

## General Description

The MIC2550 is a single-chip transceiver that complies with the physical layer specifications for Universal Serial Bus (USB).

The MIC2550 supports full-speed (12Mb/s) dual supply voltage operation (patent pending) and low-speed (1.5Mb/s) operation.

A unique dual supply voltage operation allows the MIC2550 to reference the system I/F I/O signals to a supply voltage down to 2.5V while independently powered by the USB  $V_{BUS}$ . This allows the system interface to operate at its core voltage without addition of buffering logic and also reduce system operating current.

## Features

- Compliant to *USB Specification Revision 1.1*
- Operation down to 2.5V
- Dual supply voltage operation
- Supports full-speed (12Mb/s) and low-speed (1.5Mb/s) operation
- Speed-select termination supply
- Very low power consumption meets USB suspend-current requirements
- Small 14-pin TSSOP

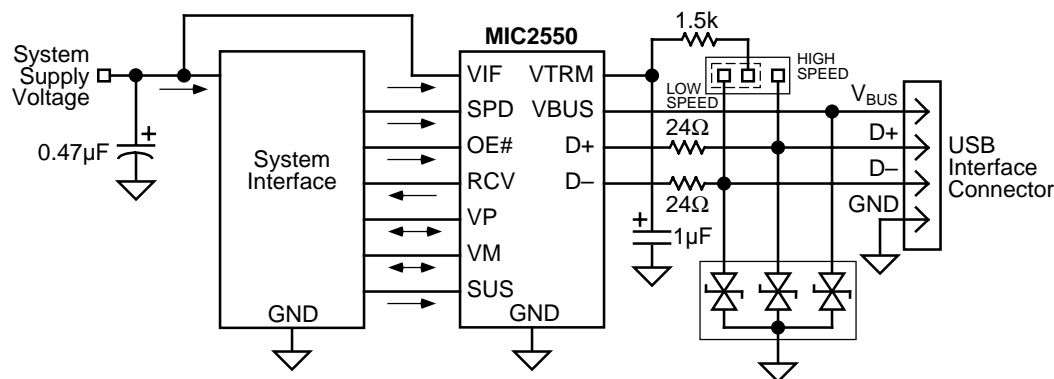
## Applications

- Personal digital assistants (PDA)
- Palmtop computers
- Cellular telephones

## Ordering Information

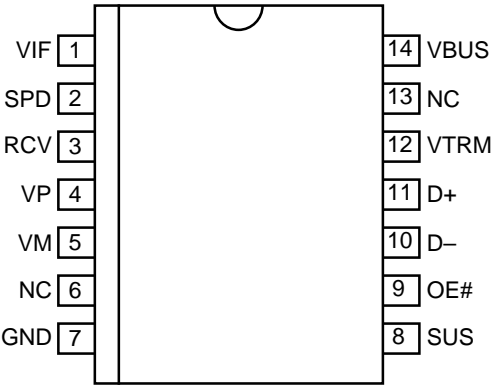
Part Number	Junction Temp. Range	Package
MIC2550BTS	-40°C to +85°C	14-Pin TSSOP

## System Diagram



Pin Configuration

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14-Pin TSSOP (TM)

Pin Description

Pin Number	Pin Name	Pin Function
1	VIF	System Interface Supply Voltage (Input): Determines logic voltage levels for system interface signaling to logic controller.
2	SPD	Speed (Input): Edge rate control. Logic high selects full-speed edge rates. Logic low selects low-speed edge rates.
3	RCV	Receive Data (Output): System interface receive data interface to logic controller.
4	VP	Plus (Input/Output): System interface signal to logic controller. If OE# is logic 1, VP is a receiver output (+); If OE# is logic 0, VP is a driver input (+).
5	VM	Minus (Input/Output): System interface signal to logic controller. If OE# is logic 1, VM is a receiver output (-); If OE# is logic 0, VM is a driver input (-).
6, 13	NC	not internally connected
7	GND	Ground: Power supply return and signal reference.
8	SUS	Suspend (Input): Logic high turns off internal circuits to reduce supply current.
9	OE#	Output Enable (Input): Active-low system interface input signal from from logic controller. Logic low causes transceiver to transmit data onto the bus. Logic high causes the transceiver to receive data from the bus.
10	D-	USB Differential Data Line - (Input/Output)
11	D+	USB Differential Data Line + (Input/Output)
12	VTRM	Termination Supply (Output): 3.3V speed termination resistor supply output.
14	VBUS	USB Supply Voltage (Input): Transceiver supply.

**Absolute Maximum Ratings (Note 1)**

Supply Voltage ( $V_{CC}$ )	+6.5V
Input Voltage ( $V_{BUS}$ )	-0.5V(min)/5.5V(max)
Output Current ( $I_{D+}$ , $I_{D-}$ )	$\pm 50$ mA
Output Current (all others)	$\pm 15$ mA
Input Current	$\pm 50$ mA
Power Dissipation ( $P_D$ )	TBD
Storage Temperature ( $T_S$ )	-65° to +150°C

ESD, **Note 3****Operating Ratings (Note 2)**

Supply Voltage ( $V_{BUS}$ )	4.0V to 5.25V
Temperature Range ( $T_A$ )	-40°C to +85°C
Junction Temperature ( $T_J$ )	160°C
Package Thermal Resistance	
TSSOP ( $\theta_{JA}$ )	100°C/W

**Electrical Characteristics**

$T_A = 25^\circ\text{C}$ , **bold** values indicate  $-40^\circ\text{C} \leq T_A \leq +85^\circ\text{C}$ ; typical values at  $V_{BUS} = 5.0\text{V}$ ,  $V_{IF} = 3.0\text{V}$ ; minimum and maximum values at  $V_{BUS} = 4.0\text{V}$  to  $5.25\text{V}$ ,  $V_{IF} = 2.5\text{V}$  to  $3.6\text{V}$ ; unless noted.

Symbol	Parameter	Condition	Min	Typ	Max	Units
<b>System and USB Interface DC Characteristics</b>						
$V_{BUS}$	USB Supply Voltage		4.0		5.25	V
$V_{IF}$	System I/F Supply voltage		2.5		5.25	V
$V_{IL}$	Low-Level Input Voltage, <b>Note 4</b>				$0.15V_{IF}$	V
$V_{IH}$	High-Level Input Voltage, <b>Note 4</b>		$0.85V_{IF}$			V
$V_{OH}$	High-Level Output Voltage, <b>Note 4</b>	$I_{OH} = 20\mu\text{A}$	$0.9V_{IF}$			V
$V_{OL}$	Low-Level Output Voltage, <b>Note 4</b>	$I_{OL} = 20\mu\text{A}$			0.1	V
$I_{IL}$	Input Leakage Current, <b>Note 4</b>				$\pm 5$	$\mu\text{A}$
$I_{IF}$	System I/F Supply Current	D- and D+ are idle, $V_{IF} = 3.6\text{V}$ , $V_{BUS} = 5.25\text{V}$ SUS = 1, OE# = 1		1		$\mu\text{A}$
		D- and D+ are idle, $V_{IF} = 3.6\text{V}$ , $V_{BUS} = 5.25\text{V}$ SUS = 0, OE# = 1		1		$\mu\text{A}$
		D- and D+ active, $C_{LOAD} = 50\text{pF}$ , SPD = 1, SUS = 0, $V_{IF} = 3.6\text{V}$ , OE# = 0		2		$\mu\text{A}$
		D- and D+ active, $C_{LOAD} = 600\text{pF}$ , SPD = 0, SUS = 0, $V_{IF} = 3.6\text{V}$ , OE# = 0		2		$\mu\text{A}$
$I_{BUS}$	USB Supply Current	D- and D+ are idle, $V_{BUS} = 5.25\text{V}$ , SPD = 0 SUS = 1, OE# = 1		140	<b>200</b>	$\mu\text{A}$
		D- and D+ are idle, $V_{BUS} = 5.25\text{V}$ , SPD = 1 SUS = 1, OE# = 1		140	<b>200</b>	$\mu\text{A}$
		D- and D+ are idle, $V_{BUS} = 5.25\text{V}$ , SPD = 0 SUS = 0, OE# = 0		140	<b>200</b>	$\mu\text{A}$
		D- and D+ are idle, $V_{BUS} = 5.25\text{V}$ , SPD = 1 SUS = 0, OE# = 1		200	<b>350</b>	$\mu\text{A}$
		D- and D+ active, $C_{LOAD} = 50\text{pF}$ , SPD = 1, SUS = 0, $V_{BUS} = 5.25\text{V}$				mA
		D- and D+ active, $C_{LOAD} = 600\text{pF}$ , SPD = 0 SUS = 0, $V_{BUS} = 5.25\text{V}$				mA
$V_{TRM}$	Termination Voltage	$I_{TRM} = 2.5\text{mA}$	3.0		3.6	V

Symbol	Parameter	Condition	Min	Typ	Max	Units
<b>Transceiver DC Characteristics</b>						
$I_{LO}$	Hi-Z State Data Line Leakage	$0V < V_{BUS} < 3.3V$ , D+, D–, OE# = 1 pins only	–10		+10	$\mu A$
$V_{DI}$	Differential Input Sensitivity	$\Omega(D+) - (D-)\Omega$ , $V_{IN} = 0.8V - 2.5V$	0.2			V
$V_{CM}$	Differential Common-Mode Range	includes $V_{DI}$ range	0.8		2.5	V
$V_{SE}$	Single-Ended Receiver Threshold		0.8		2.0	V
	Receiver Hysteresis, <b>Note 6</b>			200		mV
$V_{OL}$	Static Output Low, <b>Note 5</b>	OE# = 0, $R_L = 1.5k\Omega$ to 3.6V			0.3	V
$V_{OH}$	Static Output High, <b>Note 5</b>	OE# = 0, $R_L = 15k\Omega$ to GND	2.8		3.6	V
$V_{CRS}$	Output Signal Crossover Voltage <b>Note 6</b>		1.3		2.0	V
$C_{IN}$	Transceiver Capacitance, <b>Note 6</b>	pin to GND			20	pF
$Z_{DRV}$	Driver Output Resistance	steady state drive, <b>Note 6</b>	6		18	$\Omega$

**Low-Speed Driver Characteristics**

$t_R$	Transition Rise Time	$C_L = 50pF$ $C_L = 600pF$	75		300	ns ns
$t_F$	Transition Fall Time	$C_L = 50pF$ $C_L = 600pF$	75		300	ns ns
$t_R/t_F$	Rise and Fall Time Matching	$T_R \div T_F$	80		125	%
$V_{CRS}$	Output Signal Crossover Voltage		1.3		2.0	V

**Full-Speed Driver Characteristics**

$t_R$	Transition Rise Time	$C_L = 50pF$	4		20	ns
$t_F$	Transition Fall Time	$C_L = 50pF$	4		20	ns
$t_R/t_F$	Rise and Fall Time Matching	$T_R \div T_F$	90		111.11	%
$V_{CRS}$	Output Signal Crossover Voltage		1.3		2.0	V

- Note 1.** Exceeding the absolute maximum rating may damage the device.
- Note 2.** The device is not guaranteed to function outside its operating rating.
- Note 3.** Devices are ESD sensitive. Handling precautions recommended.
- Note 4.** Applies to the VP, VM, RCV, OE#, SPD, and SUS pins.
- Note 5.** Applies to D+, D–
- Note 6.** Not production tested. Guaranteed by design.

Symbol	Parameter	Condition	Min	Typ	Max	Units
<b>Transceiver Timing</b>						
$t_{PVZ}$	OE# to RCVR Tristate Delay	Figure 1			15	ns
$t_{PZD}$	Receiver Tristate to Transmit Delay	Figure 1	15			ns
$t_{PDZ}$	OE# to DRVVR Tristate Delay	Figure 1			15	ns
$t_{PZV}$	Driver Tri-state to Receiver Delay	Figure 1	15			ns
$t_{PLH}$	V+/V- to D+/D- Propagation Delay	Figure 4			15	ns
$t_{PHL}$	V+/V- to D+/D- Propagation Delay	Figure 4			15	ns
$t_{PLH}$	D+/D- to RCV Propagation Delay	Figure 3			15	ns
$t_{PHL}$	D+/D- to RCV Propagation Delay	Figure 3			15	ns
$t_{PLH}$	D+/D- to V+/D- Propagation Delay	Figure 3			8	ns
$t_{PHL}$	D+/D- to V+/D- Propagation Delay	Figure 3			8	ns

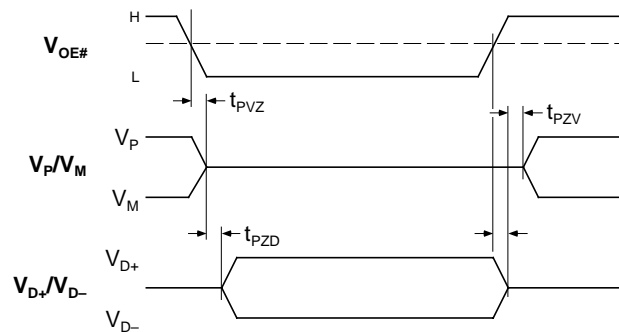


Figure 1. Enable and Disable Times

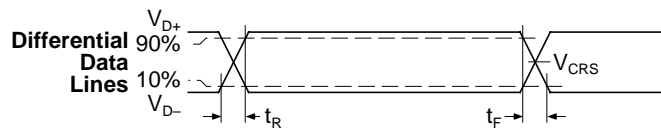
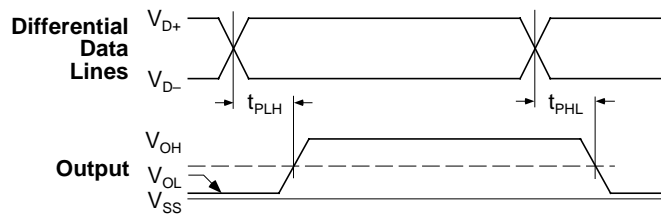
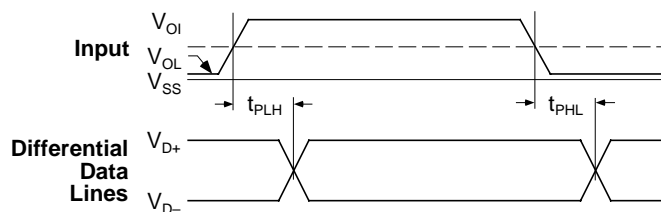


Figure 2. Rise and Fall Times

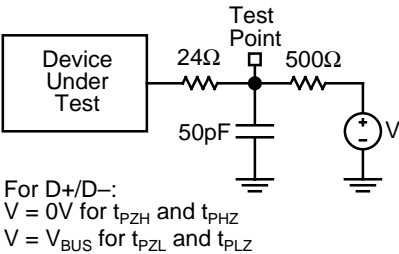
Figure 3. Receiver Propagation Delay D+/D- to RCV, V<sub>P</sub>, and V<sub>M</sub>Figure 4. Driver Propagation Delay V<sub>P</sub> and V<sub>M</sub> to D+/D-

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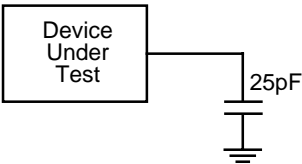
OE# = 0 (Transmit)					
Input		Output			Result
VP	VM	D+	D-	RCV	
0	0	0	0	X	SE0
0	1	0	1	0	Logic 0
1	0	1	0	1	Logic 1
1	1	1	1	X	Undefined
OE# = 1 (Receive):					
Input		Output			Result
D+	D-	VP	VM	RCV	
0	0	0	0	X	SE0
0	1	0	1	0	Logic 0
1	0	1	0	1	Logic 1
1	1	1	1	X	Undefined

Table 1. Truth Table

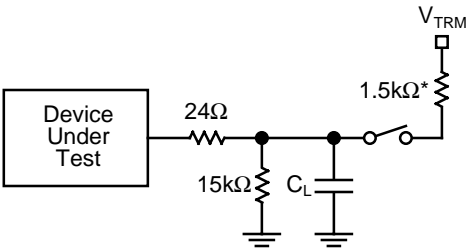
Test Circuits



Load for Enable and Disable Time (D+/D-)



VP, VM, and RCV Load

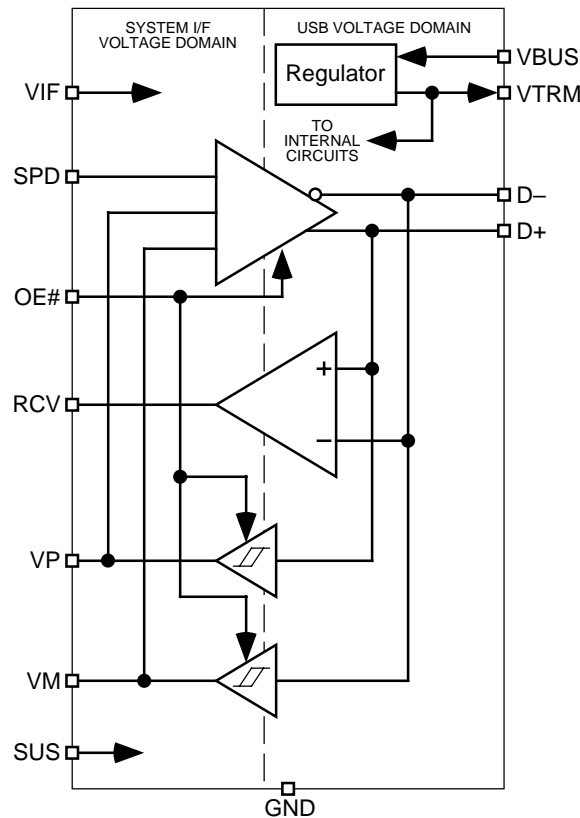


CL = 50pF, full speed  
CL = 50pF, low speed (minimum timing)  
CL = 600pF, low speed (maximum timing)  
\*1.5k on D- for low speed or D+ for high speed

D+ and D- Load

## Block Diagram

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## Applications Information

The MIC2550 is designed to provide USB connectivity in mobile systems where system supply voltages are not available to satisfy USB requirements. The MIC2550 can operate down to supply voltages of 2.5V and still meet USB physical layer specifications. As shown in the system diagram, the MIC2550 takes advantage of USB's supply voltage,  $V_{BUS}$ , to operate the transceiver. The system voltage,  $V_{IF}$ , is used to set the reference voltage used by the digital I/O lines (VP, VM, RCV, OE#, SPD, and SUS pins) interfacing to the system. Internal circuitry provides translation between the USB and system voltage domains.  $V_{IF}$  will typically be the main supply voltage rail for the system.

In addition, a 3.3V, 10% termination supply voltage,  $V_{TRM}$ , is provided to support speed selection. A 0.47 $\mu$ F (minimum) capacitor from  $V_{TRM}$  to ground is required to ensure stability. A 1.5K resistor is required between this pin and the D+ or D- lines to respectively specify full-speed or low-speed operation.

### Suspend

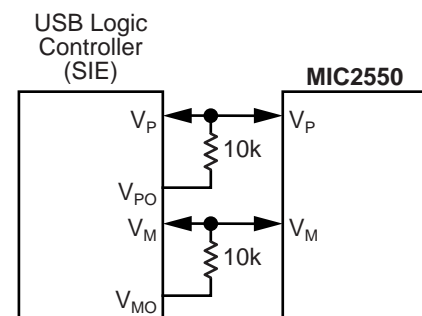
When the suspend pin (SUS) is high, power consumption is reduced to a minimum.  $V_{TRM}$  is not disabled. RCV, VP and VM are still functional to enable the device to detect USB activity. For minimal current consumption in suspend mode, it is recommended that  $OE\# = 1$ .

### External ESD Protection

The use of ESD transient protection devices is not required for operation, but is recommended.

### Nonmultiplexed Bus

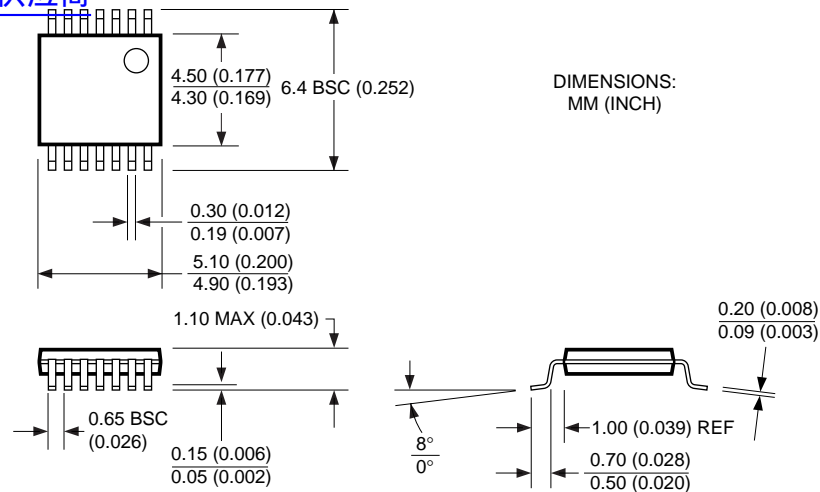
To save pin count for the USB logic controller interface, the MIC2550 was designed with  $V_P$  and  $V_M$  as bidirectional pins. To interface the MIC2550 with a nonmultiplexed data bus, resistors can be used for low cost isolation as shown in Figure 6.



**Figure 6. MIC2550 Interface to Nonmultiplexed Data Bus.**

## Package Information

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**14-Pin TSSOP (TS)**

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