)</sub>   | Output current with power off   | V <sub>CC</sub> ≤ 2.5 V  |  | See R | eceiver  | input           |                     |  |
| l <sub>OZ</sub>       | High impedance state output current                                     | DE at 0 V  |  | (     | current  | •               |                     |  |
| I <sub>OS(P)</sub>    | Peak short-circuit output current                                       |  | $V_{OS} = -7 \text{ V to } 12 \text{ V}$   | -250  |          | 250             |                     |  |
|                       | Charaki, akata akant aina ita autaut aumaat                             | DE at V <sub>CC</sub> , See Figure 8 and                                   | V <sub>OS</sub> = 12 V, D at<br>GND1       |       |          | 135             | mA                  |  |
| I <sub>OS(SS)</sub>   | Steady-state short-circuit output current                               | Figure 9   | $V_{OS} = -7 \text{ V, D at}$<br>$V_{CC1}$ | -135  |          |                 |                     |  |
| C <sub>OD</sub>       | Differential output capacitance   | ,  |  | See F | Receiver | C <sub>IN</sub> |                     |  |
| CMTI                  | Common-mode transient immunity  | See Figure 20  |  | 25    |          |                 | kV/μs               |  |

<sup>(1)</sup> The PV pin has a 50  $k\Omega$  pull-up resistor and leakage current depends on supply voltage.



#### **DRIVER SWITCHING CHARACTERISTICS**

over recommended operating conditions (unless otherwise noted)

|  | PARAMETER   |                                     | TEST CONDITIONS                 | MIN | TYP  | MAX | UNIT |
|--|---|-------------------------------------|---------------------------------|-----|------|-----|------|
| t <sub>pLH</sub> , t <sub>pHL</sub>  | Propagation delay time                                | V <sub>CC1</sub> at 5 V             |                                 |     |      | 35  | ns   |
| t <sub>sk(p)</sub>   | Pulse skew ( t <sub>p HL</sub> - t <sub>pLH</sub>  )  | V <sub>CC2</sub> at 5 V             |                                 |     | 2    | 5   | ns   |
| t <sub>pLH</sub> , t <sub>pHL</sub>  | Propagation delay time                                | V <sub>CC1</sub> at 3.3 V           | Can Figure 40                   |     |      | 40  | ns   |
| t <sub>sk(p)</sub>   | Pulse skew ( t <sub>p HL</sub> - t <sub>p LH</sub>  ) | V <sub>CC2</sub> at 5 V             |                                 |     | 2    | 5   | ns   |
| t <sub>r</sub>   | Differential output signal rise time                  |                                     |                                 | 2   | 3    | 7.5 | ns   |
| t <sub>f</sub>   | Differential output signal fall time                  | ut signal fall time                 |                                 | 2   | 3    | 7.5 | ns   |
| t <sub>pDE</sub>   | DE to ISODE prop delay                                |                                     | See Figure 14                   |     |      | 30  | ns   |
| t <sub>t(MLH)</sub> , t <sub>t(MHL)</sub>  | Output transition skew                                | Output transition skew              |                                 |     |      | 1   | ns   |
| $\begin{array}{l} t_{p(AZH)}, \ t_{p(BZH)} \\ t_{p(AZL)}, \ t_{p(BZL)} \end{array}$      | Propagation delay time, high-impedance                | -to-active output                   | $C_{L} = 50 \text{ pF},$        |     |      | 80  | ns   |
| $t_{p(AHZ)}, t_{p(BHZ)}$<br>$t_{p(ALZ)}, t_{p(BLZ)}$                                     | Propagation delay time, active-to- high-in            | mpedance output                     | RE at 0 V,<br>See Figure 12 and |     |      | 80  | ns   |
| $\begin{aligned} & t_{p(AZL)} - t_{p(BZH)}  \\ & t_{p(AZH)} - t_{p(BZL)}  \end{aligned}$ | ZH) Fnable skew time                                  |                                     | Figure 13                       |     | 0.55 | 1.5 | ns   |
| t <sub>(CFB)</sub>   | Time from application of short-circuit to             | current foldback                    | See Figure 9                    |     | 0.5  |     | μS   |
| t <sub>(TSD)</sub>   | Time from application of short-circuit to t           | T <sub>A</sub> = 25°C, See Figure 9 | 100                             |     |      | μS  |      |

#### RECEIVER ELECTRICAL CHARACTERISTICS

over recommended operating conditions (unless otherwise noted)

|  | PARAMET   | TER   | TEST  | CONDITIONS                                | MIN                   | TYP  | MAX        | UNIT |
|--|---|---|---|---|-----------------------|------|------------|------|
| V <sub>IT(+)</sub>                         | Positive-going differential i                               | input voltage threshold                           | SeeFigure 15  | I <sub>O</sub> = -8 mA                    |                       | -80  | -10        | mV   |
| V <sub>IT(-)</sub>                         | Negative-going differential                                 | input voltage threshold                           | Seerigure 15  | I <sub>O</sub> = 8 mA                     | -200                  | -120 |            | mV   |
| V <sub>hys</sub>                           | s Hysteresis voltage (V <sub>IT+</sub> – V <sub>IT-</sub> ) |   |   | •   |                       | 40   |            | mV   |
|  | I link lavel averes values                                  |   | V <sub>ID</sub> = 200 mV,   | I <sub>OH</sub> = -8 mA                   | V <sub>CC1</sub> -0.4 | 3    |            | V    |
| V <sub>OH</sub>                            | High-level output voltage                                   | V <sub>CC1</sub> at 3.3 V and V <sub>CC2</sub> at | See Figure 15   | I <sub>O H</sub> = -20 μA                 | V <sub>CC1</sub> -0.1 | 3.3  |            | V    |
| \/   | Laur laural autaut valtaga                                  | 5 V   | $V_{ID} = -200 \text{ mV},$   | I <sub>O L</sub> = 8 mA                   |                       | 0.2  | 0.4        | V    |
| $V_{OL}$                                   | Low-level output voltage                                    |   | See Figure 15   | I <sub>OL</sub> = 20 μA                   |                       | 0    | 0.1        | V    |
| \/   | High-level output voltage                                   |   | V <sub>ID</sub> = 200 mV,   | I <sub>OH</sub> = -8 mA                   | V <sub>CC1</sub> -0.8 | 4.6  | V          |      |
| V <sub>OH</sub>                            | OH Trigit-level output voltage                              | V <sub>CC1</sub> at 5 V and V <sub>CC2</sub> at 5 | See Figure 15   | I <sub>O H</sub> = -20 μA                 | V <sub>CC1</sub> -0.1 | 5    |            | V    |
| / Low lovel output volto                   | Laur laural autaut valtaga                                  | V   | $V_{ID} = -200 \text{ mV},$   | I <sub>O L</sub> = 8 mA                   |                       | 0.2  | 0.4<br>0.1 |      |
| V <sub>OL</sub>                            | Low-level output voltage                                    |   |   | I <sub>OL</sub> = -20 μA                  |                       | 0    |            | V    |
| I <sub>A</sub> , I <sub>B</sub>            |   | •   | V 7.V or 12.V   | V <sub>CC</sub> = 4.75 V or 5.25 V        |                       |      |            |      |
| I <sub>A(OFF)</sub><br>I <sub>B(OFF)</sub> | Bus pin input current                                       |   | $V_1 = -7 \text{ V or } 12 \text{ V},$<br>Other input = 0 V                 | V <sub>CC2</sub> = 0 V                    | -160                  |      | 200        | μА   |
| l <sub>l</sub>                             | Receiver enable input curr                                  | ent   | RE = 0 V  | ·   | -50                   |      | 50         | μА   |
| l <sub>oz</sub>                            | High-impedance state outp                                   | out current                                       | RE = V <sub>CC1</sub>   |   | -1                    |      | 1          | μА   |
| R <sub>ID</sub>                            | Differential input resistance                               | е   | A, B  |   | 48                    |      |            | kΩ   |
| C <sub>ID</sub>                            | Differential input capacitar                                | nce   | Test input signal is a 1 V <sub>pp</sub> amplitude , C <sub>D</sub> A and B | 1.5 MHz sine wave with is measured across |                       | 7    | 10         | pF   |
| C <sub>MR</sub>                            | Common mode rejection                                       |   | See Figure 19   |   |                       | 4    |            | V    |

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#### RECEIVER SWITCHING CHARACTERISTICS

over recommended operating conditions (unless otherwise noted)

|                                     | PARAMETER                              |  | TEST CONDITIONS          | MIN TYP | MAX | UNIT |
|-------------------------------------|--|--|--------------------------|---------|-----|------|
| t <sub>pLH</sub> , t <sub>pHL</sub> | Propagation delay time                 | \/   |                          |         | 50  | 20   |
| t <sub>sk(p)</sub>                  | Pulse skew ( $ t_{p HL} - t_{pLH} $ )  | V <sub>CC1</sub> at 5 V, V <sub>CC2</sub> at 5 V   |                          | 2       | 5   | ns   |
| $t_{pLH}, t_{pHL}$                  | Propagation delay time                 | V at 2.2 V V at 5.V                                | Coo Figure 46            |         | 55  | 20   |
| t <sub>sk(p)</sub>                  | Pulse skew ( $ t_{p HL} - t_{p LH} $ ) | V <sub>CC1</sub> at 3.3 V, V <sub>CC2</sub> at 5 V | See Figure 16            | 2       | 5   | ns   |
| t <sub>r</sub>                      | Output signal rise time                |  | 2                        | 4       | 20  |      |
| t <sub>f</sub>                      | Output signal fall time                |  |                          | 2       | 4   | ns   |
| t <sub>pZH</sub>                    | Propagation delay time, high-im        | pedance-to-high-level output                       | DE at V <sub>CC1</sub> , | 13      | 25  | 20   |
| t <sub>pHZ</sub>                    | Propagation delay time, high-lev       | See Figure 17                                      | 13                       | 25      | ns  |      |
| t <sub>pZL</sub>                    | Propagation delay time, high-im        | DE at V <sub>CC</sub> ,                            | 13                       | 25      | 20  |      |
| $t_{pLZ}$                           | Propagation delay time, low-lev        | el-to-high-impedance output                        | See Figure 18            | 13      | 25  | ns   |

#### PARAMETER MEASUREMENT INFORMATION

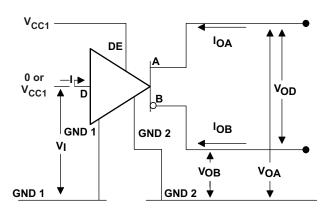


Figure 1. Open Circuit Voltage Test Circuit

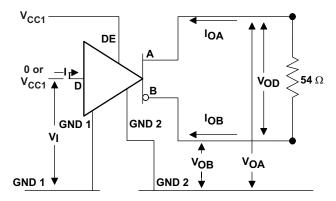


Figure 2.  $V_{\rm OD}$  Test Circuit



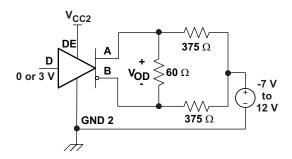


Figure 3. Driver  $V_{\text{OD}}$  with Common-mode Loading Test Circuit

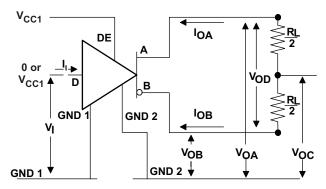


Figure 4. Driver  $V_{\text{OD}}$  and  $V_{\text{OC}}$  Without Common-Mode Loading Test Circuit

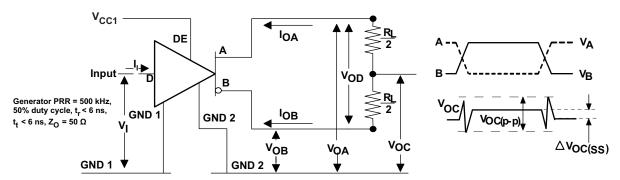


Figure 5. Steady-State Output Voltage Test Circuit and Voltage Waveforms



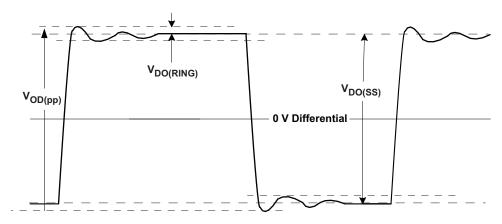


Figure 6.  $V_{\text{OD(RING)}}$  Waveform and Definitions

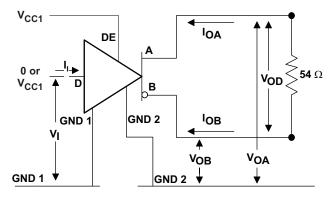


Figure 7. Input Voltage Hysteresis Test Circuit

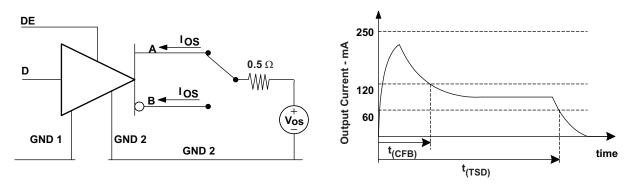


Figure 8. Driver Short-Circuit Test Circuit and Waveforms (Short Circuit applied at Time t=0)



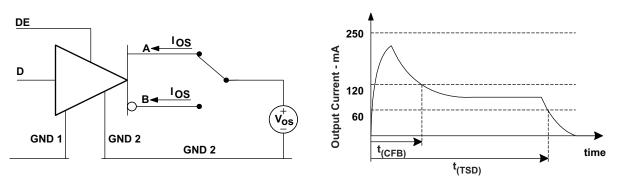


Figure 9. I<sub>OS(SS)</sub> Steady State Short Circuit Output Current Test Circuit

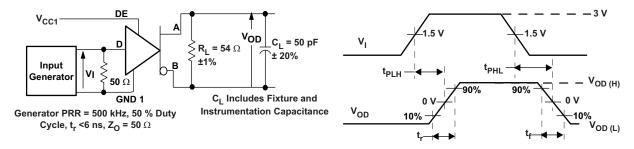


Figure 10. Driver Switching Test Circuit and Waveforms

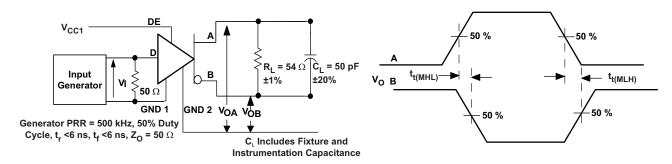


Figure 11. Driver Output Transition Skew Test Circuit and Waveforms

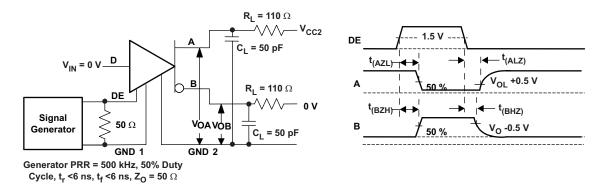


Figure 12. Driver Enable/Disable Test, D at Logic Low Test Circuit and Waveforms



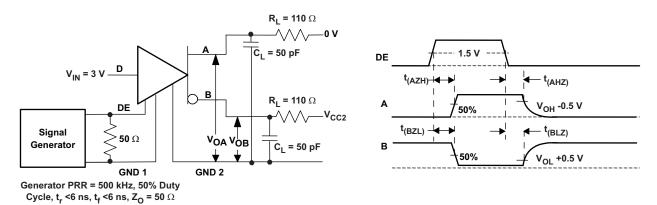


Figure 13. Driver Enable/Disable Test, D at Logic High Test Circuit and Waveforms

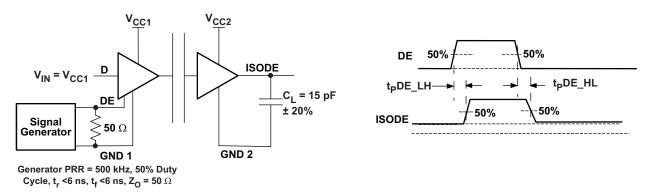


Figure 14. DE to ISODE Prop Delay Test Circuit and Waveforms

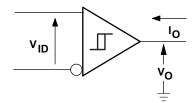


Figure 15. Receiver DC Parameter Definitions

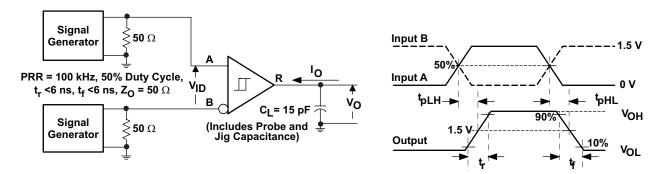


Figure 16. Receiver Switching Test Circuit and Waveforms



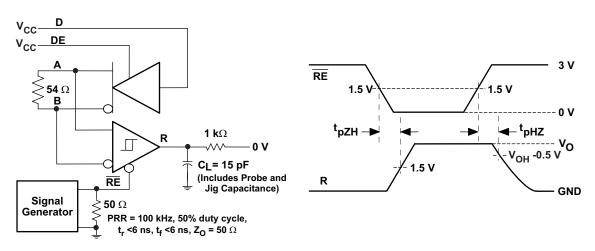


Figure 17. Receiver Enable Test Circuit and Waveforms, Data Output High

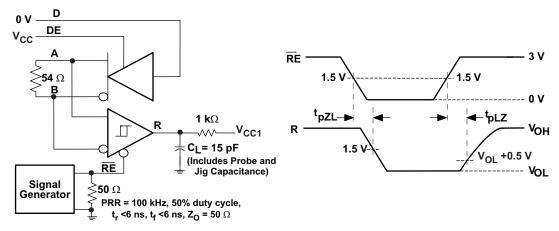


Figure 18. Receiver Enable Test Circuit and Waveforms, Data Output Low

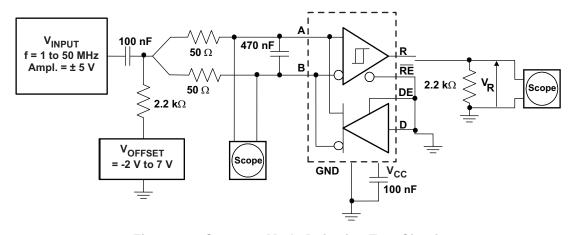


Figure 19. Common-Mode Rejection Test Circuit



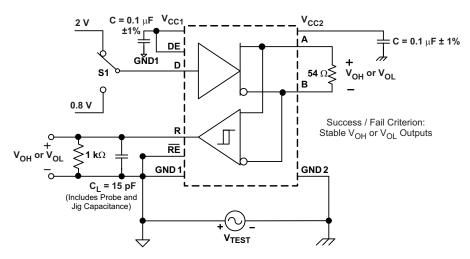


Figure 20. Common-Mode Transient Immunity Test Circuit



#### TYPICAL CHARACTERISTICS

### **DIFFERENTIAL OUTPUT VOLTAGE**

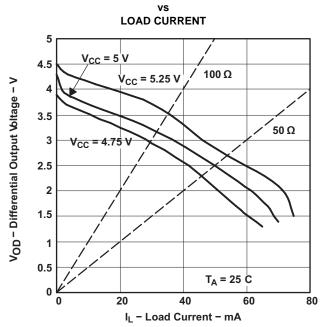
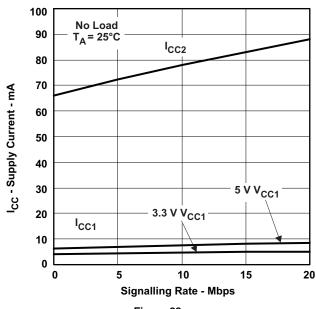


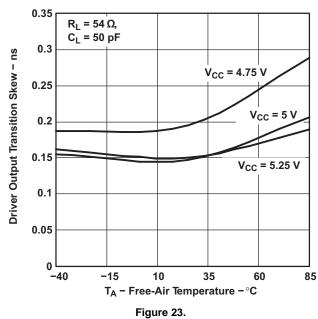
Figure 21.

# RMS SUPPLY CURRENT vs SIGNALING RATE

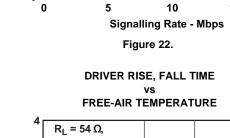


DRIVER OUTPUT TRANSITION SKEW





\_\_\_\_\_vs



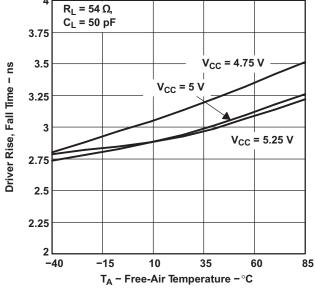
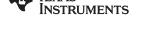
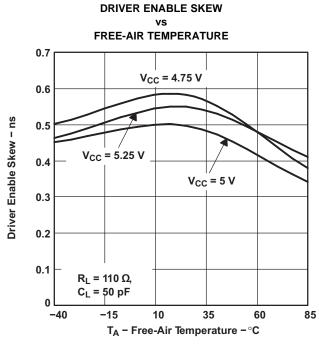


Figure 24.



## **TYPICAL CHARACTERISTICS (continued)**



HIGH-LEVEL OUTPUT VOLTAGE

VS

HIGH-LEVEL OUTPUT CURRENT

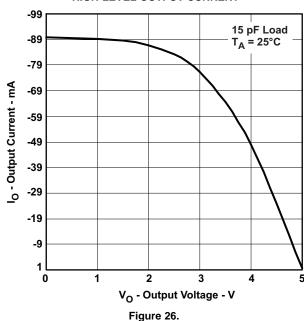
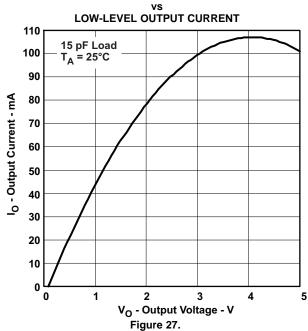


Figure 25.

LOW-LEVEL OUTPUT VOLTAGE





#### **DEVICE INFORMATION**

#### DW PACKAGE (TOP VIEW) V<sub>CC1</sub> **I** 1 ● 16 U V<sub>CC2</sub> GND 1 1 2 15 **II** GND 2 R**Ⅲ** 3 14 III NC RE II 4 13 🗖 B 12 🔟 A DE II 5 D**Ⅲ** 6 11 I NC PV **□** 7 10 III ISODE 9 🔟 GND 2 GND 1 **1** 8

## **PACKAGE PIN FUNCTION DESCRIPTION**

| NAME  | PIN NO. | FUNCTION   |
|-------|---------|--|
| Vcc1  | 1       | logic side power supply  |
| GND1  | 2, 8    | logic side ground, internally connected  |
| R     | 3       | receiver output  |
| RE    | 4       | receiver logic-low enable  |
| DE    | 5       | driver logic-high enable input   |
| D     | 6       | driver input   |
| PV    | 7       | ISO1176 chip enable, logic high applied immediately after power-up for device operation. A logic low 3-states all outputs. |
| GND2  | 9, 15   | bus side ground, internally connected  |
| ISODE | 10      | bus-side driver enable output  |
| nc    | 11, 14  | not connected internally, may be left floating   |
| Α     | 12      | non-inverting bus output   |
| В     | 13      | inverting bus output   |
| Vcc2  | 16      | bus side power supply  |

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## **DRIVER FUNCTION TABLE**

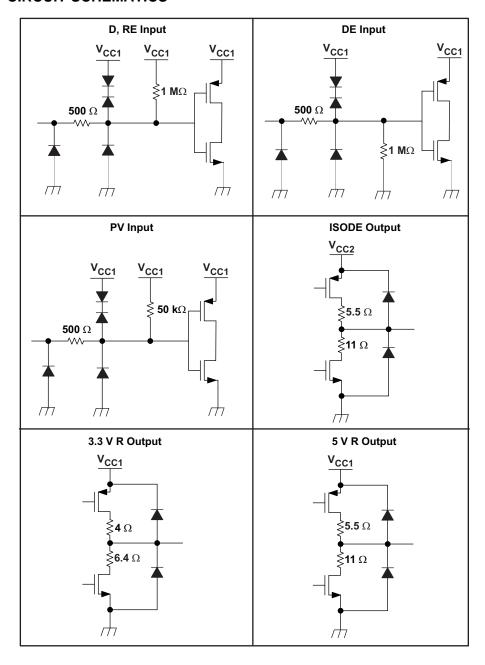
| V <sub>CC1</sub> | V <sub>CC2</sub> | POWER             | INPUT           | ENABLE        | ENABLE               | OUTI | PUTS |
|------------------|------------------|-------------------|-----------------|---------------|----------------------|------|------|
|                  |                  | (PV)<br>(ISO1176) | (D)             | INPUT<br>(DE) | OUTPUT<br>(ISODE)    | Α    | В    |
| PU               | PU               | H or open         | Н               | Н             | Н                    | Н    | L    |
| PU               | PU               | H or open         | L               | Н             | Н                    | L    | Н    |
| PU               | PU               | H or open         | Χ               | L             | L                    | Z    | Z    |
| PU               | PU               | H or open         | Χ               | open          | L                    | Z    | Z    |
| PU               | PU               | H or open         | open            | Н             | Н                    | Н    | L    |
| PD               | PU               | X                 | Χ               | Х             | L                    | Z    | Z    |
| PU               | PD               | X                 | Χ               | Х             | L                    | Z    | Z    |
| PD               | PD               | Х                 | Χ               | Х             | L                    | Z    | Z    |
| X                | Х                | L                 | Χ               | Х             | L                    | Z    | Z    |
| H = high lev     | el, L= low leve  | el, X = don't ca  | are, Z = high i | mpedance (of  | ff), ? = indetermina | te   | •    |

## **RECEIVER FUNCTION TABLE**

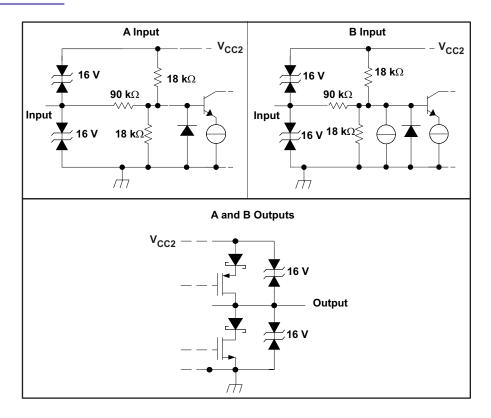
| V <sub>CC1</sub>   | V <sub>CC2</sub>   | POWER VALID<br>(PV) (ISO1176) | DIFFERENTIAL INPUT V <sub>ID</sub> = (V <sub>A</sub> - V <sub>B</sub> ) | ENABLE<br>(RE) | OUTPUT<br>®) |
|--------------------|--------------------|-------------------------------|---|----------------|--------------|
| PU                 | PU                 | H or open                     | -0.01 V ≤ V <sub>ID</sub>   | L              | Н            |
| PU                 | PU                 | H or open                     | -0.2 V < V <sub>ID</sub> < -0.01 V                                      | L              | ?            |
| PU                 | PU                 | H or open                     | V <sub>ID</sub> ≤ -0.2 V  | L              | L            |
| PU                 | PU                 | H or open                     | X   | Н              | Z            |
| PU                 | PU                 | H or open                     | X   | open           | Z            |
| PU                 | PU                 | H or open                     | Open circuit  | L              | Н            |
| PU                 | PU                 | H or open                     | Short Circuit   | L              | Н            |
| PU                 | PU                 | H or open                     | Idle (terminated) bus   | L              | Н            |
| PD                 | PU                 | X                             | X   | Х              | Z            |
| PU                 | PD                 | H or open                     | X   | L              | Н            |
| PD                 | PD                 | X                             | X   | Х              | Z            |
| Х                  | Х                  | L                             | X   | Х              | Z            |
| H = high level, L= | low level, X = dor | n't care, Z = high impedance  | e (off), ? = indeterminate  |                |              |



## **EQUIVALENT CIRCUIT SCHEMATICS**







#### **IEC SAFETY LIMITING VALUES**

Safety limiting intends to prevent potential damage to the isolation barrier upon failure of input or output circuitry. A Failure of the IO can allow low resistance to ground or the supply and, without current limiting, dissipate sufficient power to overheat the die and damage the isolation barrier potentially leading to secondary system failures.

|                | PARAMETER                               | TEST CONDITIONS |  |  | TYP | MAX | UNIT |
|----------------|---|-----------------|--|--|-----|-----|------|
| Is             | Safety input, output, or supply current | DW-16           | $\theta_{JA} = 212$ °C/W, $V_I = 5.5$ V, $T_J = 170$ °C, $T_A = 25$ °C |  |     | 128 | mA   |
| T <sub>S</sub> | Maximum case temperature                | DW-16           |  |  |     | 150 | °C   |

The safety-limiting constraint is the absolute maximum junction temperature specified in the absolute maximum ratings table. The power dissipation and junction-to-air thermal impedance of the device installed in the application hardware determines the junction temperature. The assumed junction-to-air thermal resistance in the Thermal Characteristics table is that of a device installed in the JESD51-3, Low Effective Thermal Conductivity Test Board for Leaded Surface Mount Packages and is conservative. The power is the recommended maximum input voltage times the current. The junction temperature is then the ambient temperature plus the power times the junction-to-air thermal resistance.



#### THERMAL CHARACTERISTICS

over recommended operating conditions (unless otherwise noted)

|                      | PARAMETER                            | TEST CONDITIONS  | MIN | TYP  | MAX | UNIT   |
|----------------------|--------------------------------------|--|-----|------|-----|--------|
| $\theta_{JA}$        | Junction-to-air                      | Low-K thermal resistance <sup>(1)</sup>  |     | 168  |     | 90 444 |
|                      |                                      | High-K board <sup>(1)</sup>  |     | 96.1 |     | °C/W   |
| $\theta_{JB}$        | Junction-to-board thermal resistance |  |     | 61   |     | °C/W   |
| $\theta_{\text{JC}}$ | Junction-to-case thermal resistance  |  |     | 48   |     | °C/W   |
| $P_D$                | Device power dissipation             | $V_{CC1} = V_{CC2} = 5.25 \text{ V}, T_J = 150^{\circ}\text{C}, C_L = 15 \text{ pF},$<br>Input a 20 MHz 50% duty cycle square wave |     |      | 220 | mW     |

(1) Tested in accordance with the Low-K or High-K thermal metric definitions of EIA/JESD51-3 for leaded surface mount packages.

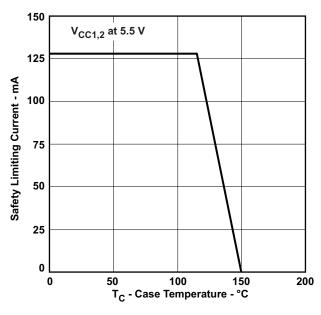


Figure 28. DW-16  $\theta_{\text{JC}}$  Thermal Derating Curve per IEC 60747-5-2

#### PACKAGE CHARACTERISTICS

over operating free-air temperature range (unless otherwise noted)

|                 | PARAMETER   | TEST CONDITIONS   | MIN   | TYP               | MAX | UNIT |
|-----------------|---|---|-------|-------------------|-----|------|
| L(I01)          | Minimum air gap (Clearance)                         | Shortest terminal to terminal distance through air  | 8.34  |                   |     | mm   |
| L(102)          | Minimum external tracking (Creepage) <sup>(1)</sup> | Shortest terminal to terminal distance across the package surface   | 8.1   |                   |     | mm   |
| CTI             | Tracking resistance (Comparative Tracking Index)    | DIN IEC 60112 / VDE 0303 Part 1   | ≥175  |                   |     | V    |
|                 | Minimum Internal Gap (Internal Clearance)           | Distance through the insulation   | 0.008 |                   |     | mm   |
| R <sub>IO</sub> | Isolation resistance                                | Input to output, V <sub>IO</sub> = 500 V, all pins on each side of the barrier tied together creating a two-terminal device |       | >10 <sup>12</sup> |     | Ω    |
| C <sub>IO</sub> | Barrier capacitance Input to output                 | V <sub>I</sub> = 0.4 sin (4E6πt)  |       | 2                 |     | pF   |
| Cı              | Input capacitance to ground                         | $V_1 = 0.4 \sin (4E6\pi t)$   |       | 2                 |     | pF   |

<sup>(1)</sup> Creepage and clearance requirements should be applied according to the specific equipment isolation standards of an application. Care should be taken to maintain the creepage and clearance distance of a board design to ensure that the mounting pads of the isolator on the printed circuit board do not reduce this distance.

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Creepage and clearance on a printed circuit board become equal according to the measurement techniques shown in the Isolation Glossary. Techniques such as inserting grooves and/or ribs on a printed circuit board are used to help increase these specifications.

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#### **REGULATORY INFORMATION**

| VDE                                  | CSA  | UL   |
|--------------------------------------|--|--|
| Certified according to IEC 60747-5-2 | Approved under CSA Component Acceptance Notice | Recognized under 1577<br>Component Recognition<br>Program <sup>(1)</sup> |
| File Number: 40014131                | File Number: 1698195                           | File Number: E181974   |

<sup>(1)</sup> Production tested ≥ 3000 Vrms for 1 second in accordance with UL 1577.

#### **IEC 60554-1 RATINGS TABLE**

| PARAMETER                   | TEST CONDITIONS                | SPECIFICATION |
|-----------------------------|--------------------------------|---------------|
| Basic isolation group       | Material group                 | IIIa          |
|                             | Rated mains voltage < 150 VRMS | I-IV          |
| Installation classification | Rated mains voltage < 300 VRMS | I-III         |
|                             | Rated mains voltage < 400 VRMS | I-II          |

#### **IEC 60747-5-2 INSULATION CHARACTERISTICS**

over recommended operating conditions (unless otherwise noted)

|                | PARAMETER                          | SPECIFICATION  | UNIT             |   |
|----------------|------------------------------------|--|------------------|---|
| $V_{IORM}$     | Maximum working insulation voltage |  | 560              | V |
| $V_{PR}$       | Input to output test voltage       | Method b1, V <sub>PR</sub> = V <sub>IORM</sub> × 1.875, 100% Production test with t = 1 s, Partial discharge <5 pC | 1050             | V |
| $V_{IOTM}$     | Transient overvoltage              | t = 60 s   | 4000             | V |
| R <sub>S</sub> | Insulation resistance              | $V_{IO}$ = 500 V at $T_S$  | >10 <sup>9</sup> | Ω |
|                | Pollution degree                   |  | 2                |   |



#### APPLICATION INFORMATION

#### **Transient Voltages**

Isolating of a circuit insulates it from other circuits and earth, so that noise voltage develops across the insulation rather than circuit components. The most common noise threat to data-line circuits is voltage surges or electrical fast transients that occur after installation. The transient ratings of the ISO1176 standard are sufficient for all but the most severe installations. However, some equipment manufacturers use ESD generators to test equipment transient susceptibility. This practice can exceed insulation ratings. ESD generators simulate static discharges that may occur during device or equipment handling with low-energy but high-voltage transients.

Figure 29 models the ISO1176 bus IO connected to a noise generator.  $C_{IN}$  and  $R_{IN}$  is the device, and any other stray or added capacitance or resistance across the A or B pin to GND2.  $C_{ISO}$  and  $R_{ISO}$  is the capacitance and resistance between GND1 and GND2 of the ISO1176, plus those of any other insulation (transformer, etc.). Stray inductance is assumed to be negligible.

From this model, the voltage at the isolated bus return is

$$v_{GND2} = v_N \frac{Z_{ISO}}{Z_{ISO} + Z_{IN}}$$
 (1)

and is always less than 16 V from  $V_N$ . If the ISO1176 is tested as a stand-alone device,

- $R_{IN} = 6 \times 10^4 \Omega$ ,
- $C_{IN}$ = 16 x 10<sup>-12</sup> F,
- $R_{ISO} = 10^9 \Omega$  and
- $C_{ISO} = 10^{-12} \text{ F.}$

Notice from Figure 29 that the resistor ratio determines the voltage ratio at low frequencies, and that the inverse capacitance ratio determines the voltage ration at high frequencies. In the stand-alone case and for low frequencies,

$$\frac{v_{GND2}}{v_N} = \frac{R_{ISO}}{R_{ISO} + R_{IN}} = \frac{10^9}{10^9 + 6x10^4}$$
 (2)

or essentially all of the noise appears across the barrier.

At high frequencies,

$$\frac{v_{GND2}}{v_N} = \frac{\frac{1}{C_{ISO}}}{\frac{1}{C_{ISO}} + \frac{1}{C_{IN}}} = \frac{1}{1 + \frac{C_{ISO}}{C_{IN}}} = \frac{1}{1 + \frac{1}{16}} = 0.94$$

and 94% of  $V_N$  appears across the barrier. As long as  $R_{\rm ISO}$  is greater than  $R_{\rm IN}$  and  $C_{\rm ISO}$  is less than  $C_{\rm IN}$ , most of the transient noise appears across the isolation barrier, as it should.

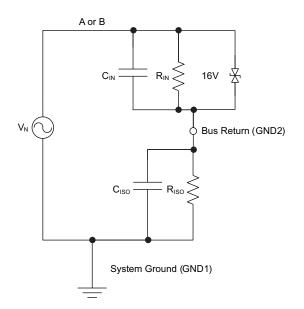


Figure 29. Device Model For Static Discharge Testing

Using ESD generators to test equipment transient susceptibility, or considering product claims of ESD ratings above the barrier transient ratings of an isolated interface is not recommended. ESD is best managed through recessing or covering connector pins in a conductive connector shell, and by proper installer training.

20

#### ISO1176 "Sticky Bit" Issue (Under Certain Conditions)

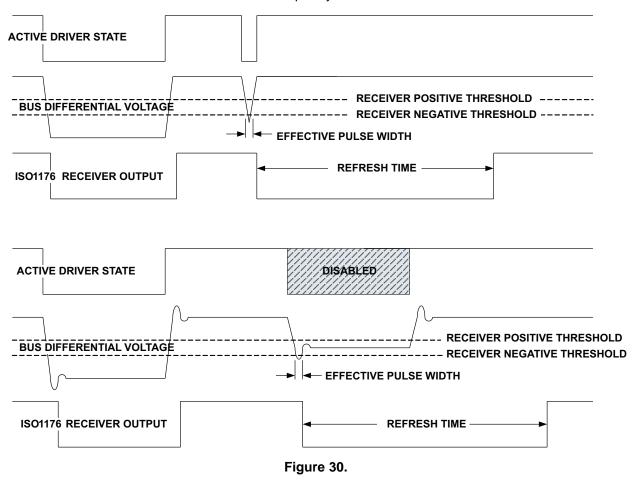
Summary: In applications with sufficient differential noise on the bus, the output of the ISO1176 receiver may "stick" at an incorrect state for up to 30 μs.

Description: The ISO1176 isolated Profibus (RS-485) transceiver is rated for signaling up to 40 Mbps on twisted-pair bus lines. The receiver thresholds comply with RS-485 and Profibus specifications; an input differential voltage  $V_{ID} = V_A - V_B > 200$  mV causes a logic High on the R output, and  $V_{ID} < -200$  mV causes a logic Low on the R output. To assure a known receiver output when the bus is shorted or idle, the upper threshold is set below zero, such that  $V_{ID} = 0$  mV causes a logic High on the R output. The data sheet specifies a typical upper threshold ( $V_{IT-}$ ) of -80 mV and a typical lower threshold ( $V_{IT-}$ ) of -120 mV.

At a signaling rate of 40 Mbps, each valid data bit has a duration of 25 ns. At typical Profibus signaling rates of 12 Mbps or lower, each valid data bit has a duration of 83 ns or more. The ISO1176 correctly sets the R output for each of these valid data bits.

In applications with a high degree of differential noise on the bus lines, it is possible to get short periods when an invalid bus voltage triggers a change in state of the internal receiver circuits. An issue with the digital isolation channel in the ISO1176 may cause the invalid receiver state to "stick" rather than immediately transition back to the correct state. The receiver output will always transition to the correct state, but may stick in the incorrect state for up to  $30~\mu s$ . This can cause a temporary loss of data.

Figure 30 shows two cases which could result in temporary loss of data.





#### **REVISION HISTORY**

| Changes from Original (March 2008) to Revision A   | Page |
|--|------|
| Added the Bus-Pin ESD Protection bullet and sub bullets to the Features List   | 1    |
| Added 3.3-V Inputs are 5-V Tolerant to the Features List   | 1    |
| Added Bus pins to GND1 and Bus pins to GND2 to the ESD information of the Abs Max R  |      |
| Added the APPLICATION INFORMATION section  | _    |
| Changes from Revision A (May 2008) to Revision B   | Page |
| Changed L(IO1), Minimum air gap (Clearance) in the PACKAGE CHARACTERISTICS tab To: 8.34mm.   |      |
| Changes from Revision B (June 2008) to Revision C  | Page |
| Changed the text in the second paragraph of the DESCRIPTON From: whenever the drive To: allowing up to 160 nodes.  |      |
|  | Page |
| Changes from Revision C (October 2008) to Revision D   |      |
| Added 560-Vpeak V <sub>IORM</sub> to the first Features List   | 1    |
| Added 560-Vpeak V <sub>IORM</sub> to the first Features List   |      |
| <ul> <li>Added 560-Vpeak V<sub>IORM</sub> to the first Features List</li> <li>Added UL 1577, IEC 60747-5-2 (VDE 0884, Rev. 2), to the Features List</li> </ul> | 1    |
| <ul> <li>Added 560-Vpeak V<sub>IORM</sub> to the first Features List</li> <li>Added UL 1577, IEC 60747-5-2 (VDE 0884, Rev. 2), to the Features List</li> </ul> |      |





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20-Feb-2010

#### **PACKAGING INFORMATION**

| Orderable Device | Status <sup>(1)</sup> | Package<br>Type | Package<br>Drawing | Pins | Package<br>Qty | e Eco Plan <sup>(2)</sup> | Lead/Ball Finish | MSL Peak Temp <sup>(3)</sup> |
|------------------|-----------------------|-----------------|--------------------|------|----------------|---------------------------|------------------|------------------------------|
| ISO1176DW        | ACTIVE                | SOIC            | DW                 | 16   | 40             | Green (RoHS & no Sb/Br)   | Call TI          | Level-2-260C-1 YEAR          |
| ISO1176DWG4      | ACTIVE                | SOIC            | DW                 | 16   | 40             | Green (RoHS & no Sb/Br)   | Call TI          | Level-2-260C-1 YEAR          |
| ISO1176DWR       | ACTIVE                | SOIC            | DW                 | 16   | 2000           | Green (RoHS & no Sb/Br)   | Call TI          | Level-2-260C-1 YEAR          |
| ISO1176DWRG4     | ACTIVE                | SOIC            | DW                 | 16   | 2000           | Green (RoHS & no Sb/Br)   | Call TI          | Level-2-260C-1 YEAR          |

<sup>(1)</sup> The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined.

**Pb-Free** (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

**Pb-Free (RoHS Exempt):** This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

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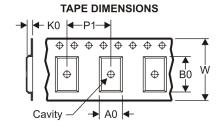


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10-Sep-2009

## TAPE AND REEL INFORMATION





| A0 | Dimension designed to accommodate the component width     |
|----|---|
| B0 | Dimension designed to accommodate the component length    |
| K0 | Dimension designed to accommodate the component thickness |
| W  | Overall width of the carrier tape                         |
| P1 | Pitch between successive cavity centers                   |

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE

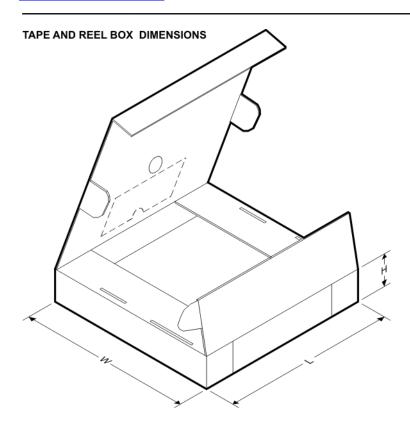


#### \*All dimensions are nominal

| Device     | Package<br>Type | Package<br>Drawing |    |      | Reel<br>Diameter<br>(mm) | Reel<br>Width<br>W1 (mm) | A0<br>(mm) | B0<br>(mm) | K0<br>(mm) | P1<br>(mm) | W<br>(mm) | Pin1<br>Quadrant |
|------------|-----------------|--------------------|----|------|--------------------------|--------------------------|------------|------------|------------|------------|-----------|------------------|
| ISO1176DWR | SOIC            | DW                 | 16 | 2000 | 330.0                    | 16.4                     | 10.75      | 10.7       | 2.7        | 12.0       | 16.0      | Q1               |

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10-Sep-2009

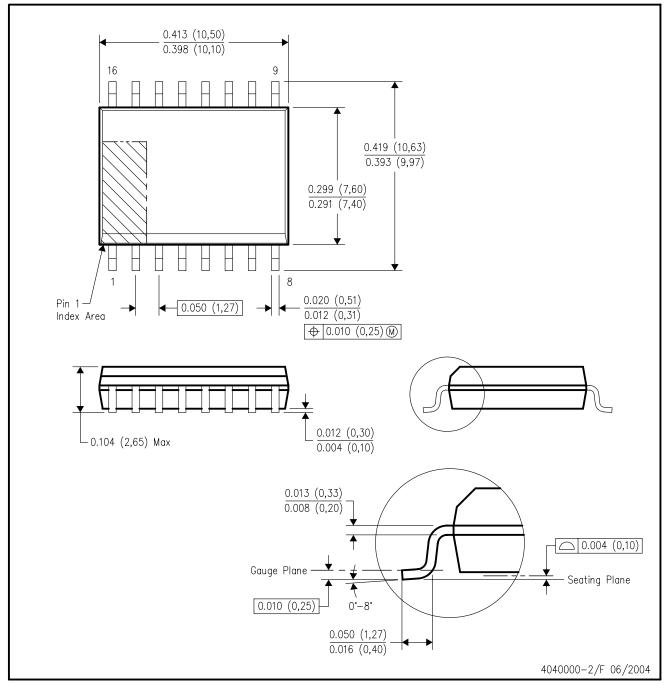


#### \*All dimensions are nominal

| ĺ | Device     | Package Type | Package Drawing | Pins | SPQ  | Length (mm) | Width (mm) | Height (mm) |
|---|------------|--------------|-----------------|------|------|-------------|------------|-------------|
|   | ISO1176DWR | SOIC         | DW              | 16   | 2000 | 358.0       | 335.0      | 35.0        |

## DW (R-PDSO-G16)

## PLASTIC SMALL-OUTLINE PACKAGE

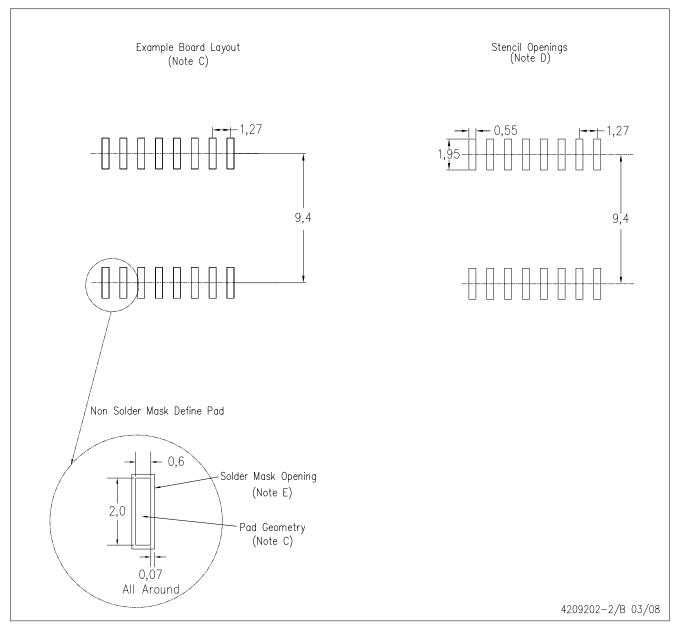


NOTES: /

- A. All linear dimensions are in inches (millimeters).
- B. This drawing is subject to change without notice.
- C. Body dimensions do not include mold flash or protrusion not to exceed 0.006 (0,15).
- D. Falls within JEDEC MS-013 variation AA.



# DW (R-PDSO-G16)



NOTES:

- A. All linear dimensions are in millimeters.
- B. This drawing is subject to change without notice.
- C. Refer to IPC7351 for alternate board design.
- D. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC—7525
- E. Customers should contact their board fabrication site for solder mask tolerances between and around signal pads.



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