# MOS INTEGRATED CIRCUIT $\mu PD8884A$

## (10680 PIXELS $\times$ 4 LINES) $\times$ 3 COLOR CCD LINEAR IMAGE SENSOR

#### DESCRIPTION

EL

The  $\mu$ PD8884A is a color CCD (Charge Coupled Device) linear image sensor which changes optical images to electrical signal and has the function of color separation.

The  $\mu$ PD8884A has 3 rows of (10680 × 4) staggered pixels, and each row has a dual-sided readout-type charge transfer register. And it has reset feed-through level clamp circuits and voltage amplifiers. Therefore, it is suitable for 4800 dpi/A4 color image scanners.

#### FEATURES

- Valid photocell  $(10680 \text{ pixels} \times 4) \times 3$
- Photocell's size : 4  $\mu$ m
- Line spacing : Quad staggered pixels 96 μm (24 lines) Red line - Green line, Green line - Blue line
   Color filter : Primary colors (red, green and blue), pigment filter (with light resistance 10<sup>7</sup> lx•hour)
   Resolution : 192 dot/mm A4 (210 × 297 mm) size (shorter side) 4800 dpi US letter (8.5" × 11") size (shorter side)
   Drive clock level : CMOS output under 5 V operation
   Data rate : 5.0 MHz Max.
- Power supply : +12 V
  On-chip circuits : Reset feed-through level clamp circuits
  - Voltage amplifiers

#### **ORDERING INFORMATION**

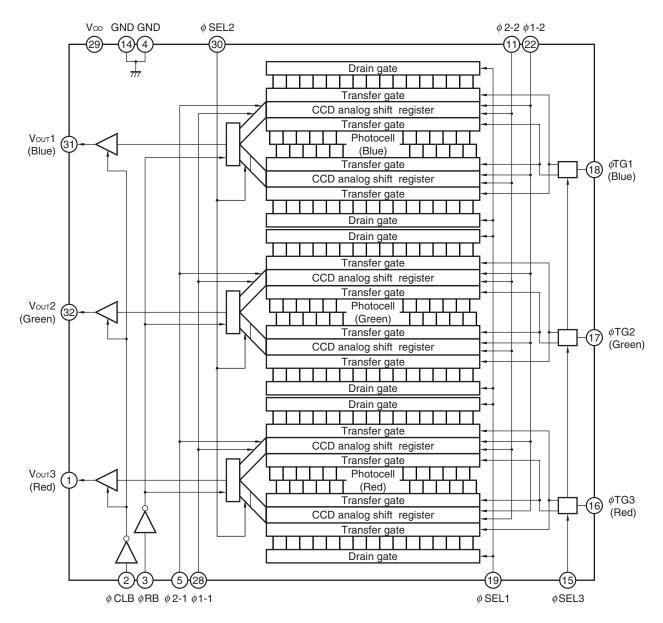
Part Number	Package
μPD8884ACY-A	CCD linear image sensor 32-pin plastic DIP (10.16 mm (400))

**Remark** The  $\mu$  PD8884ACY-A is a lead-free product.

The information in this document is subject to change without notice. Before using this document, please confirm that this is the latest version. Not all products and/or types are available in every country. Please check with an NEC Electronics sales representative for availability and additional information.

Document No. S17546EJ1V0DS00 (1st edition) Date Published May 2005 NS CP (K) Printed in Japan

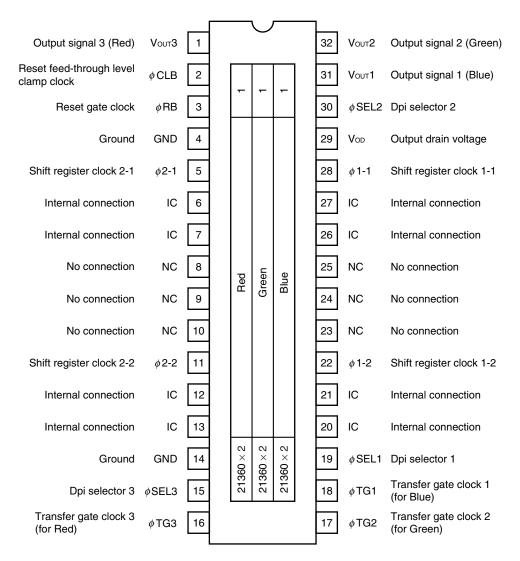
#### **BLOCK DIAGRAM**



#### PIN CONFIGURATION (Top View)

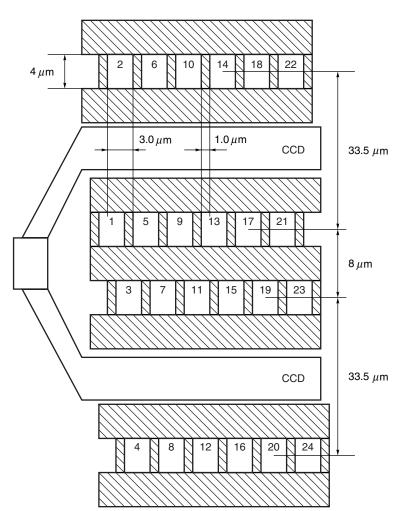
#### CCD linear image sensor 32-pin plastic DIP (10.16 mm (400))

• *µ*PD8884ACY-A



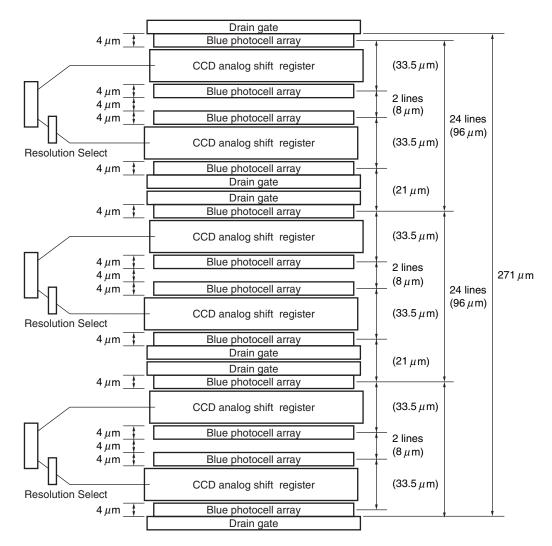
Cautions 1. Leave pins 6, 7, 12, 13, 20, 21, 26, 27 (IC) unconnected.

2. Connect the No connection pins (NC) to GND.

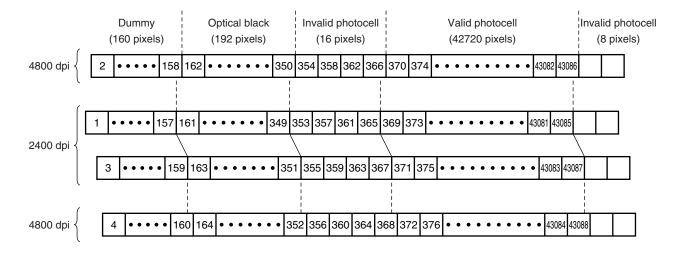


PHOTOCELL STRUCTURE DIAGRAM (4800 dpi, for each color)





#### PHOTOCELL ARRAY STRUCTURE DIAGRAM-2 (Dummy, OB, for each color)



#### ABSOLUTE MAXIMUM RATINGS ( $T_A = +25^{\circ}C$ )

Parameter	Symbol	Ratings	Unit
Output drain voltage	Vod	-0.3 to +15	V
Shift register clock voltage	Vø1, Vø2	-0.3 to +8	V
Reset gate clock voltage	V <i>ø</i> ₽₿	-0.3 to +8	V
Reset feed-through level clamp clock voltage	Vøclb	-0.3 to +8	V
Dpi select signal voltage	Vøseli to Vøsels	-0.3 to +8	V
Transfer gate clock voltage	Vøтg1 to Vøтg3	-0.3 to +8	V
Operating ambient temperature Note	Та	0 to +60	°C
Storage temperature	T <sub>stg</sub>	-40 to +70	°C

Note Use at the condition without dew condensation.

Caution Product quality may suffer if the absolute maximum rating is exceeded even momentarily for any parameter. That is, the absolute maximum ratings are rated values at which the product is on the verge of suffering physical damage, and therefore the product must be used under conditions that ensure that the absolute maximum ratings are not exceeded.

Parameter	Symbol	Min.	Тур.	Max.	Unit
Output drain voltage	Vod	11.5	12.0	12.5	V
Shift register clock high level	Vø1H, Vø2H	4.75	5.0	5.5	V
Shift register clock low level	Vø1L, Vø2L	-0.3	0	+0.3	V
Reset gate clock high level	Vørbh	4.5	5.0	5.5	V
Reset gate clock low level	Vørbl	-0.3	0	+0.3	V
Reset feed-through level clamp clock high level	Vøclbh	4.5	5.0	5.5	V
Reset feed-through level clamp clock low level	Vøclbl	-0.3	0	+0.3	V
Dpi select signal high level	Vøselih to Vøselih	4.5	5.0	5.5	V
Dpi select signal low level	Vøselil to Vøselil	-0.3	0	+0.3	V
Transfer gate clock high level	Vøтg1н to Vøтg3н	4.5	5.0	5.5	V
Transfer gate clock low level	Vøtgil to Vøtgil	-0.3	0	+0.3	V
Data rate	førв	-	2.0	5.0	MHz
Clock pulse frequency	fø1, fø2	_	1.0	10.0	MHz

#### **RECOMMENDED OPERATING CONDITIONS (TA = +25°C)**

## ELECTRICAL CHARACTERISTICS

Parameter		Symbol	Test Conditions	Min.	Тур.	Max.	Unit
Saturation voltage		Vsat		2.3	2.7	-	V
Saturation exposure	Red	SER		-	0.79	-	lx•s
	Green	SEG		-	0.87	-	lx•s
	Blue	SEB		-	1.35	_	lx•s
Photo response non-unif	ormity	PRNU	Vout = 1.0 V	-	6	20	%
Average dark signal		ADS	Light shielding	-	0.1	4.0	mV
Dark signal non-uniformi	ty	DSNU	Light shielding	-	2.0	8.0	mV
Power consumption		Pw		-	380	540	mW
Output impedance		Zo		-	0.4	1.0	kΩ
Response	Red	RR		2.38	3.40	4.42	V/lx•s
	Green	Rg		2.17	3.10	4.03	V/lx•s
	Blue	Rв		1.40	2.00	2.60	V/lx•s
Offset level Note	·	Vos		4.5	6.0	7.5	V
Total transfer efficiency		TTE	Vout = 1.0 V Clock pulse frequency = 10 MHz	92	98	-	%
Response peak	Red			-	630	-	nm
	Green			-	540	-	nm
	Blue			-	460	-	nm
Image lag		IL	Vout = 1.0 V	-	0.05	3.0	%
Response difference between inside and outside		RDIO	Vout = 1.0 V	-	1.0	6.0	%
Potocell array imbalance		PAIIN	Vout = 1.0 V	-	1.0	6.0	%
		PAlout	Vout = 1.0 V	-	1.0	6.0	%
Reset feed-through noise	Note Ə	RFTN	Light shielding	-	-500	+1000	mV
Random noise (CDS)		$\sigma$ CDS	Light shielding	-	1.2	_	mV

Note Refer to TIMING CHART 2-1 to 2-3.

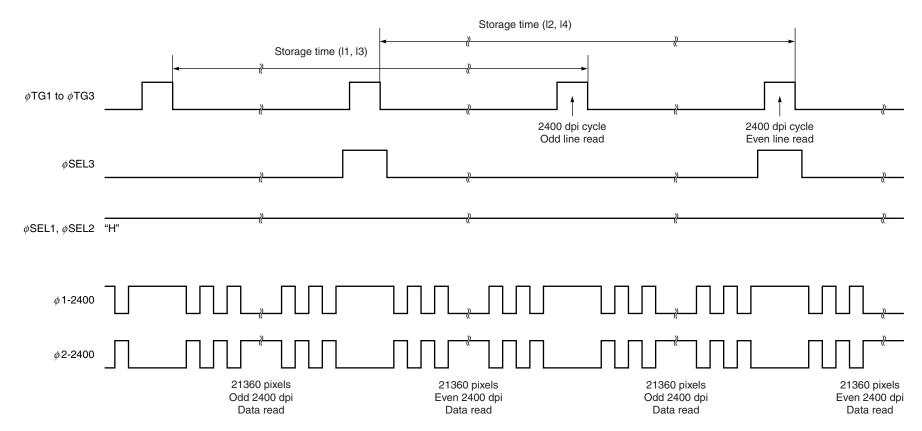
#### INPUT PIN CAPACITANCE ( $T_A = +25^{\circ}C$ , $V_{OD} = 12 V$ )

Parameter	Symbol	Pin name	Pin No.	Min.	Тур.	Max.	Unit
Shift register clock pin capacitance 1	Cø 1-1	φ1-1	28	_	750	_	pF
Shift register clock pin capacitance 2	Cø1-2	<i>φ</i> 1-2	22	-	750	-	pF
Shift register clock pin capacitance 3	Cø2-1	φ2-1	5	-	750	_	pF
Shift register clock pin capacitance 4	Cø2-2	φ <b>2-2</b>	11	-	750	_	pF
Reset gate clock pin capacitance	C ∉ RB	φRB	3	-	20	-	pF
Reset feed-through level clamp clock pin capacitance	C∳CLB	φ CLB	2	-	20	_	pF
Select signal and gain pin capacitance	CøSEL1	¢SEL1	19	-	20	-	pF
	CøSEL2	ØSEL2	30	-	20	-	pF
	Cø SEL3	¢SEL3	15	-	20	_	pF
Transfer gate clock pin capacitance	Cøtg	¢TG1	18	-	20	_	pF
		φTG2	17	-	20	_	pF
		φTG3	16	_	20	_	pF

**Remark**  $C_{\phi 1-1}$  to  $C_{\phi 2-2}$  show the equivalent capacity of the real drive including the capacity of between each clock pin ( $\phi 1-1$ ,  $\phi 1-2$ ,  $\phi 2-1$  and  $\phi 2-2$ ).

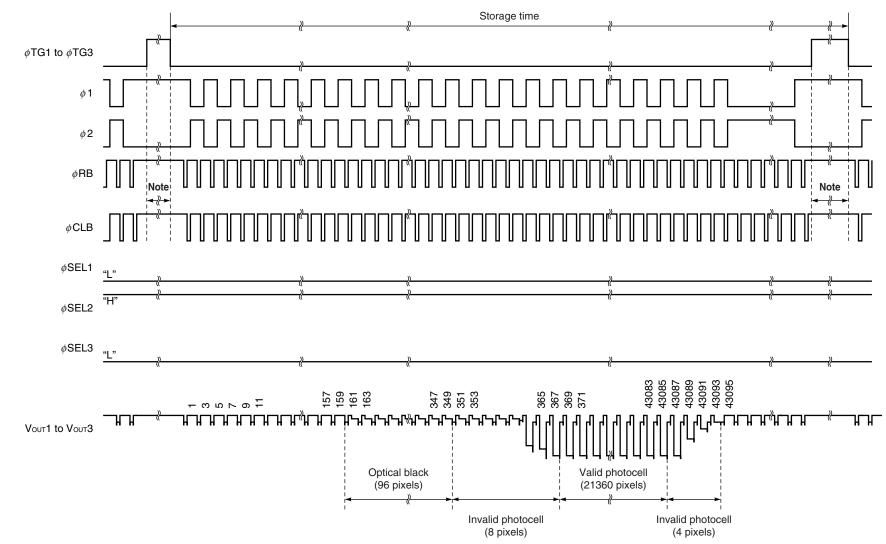
#### **INPUT SIGNAL TABLE**

Mode	ØSEL1	ØSEL2	ØSEL3	Note
	(Even-line enable switch)	(CCD-drain switch)	(TG-select switch)	
4800 dpi	High level	High level	High level	Even-line electron read photodiode to CCD
	High level	High level	Low level	Odd-line electron read photodiode to CCD
2400 dpi	Low level	High level	Low level	Odd-line electron read photodiode to CCD
				Even-line electron sink to drain
1200 dpi	Low level	Low level	Low level	1, 5, 9, 13, : Line photodiode use
600 dpi	]			2 to 4, 6 to 8, 10 to 12, : Sink to drain



TIMING CHART 1-1 (4800 dpi, for each color)

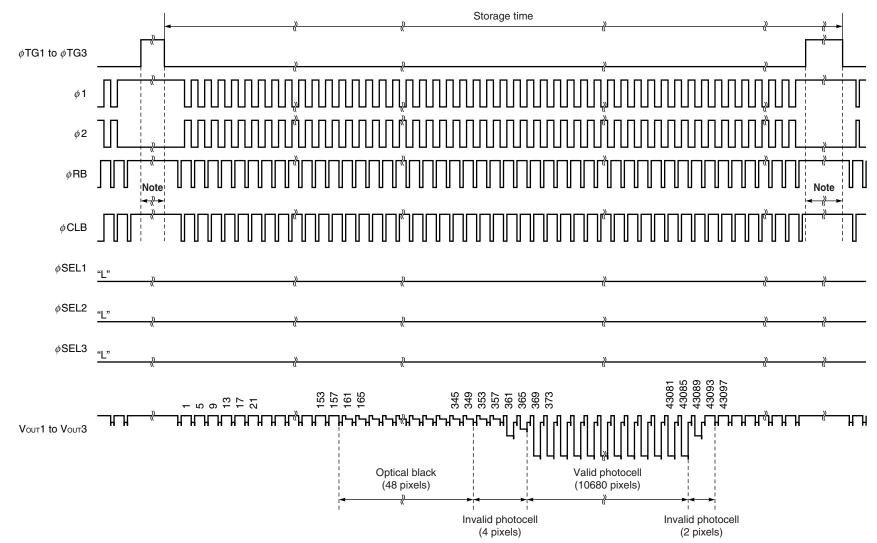
**Remark** Above means, storage time of each photocell array is "TG period × 2". And storage time of (11, 13) and (12, 14) is a half overlap each other.



## **TIMING CHART 1-2 (2400 dpi, for each color)**

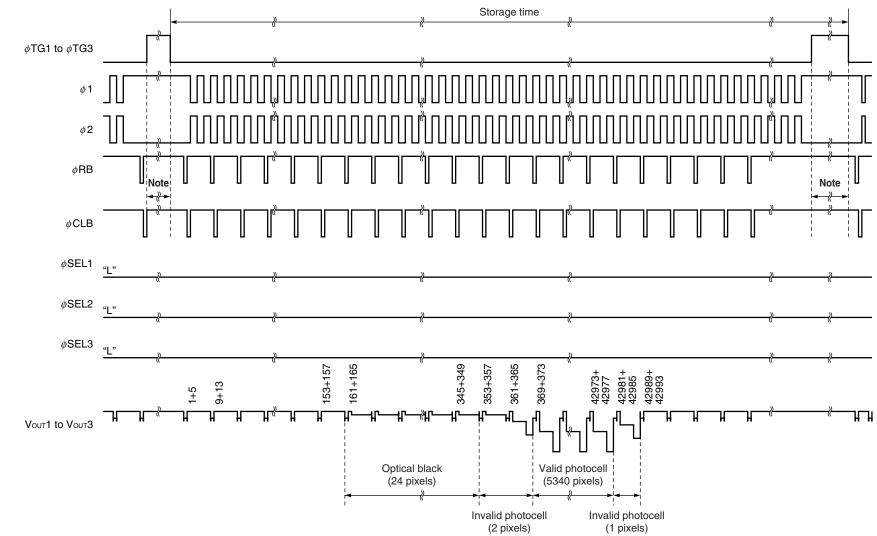
**Note** Set the  $\phi$ RB and the  $\phi$ CLB to high level during this period.

## NEC



**Note** Set the  $\phi$  RB and the  $\phi$  CLB to high level during this period.

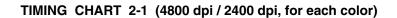
Ξ

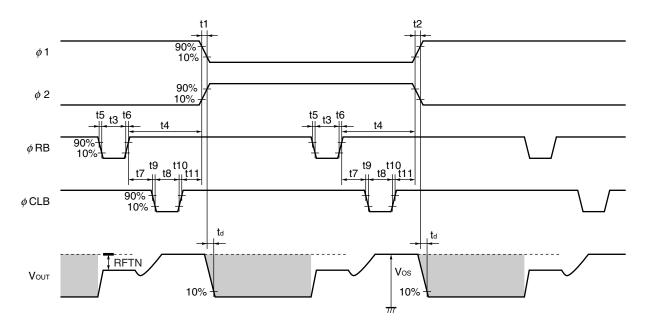


## <sup>™</sup> TIMING CHART 1-4 (600 dpi, for each color)

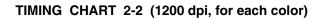
**N Note** Set the  $\phi$ RB and the  $\phi$ CLB to high level during this period.

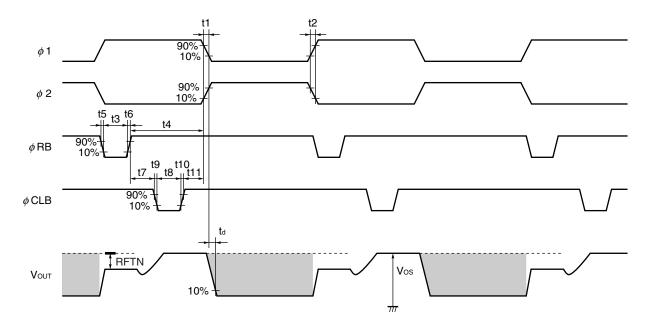
Remark 2 pixels data merge at the charge detected capacitance.





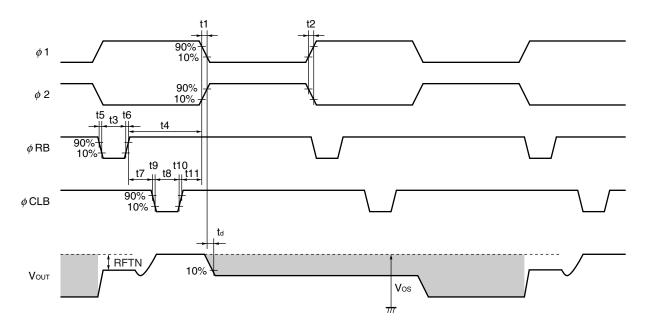
Symbol	Min.	Тур.	Max.	Unit
t1, t2	0	30	_	ns
t3	20	100	-	ns
t4	40	150	-	ns
t5, t6	0	10	-	ns
t7	-10	+25	-	ns
t8	20	100	-	ns
t9, t10	0	10	_	ns
t11	10	25	_	ns
td	_	15	_	ns





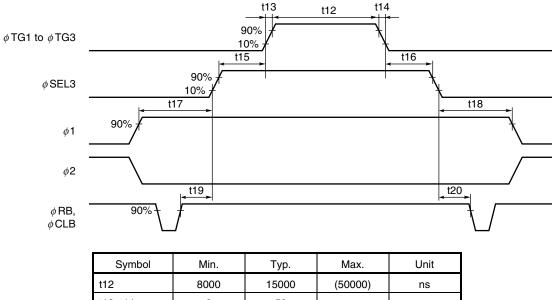
Symbol	Min.	Тур.	Max.	Unit
t1, t2	0	30	_	ns
t3	20	100	-	ns
t4	40	150	-	ns
t5, t6	0	10	-	ns
t7	-10	+25	-	ns
t8	20	100	-	ns
t9, t10	0	10	-	ns
t11	10	25	_	ns
ta	_	15	_	ns

#### TIMING CHART 2-3 (600 dpi, for each color)



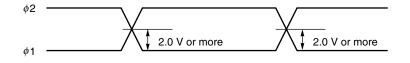
Symbol	Min.	Тур.	Max.	Unit
t1, t2	0	30	-	ns
t3	20	100	-	ns
t4	40	150	-	ns
t5, t6	0	10	-	ns
t7	-10	+25	-	ns
t8	20	100	-	ns
t9, t10	0	10	-	ns
t11	10	25	-	ns
ta	_	15	-	ns

#### TIMING CHART 3 (readout)



112	8000	15000	(50000)	ns
t13, t14	0	50	-	ns
t15, t16	1000	2000	-	ns
t17	1000	2000	-	ns
t18	7000	10000	_	ns
t19, t20	500	1000	-	ns

## ø1, ø2 CROSS POINTS



**Remark** Adjust cross points of  $\phi 1$  and  $\phi 2$  with input resistance of each pin.

#### DEFINITIONS OF CHARACTERISTIC ITEMS

1. Saturation voltage : Vsat

Output signal voltage at which the response linearity is lost. Photo pixel and CCD register electron saturate level.

- Saturation exposure : SE
   Product of intensity of illumination (lx) and storage time (s) when saturation of output voltage occurs.
- 3. Photo response non-uniformity : PRNU

The output signal non-uniformity of all the valid pixels when the photosensitive surface is applied with the light of uniform illumination. PRNU of 4800 dpi is calculated by the following formula.

PRNUIN (%) = 
$$\frac{\Delta x}{\overline{x}} \times 100$$
  
 $\Delta x$ : maximum of  $|x_j - \overline{x}|$   
 $\overline{x} = \frac{\sum_{j=1}^{IV} x_j}{IV}$ 

 $x_{j} \hspace{0.1 cm}:\hspace{0.1 cm} \text{Output voltage of valid pixel number } j$ 

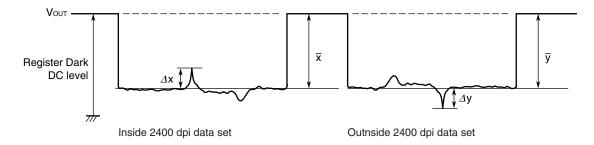
PRNUout (%) = 
$$\frac{\Delta y}{\overline{y}} \times 100$$
  
 $\Delta x$ : maximum of  $|y_j - \overline{y}|$   
 $\overline{y} = \frac{\sum_{j=1}^{IO} y_j}{12}$ 

10

y<sub>j</sub>: Output voltage of valid pixel number j

- IV : Number of inside valid pixels (21360 bits)
- IO : Number of outside valid pixels (21360 bits)

The following figure shows output waveform of 4800 dpi mode.



4. Average dark signal : ADS

Average output signal voltage of all the valid pixels at light shielding. This is calculated by the following formula.

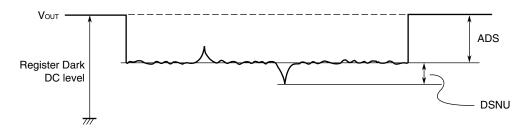
ADS (mV) = 
$$\frac{\sum_{j=1}^{Vaild pixels} d_j}{Valid pixels}$$
$$d_j : Dark signal of valid pixel number j$$

5. Dark signal non-uniformity : DSNU

Absolute maximum of the difference between ADS and voltage of the highest or lowest output pixel of all the valid pixels at light shielding. This is calculated by the following formula.

DSNU (mV) : maximum of  $|d_j - ADS|_{j=1 \text{ to Valid pixels}}$ 

dj : Dark signal of valid pixel number j



6. Output impedance : Zo

Impedance of the output pins viewed from outside.

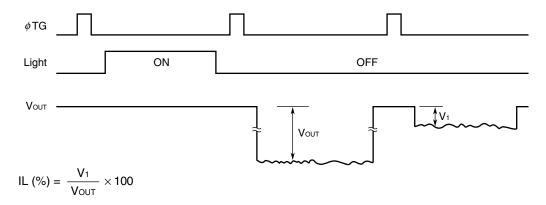
7. Response : R

Output voltage divided by exposure (lx•s). Note that the response varies with a light source (spectral characteristic). R of 4800 dpi is defined as following (refer to **3. Photo response non-uniformity**).

RIN :  $\overline{x}$  divided by exposure (lx•s) Rout :  $\overline{y}$  divided by exposure (lx•s)

8. Image lag : IL

The rate between the last output voltage and the next one after read out the data of a line.

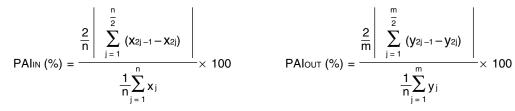


9. Response difference between inside and outside : RDIO Difference of average output voltage between inside 2400 dpi and outside 2400 dpi (refer to 3. Photo response non-uniformity).

$$\mathsf{RDIO}\ (\%) = \frac{2 \, |\, \overline{x} - \overline{y}\,|}{\overline{x} + \overline{y}} \times 100$$

10. Photocell array imbalance : PAI

PAI is calculated by following formula (refer to 3. Photo response non-uniformity).



- x<sub>i</sub> : Output voltage of each pixel
- n : Number of valid pixels (21360 bits)

y<sub>i</sub>: Output voltage of each pixel

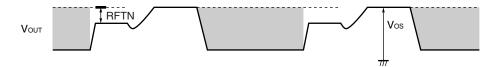
m : Number of valid pixels (21360 bits)

11. Offset level: Vos

DC level of output signal is defined as follows.

12. Reset feed-through noise : RFTN

Reset feed-through noise (RFTN) are defined as follows.



#### 13. Random noise (CDS) : $\sigma$ CDS

Random noise  $\sigma$ CDS is defined as the standard deviation of a valid pixel output signal with 100 times (=100 lines) data sampling at dark (light shielding).  $\sigma$ CDS is calculated by the following procedure.

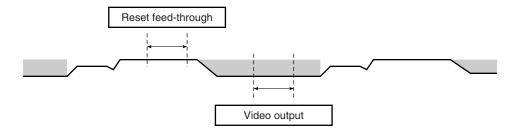
- 1. One valid photocell in one reading is fixed as measurement point.
- The output level is measured during the reset feed-through period which is averaged over 100 ns to get "VDi".
- 3. The output level is measured during the video output time averaged over 100 ns to get "VOi".
- 4. The correlated double sampling output is defined by the following formula.

 $VCDS_i = VD_i - VO_i$ 

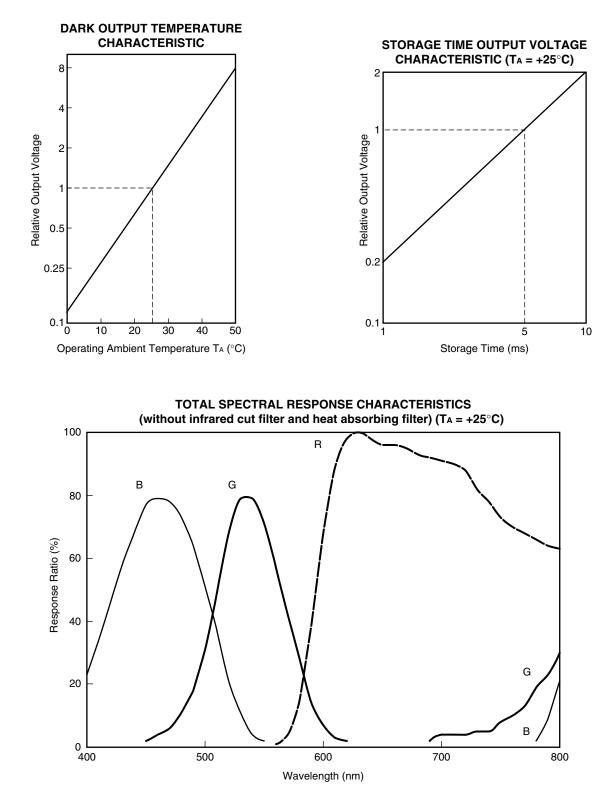
- 5. Repeat the above procedure (1 to 4) for 100 times (= 100 lines).
- 6. Calculate the standard deviation  $\sigma$ CDS using the following formula equation.

$$\sigma$$
 CDS (mV) =  $\sqrt{\frac{\sum_{i=1}^{100} (VCDS_i - \overline{V})^2}{100}}$ ,  $\overline{V} = \frac{1}{100} \sum_{i=1}^{100} VCDS_i$ 

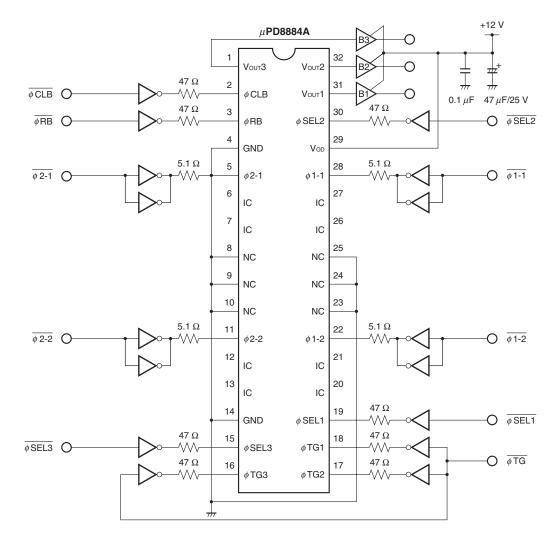
The following figure shows output waveform (valid photocell under dark condition).



#### STANDARD CHARACTERISTIC CURVES (Reference Value)



#### APPLICATION CIRCUIT EXAMPLE



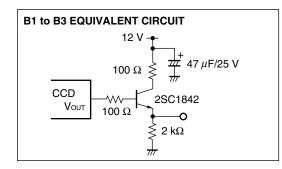
Cautions 1. Leave pins 6, 7, 12, 13, 20, 21, 26, 27 (IC) unconnected.

2. Connect the No connection pins (NC) to GND.

**Remarks 1.**  $\phi$ RB,  $\phi$ CLB,  $\phi$ TG1 to  $\phi$ TG3 and  $\phi$ SEL1 to  $\phi$ SEL3 driving inverters shown in the above application circuit example are the 74HC04.

 $\phi$ 1-1 to  $\phi$ 2-2 driving inverters shown in the above application circuit example are the 74HC04 ( $\leq$  2.0 MHz) or the 74AC04 (> 2.0 MHz).

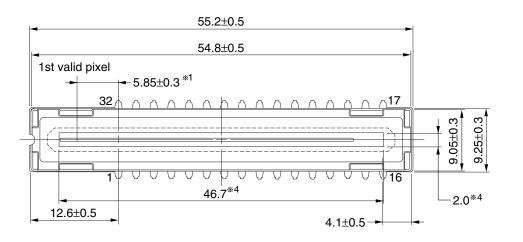
2. Inverters B1 to B3 in the above application circuit example are shown in the figure below.

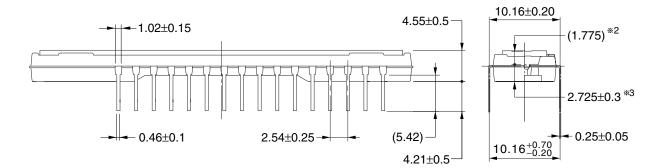


#### PACKAGE DRAWING

## μ**PD8884ACY** CCD LINEAR IMAGE SENSOR 32-PIN PLASTIC DIP (10.16 mm (400))

(Unit : mm)





Name	Dimensions	Refractive index
Plastic cap	52.2×6.4×0.8 (0.7 <sup>**5</sup> )	1.5

%1 1st valid pixel → The center of the pin1

※2 The surface of the CCD chip → The top of the cap
※3 The bottom of the package → The surface of the CCD chip \*4 Mirror finishied surface

\*5 Thickness of mirror finished surface

#### **RECOMMENDED SOLDERING CONDITIONS**

When soldering this product, it is highly recommended to observe the conditions as shown below. If other soldering processes are used, or if the soldering is performed under different conditions, please make sure to consult with our sales offices.

For technical information, see the following website. Semiconductor Device Mount Manual (http://www.necel.com/pkg/en/mount/index.html)

#### Type of Through-hole Device

#### $\mu$ PD8884ACY-A : CCD linear image sensor 32-pin plastic DIP (10.16 mm (400))

Process	Conditions
Partial heating method	Pin temperature : 300 °C or below, Heat time : 3 seconds or less (per pin)

Cautions 1. During assembly care should be taken to prevent solder or flux from contacting the plastic cap. The optical characteristics could be degraded by such contact.

2. Soldering by the solder flow method may have deleterious effects on prevention of plastic cap soiling and heat resistance. So the method cannot be guaranteed.

## NOTES ON HANDLING THE PACKAGES

## **1** DUST AND DIRT PROTECTING

The optical characteristics of the CCD will be degraded if the cap is scratched during cleaning. Don't either touch plastic cap surface by hand or have any object come in contact with plastic cap surface. Should dirt stick to a plastic cap surface, blow it off with an air blower. For dirt stuck through electricity ionized air is recommended. And if the plastic cap surface is grease stained, clean with our recommended solvents.

#### O CLEANING THE PLASTIC CAP

Care should be taken when cleaning the surface to prevent scratches.

We recommend cleaning the cap with a soft cloth moistened with one of the recommended solvents below. Excessive pressure should not be applied to the cap during cleaning. If the cap requires multiple cleanings it is recommended that a clean surface or cloth be used.

#### **O RECOMMENDED SOLVENTS**

The following are the recommended solvents for cleaning the CCD plastic cap.

Use of solvents other than these could result in optical or physical degradation in the plastic cap. Please consult your sales office when considering an alternative solvent.

Solvents	Symbol
Ethyl Alcohol	EtOH
Methyl Alcohol	MeOH
Isopropyl Alcohol	IPA
N-methyl Pyrrolidone	NMP

## **② MOUNTING OF THE PACKAGE**

The application of an excessive load to the package may cause the package to warp or break, or cause chips to come off internally. Particular care should be taken when mounting the package on the circuit board. Don't have any object come in contact with plastic cap. You should not reform the lead frame. We recommended to use a IC-inserter when you assemble to PCB.

Also, be care that the any of the following can cause the package to crack or dust to be generated.

- 1. Applying heat to the external leads for an extended period of time with soldering iron.
- 2. Applying repetitive bending stress to the external leads.
- 3. Rapid cooling or heating

### ③ OPERATE AND STORAGE ENVIRONMENTS

Operate in clean environments. CCD image sensors are precise optical equipment that should not be subject to mechanical shocks. Exposure to high temperatures or humidity will affect the characteristics. So avoid storage or usage in such conditions.

Keep in a case to protect from dust and dirt. Dew condensation may occur on CCD image sensors when the devices are transported from a low-temperature environment to a high-temperature environment. Avoid such rapid temperature changes.

For more details, refer to our document "Review of Quality and Reliability Handbook" (C12769E)

#### **④ ELECTROSTATIC BREAKDOWN**

CCD image sensor is protected against static electricity, but destruction due to static electricity is sometimes detected. Before handling be sure to take the following protective measures.

- 1. Ground the tools such as soldering iron, radio cutting pliers of or pincer.
- 2. Install a conductive mat or on the floor or working table to prevent the generation of static electricity.
- 3. Either handle bare handed or use non-chargeable gloves, clothes or material.
- 4. Ionized air is recommended for discharge when handling CCD image sensor.
- 5. For the shipment of mounted substrates, use box treated for prevention of static charges.
- 6. Anyone who is handling CCD image sensors, mounting them on PCBs or testing or inspecting PCBs on which CCD image sensors have been mounted must wear anti-static bands such as wrist straps and ankle straps which are grounded via a series resistance connection of about 1 MΩ.

[MEMO]

#### NOTES FOR CMOS DEVICES -

#### **1** VOLTAGE APPLICATION WAVEFORM AT INPUT PIN

Waveform distortion due to input noise or a reflected wave may cause malfunction. If the input of the CMOS device stays in the area between  $V_{IL}$  (MAX) and  $V_{IH}$  (MIN) due to noise, etc., the device may malfunction. Take care to prevent chattering noise from entering the device when the input level is fixed, and also in the transition period when the input level passes through the area between  $V_{IL}$  (MAX) and  $V_{IH}$  (MIN).

#### (2) HANDLING OF UNUSED INPUT PINS

Unconnected CMOS device inputs can be cause of malfunction. If an input pin is unconnected, it is possible that an internal input level may be generated due to noise, etc., causing malfunction. CMOS devices behave differently than Bipolar or NMOS devices. Input levels of CMOS devices must be fixed high or low by using pull-up or pull-down circuitry. Each unused pin should be connected to VDD or GND via a resistor if there is a possibility that it will be an output pin. All handling related to unused pins must be judged separately for each device and according to related specifications governing the device.

#### **③** PRECAUTION AGAINST ESD

A strong electric field, when exposed to a MOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop generation of static electricity as much as possible, and quickly dissipate it when it has occurred. Environmental control must be adequate. When it is dry, a humidifier should be used. It is recommended to avoid using insulators that easily build up static electricity. Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work benches and floors should be grounded. The operator should be grounded using a wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions need to be taken for PW boards with mounted semiconductor devices.

#### **(4)** STATUS BEFORE INITIALIZATION

Power-on does not necessarily define the initial status of a MOS device. Immediately after the power source is turned ON, devices with reset functions have not yet been initialized. Hence, power-on does not guarantee output pin levels, I/O settings or contents of registers. A device is not initialized until the reset signal is received. A reset operation must be executed immediately after power-on for devices with reset functions.

#### 5 POWER ON/OFF SEQUENCE

In the case of a device that uses different power supplies for the internal operation and external interface, as a rule, switch on the external power supply after switching on the internal power supply. When switching the power supply off, as a rule, switch off the external power supply and then the internal power supply. Use of the reverse power on/off sequences may result in the application of an overvoltage to the internal elements of the device, causing malfunction and degradation of internal elements due to the passage of an abnormal current.

The correct power on/off sequence must be judged separately for each device and according to related specifications governing the device.

#### **(6)** INPUT OF SIGNAL DURING POWER OFF STATE

Do not input signals or an I/O pull-up power supply while the device is not powered. The current injection that results from input of such a signal or I/O pull-up power supply may cause malfunction and the abnormal current that passes in the device at this time may cause degradation of internal elements. Input of signals during the power off state must be judged separately for each device and according to related specifications governing the device.

- The information in this document is current as of May, 2005. The information is subject to change without notice. For actual design-in, refer to the latest publications of NEC Electronics data sheets or data books, etc., for the most up-to-date specifications of NEC Electronics products. Not all products and/or types are available in every country. Please check with an NEC Electronics sales representative for availability and additional information.
- No part of this document may be copied or reproduced in any form or by any means without the prior written consent of NEC Electronics. NEC Electronics assumes no responsibility for any errors that may appear in this document.
- NEC Electronics does not assume any liability for infringement of patents, copyrights or other intellectual property rights of third parties by or arising from the use of NEC Electronics products listed in this document or any other liability arising from the use of such products. No license, express, implied or otherwise, is granted under any patents, copyrights or other intellectual property rights of NEC Electronics or others.
- Descriptions of circuits, software and other related information in this document are provided for illustrative purposes in semiconductor product operation and application examples. The incorporation of these circuits, software and information in the design of a customer's equipment shall be done under the full responsibility of the customer. NEC Electronics assumes no responsibility for any losses incurred by customers or third parties arising from the use of these circuits, software and information.
- While NEC Electronics endeavors to enhance the quality, reliability and safety of NEC Electronics products, customers agree and acknowledge that the possibility of defects thereof cannot be eliminated entirely. To minimize risks of damage to property or injury (including death) to persons arising from defects in NEC Electronics products, customers must incorporate sufficient safety measures in their design, such as redundancy, fire-containment and anti-failure features.
- NEC Electronics products are classified into the following three quality grades: "Standard", "Special" and "Specific".

The "Specific" quality grade applies only to NEC Electronics products developed based on a customerdesignated "quality assurance program" for a specific application. The recommended applications of an NEC Electronics product depend on its quality grade, as indicated below. Customers must check the quality grade of each NEC Electronics product before using it in a particular application.

- "Standard": Computers, office equipment, communications equipment, test and measurement equipment, audio and visual equipment, home electronic appliances, machine tools, personal electronic equipment and industrial robots.
- "Special": Transportation equipment (automobiles, trains, ships, etc.), traffic control systems, anti-disaster systems, anti-crime systems, safety equipment and medical equipment (not specifically designed for life support).
- "Specific": Aircraft, aerospace equipment, submersible repeaters, nuclear reactor control systems, life support systems and medical equipment for life support, etc.

The quality grade of NEC Electronics products is "Standard" unless otherwise expressly specified in NEC Electronics data sheets or data books, etc. If customers wish to use NEC Electronics products in applications not intended by NEC Electronics, they must contact an NEC Electronics sales representative in advance to determine NEC Electronics' willingness to support a given application.

(Note)

- (1) "NEC Electronics" as used in this statement means NEC Electronics Corporation and also includes its majority-owned subsidiaries.
- (2) "NEC Electronics products" means any product developed or manufactured by or for NEC Electronics (as defined above).