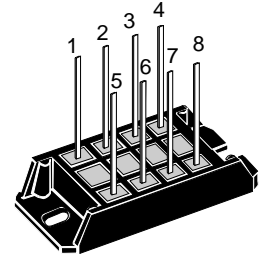
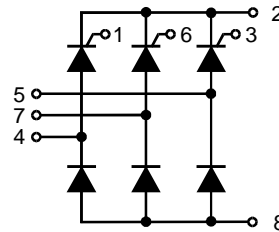


# Three Phase Half Controlled Rectifier Bridge

$I_{dAVM} = 20 \text{ A}$   
 $V_{RRM} = 1200-1600 \text{ V}$

| $V_{RSM}$<br>$V_{DSM}$<br>V | $V_{RRM}$<br>$V_{DRM}$<br>V | Type         |
|-----------------------------|-----------------------------|--------------|
| 1300                        | 1200                        | VVZ 12-12io1 |
| 1500                        | 1400                        | VVZ 12-14io1 |
| 1700                        | 1600                        | VVZ 12-16io1 |



| Symbol  | Test Conditions   | Maximum Ratings  |
|---|---|--|
| $I_{dAV}$<br>$I_{dAVM}$<br>$I_{FRMS}, I_{TRMS}$ | $T_K = 100^\circ\text{C}$ ; module<br>module<br>per leg   | 15 A<br>20 A<br>12 A   |
| $I_{FSM}, I_{TSM}$                              | $T_{VJ} = 45^\circ\text{C}$ ;<br>$V_R = 0$  | $t = 10 \text{ ms}$ (50 Hz), sine 110 A<br>$t = 8.3 \text{ ms}$ (60 Hz), sine 115 A  |
|   | $T_{VJ} = T_{VJM}$<br>$V_R = 0$   | $t = 10 \text{ ms}$ (50 Hz), sine 100 A<br>$t = 8.3 \text{ ms}$ (60 Hz), sine 105 A  |
| $I^2t$  | $T_{VJ} = 45^\circ\text{C}$<br>$V_R = 0$  | $t = 10 \text{ ms}$ (50 Hz), sine 60 A <sup>2</sup> s<br>$t = 8.3 \text{ ms}$ (60 Hz), sine 55 A <sup>2</sup> s                      |
|   | $T_{VJ} = T_{VJM}$<br>$V_R = 0$   | $t = 10 \text{ ms}$ (50 Hz), sine 50 A <sup>2</sup> s<br>$t = 8.3 \text{ ms}$ (60 Hz), sine 45 A <sup>2</sup> s                      |
| $(di/dt)_{cr}$                                  | $T_{VJ} = T_{VJM}$<br>$f = 400 \text{ Hz}$ , $t_p = 200 \mu\text{s}$<br>$V_D = 2/3 V_{DRM}$<br>$I_G = 0.3 \text{ A}$ ,<br>$di_G/dt = 0.3 \text{ A}/\mu\text{s}$ | repetitive, $I_T = 50 \text{ A}$ 150 A/ $\mu\text{s}$<br>non repetitive, $I_T = 1/3 \sim I_{dAV}$ 500 A/ $\mu\text{s}$               |
| $(dv/dt)_{cr}$                                  | $T_{VJ} = T_{VJM}$ ; $V_{DR} = 2/3 V_{DRM}$<br>$R_{GK} = \infty$ ; method 1 (linear voltage rise)   | 1000 V/ $\mu\text{s}$  |
| $V_{RGM}$                                       |   | 10 V   |
| $P_{GM}$  | $T_{VJ} = T_{VJM}$<br>$I_T = I_{TAVM}$  | $t_p = 30 \mu\text{s}$ $\leq 10 \text{ W}$<br>$t_p = 500 \mu\text{s}$ $\leq 5 \text{ W}$<br>$t_p = 10 \text{ ms}$ $\leq 1 \text{ W}$ |
| $P_{GAVM}$                                      |   | 0.5 W  |
| $T_{VJ}$  |   | -40...+125 °C  |
| $T_{VJM}$                                       |   | 125 °C   |
| $T_{stg}$                                       |   | -40...+125 °C  |
| $V_{ISOL}$                                      | 50/60 Hz, RMS<br>$I_{ISOL} \leq 1 \text{ mA}$   | $t = 1 \text{ min}$ 3000 V~<br>$t = 1 \text{ s}$ 3600 V~   |
| $M_d$   | Mounting torque   | (M5) 2-2.5 Nm<br>(10-32 UNF) 18-22 lb.in.  |
| Weight  | typ.  | 28 g   |

## Features

- Package with DCB ceramic base plate
- Isolation voltage 3600 V~
- Planar passivated chips
- Soldering terminals
- UL registered E 72873

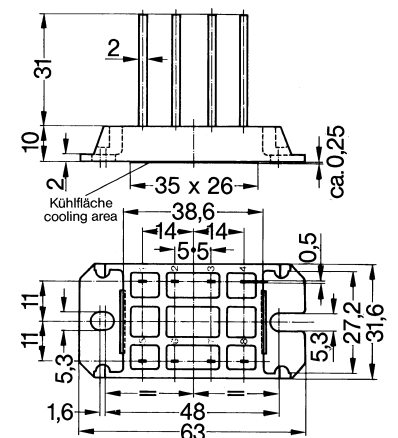
## Applications

- Input rectifier for switch mode power supplies (SMPS)
- Softstart capacitor charging
- Electric drives and auxiliaries

## Advantages

- Easy to mount with two screws
- Space and weight savings
- Improved temperature and power cycling

## Dimensions in mm (1 mm = 0.0394")



Data according to IEC 60747 and refer to a single thyristor/diode unless otherwise stated. IXYS reserves the right to change limits, test conditions and dimensions.

| Symbol     | Test Conditions   | Characteristic Values   |   |
|------------|---|---|---|
| $I_R, I_D$ | $V_R = V_{RRM}; V_D = V_{DRM}$<br>$T_{VJ} = T_{VJM}$<br>$T_{VJ} = 25^\circ\text{C}$                         | $\leq 5$ mA<br>$\leq 0.3$ mA  |   |
| $V_F, V_T$ | $I_F, I_T = 30$ A, $T_{VJ} = 25^\circ\text{C}$  | $\leq 2$ V  |   |
| $V_{T0}$   | For power-loss calculations only  | 1.1 V   |   |
| $r_T$      | ( $T_{VJ} = 125^\circ\text{C}$ )  | 30 m $\Omega$   |   |
| $V_{GT}$   | $V_D = 6$ V;<br>$T_{VJ} = 25^\circ\text{C}$<br>$T_{VJ} = -40^\circ\text{C}$                                 | $\leq 1.0$ V<br>$\leq 1.2$ V  |   |
| $I_{GT}$   | $V_D = 6$ V;<br>$T_{VJ} = 25^\circ\text{C}$<br>$T_{VJ} = -40^\circ\text{C}$<br>$T_{VJ} = 125^\circ\text{C}$ | $\leq 65$ mA<br>$\leq 80$ mA<br>$\leq 50$ mA  |   |
| $V_{GD}$   | $T_{VJ} = T_{VJM};$<br>$T_{VJ} = T_{VJM};$  | $V_D = 2/3 V_{DRM}$<br>$V_D = 2/3 V_{DRM}$  | $\leq 0.2$ V<br>$\leq 5$ mA                     |
| $I_L$      | $I_G = 0.3$ A; $t_G = 30$ $\mu\text{s}$<br>$di_G/dt = 0.3$ A/ $\mu\text{s}$                                 | $T_{VJ} = 25^\circ\text{C}$<br>$T_{VJ} = -40^\circ\text{C}$<br>$T_{VJ} = 125^\circ\text{C}$ | $\leq 150$ mA<br>$\leq 200$ mA<br>$\leq 100$ mA |
| $I_H$      | $T_{VJ} = 25^\circ\text{C}; V_D = 6$ V; $R_{GK} = \infty$   | $\leq 100$ mA   |   |
| $t_{gd}$   | $T_{VJ} = 25^\circ\text{C}; V_D = 1/2 V_{DRM}$<br>$I_G = 0.3$ A; $di_G/dt = 0.3$ A/ $\mu\text{s}$           | $\leq 2$ $\mu\text{s}$  |   |
| $t_q$      | $T_{VJ} = 125^\circ\text{C}; I_T = 15$ A, $t_p = 300$ $\mu\text{s}$ , $-di/dt = 10$ A/ $\mu\text{s}$        | typ. 150 $\mu\text{s}$  |   |
| $Q_r$      | $V_R = 100$ V, $dv/dt = 20$ V/ $\mu\text{s}$ , $V_D = 2/3 V_{DRM}$  | 75 $\mu\text{C}$  |   |
| $R_{thJC}$ | per thyristor (diode); DC current<br>per module   | 2.5 K/W<br>0.42 K/W   |   |
| $R_{thJH}$ | per thyristor (diode); DC current<br>per module   | 3.1 K/W<br>0.52 K/W   |   |
| $d_s$      | Creeping distance on surface  | 7 mm  |   |
| $d_A$      | Creepage distance in air  | 7 mm  |   |
| $a$        | Max. allowable acceleration   | 50 m/s <sup>2</sup>   |   |